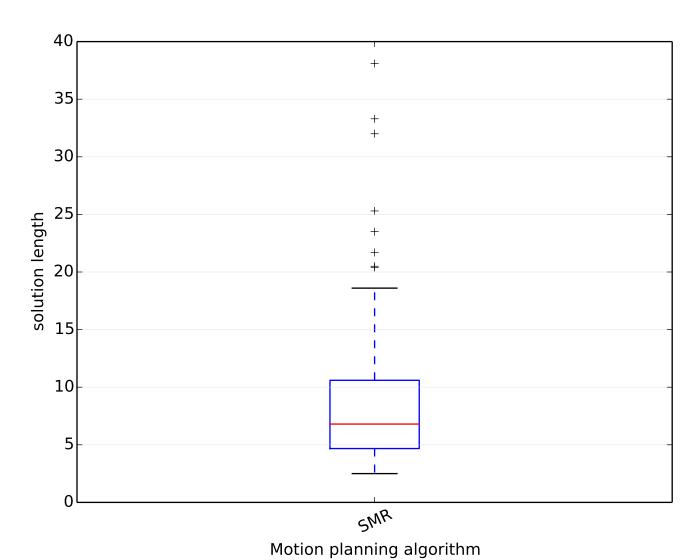
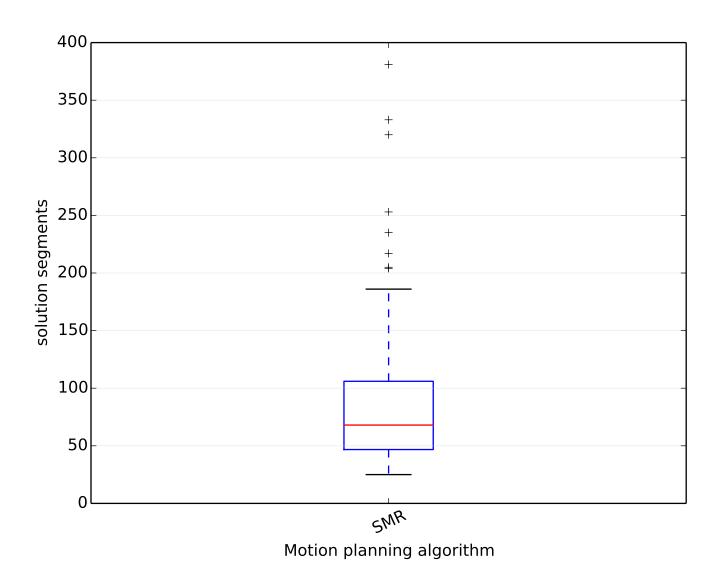
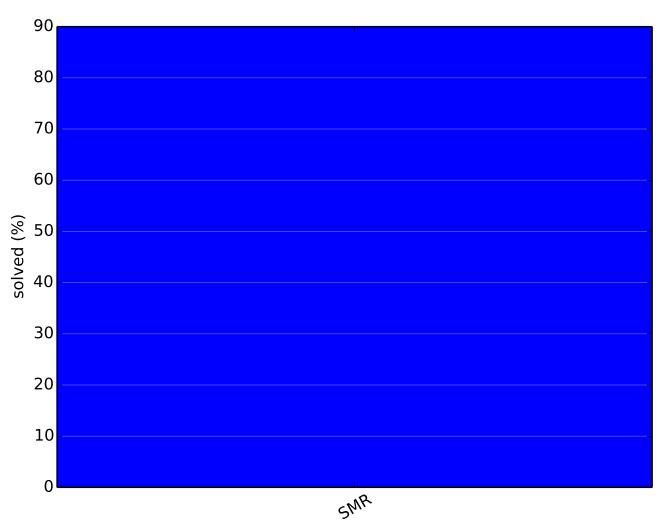


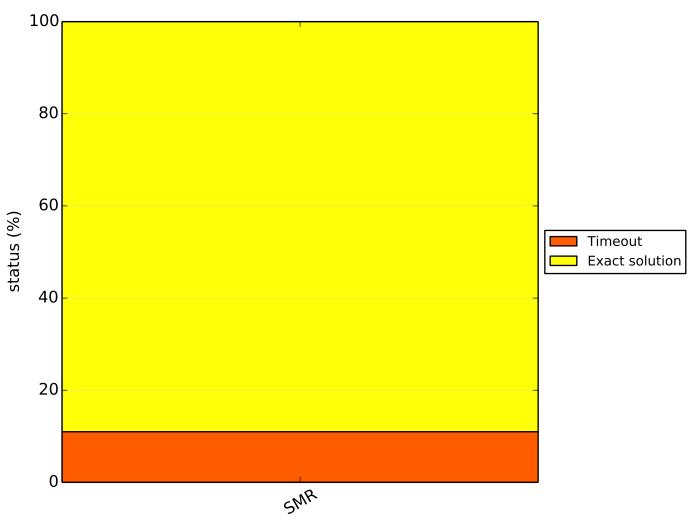
Motion planning algorithm



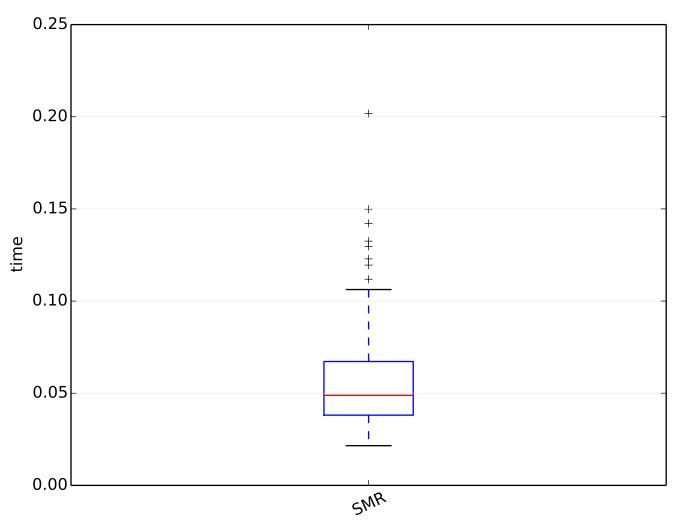




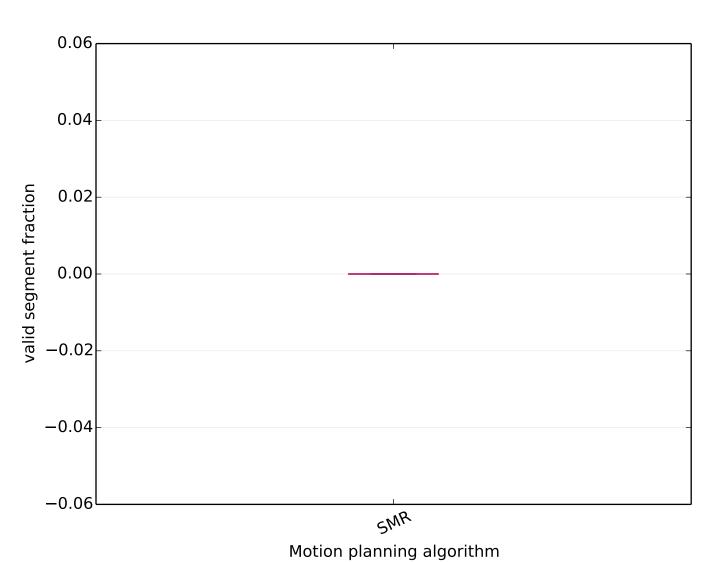
Motion planning algorithm



Motion planning algorithm



Motion planning algorithm



Experiment "benchmark\_sd0.000000"

Number of averaged runs: 100

Time limit per run: 20 seconds

Memory limit per run: 1000 MB