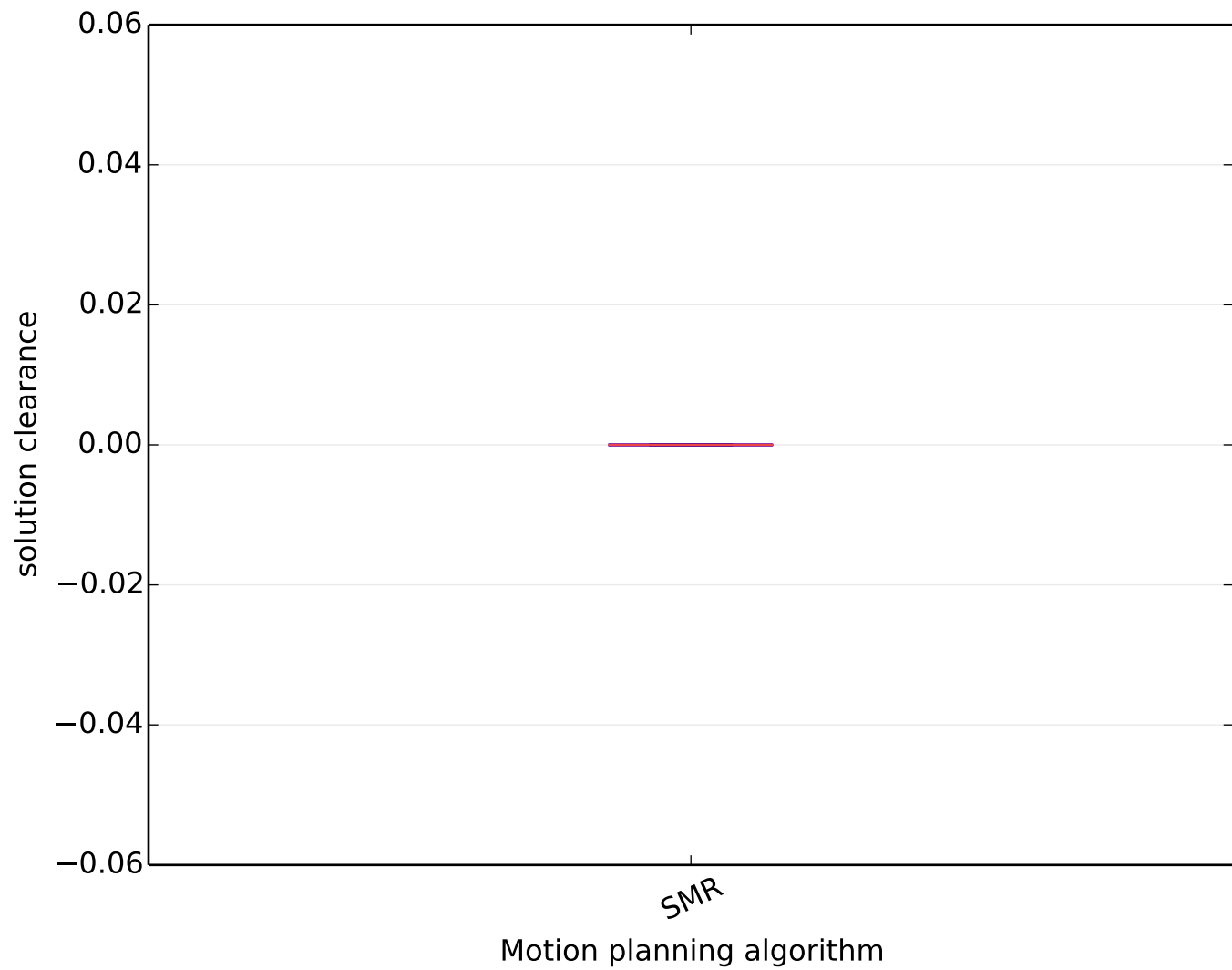
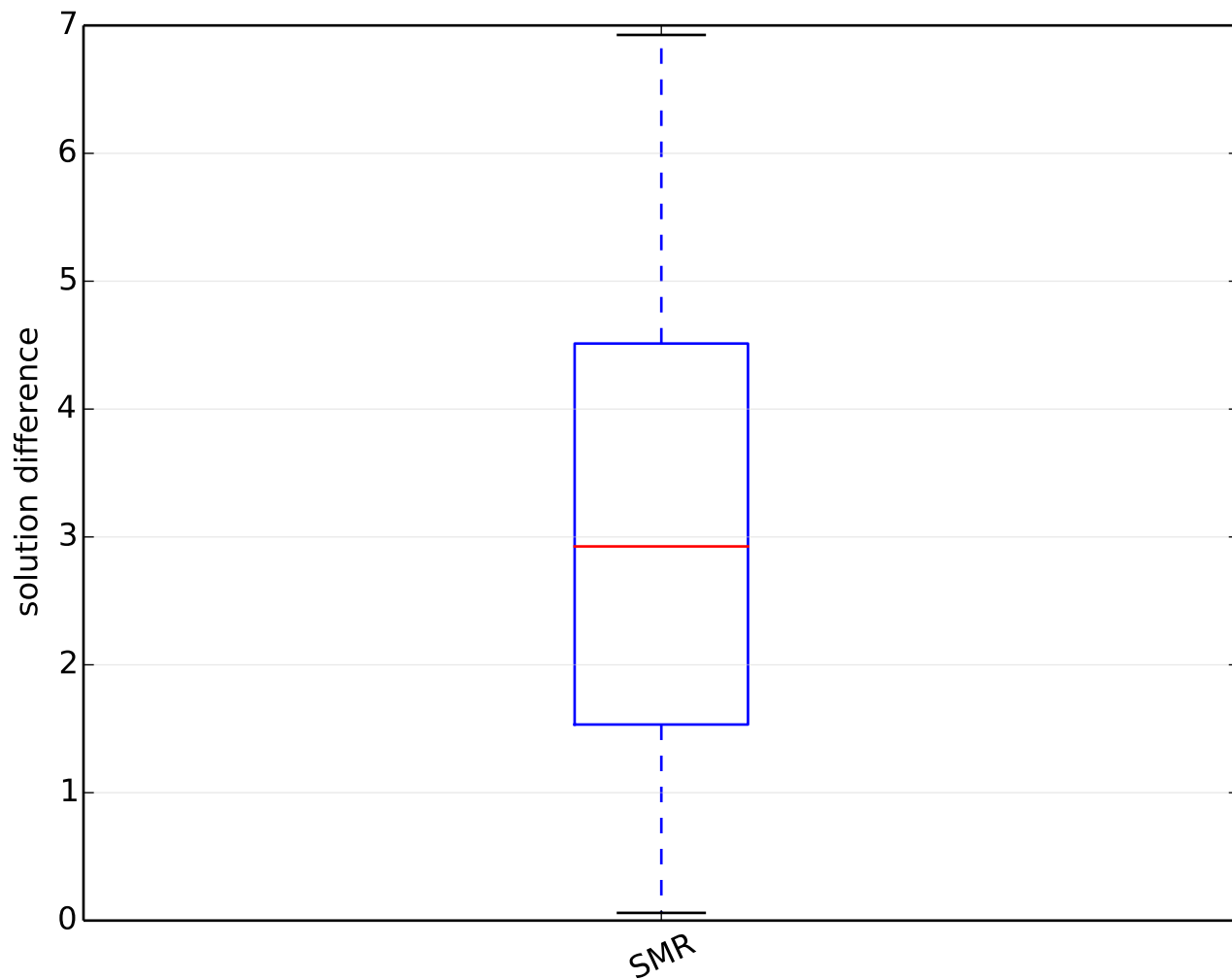
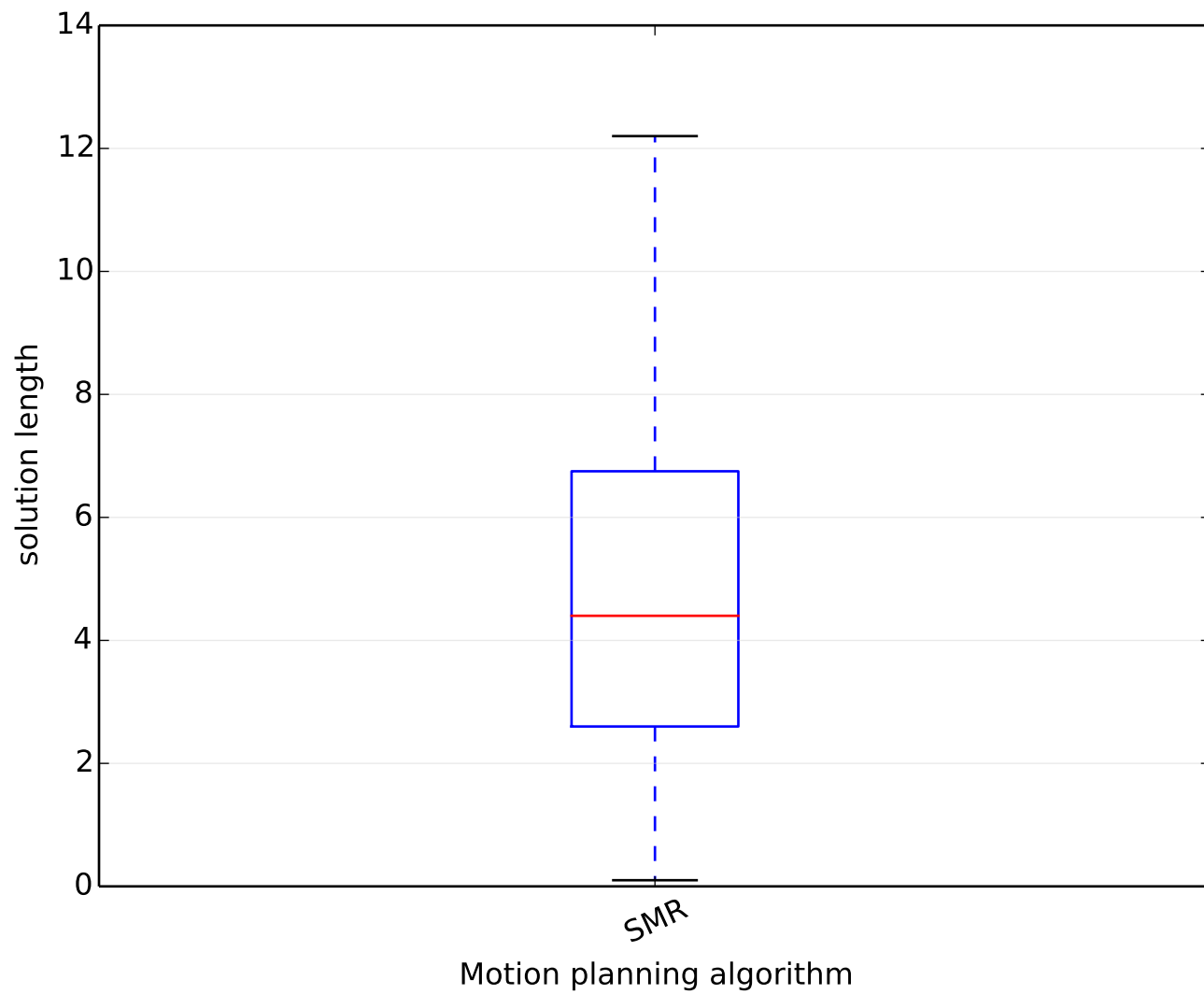
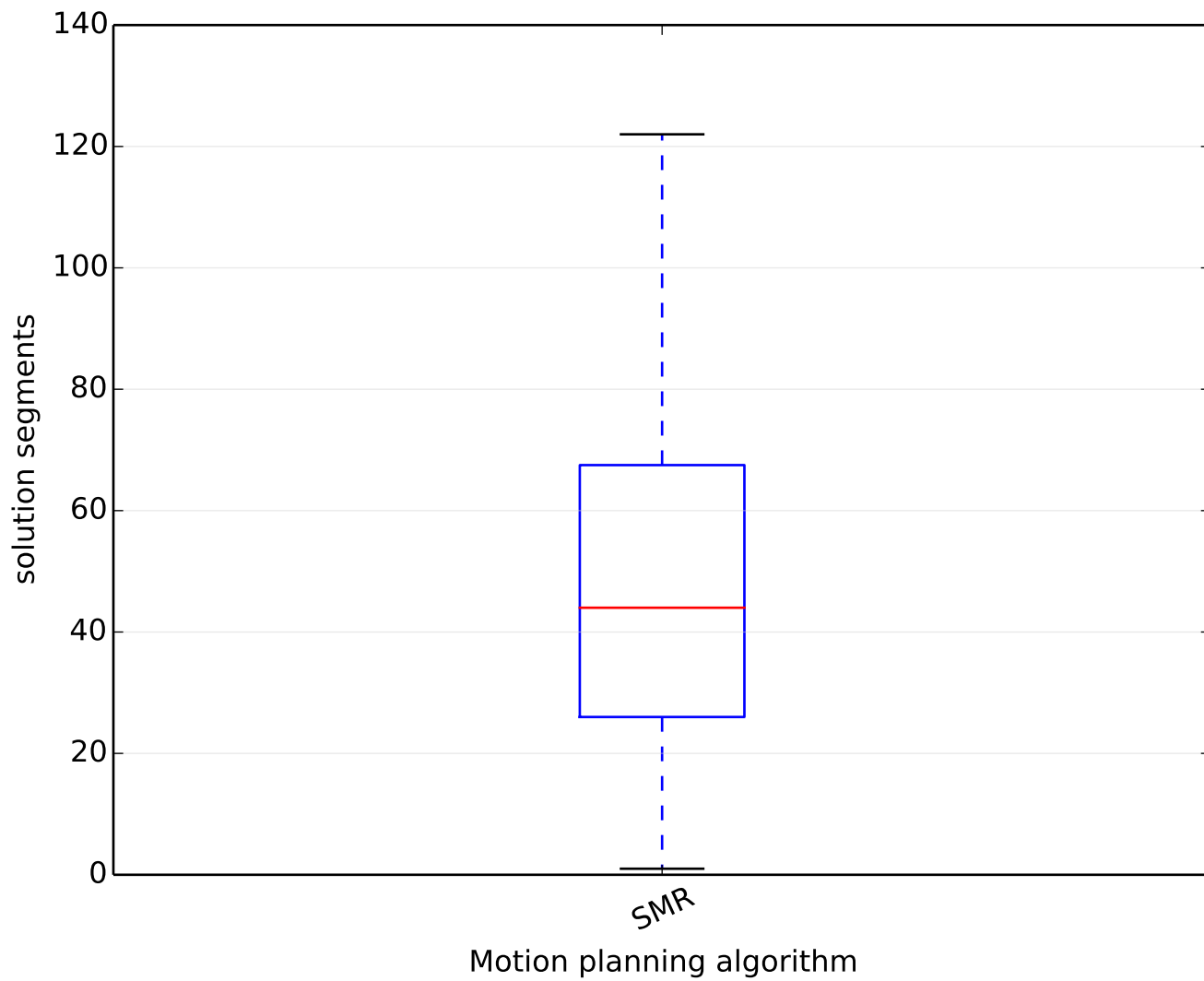


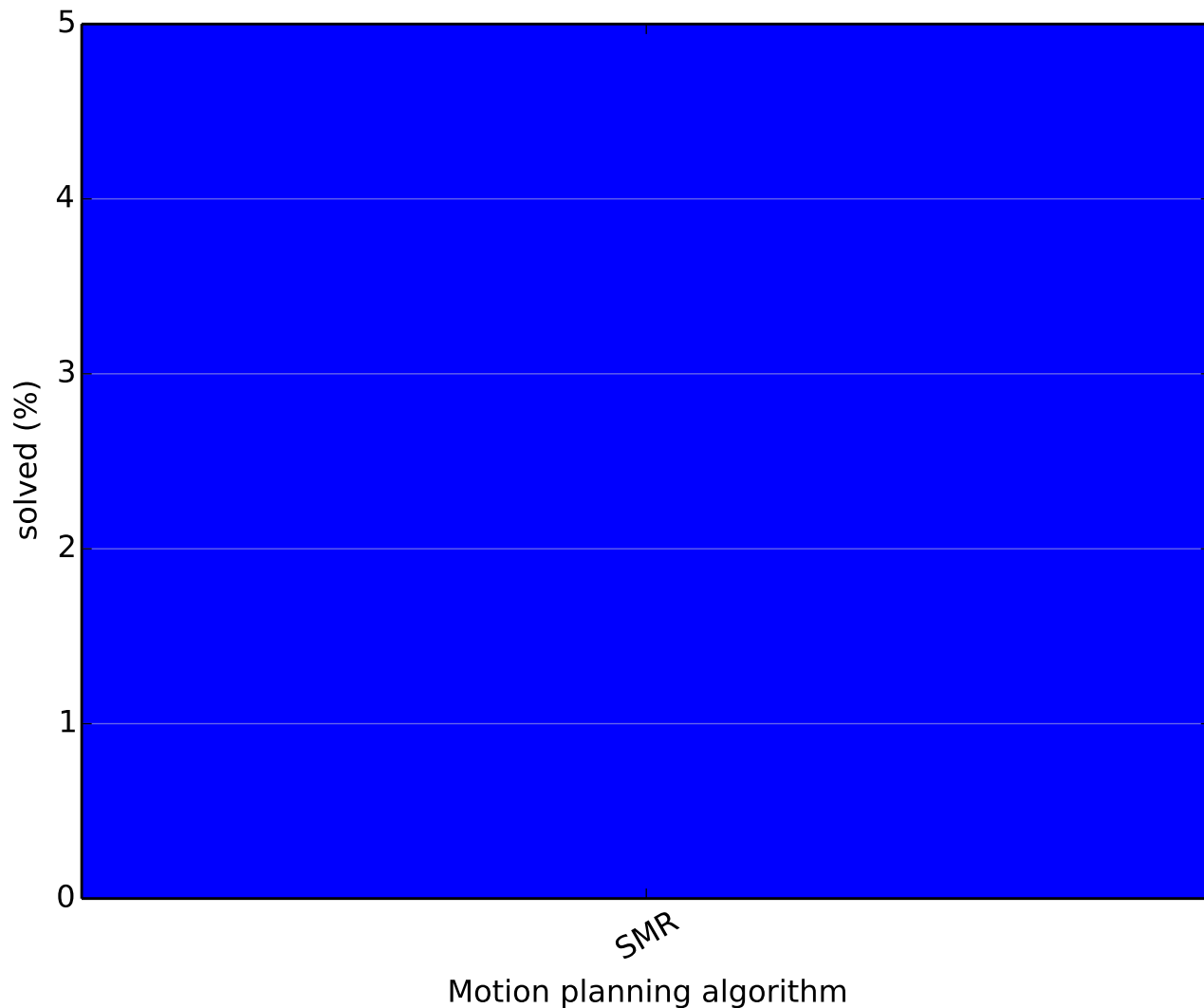
Motion planning algorithm

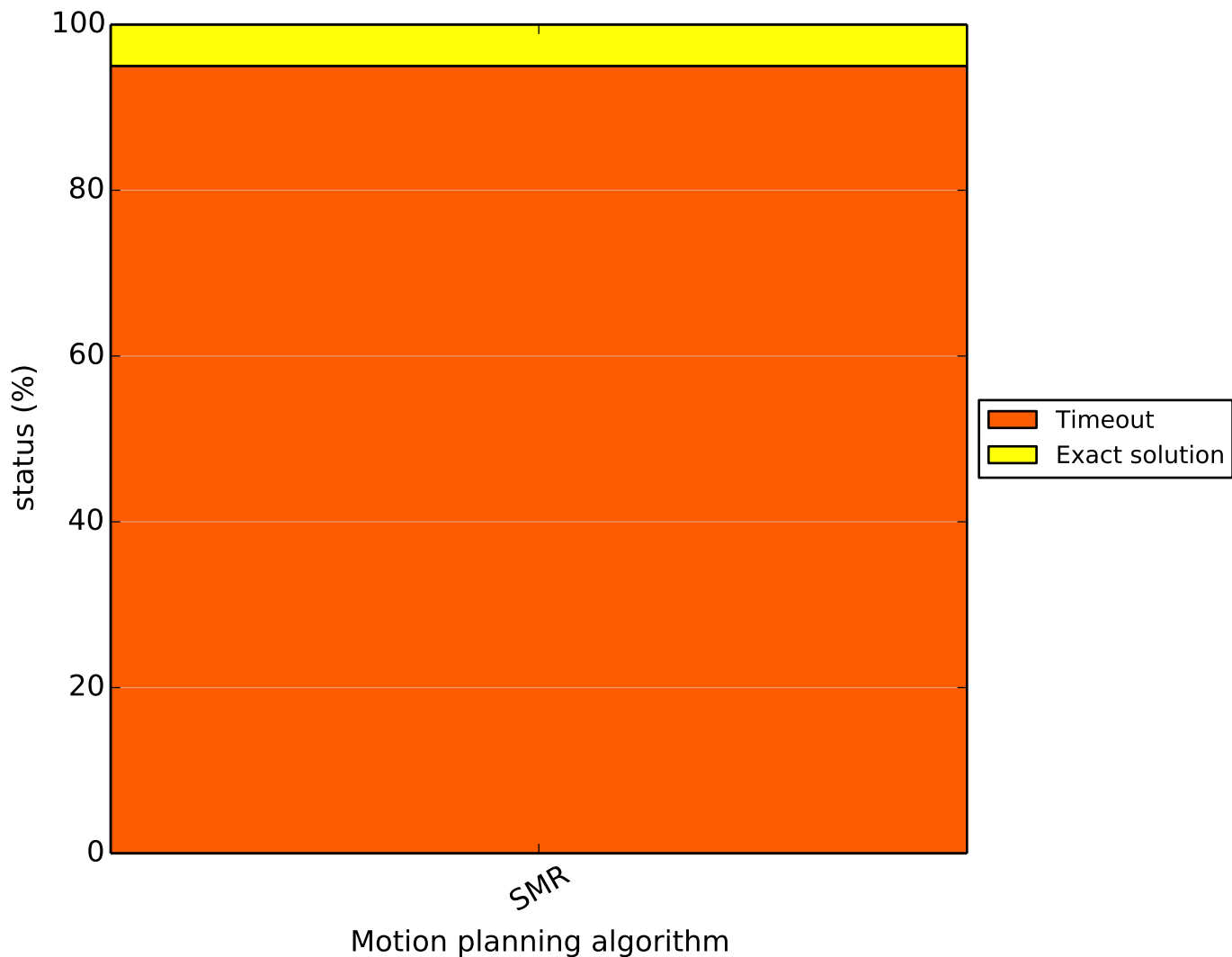


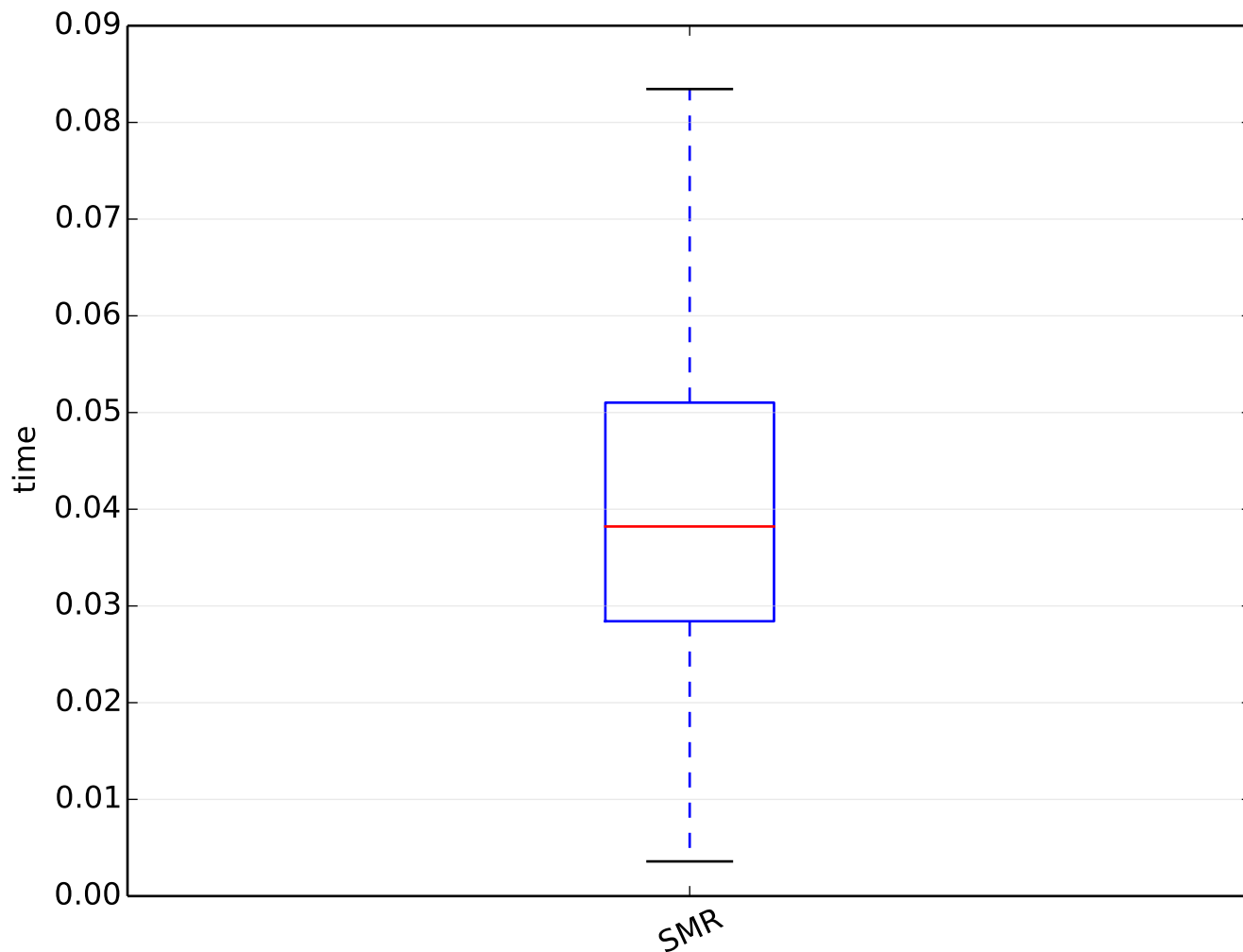


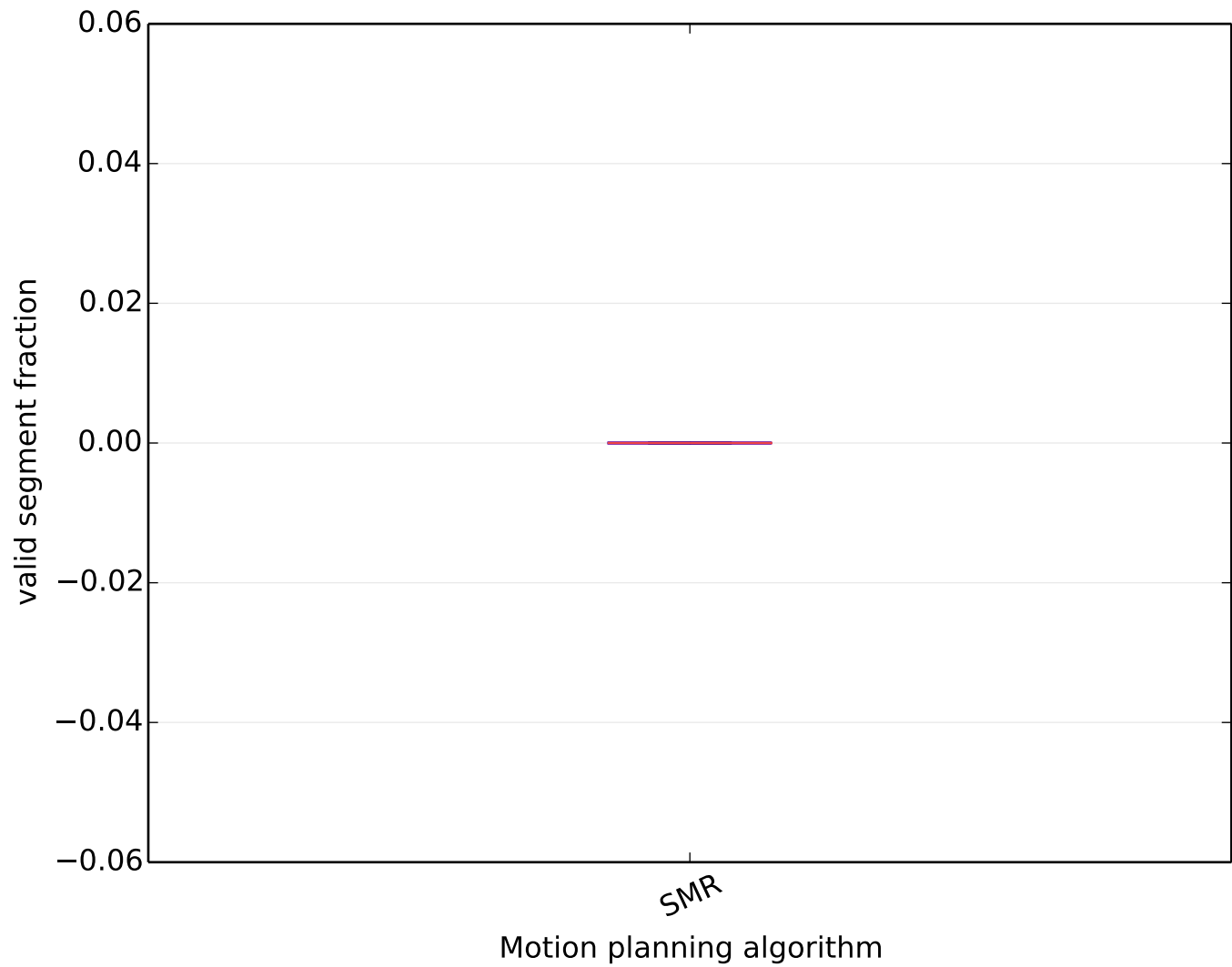












Experiment "benchmark_sd0.030000"

Number of averaged runs: 100

Time limit per run: 20 seconds

Memory limit per run: 1000 MB