

## 3dVPM - 3D Unsteady Vortex Panel Method

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# Chapter 1

## Hierarchical Index

### 1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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## Chapter 2

# Class Index

### 2.1 Class List

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## Chapter 3

# Class Documentation

### 3.1 Domain Class Reference

[Domain](#) class to compute velocity off-surface.

```
#include <domain.hpp>
```

#### Public Member Functions

- void **set\_domain\_ranges** (const int i, const int j, const int k)
- int [get\\_IMAX](#) () const  
*returns maximum nodes in x direction*
- int [get\\_JMAX](#) () const  
*returns maximum nodes in y direction*
- int [get\\_KMAX](#) () const  
*returns maximum nodes in z direction*
- int [n\\_nodes](#) () const  
*returns total number of nodes*

#### Public Attributes

- std::vector< [vector3d](#) > [nodes](#)  
*point data of the domain mesh file*

#### 3.1.1 Detailed Description

[Domain](#) class to compute velocity off-surface.

The documentation for this class was generated from the following files:

- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/domain.hpp
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/domain.cpp

### 3.2 matlab\_writer Class Reference

writes output in matlab format. DO NOT USE - NOT a standard format

```
#include <matlab_writer.hpp>
```

## Public Member Functions

- void **write\_surface\_mesh** (std::string filename, const std::shared\_ptr< [Surface](#) > surface)
- template<class T >  
void **write\_surface\_data** (std::string filename, const std::shared\_ptr< [Surface](#) > surface, const std::vector< T > &data, std::string name, bool writemesh=false)
- template<class T >  
void **write\_domain\_data** (std::string filename, std::shared\_ptr< [Domain](#) > domain, std::vector< T > data, std::string name, bool writemesh)

### 3.2.1 Detailed Description

writes output in matlab format. DO NOT USE - NOT a standard format

The documentation for this class was generated from the following files:

- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/matlab\_writer.hpp
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/matlab\_writer.cpp

## 3.3 Parameters Class Reference

Defines certain parameters used in the panel method.

```
#include <parameters.hpp>
```

### Static Public Attributes

- static double [inversion\\_tolerance](#) = 1e-12  
*tolerance check for division*
- static double [farfield\\_factor](#) = 10.0  
*farfield factor*
- static double [trailing\\_edge\\_wake\\_shed\\_factor](#) = 0.25  
*controls the trailing edge wake panel distance*
- static bool [unsteady\\_problem](#) = false  
*decides whether problem is steady or unsteady*
- static bool [static\\_wake](#) = false  
*decides whether to use static wake or force free wake model*
- static double [static\\_wake\\_length](#) = 1.0  
*sets static wake length*
- static bool [use\\_vortex\\_core\\_model](#) = false  
*decides whether to use vortex core model*

### 3.3.1 Detailed Description

Defines certain parameters used in the panel method.

The documentation for this class was generated from the following files:

- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/parameters.hpp
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/parameters.cpp

## 3.4 PLOT3D Class Reference

**PLOT3D** class to read plot3D mesh file and manipulates surface object.

```
#include <plot3d.hpp>
```

### Public Member Functions

- void **set\_surface\_filename** (std::string)  
*set file name to read*
- void **set\_surface** (std::shared\_ptr< **Surface** >)  
*connect to surface object*
- void **flip\_normals** (bool)  
*Flips the normals of the surface.*
- void **read\_surface** (std::string name)  
*read the plot3d mesh file*
- void **build\_topology** ()  
*buid topology from mesh file*
- void **set\_domain** (std::shared\_ptr< **Domain** >)  
*connect to domain object*
- void **read\_domain** (std::string name)  
*read mesh file for the domain*

#### 3.4.1 Detailed Description

**PLOT3D** class to read plot3D mesh file and manipulates surface object.

The documentation for this class was generated from the following files:

- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/plot3d.hpp
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/plot3d.cpp

## 3.5 Solver Class Reference

**Solver** class for 3D unsteady panel method.

```
#include <solver.hpp>
```

### Public Member Functions

- **Solver** (int argC, char \*\*argS)  
*constructor - takes command line arguments*
- void **add\_surface** (const std::shared\_ptr< **Surface** >)  
*attaches surface object with solver*
- void **add\_wake** (const std::shared\_ptr< **Wake** >)  
*attaches wake object with solver*
- void **add\_logger** (const std::shared\_ptr< **vtk\_writer** >)  
*attaches vtk-logger object with solver*
- void **add\_logger** (const std::shared\_ptr< **matlab\_writer** >)  
*attaches matlab-logger object with solver*
- void **set\_free\_stream\_velocity** (const **vector3d** &)

- Set free stream velocity.*
- void `set_reference_velocity` (const `vector3d` &)
- Set reference velocity.*
- void `set_fluid_density` (const double value)
- Set fluid density velocity.*
- void `solve` (const double dt, int iteration=0)
- driver function of solver*
- void `convect_wake` (const double &dt)
- convects the wake with local induced velocity*
- void `compute_domain_velocity` (const std::shared\_ptr< `Domain` > domain)
- compute velocity at each node in the domain*
- void `finalize_iteration` ()
- performs some post-solution operations*
- `vector3d` `get_body_forces` () const
- Returns body force vectors.*
- `vector3d` `get_body_force_coefficients` () const
- Returns body force coefficients.*
- double `get_pressure_coefficient` (const int panel) const
- Returns pressure coefficients.*
- void `write_output` (const int &iteration) const
- Write output to a file.*
- void `write_matlab_output` () const
- Write output to matlab format - do not use!*

### 3.5.1 Detailed Description

`Solver` class for 3D unsteady panel method.

`Solver` class calculates the solution of the given problem. Takes input in terms of surface, wake, configurational parameters such as surface velocity, free stream velocity, reference velocity, density, etc. Calculates the solution in terms of surface velocity, pressure, body forces (and force coefficients). Also write output to vtk files.

### 3.5.2 Member Function Documentation

#### 3.5.2.1 void `Solver::solve` ( const double *dt*, int *iteration* = 0 )

driver function of solver

The function is responsible for solution of given problem. The function calculates and influence coefficients, applied boundary conditions, builds system of equations, solves them, post-processes solution, write them in output file.

The documentation for this class was generated from the following files:

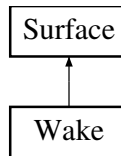
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/solver.hpp
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/solver.cpp

## 3.6 Surface Class Reference

`Surface` class to represent geometry and perform various operations on it.

```
#include <surface.hpp>
```

Inheritance diagram for `Surface`:



## Public Member Functions

- `int n_panels () const`  
*returns number of panels in the current surface*
- `int n_nodes () const`  
*returns total number of nodes in the current surface*
- `void compute_panel_components ()`  
*Computes the panel components.*
- `vector3d & get_collocation_point (int panel)`  
*returns panel's collocation point by reference*
- `vector3d get_collocation_point (int panel) const`  
*returns panel's collocation point*
- `void translate_surface (const vector3d &dX)`  
*translates the surface by distance dX*
- `void rotate_surface (vector3d dTheta, bool isRadian)`  
*rotates the surface by an angle*
- `void set_linear_velocity (const vector3d &)`  
*Set the linear velocity of the surface.*
- `void set_angular_velocity (vector3d vel, bool isRadian_sec)`  
*Set angular velocity of the body.*
- `int n_trailing_edge_nodes () const`  
*returns number of trailing edge nodes*
- `int n_trailing_edge_panels () const`  
*returns number of trailing edge panels*
- `vector3d get_trailing_edge_bisector (const int) const`  
*returns trailing edge bisector*
- `vector3d get_kinematic_velocity (const vector3d &) const`  
*returns kinematic velocity at a point on surface*
- `vector3d get_panel_normal (const int) const`  
*return panel's normal vector*
- `double compute_source_panel_influence (const int panel, const vector3d &node) const`  
*computes the influence coefficient due to source panel*
- `double compute_doublet_panel_influence (const int panel, const vector3d &node) const`  
*computes the influence coefficient due to doublet panel*
- `std::pair< double, double > compute_source_doublet_panel_influence (const int panel, const vector3d &node) const`  
*computes the influence coefficient due to source and doublet panel*
- `vector3d transform_point_panel (int panel, const vector3d &x) const`  
*transforms a point in a panel's local coordinate*
- `vector3d transform_vector_panel_inverse (int panel, const vector3d &x) const`  
*transforms a point from panel's local coordinate to global coordinate*
- `vector3d transform_vector_panel (int panel, const vector3d &x) const`  
*transforms a vector in a panel's local coordinate*
- `double get_panel_area (const int &panel) const`

*transforms a vector from panel's local coordinate to global coordinate*

- [vector3d compute\\_source\\_panel\\_unit\\_velocity](#) (const int &panel, const [vector3d](#) &node) const  
*computes the induced velocity due to source panel at a point*
- [vector3d compute\\_doublet\\_panel\\_unit\\_velocity](#) (const int &panel, const [vector3d](#) &node) const  
*computes the induced velocity due to doublet panel at a point*

## Public Attributes

- std::vector< [vector3d](#) > [nodes](#)  
*stores node data containing x,y,z coordinate*
- std::vector< std::vector< int > > [panels](#)  
*panel vector containing vector of its nodes*
- std::vector< std::vector< int > > [panel\\_neighbours](#)  
*stores the neighbouring panel ids*
- std::vector< int > [trailing\\_edge\\_nodes](#)  
*nodes on trailing edge*
- std::vector< int > [upper\\_TE\\_panels](#)  
*panels connected to upper trailing edge*
- std::vector< int > [lower\\_TE\\_panels](#)  
*panels connected to lower trailing edge*

## 3.6.1 Detailed Description

[Surface](#) class to represent geometry and perform various operations on it.

Class for containing geometry entities and functions to perform operations on them

## 3.6.2 Member Function Documentation

### 3.6.2.1 double Surface::compute\_doublet\_panel\_influence ( const int *panel*, const [vector3d](#) & *node* ) const

computes the influence coefficient due to doublet panel

Parameters

in	<i>panel</i>	doublet panel whose influence is sought
in	<i>node</i>	point which is being influenced by <b>panel</b>
in	<i>double</i>	return influence due to unit doublet strength panel

### 3.6.2.2 [vector3d](#) Surface::compute\_doublet\_panel\_unit\_velocity ( const int & *panel*, const [vector3d](#) & *node* ) const

computes the induced velocity due to doublet panel at a point

Parameters

in	<i>panel</i>	doublet panel
in	<i>node</i>	point at which induced velocity by <b>panel</b> is sought
in	<a href="#">vector3d</a>	return induced velocity vector

### 3.6.2.3 void Surface::compute\_panel\_components ( )

Computes the panel components.

computes panel collocation point, panel local coordinates, area, panel transformations and farfield factors

**3.6.2.4** `std::pair< double, double > Surface::compute_source_doublet_panel_influence ( const int panel, const vector3d & node ) const`

computes the influence coefficient due to source and doublet panel

Parameters

in	<i>panel</i>	panel whose influence is sought
in	<i>node</i>	point which is being influenced by <b>panel</b>
in	<i>pair&lt; double, double &gt;</i>	return influence due to unit strength source and doublet panel

**3.6.2.5** `double Surface::compute_source_panel_influence ( const int panel, const vector3d & node ) const`

computes the influence coefficient due to source panel

Parameters

in	<i>panel</i>	source panel whose influence is sought
in	<i>node</i>	point which is being influenced by <b>panel</b>
in	<i>double</i>	return in the influence due to unit source strength panel

**3.6.2.6** `vector3d Surface::compute_source_panel_unit_velocity ( const int & panel, const vector3d & node ) const`

computes the induced velocity due to source panel at a point

Parameters

in	<i>panel</i>	source panel
in	<i>node</i>	point at which induced velocity by <b>panel</b> is sought
in	<i>vector3d</i>	return induced velocity vector

**3.6.2.7** `vector3d & Surface::get_collocation_point ( int panel )`

returns panel's collocation point by reference

Parameters

in	<i>panel</i>	panel number
out	<i>vector3d&amp;</i>	panel collocation point by reference

**3.6.2.8** `vector3d Surface::get_collocation_point ( int panel ) const`

returns panel's collocation point

Parameters

in	<i>panel</i>	panel number
out	<i>vector3d</i>	panel collocation point

**3.6.2.9** `vector3d Surface::get_kinematic_velocity ( const vector3d & x ) const`

returns kinematic velocity at a point on surface

## Parameters

in	x	input location
out	<i>vector3d</i>	kinematic velocity due to surface's motion

3.6.2.10 **vector3d** Surface::get\_trailing\_edge\_bisector ( const int *TE\_node* ) const

returns trailing edge bisector

## Parameters

in	<i>TE_node</i>	trailing edge node
out	<i>vector3d</i>	normalized vector which points in the bisector at <b>TE_node</b>

## 3.6.2.11 int Surface::n\_nodes ( ) const

returns total number of nodes in the current surface

## Parameters

out	int	total number of nodes in the surface
-----	-----	--------------------------------------

## 3.6.2.12 int Surface::n\_panels ( ) const

returns number of panels in the current surface

## Parameters

out	int	total number of panels in the surface
-----	-----	---------------------------------------

3.6.2.13 void Surface::rotate\_surface ( **vector3d** *dTheta*, bool *isRadian* )

rotates the surface by an angle

## Parameters

in	<i>dTheta</i>	angle by which to rotate the surface
in	<i>isRadian</i>	true if <b>dTheta</b> is in radians, false otherwise

3.6.2.14 void Surface::set\_angular\_velocity ( **vector3d** *vel*, bool *isRadian\_sec* )

Set angular velocity of the body.

## Parameters

in	<i>vel</i>	angular velocity
in	<i>isRadian_sec</i>	true if <b>vel</b> is in radians per seconds

3.6.2.15 void Surface::translate\_surface ( const **vector3d** & *dX* )

translates the surface by distance dX



## Parameters

in	dX	distance vector
----	----	-----------------

## 3.6.3 Member Data Documentation

3.6.3.1 `std::vector<std::vector<int> > Surface::panel_neighbours`

stores the neighbouring panel ids

stores neighbouring panel ids - required in surface velocity calculations

3.6.3.2 `std::vector<std::vector<int> > Surface::panels`

panel vector containing vector of its nodes

represents panel vector. Each panel contains node number associated with it the node numbers are in counter-clockwise order

The documentation for this class was generated from the following files:

- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/surface.hpp
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/surface.cpp

## 3.7 vector3d Class Reference

`vector3d` class to represent an array of size 3

```
#include <vector3d.h>
```

## Public Member Functions

- `vector3d` (double a, double b, double c)
- `vector3d` (const `vector3d` &vec)
- double `operator[]` (int i) const
- double & `operator[]` (int i)
- void `operator=` (const `vector3d` &vec)
- const `vector3d` & `operator=` (const `vector3d` &vec) const
- double `dot` (const `vector3d` &vec)
- `vector3d` `cross` (const `vector3d` &vec) const
- void `normalize` ()
- double `squared_norm` () const
- double `norm` () const
- int `size` () const
- `vector3d` `operator-` (const `vector3d` &vec) const
- `vector3d` `operator+` (const `vector3d` &vec) const
- void `print` ()
- `vector3d` `operator/` (const double &val) const
- `vector3d` `operator*` (const double &val) const
- void `operator=` (const double val)
- `vector3d` `operator-` () const
- `operator vector3d &` ()
- `operator vector3d const &` () const
- double \* `begin` ()
- void `operator+=` (const `vector3d` &vec)

- void **operator-=** (const [vector3d](#) &vec)
- void **operator\*=** (const double &x)
- [vector3d](#) **operator/** (const [vector3d](#) &vec) const

## Friends

- std::ostream & **operator<<** (std::ostream &os, const [vector3d](#) &vec)

### 3.7.1 Detailed Description

[vector3d](#) class to represent an array of size 3

useful in representing 3d point coordinates, vectors, forces, etc. Also performs some basic operations, helps in reducing equations sizes

The documentation for this class was generated from the following file:

- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/vector3d.h

## 3.8 vtk\_writer Class Reference

[vtk\\_writer](#) class to write output in vtk format

```
#include <vtk_writer.hpp>
```

### Public Member Functions

- template<class T >  
void [write\\_surface\\_data](#) (std::string filename, const std::shared\_ptr< [Surface](#) > surface, const std::vector< T > &data, std::string name, bool writemesh)  
*writes surface data to a file*
- void [write\\_surface\\_mesh](#) (std::string filename, std::shared\_ptr< [Surface](#) >)  
*write mesh data to vtk format*
- void [write\\_domain\\_mesh](#) (std::string filename, std::shared\_ptr< [Domain](#) >)  
*write domain mesh to vtk format*
- template<class T >  
void [write\\_domain\\_data](#) (std::string filename, std::shared\_ptr< [Domain](#) > domain, std::vector< T > data, std::string name, bool writemesh)  
*writes surface data to a file*

### 3.8.1 Detailed Description

[vtk\\_writer](#) class to write output in vtk format

### 3.8.2 Member Function Documentation

- 3.8.2.1 template<class T > void vtk\_writer::write\_domain\_data ( std::string *filename*, std::shared\_ptr< [Domain](#) > *domain*, std::vector< T > *data*, std::string *name*, bool *writemesh* ) [inline]

writes surface data to a file

## Parameters

in	<i>filename</i>	filename of the output file, extension will be attaced automatically
in	<i>domain</i>	domain to write
in	<i>data</i>	data to write for a given <b>domain</b>
in	<i>name</i>	name of the <b>data</b> variable
in	<i>writemesh</i>	true if mesh data needs to be written, else false

3.8.2.2 `template<class T > void vtk_writer::write_surface_data ( std::string filename, const std::shared_ptr< Surface > surface, const std::vector< T > & data, std::string name, bool writemesh ) [inline]`

writes surface data to a file

## Parameters

in	<i>filename</i>	filename of the output file, extension will be attaced automatically
in	<i>surface</i>	surface to write
in	<i>data</i>	data to write for a given <b>surface</b>
in	<i>name</i>	name of the <b>data</b> variable
in	<i>writemesh</i>	true if mesh data needs to be written, else false

The documentation for this class was generated from the following files:

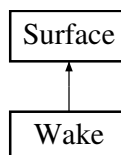
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/vtk\_writer.hpp
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/vtk\_writer.cpp

## 3.9 Wake Class Reference

[Wake](#) class to represent wake of a body.

```
#include <wake.hpp>
```

Inheritance diagram for Wake:



### Public Member Functions

- void [add\\_lifting\\_surface](#) (const std::shared\_ptr< [Surface](#) > surf)  
*associate with surface object*
- void [initialize](#) (const [vector3d](#) &free\_stream\_velocity, const double &dt)  
*create first row of wake panels*
- void [build\\_topology](#) ()  
*build topology of the wake panels, such as connectivity information*
- void [shed\\_wake](#) (const [vector3d](#) &free\_stream\_velocity, double dt)  
*adds a row of wake panels*

### Additional Inherited Members

### 3.9.1 Detailed Description

[Wake](#) class to represent wake of a body.

The documentation for this class was generated from the following files:

- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/wake.hpp
- /home/pranav/Google Drive/Classes/wind-turbine/panel\_method/code/3dVPM/3dVPM/src/wake.cpp