

Diverse Image-to-Image Translation via Disentangled Representations

Code available!
<http://bit.ly/DRIT-ECCV18>

UNIVERSITY OF CALIFORNIA
UC MERCED

VT
 VIRGINIA TECH™

Hsin-Ying Lee^{*1} Hung-Yu Tseng^{*1} Jia-Bin Huang² Maneesh Singh³ Ming-Hsuan Yang^{1,4}

¹University of California, Merced

²Virginia Tech

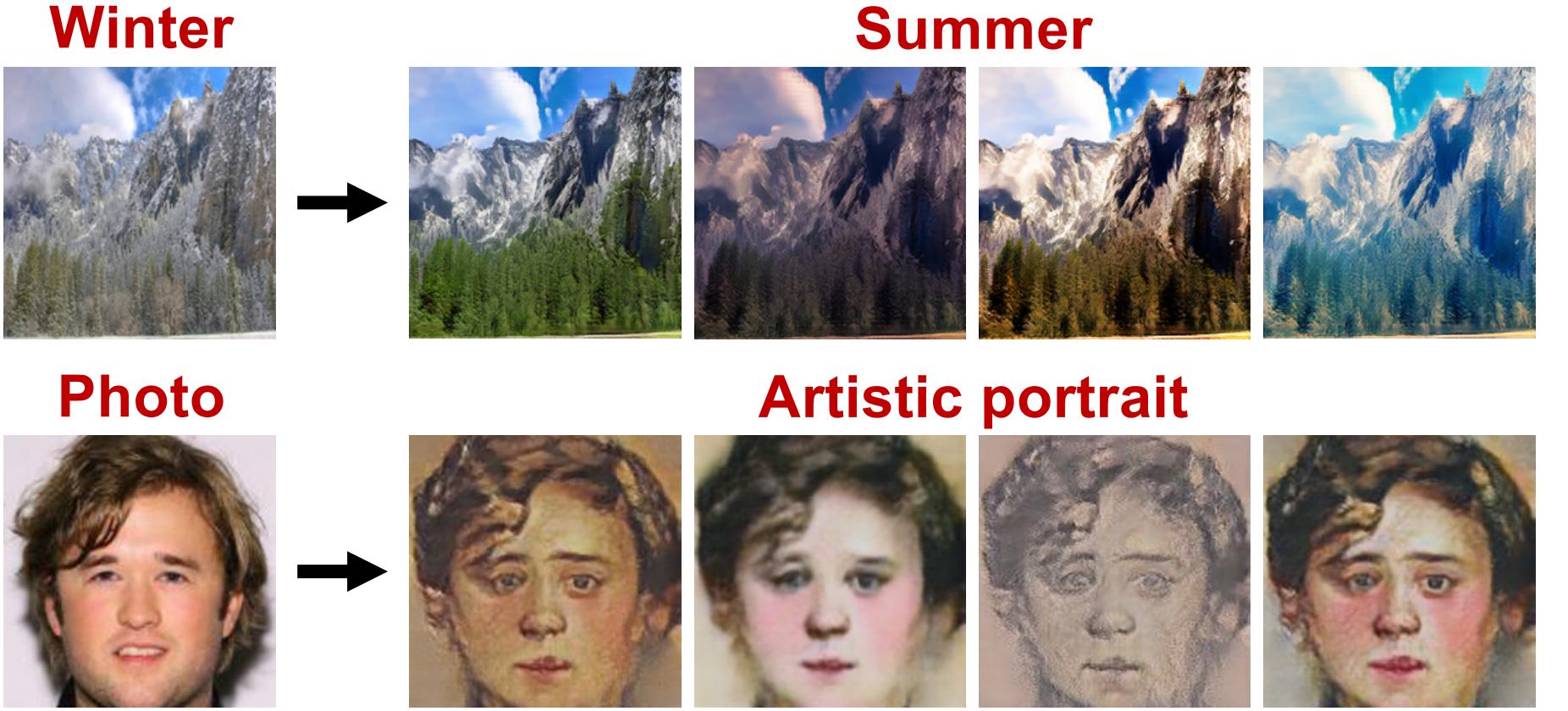
³Verisk Analytics

⁴Google Cloud AI

Verisk
 Analytics

Google Cloud

Image-to-image translation



Challenges

1. Lack of aligned training pairs
2. Multiple possible outputs given single input image

	Paired data	Unpaired data
One-to-one	Pix2pix [Isola et al.]	DiscoGAN [Kim et al.] CycleGAN [Zhu et al.] UNIT [Liu et al.]
One-to-many	BicycleGAN [Zhu et al.] Pix2pixHD [Wang et al.]	DRIT (Ours)

Contributions

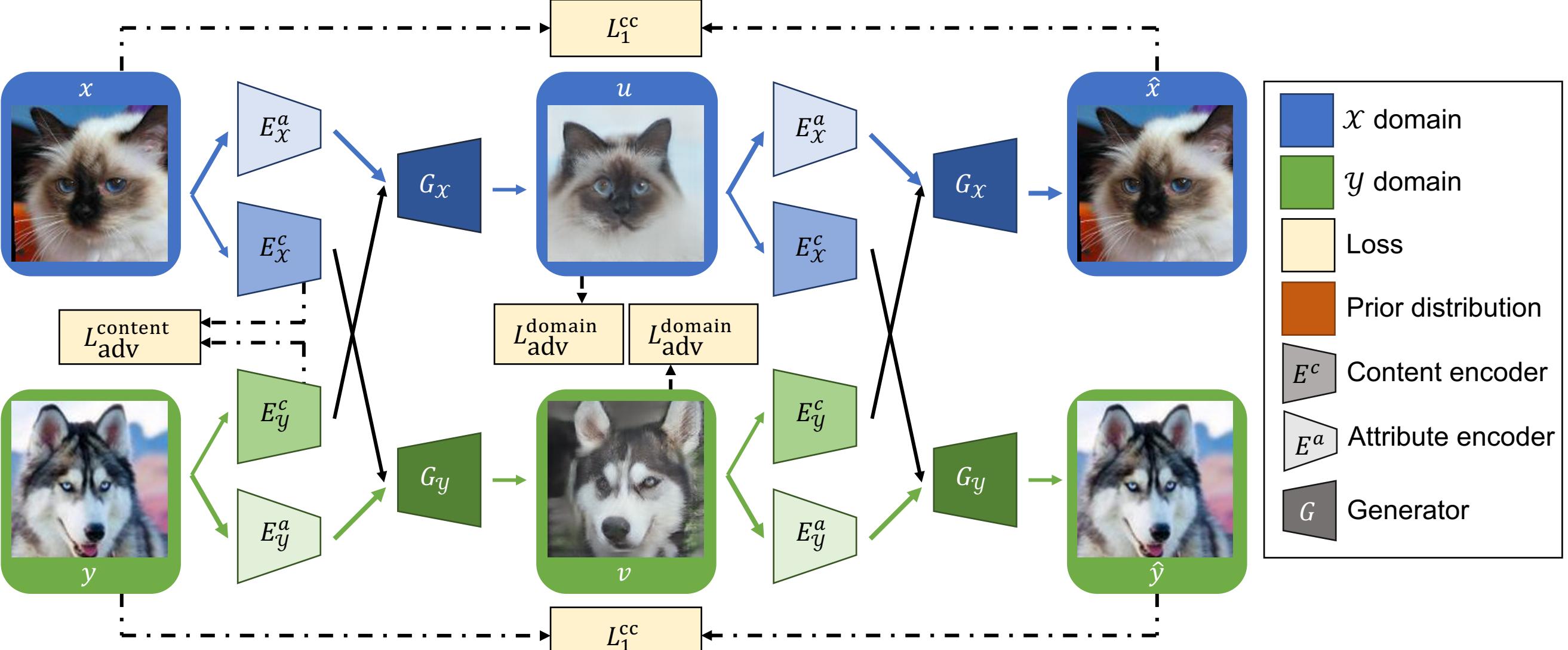
1. Disentangled representation & cross cycle consistency
2. Diverse translation from unpaired data
3. Competitive performance on domain adaptation

References

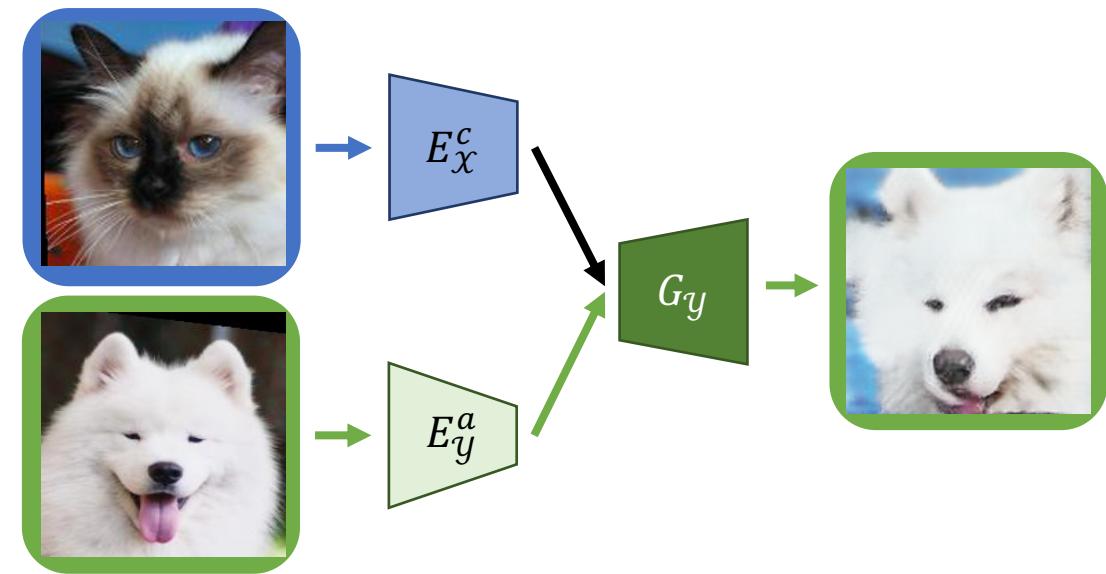
- [1] Liu et al. Unsupervised Image-to-Image Translation Networks. In NIPS, 2017
- [2] Zhu et al. Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks. In ICCV, 2017
- [3] Zhu et al. Toward Multimodal Image-to-Image Translation. In NIPS, 2017

Disentangled representation for image-to-image translation (DRIT)

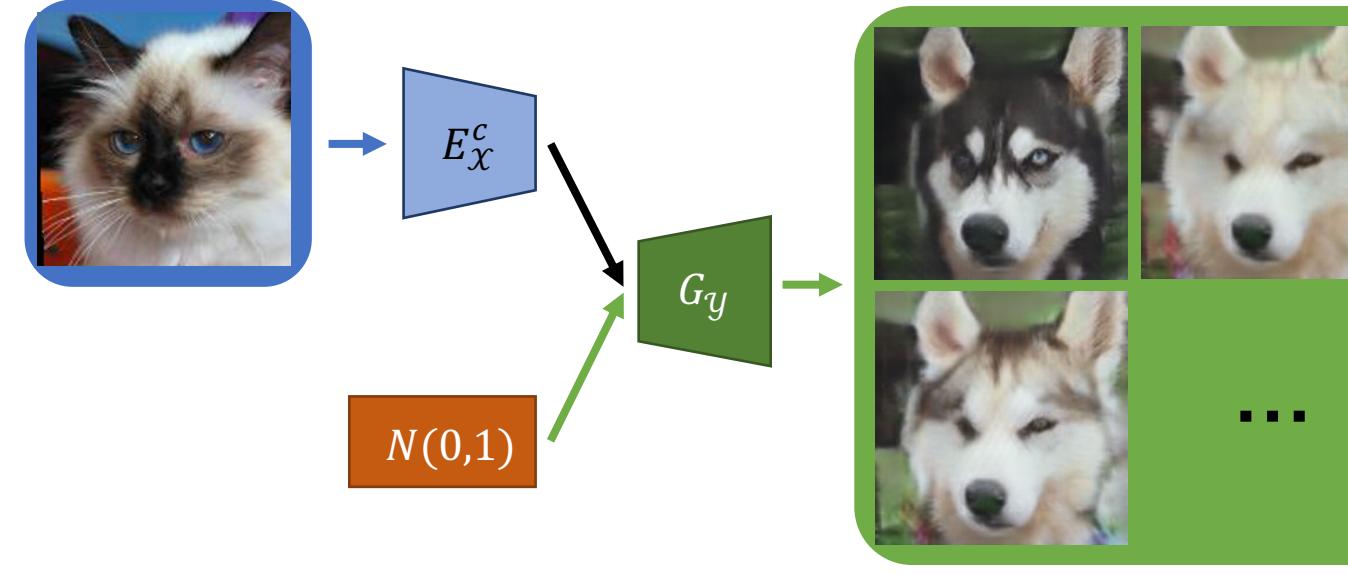
Training



Example guided translation



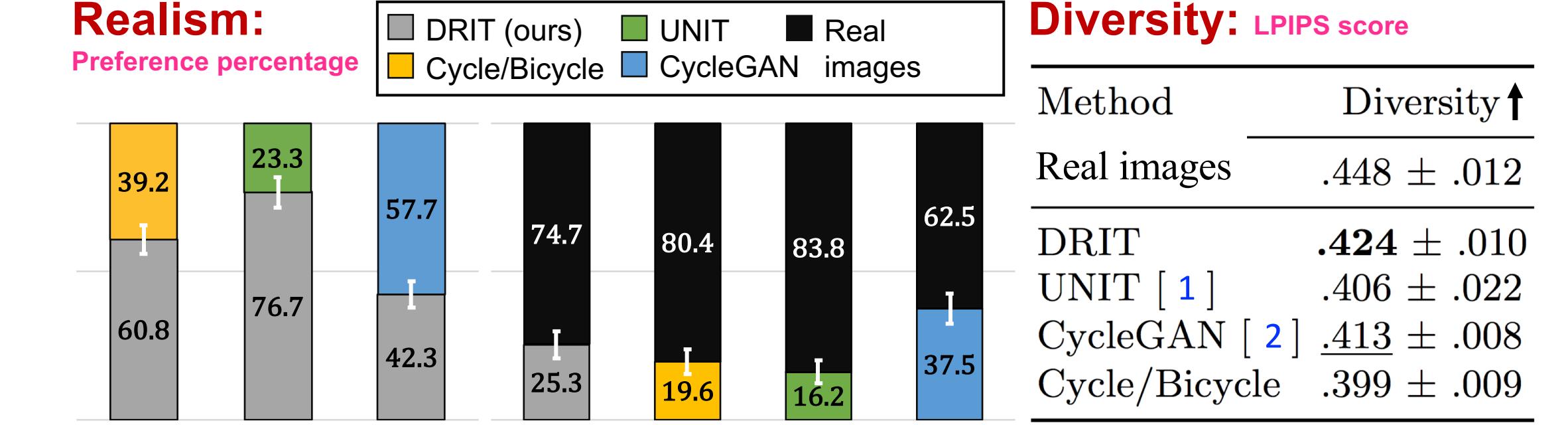
Randomly sampled translation



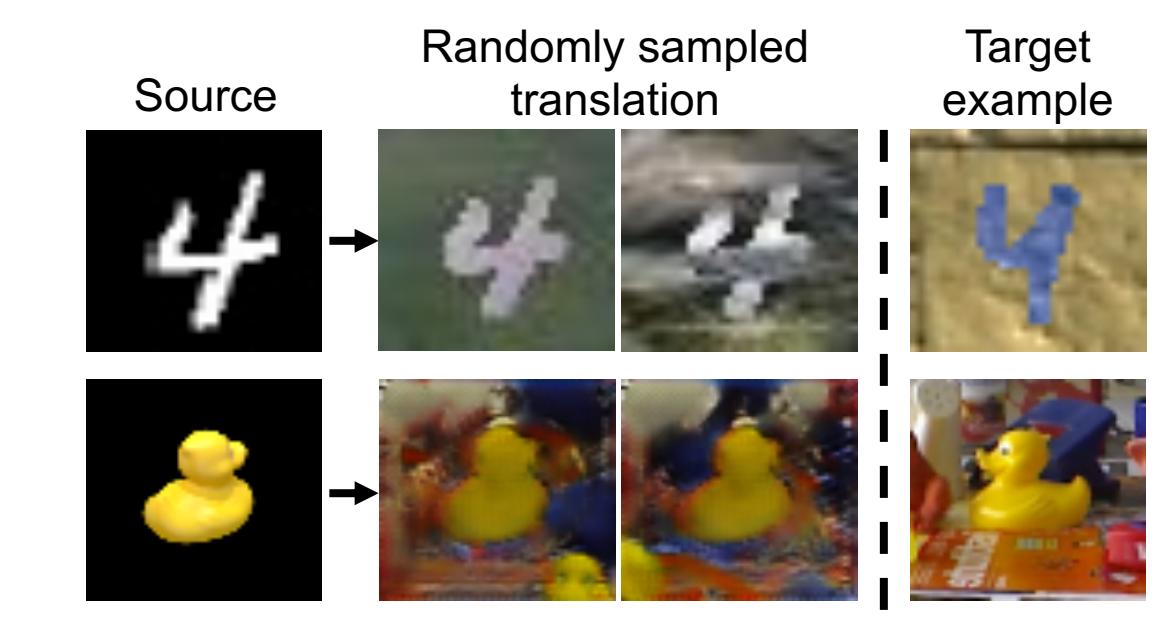
Experimental results



Realism: Preference percentage



Domain adaptation



(a) MNIST-M

Model	Classification Accuracy (%)	Mean Angle Error (°)
Source-only	56.6	73.7 (89.2)
CycleGAN [2]	74.5	47.45
Ours, ×1	86.93	42.06
Ours, ×3	90.21	37.35
Ours, ×5	91.54	34.4
Target-only	96.5	12.3 (6.47)

(b) LineMOD