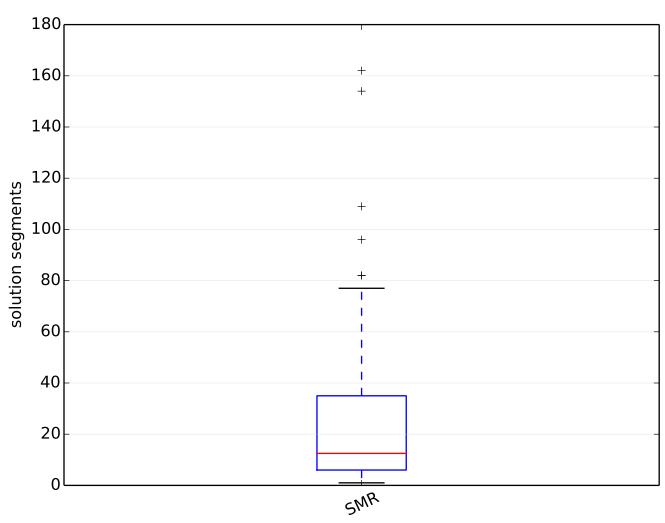
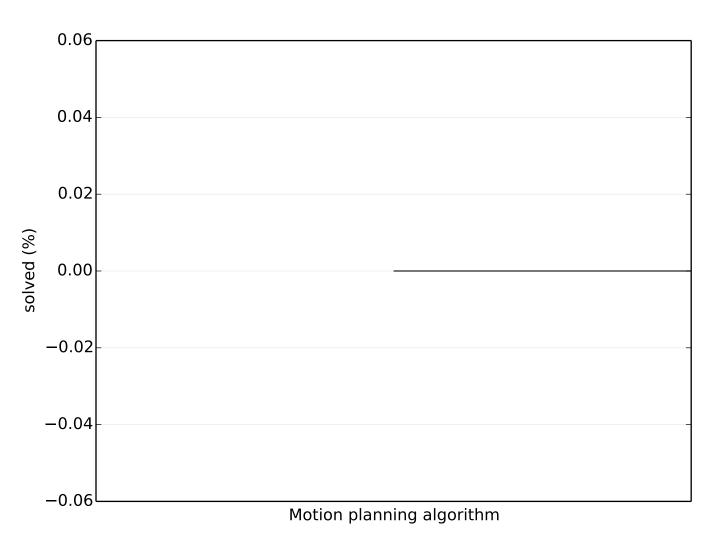
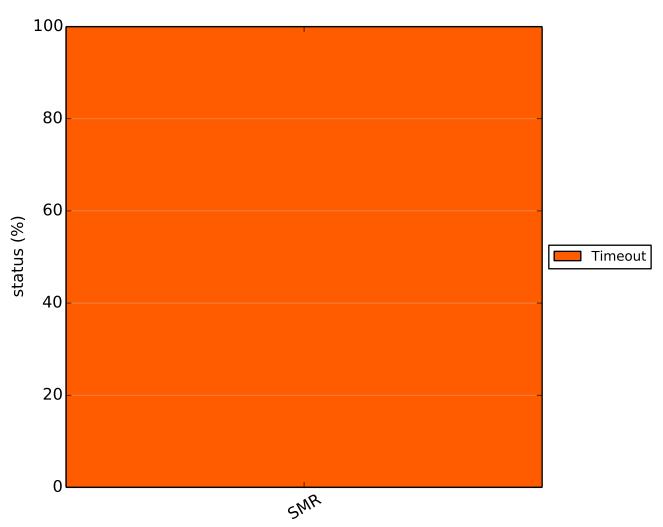


Motion planning algorithm

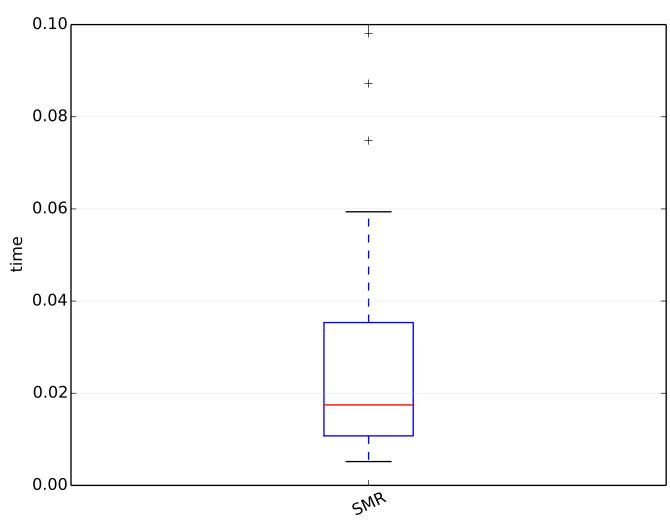


Motion planning algorithm

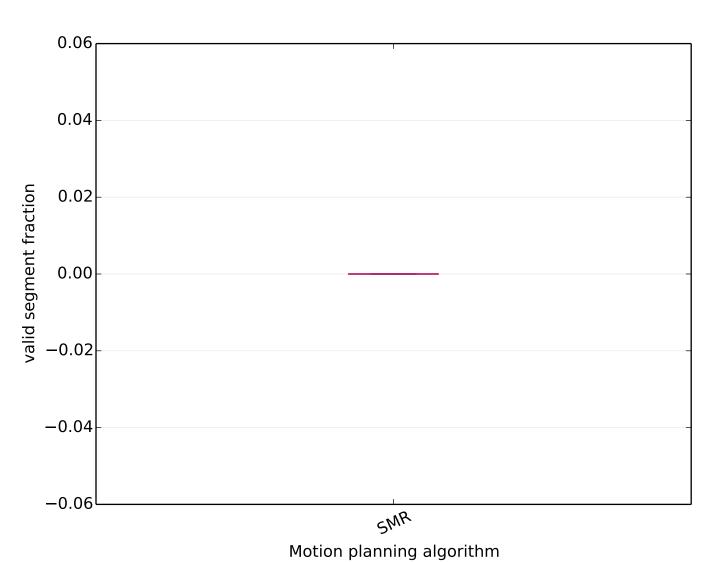




Motion planning algorithm



Motion planning algorithm



Experiment "benchmark_sd0.040000"

Number of averaged runs: 100

Time limit per run: 20 seconds

Memory limit per run: 1000 MB