

UNIVERSITY OF TORONTO
Faculty of Applied Science and Engineering
FINAL EXAMINATION, DECEMBER 2001
Fourth Year
AER 501F -- Advanced Mechanics of Structures
Examiner – J. S. Hansen

Note: This is a closed book examination. Calculators are allowed.
Answer ALL questions.

MARKS

1. Answer the following as briefly as possible:

- (5) (a) The potential energy for a two degree of freedom system is given by

$$\Phi(x) = \frac{1}{2} [x^2 - 3xy + y^2] - Px - 2Py$$

where x, y are the generalized coordinates. Is the equilibrium configuration for this system stable or unstable. Why?

- (5) (b) Describe the essential differences between forced and natural boundary conditions in structural mechanics problems.
- (5) (c) Describe the relation between the methods of Galerkin and Ritz in terms of the relation between the Principals of Virtual Work and a Stationary Value of the Total Potential Energy?
- (5) (d) When solving for the natural frequencies of a vibrating shell using the finite element method you determine that the least natural frequency is negative. What does this imply?
- (5) (e) The rectangular element illustrated in Figure 1 is to be used in a finite element analysis which requires C^0 continuous trial functions. The unknown variables are the deflections in the x, y directions $u(x, y), v(x, y)$.



Figure 1

The trial functions are adopted in the form

$$\bar{u}(x, y) = a_0 + a_1 x + a_2 x^2 + a_3 x^3$$

$$\bar{v}(x, y) = b_0 + b_1 y + b_2 y^2 + b_3 y^3$$

Are these trial functions acceptable within the context of a finite element analysis using the element shown? Why or why not?

- (5) (f) The beam problem illustrated in Figure 2 is to be analyzed using the finite element method. What choice of grid will assist in obtaining an accurate solution? Explain your answer.

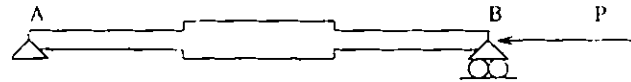


Figure 2

- (10) 2. Given the optimization problem

$$F(X_1, X_2) = X_1^3 + 2X_1X_2^2 + 2X_1^2 - X_1X_2 + X_2^2 + 3X_1 - X_2$$

Consider the current design point to be $X_1^o = 1$; $X_2^o = 2$. Based on the desire to obtain a minimum value of $F(X_1, X_2)$ determine:

- (a) The search direction relative to the current design to be used using the method of steepest descent.
- (b) The equations to be solved in the next step using Newton's method.
- (40) 3. A curved cantilevered beam is shown in Figure 3. The Total Potential Energy for this problem is

$$\Phi = \frac{EA}{2R} \int_0^{\pi/2} [(u + v')^2 + Z(u + u'')^2] d\theta - Fv(\pi/2)$$

while the forced boundary conditions are:

$$u(0) = u'(0) = v(0) = 0$$

In the above, primes denote derivatives with respect to θ . In addition, E , A and R are the Young's modulus, the beam cross-sectional area and the radius of the beam centre-line respectively while Z is a shape parameter which is constant.

- (a) Using the calculus of variations determine the equilibrium equations and the natural boundary conditions for this problem.
- (b) Using the trial functions $\hat{u}(\theta) = a_1(1 - \cos \theta)$ and $\hat{v}(\theta) = a_2 \sin \theta$ determine the algebraic equilibrium equations using the method of Ritz.
- Note: It is not necessary to solve the resulting equations.
- (c) Determine the simplest basis functions which can be used to model $u(\theta)$, $v(\theta)$ within the context of the finite element method.
- (20) 4. The symmetric truss shown in Figure 4 is subjected to loads P_1, P_2 as illustrated and the response variables u_1, u_2 have direction and sign corresponding to these loads. The design variables in the problem are the cross-sectional areas of the bars designated as A_1, A_2 and the location of the middle node determined by Y . Young's modulus E is the same for all bars and is fixed.

Three load cases are to be considered:

Case 1: $P_1^1 = 40$; $P_2^1 = 0$
Case 2: $P_1^2 = 0$; $P_2^2 = 25$
Case 3: $P_1^3 = 15$; $P_2^3 = 15$

(Note: In the above, the superscript refers to the load case.) The stresses in the bars must satisfy:

Bar 1: $-15 \leq \sigma_1 \leq 20$
Bar 2: $-10 \leq \sigma_2 \leq 10$

Using the displacement approach, formulate the optimal design problem which will yield a minimum weight design. It is not necessary to solve the equations, but the formulation should be completed to a stage where the next step would be to solve the equations.

TOTAL
(100)

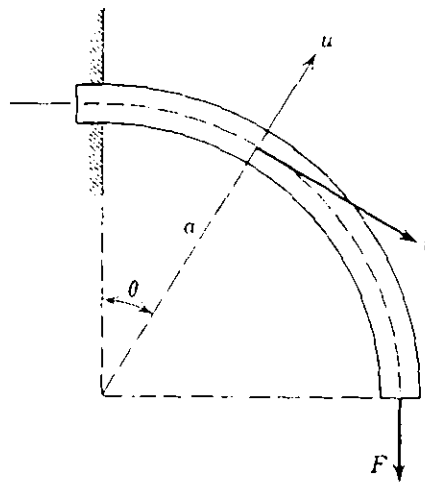


Figure 3

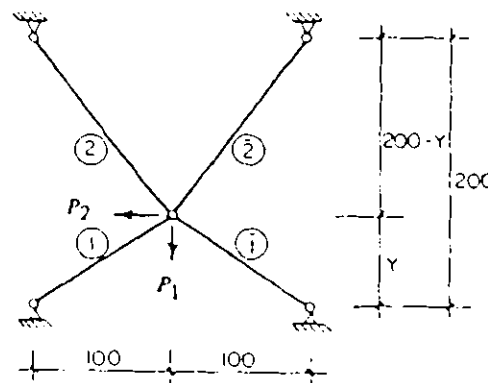


Figure 4