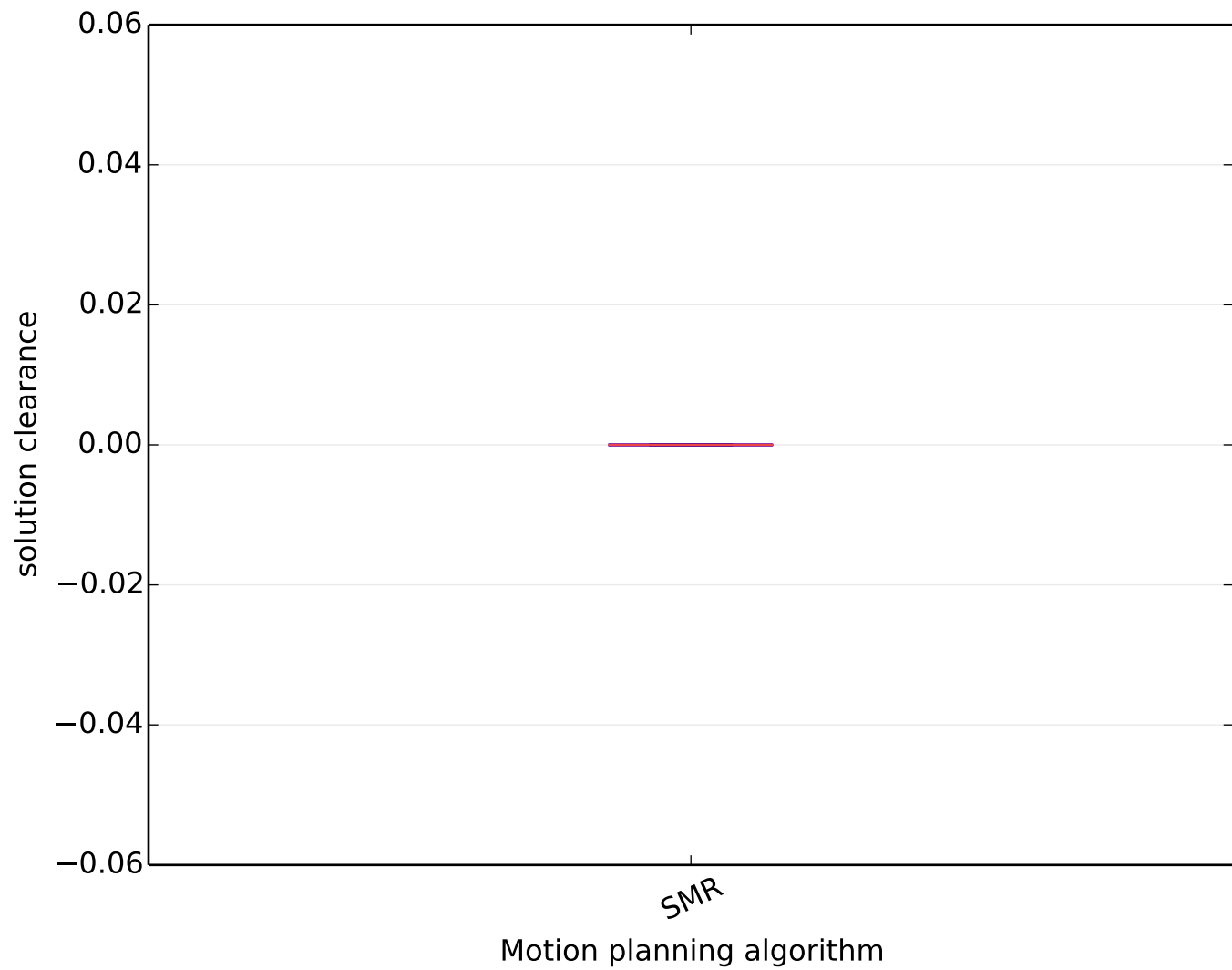
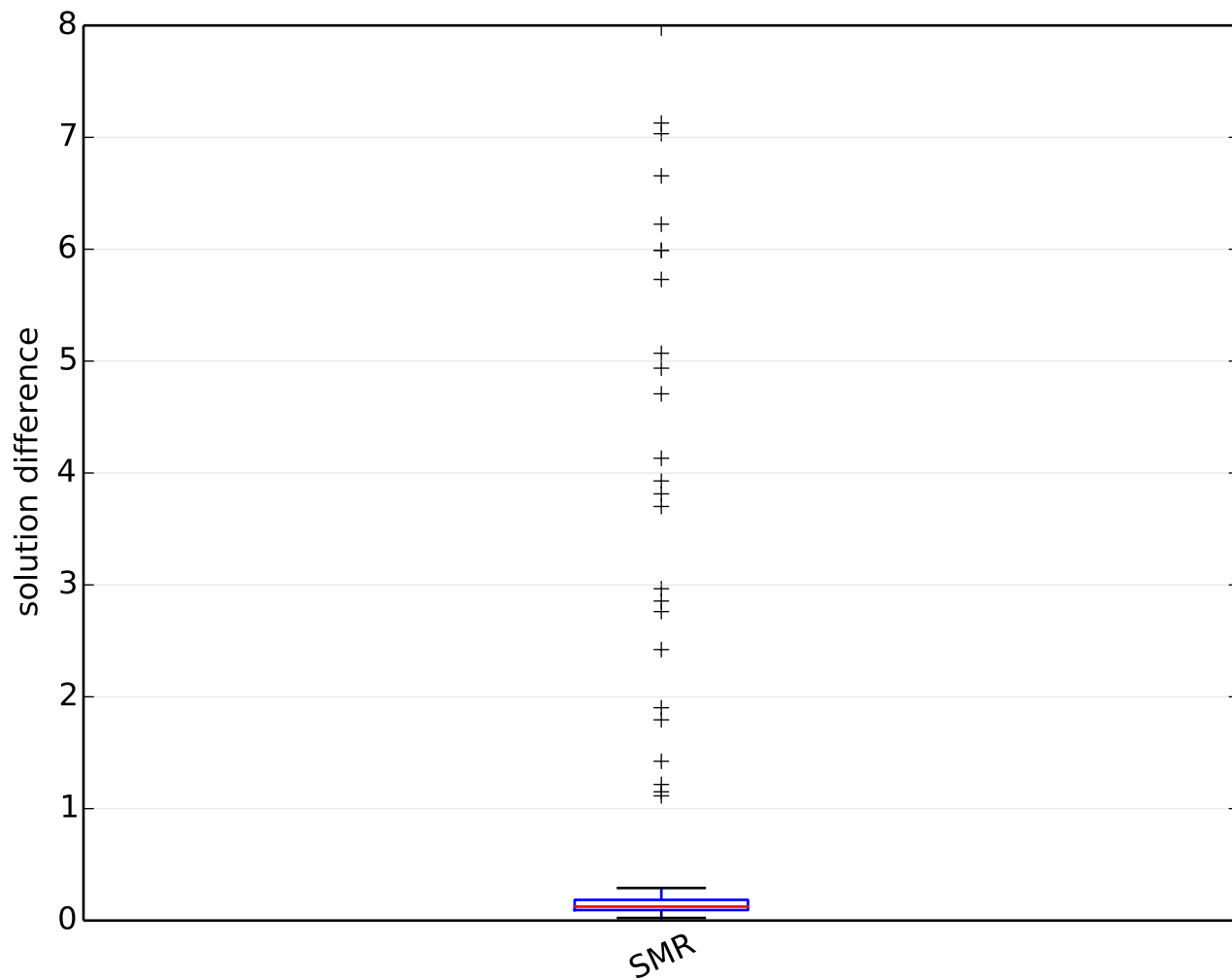
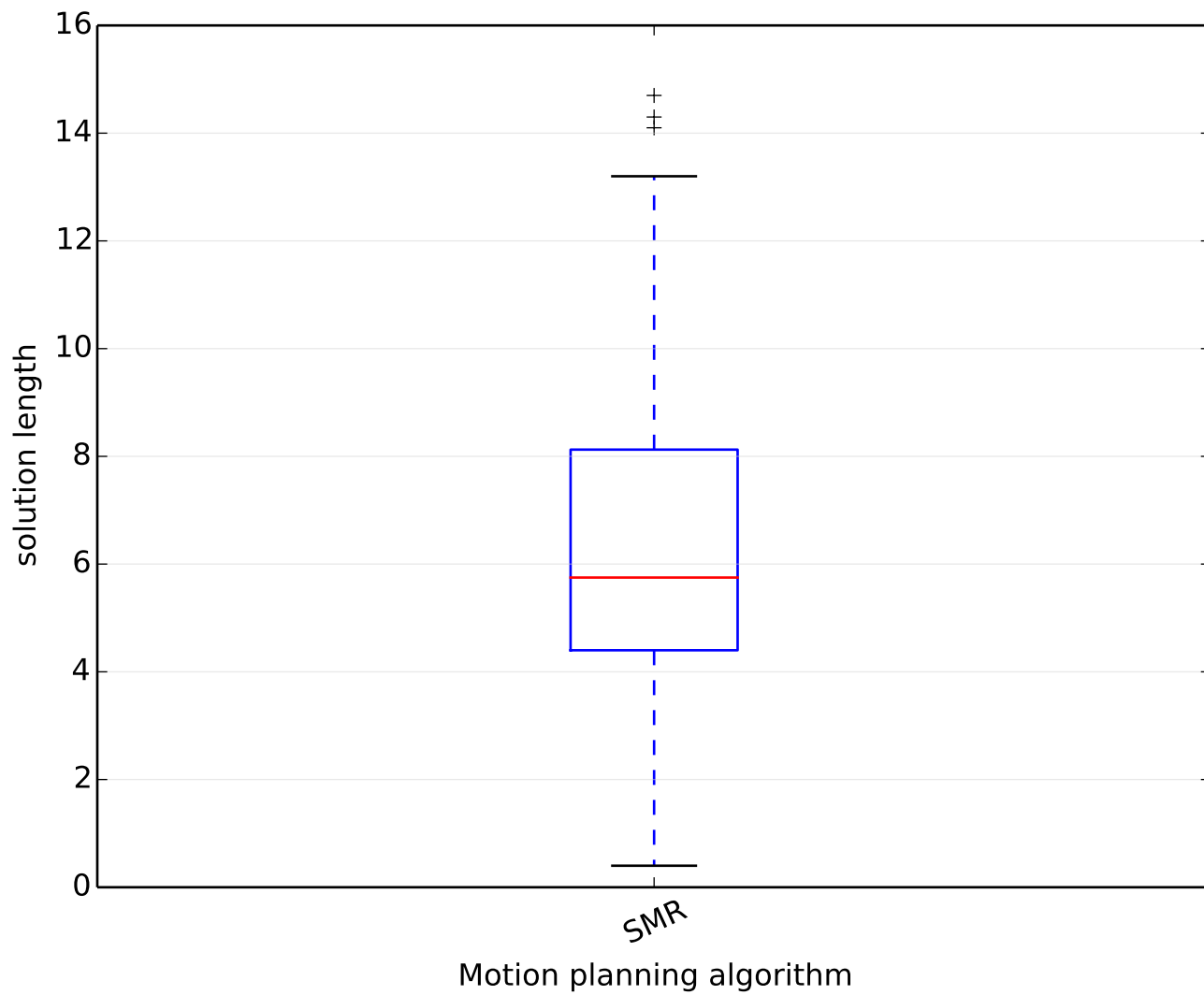


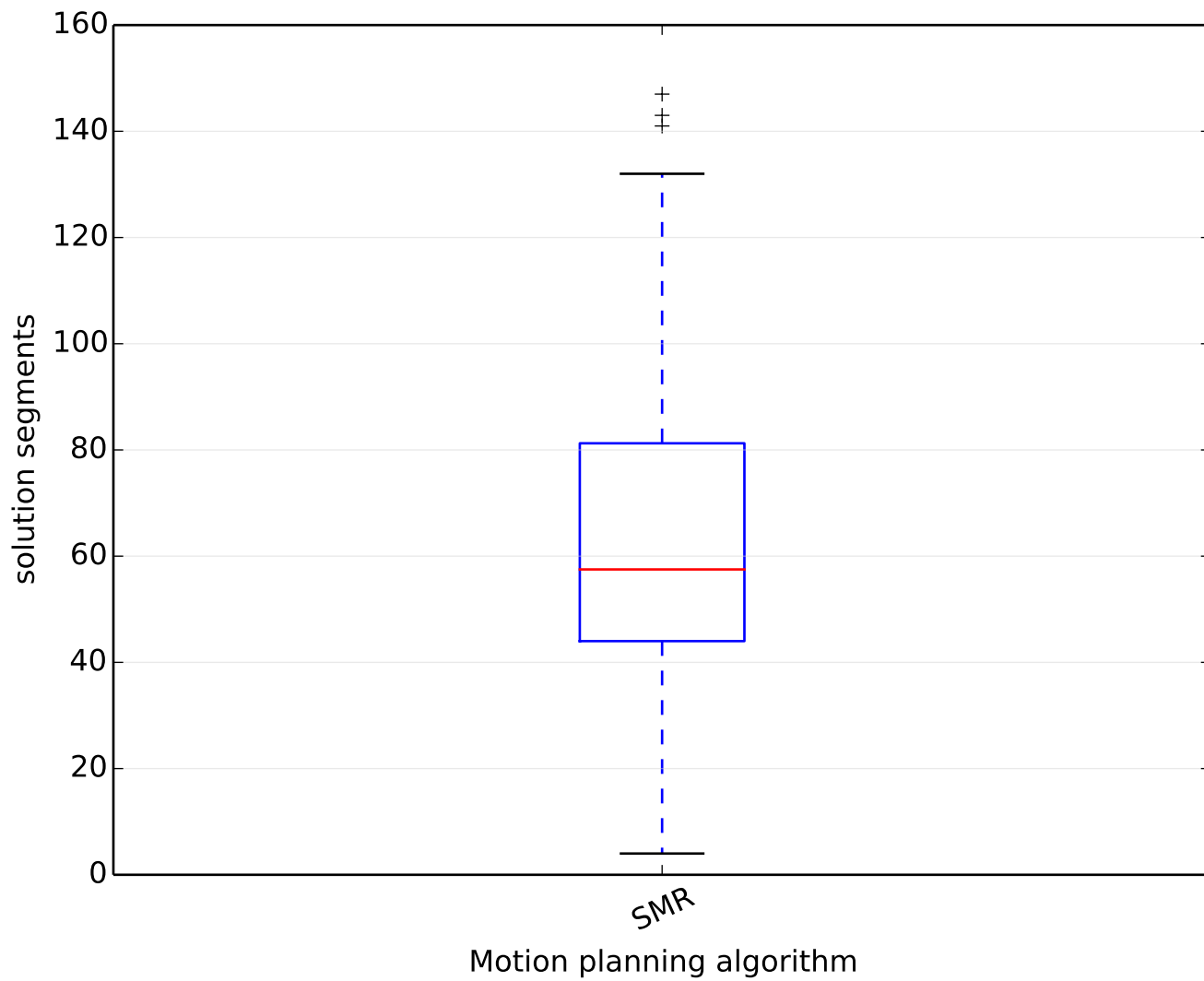
Motion planning algorithm

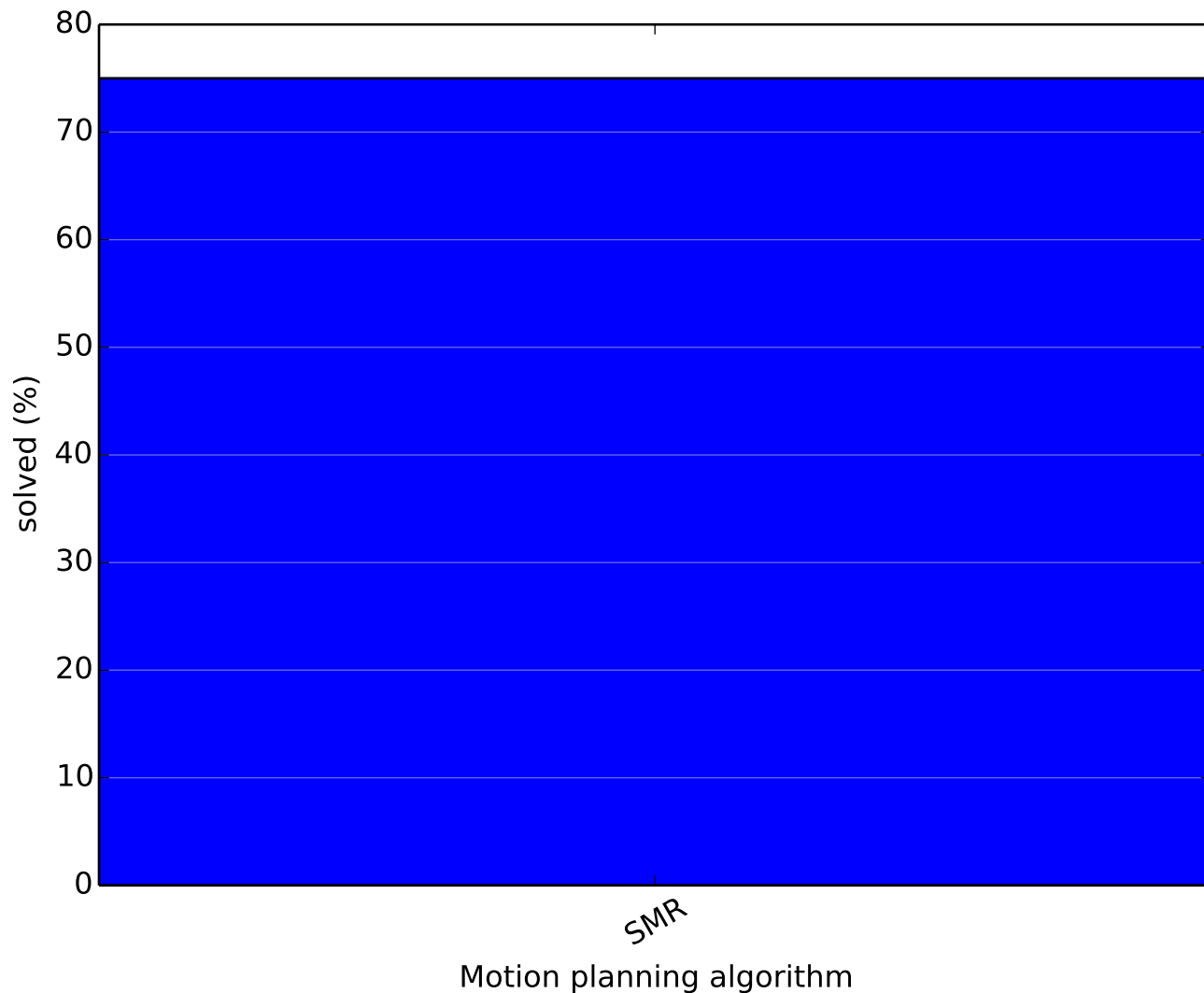


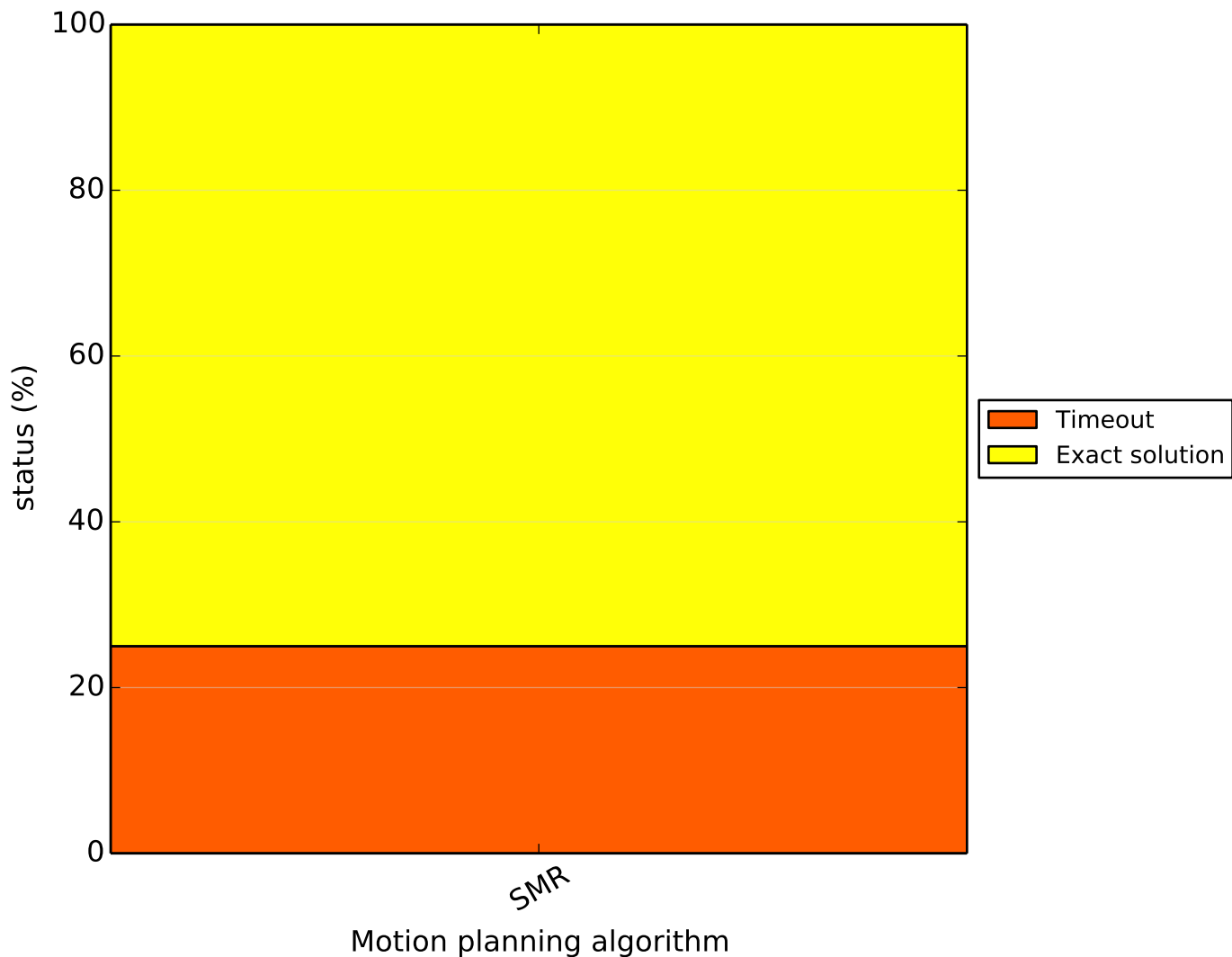


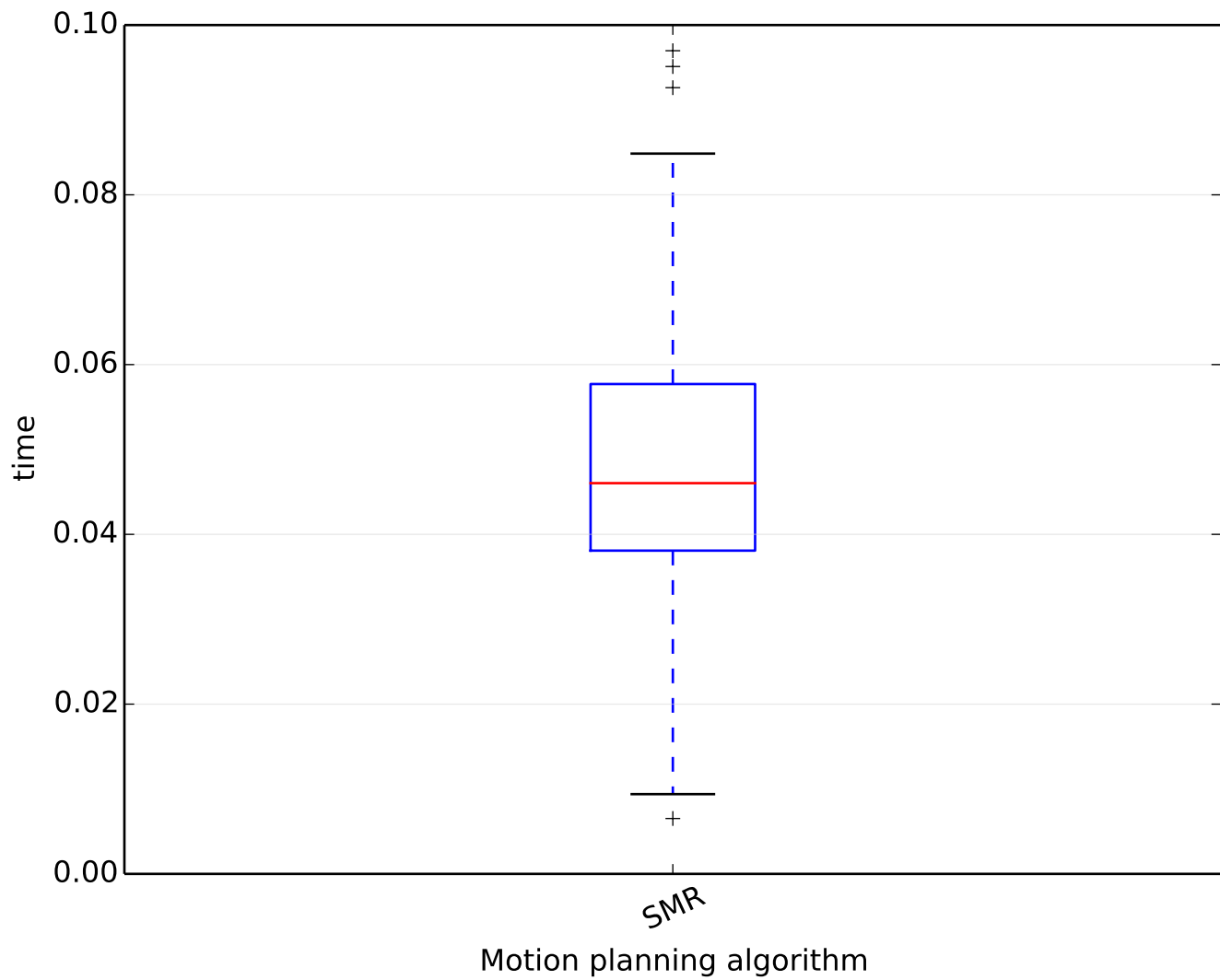


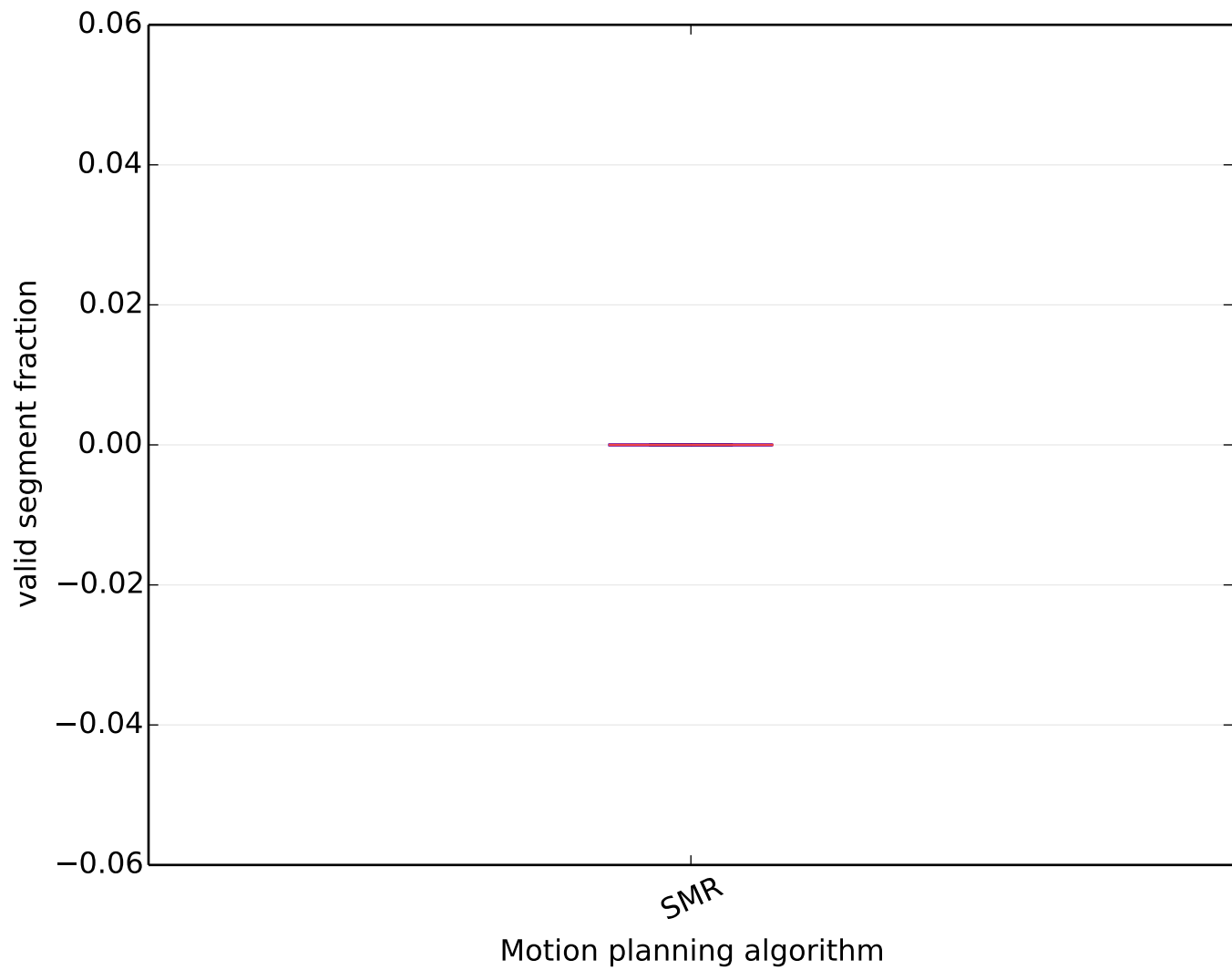












Experiment "benchmark"

Number of averaged runs: 100

Time limit per run: 20 seconds

Memory limit per run: 1000 MB