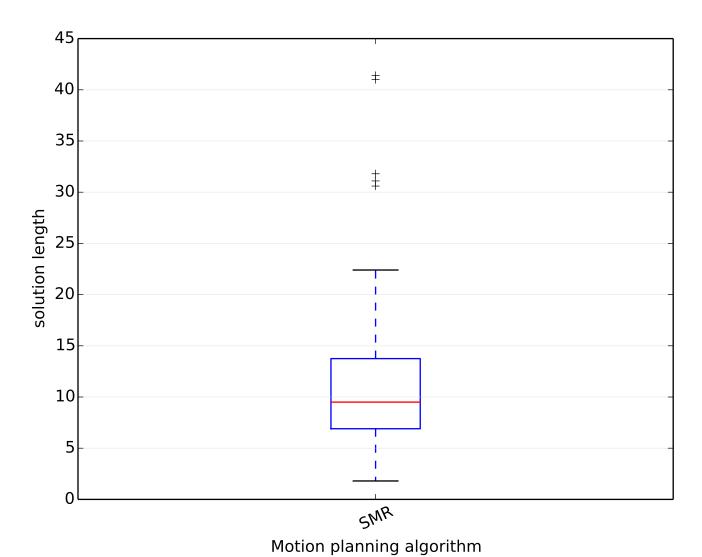
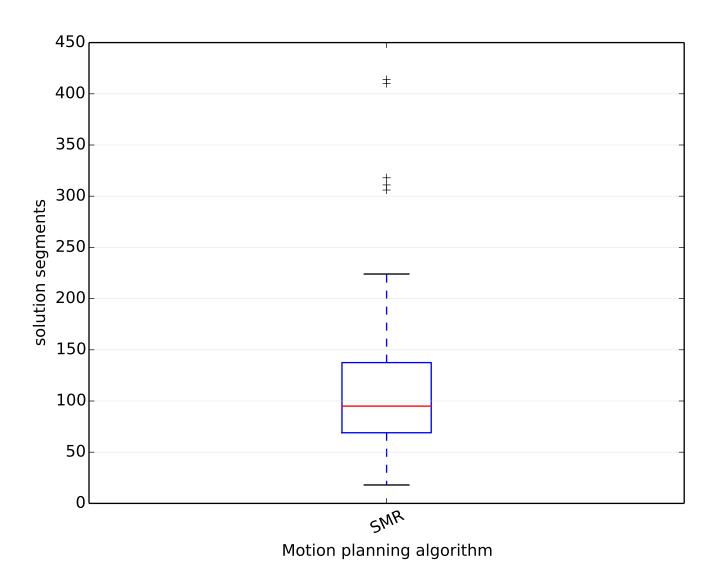
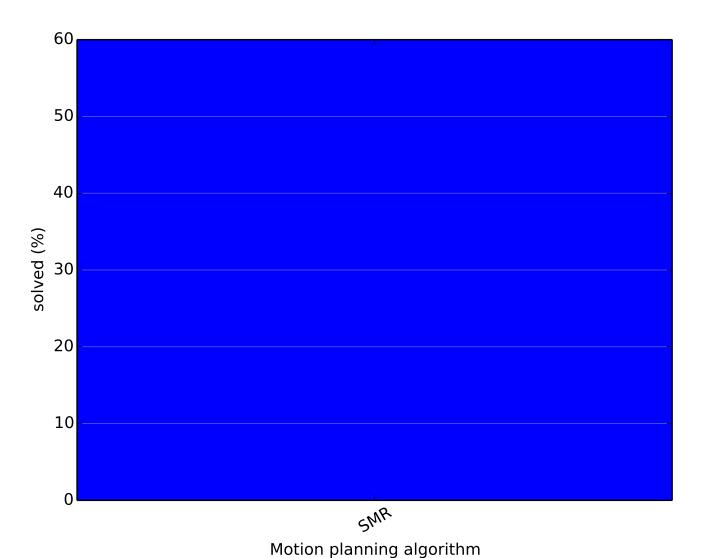
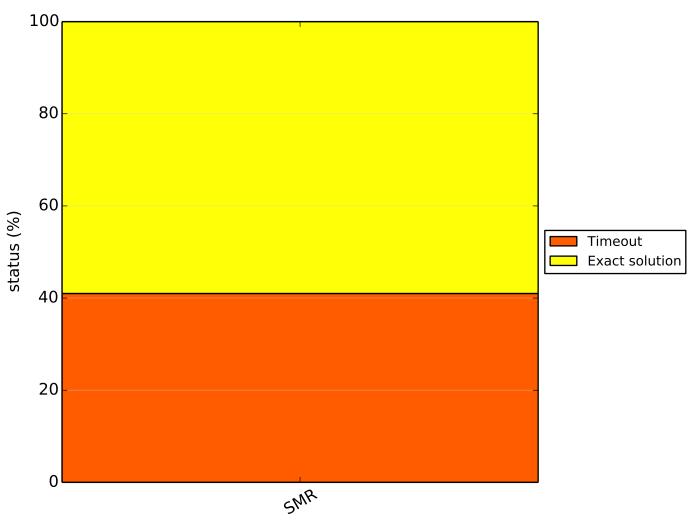


Motion planning algorithm

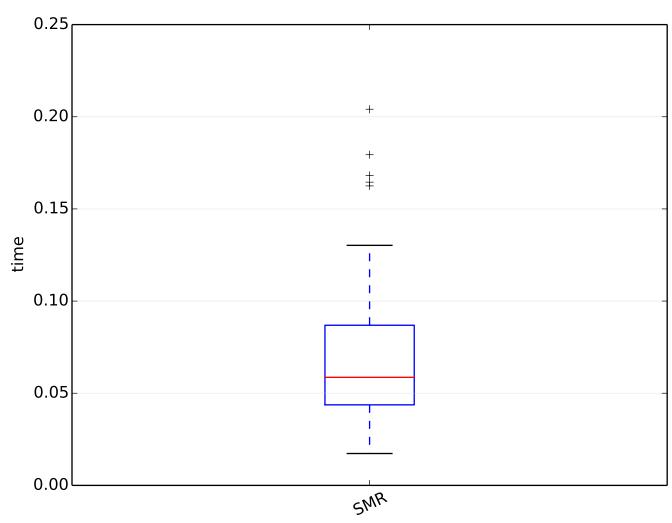




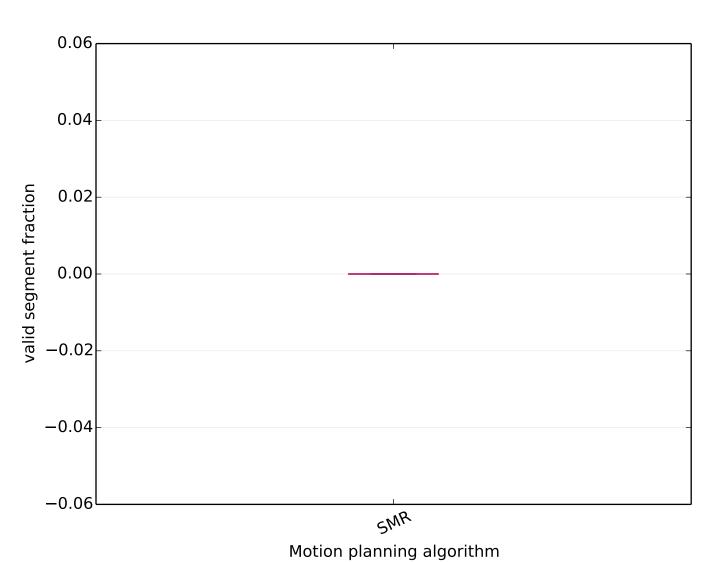




Motion planning algorithm



Motion planning algorithm



Experiment "benchmark_nodes20000"

Number of averaged runs: 100

Time limit per run: 20 seconds

Memory limit per run: 1000 MB