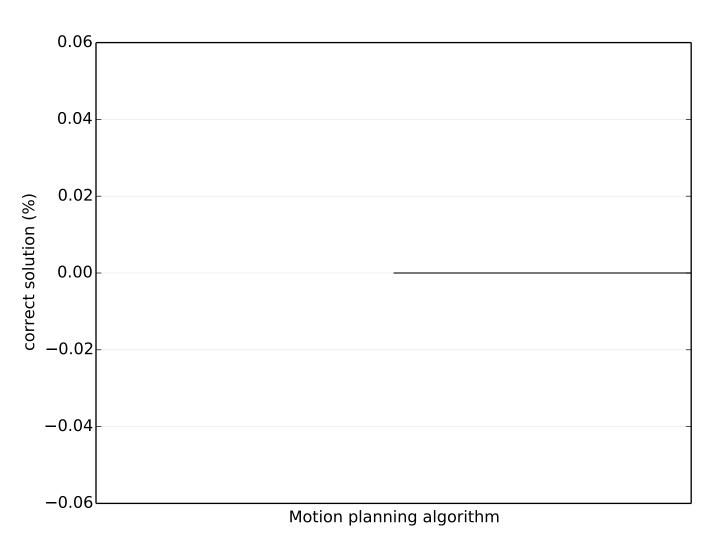
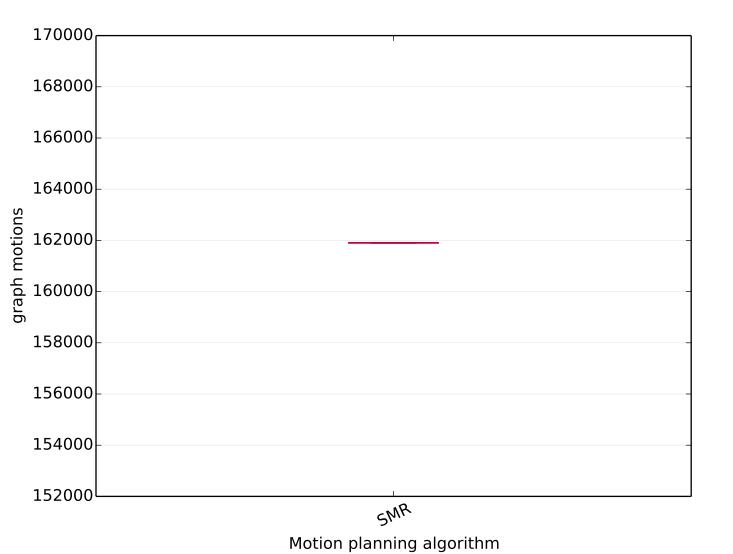
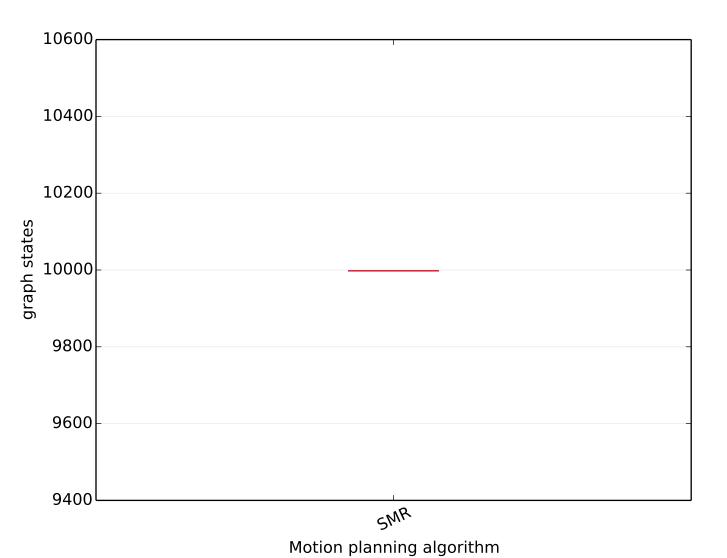
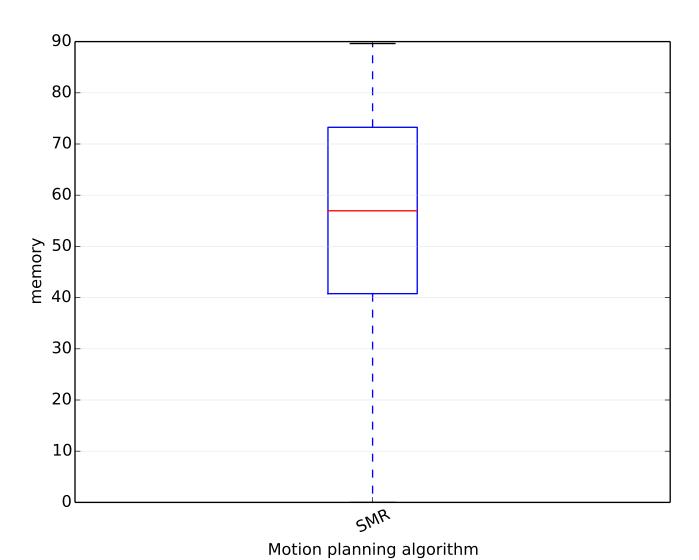


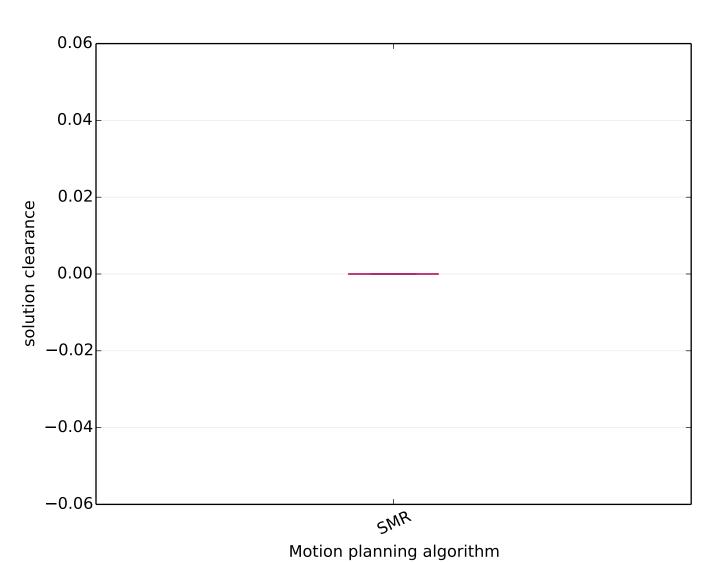
Motion planning algorithm

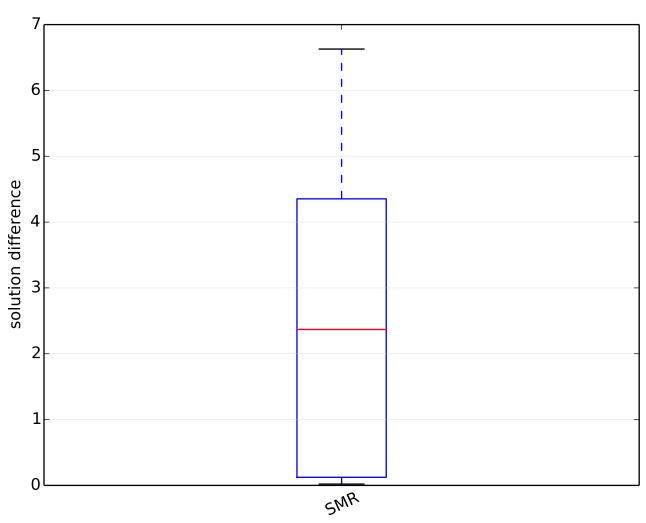




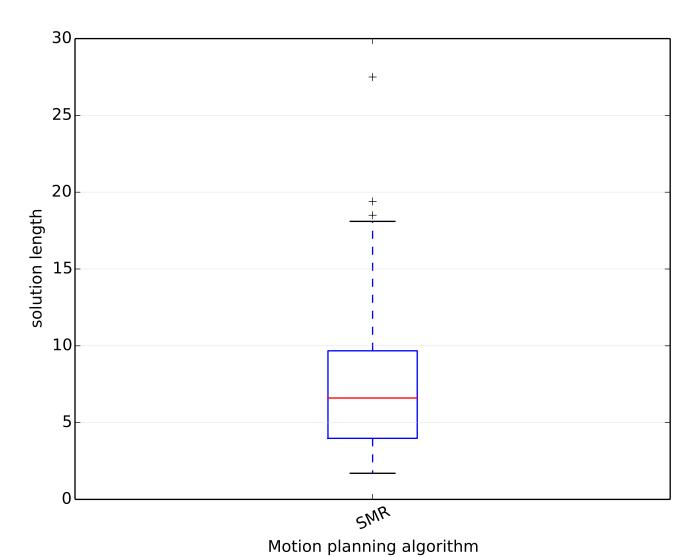


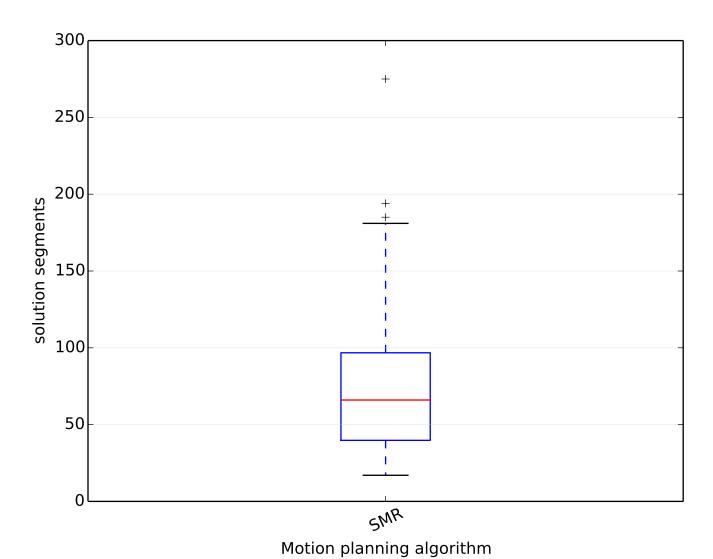


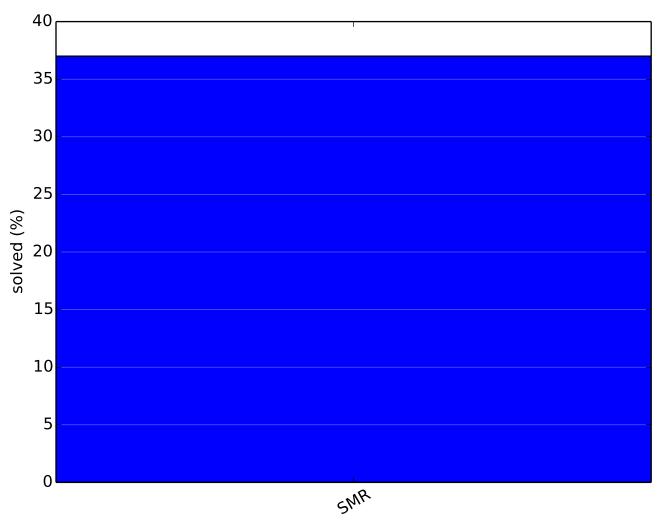




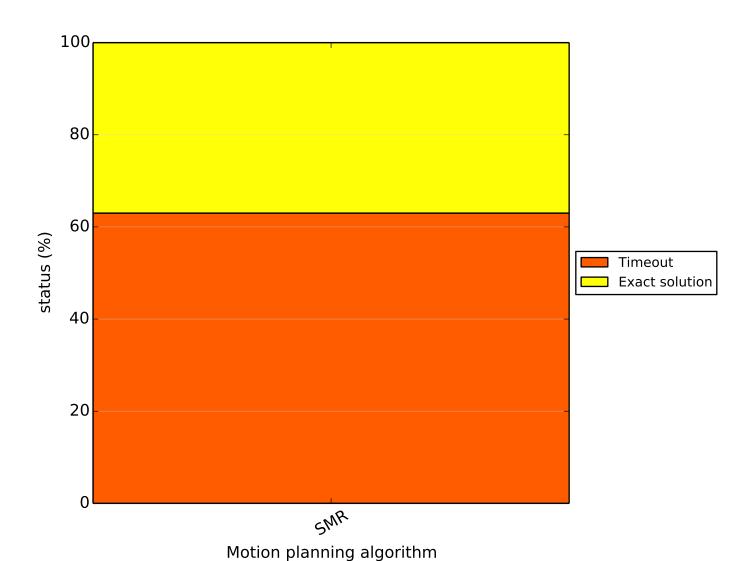
Motion planning algorithm

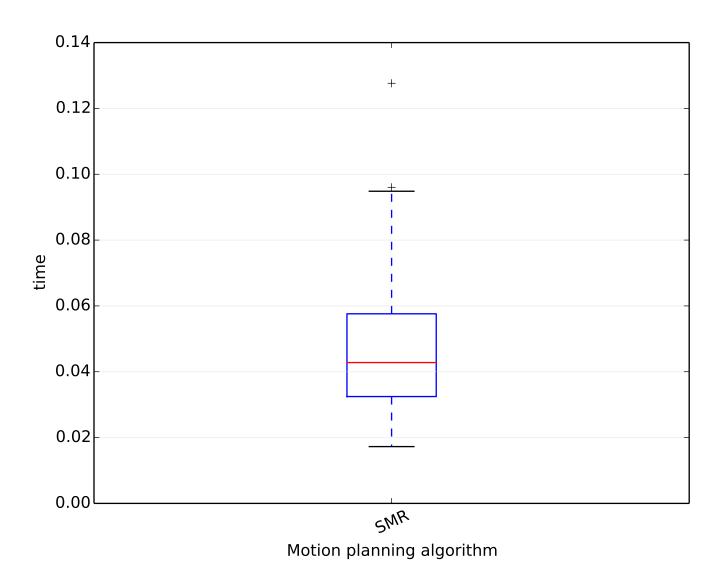


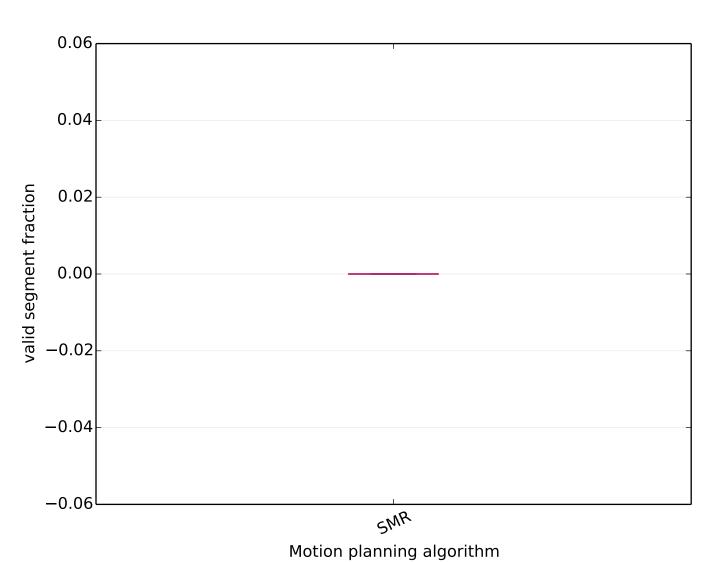




Motion planning algorithm







Experiment "benchmark_nodes10000"

Number of averaged runs: 100

Time limit per run: 20 seconds

Memory limit per run: 1000 MB