$$f(x)dx = g(y)dy$$

Exact

$$d\mathbf{U} = \mathbf{M} \ dx + \mathbf{N} \ dy = 0$$
 Exact  $\iff \partial M/\partial y = \partial N/\partial x$  
$$\mathbf{M} = \frac{\partial U}{\partial x}, N = \frac{\partial U}{\partial y}$$

Partial Integration:

$$\overline{U = \int M dx} = F + C(y)$$
Treat y as a constant
$$Find C'(y) \rightarrow \frac{\partial F}{\partial y} + C'(y) = \frac{\partial U}{\partial y}$$

Then integrate to find C(y) and U(x, y)

#### Linear, first order

$$y' + p(x)y = q(x)$$

Integrating factor  $\rightarrow m = e^{\int p(x)dx} \rightarrow d[vm] = m \, a(x) \, dx$ 

### **Homogeneous Function**

$$g(tx, ty) = t^n g(x, y)$$

#### **Homogeneous DE**

$$y' = f(x)$$
 and  $f(tx, ty) = f(x, y)$   
 $y = vx$   $\frac{dy}{dx} = v + x \frac{dv}{dx}$  or  $x = vy$   $\frac{dx}{dy} = v + y \frac{dv}{dy}$ 

Separate variables and use integrating factor

#### Wronskian

$$W(f_1, f_2, \dots, f_n) = \det \begin{vmatrix} f_1 & f_2 & \cdots & f_n \\ f'_1 & f'_2 & \cdots & f'_n \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)} & f_1^{(n-1)} & \cdots & f_n^{(n-1)} \end{vmatrix}$$

#### Superposition for linear DE

If y and z are solutions of y'' + ay' + by = 0 so is  $C_1y + C_2z$ .

#### 2nd order, constant coefficient

$$y'' + ay' + by = f(x)$$

Find  $y_h$  solving with f(x) = 0

Find roots  $m_1, m_2$  of  $m^2 + am + b = 0$ 

$$m_1 \neq m_2 \in \mathbb{R} \quad \rightarrow \quad \blacksquare = C_1 e^{m_1 x} + C_2 e^{m_2 x}$$

$$m = \alpha \pm i\beta$$
  $\rightarrow$   $\blacksquare = e^{\alpha x}(C_1 \cos \beta x + C_2 \sin \beta x)$ 

$$m$$
 repeated  $n$  times:  $\rightarrow (C_1 + C_2 x + \cdots + C_n x^n)[\blacksquare]$ 

Find  $y_n$ , then  $y = y_h + y_n$ 

## **Undetermined coefficients**

Convert to D-form

$$D^n = d^n/dx$$

Find roots of the characteristic equation  $m_i$ 

Find roots of the RHS by inverse inspection  $m_i$ 

Limitation: RHS must be such that we can find  $m_i^{\prime}$ 

Write y considering every  $m_i$  and  $m'_i$ 

Identify  $y_h$  and  $y_p$ 

Subs  $y_p$  in the DE to find the constants

 $y_h$  constants are found using the initial conditions

#### **Variation of parameters**

$$(D^n + a_{n-1}D^{n-1} + \dots + D + a_0)y = q(x)$$

Find  $y_h$  as in undetermined coefficients. Write:

$$y_h = C_1 y_1 + C_2 y_2 + \dots + C_n y_n$$

$$y_p = \mathbf{v}_1 y_1 + \mathbf{v}_2 y_2 + \dots + \mathbf{v}_n y_n$$

Find derivatives for  $y_i$  and solve the system for  $v'_i$ 

$$\begin{bmatrix} y_1 & y_2 & \cdots & y_n \\ y'_1 & y'_2 & \cdots & y'_n \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(p)} & y_2^{(p)} & \cdots & y_n^{(p)} \end{bmatrix} \begin{bmatrix} v'_1 \\ v'_2 \\ \vdots \\ v'_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \cdots \\ q(x) \end{bmatrix}$$

Find  $v_i$  integrating  $v_i$ 

Bernoulli

$$y' + p(x)y = q(x)y^{n}$$

$$y = v^{-1/(n-1)} \rightarrow \frac{dy}{dx} = \frac{dy}{dv}\frac{dv}{dx} = \frac{-1}{n-1} \left[ v^{-n/(n-1)} \right] \frac{dv}{dx}$$

$$v' - (n-1)p(x)v = -(n-1)q(x)$$

Euler

$$b_n x^n y^{(n)} + b_{n-1} x^{n-1} y^{n-1} + \dots + b_1 x y' + b_0 y = 0$$

$$z = \ln(x) \rightarrow x = e^z$$

$$y^{(n)} = \frac{1}{x^n} D(D-1)(D-2) \dots (D-n+1) y \text{, where } D = \frac{d}{dz}$$

Solve the resulting linear equation.

#### **Power series solution**

f(x) is an **analytic function** if it has a power series represent. around  $x_0$ . Initial Value Problem (IVP)

$$y' + p(x)y = q(x)$$

$$y' + p(x)y = q(x)$$

$$y(x_0) = y_0$$
  $p, q$  analytic about  $x_0$ 

$$y = \sum_{n=0}^{\infty} a_n (x - x_0)^n$$
  $a_n = \frac{1}{n!} y^{(n)}(x_0),$  in  $(x_0 - h, x_0 + h)$ 

Subs the IC to find  $y'(x_0)$ 

Differentiate the DE and subs  $y(x_0)$  and  $y'(x_0)$  to find  $y''(x_0)$ Drawback: differentiating the DE might not be practical.

#### Power series solution using recurrence relation

$$y = \sum_{n=0}^{\infty} a_n (x - x_0)^n$$
  

$$y' = \sum_{n=1}^{\infty} n \ a_n (x - x_0)^{n-1}$$
  

$$y'' = \sum_{n=2}^{\infty} (n-1) \ a_n (x - x_0)^{n-2}$$

Subs in the equation.

Shift indices in the summations so that the power of x is the same in all Be careful not to loose terms!

The coefficients of each power  $x^k$  must be equal in LHS and RHS

Find recurrence relation for the each  $a_n$ 

Subs  $a_n$  in y(x) and expand the summations as needed.

Shifting 
$$\sum_{n=0}^{\infty} C_n x^{n+a} = \sum_{n=a}^{\infty} C_{n-a} x^n$$

## Singularities and the method of Frobenius

y'' + p(x)y' + q(x)y = f(x)p, q analytical about  $x_0; x_0$  ordinary **Singular point of the DE**: p, q or f has zero denominator about  $x_0$ . **Regular singular:**  $(x - x_0)p(x)$  and  $(x - x_0)^2q(x)$  are analytical Ordinary: not singular. Irregular: Not regular

If equation has a regular singular point at  $x_0$ , use a Frobenius series:

$$y=\sum_{n=0}^{\infty}C_nz^{n+r}$$
  $z=(x-x0)$ , where  $r\in\mathbb{R}$   $y'=\sum_{n=0}^{\infty}(n+r)\ C_n\ z^{n+r-1}$   $y''=\sum_{n=0}^{\infty}(n+r)\ (n+r-1)\ C_n\ z^{n+r-2}$  Subs in the equation, shift indices etc. (same as pwr series)

Assume  $C_0 \neq 0$  to find values for  $r_1, r_2 \ (r_1 \geq r_2)$ .

Find the recurrence  $C_n$  using  $r = r_1$ . Write  $y_1(x)$ .

For the **second solution**, find the recurrence 
$$C_n^*$$
 as: 
$$\begin{cases} \text{If } r_1 - r_2 \notin \mathbb{Z} & y_2 = \sum_{n=0}^\infty C_n^* \, z^{n+r_2} \\ \text{If } r_1 = r_2 & y_2 = y_1 \ln(z) + \sum_{n=0}^\infty C_n^* \, z^{n+r_1} \\ \text{If } r_1 - r_2 \in \mathbb{N} & y_2 = Ky_1 \ln(z) + \sum_{n=0}^\infty C_n^* \, z^{n+r_2} \\ \text{Subs } y_2 \text{ into the DE and obtain an equation for } K \end{cases}$$

Final solution:  $y(x) = y_1 + y_2$ 

Bessel's equation of order 
$$\nu$$

$$x^{2}y'' + xy' + (x^{2} - v^{2})y = 0$$

$$y(x) = C_{0} J_{v} + C_{1} Y_{v}$$

$$v \in \mathbb{R}, v \ge 0, x > 0$$

Bessel function of the 1st kind: 
$$J_{\nu} = C_0 \sum_{n=0}^{\infty} \frac{(-1)^n}{2^{2n} \, n! (1+\nu) (2+\nu) ... (n+\nu)} x^{2n+\nu}$$

Bessel function of the 2<sup>nd</sup> kind:  $Y_{\nu} = \cdots$ 

<sup>&</sup>lt;sup>1</sup> Subs  $y_2$  into the DE and the  $\ln \square$  term vanishes as the terms it multiplies are equal to  $y_1$ . <sup>2</sup> We use  $C_0 = 1$  for convenience

 $<sup>^3</sup>$  Subs the found solution  $y_1$  after simplifications

### **Matrices and vectors**

 $A = [a_{ij}] \rightarrow i$ : row j:column

 $a_{1j}$ : row matrix  $a_{i1}$ : column matrix

$$\frac{dA}{dt} = \dot{A} = \left[\frac{da_{ij}}{dt}\right] = [\dot{a}_{ij}] \qquad \qquad \int A(\tau)d\tau = \left[\int a_{ij}(\tau)d\tau\right]$$

 $\boldsymbol{a} \cdot \boldsymbol{b} = ||\boldsymbol{a}|| \, ||\boldsymbol{b}|| \cos(\theta) \quad ||\boldsymbol{a}|| = \sqrt{a_{kk}^2}$ 

$$\operatorname{comp}_b a = a \cdot \frac{b}{||b||}$$
 (component of  $a$  in  $b$ )  $\operatorname{proj}_b a = a \cdot \frac{b}{||b||^2} b$  (projection of  $a$  in  $b$ )

Conjugate:  $\bar{A}$ :  $a_{ij} = \alpha_{ij} \pm i \beta_{ij} \rightarrow \overline{a_{ij}} = \alpha_{ij} \mp i \beta_{ij}$ 

Rank: largest non zero determinant; number of independent vectors;

 $C = AB \rightarrow 0 \le \operatorname{rank}(C) \le \min\{\operatorname{rank}(A), \operatorname{rank}(B)\}\$ 

Trace:  $tr(A) = \sum a_{ii}$  tr(A+B) = tr(A) + tr(B)tr(AB) = tr(BA) $tr(AB) \neq tr(BA)$ 

#### **Identities**

$$A^T = a_{ji}$$
  $[A^T]^T = A$   $[A \pm B]^T = A^T \pm B^T$   
 $[cA]^T = cA^T$   $[ABC]^T = C^TB^TA^T$ 

$$[AB]^T = B^T A^T = BA \neq AB$$

If A is symmetric, then so is  $B^TAB$ ,  $\forall B$ 

$$a_{ij} \in \mathbb{R} \ \rightarrow A = \bar{A}$$

#### Square matrices

Symmetric:  $A = A^T$ Skew-Symmetric:  $A = -A^T$ 

Non negative definite:  $x^T A x \ge 0$ Positive definite:  $x^T A x > 0$ 

Indefinite:  $(x^T A x)(y^T A y) < 0$   $x, y \in \mathbb{R}^n$ 

Orthogonal  $A^T = A^{-1} \rightarrow A^T A = I$ 

Nilpotent:  $A^k = 0$  and  $A^{k-1} \neq 0$   $k \in \mathbb{Z}$ 

Idempotent:  $A^2 = A$ 

Unitary:  $A^{-1} = \bar{A}^T$ Involutory:  $A^2 = I$ 

Positive:  $a_{ij} > 0 \quad \forall i, j$ Non-negative:  $a_{ij} \ge 0 \quad \forall i, j$ 

Diagonal Dominant:  $|a_{ii}| \ge \sum_{i \ne j} |a_{ij}|$  Strictly Diag Dom:  $|a_{ii}| > \sum_{i \ne j} |a_{ij}|$ 

Hermitian:  $A = \bar{A}^T$  Skew Hermitian:  $A = -\bar{A}^T$ Associate:  $[\overline{A}]^T$ 

**Determinants** det(A) = |A|

A is a  $(n \times n)$  matrix, then:

 $|A| = \sum_{k=1}^{n} a_{ik} C_{ik}$ , for any row i

Adjoint matrix  $C^T$  is the transpose of the cofactor's matrix.

# Inverse

Inverses are unique

$$A A^{-1} = I$$
  $A^{-1} = \frac{c^T}{|A|}$ 

## **Properties of determinants**

$$|A||B| = |AB| \qquad |A| = |A^T|$$

If any col or row is null, then |A| = 0

If operate columns or rows, then |A| does not change

If swap columns or rows, then |A| changes sign

If two columns or rows are proportional then |A| = 0

If one column or row is the linear combination of others then |A| = 0

Multiply column or row by  $\alpha$  then  $|B| = \alpha |A|$ 

If |A| = 0, A is singular and has no inverse.

#### Set of vectors

LIN ALG

 $\{\mathbf{v}_i\}$  are linearly independent  $\Leftrightarrow \alpha_k \mathbf{v}_k = 0$  for at least one set of  $\alpha_i$ .

 $\{\mathbf{v}_i\}$  is a base if exists a unique choice of scalars for every vector  $\mathbf{u}$ . That is,

 $\{\mathbf{v}_i\}$  are independent

 $\{\mathbf v_i\}$  is orthogonal  $\Longleftrightarrow \mathbf v_i^T \mathbf v_i = 0$ ,  $\forall i \neq j$ 

 $\{\mathbf{v}_i\}$  is orthonormal  $\Leftrightarrow ||\mathbf{v}_i|| = 1$ ,  $\forall i$ 

Normalization:  $\tilde{\mathbf{v}} = \frac{\mathbf{v}}{||\mathbf{v}||}$ 

Gram-Schmidt orthogonalization of  $\{v_i\}$ 

$$u_1 = v_1$$
  $u_2 = v_2 - \frac{v_2 \cdot u_1}{||u_1||^2} u_1$   $u_3 = v_3 - \frac{v_3 \cdot u_1}{||u_1||^2} u_1 - \frac{v_3 \cdot u_2}{||u_2||^2} u_2$ 

$$\mathbf{u}_m = \mathbf{v}_m - \sum_{k=1}^{m-1} \operatorname{proj}_{\mathbf{u}_k} \mathbf{v}_m = \mathbf{v}_m - \sum_{k=1}^{m-1} \frac{\mathbf{v}_m \cdot \mathbf{u}_k}{||\mathbf{u}_k||^2} \mathbf{u}_k$$

# Systems of linear equations

$$A x = b$$

Cramer's rule:  $x_j = \frac{\Delta_j}{|A|}$  , where  $\Delta_j = \left|A_j\right|$  and  $A_j$  is A with column jreplaced by vector **b**.

 $|A| \neq 0, \boldsymbol{b} \neq 0 \rightarrow \text{unique solution}$ 

 $|A| \neq 0, \mathbf{b} = 0 \rightarrow x = 0$ 

|A| = 0,  $\boldsymbol{b} = 0 \rightarrow \text{infinite solutions}$ 

 $|A| \neq 0$ ,  $b \neq 0 \rightarrow$  infinite solutions  $\Leftrightarrow \Delta_i = 0$ ,  $\forall i$ . Otherwise, no solution.

A is diagonal: system is called uncoupled or the variables are called

A and B are similar:  $B = P^{-1}AP$  and PB = AP, where P is the set of eigenvectors.

#### **Gaussian Elimination**

Operate equations/rows to uptriangularize the system.

Back substituition to find variables.

#### Augmented matrix

$$A \mathbf{x} = \mathbf{b} \rightarrow [A:\mathbf{b}]$$

Operate rows to find  $[I: \widetilde{\boldsymbol{b}}]$ 

Operate  $[A: \mathbf{b}: I]$  to find solution and inverse as  $[I: \mathbf{x}: A^{-1}]$ 

#### LU Factorization

$$A = LU \rightarrow Ux = \tilde{b} \rightarrow LUx = b \rightarrow Ux = y \rightarrow Ly = b$$

Iterative method: Jacobi

$$\begin{cases} ax + by = c \\ dx + ey = f \end{cases} \Rightarrow \begin{cases} x = (c - by)/a \\ y = (f - dx)/e \end{cases} \Rightarrow \begin{cases} \text{Initial guess for x,y} \\ \text{Iterate} \end{cases}$$

## **Eigenvalues and Eigenvectors**

 $A x_i = \lambda_i x_i \Rightarrow \text{Characteristic equation (CE): } (A - \lambda_i I) x_i = 0, \forall i$ 

Find eigenvalues  $\lambda_i$  as the scalar roots of the CE

Replace every  $\lambda_i$  in the CE to find eigenvectors  $x_i$  associated to each  $\lambda_i$ 

 $\rightarrow x_i$  must be linearly independent

 $\rightarrow$  A is a zero of its characteristic equation (Cayley Hamilton).

$$|A| = \prod \lambda_i \quad tr(A) = \sum \lambda_i$$

If, for any i,  $\lambda_i = 0 \Rightarrow A$  is singular

If A is real and symmetric  $\Rightarrow \lambda_i \in \mathbb{R}$ 

If A is diagonal  $\Rightarrow A = diag(\lambda_i)$  and  $A^{-1} = diag(1/\lambda_i)$ 

If A is upper or lower triangular  $\Rightarrow \lambda_{ii} = a_{ii}$  and  $|A| = \prod a_{ii}$ 

## **Companion Matrix**

$$p(x) = x^{n} + a_{1}x^{n-1} + \dots + a_{n-1}x + a_{n} = 0$$

$$\Rightarrow p(x) = x^n - (a_n - a_{n-1}x - \dots - a_1x^{n-1})$$

$$\Rightarrow p(x) = x^{n} - (a_{n} - a_{n-1}x - \dots - a_{1}x^{n-1})$$

$$C = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & \ddots & \vdots & 0 \\ \vdots & \vdots & \ddots & 1 & 0 \\ 0 & 0 & \dots & 0 & 1 \\ -a_{n} & -a_{n-1} & \dots & -a_{2} & -a_{1} \end{bmatrix} \Rightarrow \begin{cases} |C| = p(x) \\ \text{Eigenvalues are the roots of } p(x) \end{cases}$$

#### **Partitioned Matrix**

$$AB = C \Rightarrow \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} [B_1 \quad B_1] = \begin{bmatrix} A_1 B_1 & A_1 B_2 \\ B_2 B_1 & A_2 B_2 \end{bmatrix}$$

$$A = \begin{bmatrix} A_1 & 0 & \cdots & 0 \\ 0 & A_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & A_n \end{bmatrix} \Rightarrow \det(A) = |A| = |A_1| |A_2| \dots |A_n|$$

$$\mathcal{L}{f(t)} = \int_0^\infty e^{-st} f(t) dt = F(s)$$

 $\mathcal{L}^{-1}{F(s)} = f(t)$ 

Workflow: IVP 
$$\rightarrow \mathcal{L}(t \rightarrow s) \rightarrow \text{Algebra} \rightarrow \mathcal{L}^{-1}(s \rightarrow t)$$

#### **Properties - linearity**

$$\mathcal{L}{f} = F$$
  $\mathcal{L}{g} = G$   $f = f(t)$   $g = g(t)$   $F = F(s)$   $G = G(s)$ 

$$\mathcal{L}{f+g} = F+G \qquad \mathcal{L}^{-1}{F+G} = f+g$$

$$\mathcal{L}\{a\ f\} = a\ F\ \mathcal{L}^{-1}\{a\ F\} = a\ f\ a\in\mathbb{R}$$

#### **Operations**

$$\mathcal{L}\{f'\} = sF - f(0)$$

$$\mathcal{L}\{f^{(n)}\} = s^n F - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - f^{(n-1)}(0)$$

$$\mathcal{L}\lbrace e^{at}f\rbrace = F(s-a) \quad \mathcal{L}\lbrace f(t-a)\rbrace = e^{-at}F$$

$$\mathcal{L}\{\int_0^t f(u)du\} = \frac{1}{2}F$$

#### Periodic function:

$$f(t+\omega) = f(t) \Rightarrow \mathcal{L}{f} = \frac{1}{1-e^{-s\omega}} \int_0^{\omega} f(t)e^{-st} du$$

#### **Partial fractions**

$$H = \frac{F(s)}{G(s)} = \frac{a_0 + a_1 s + a_2 s^2 + \dots + a_p s^p}{b_0 + b_1 s + b_2 s^2 + \dots + b_r s^r} \quad \begin{cases} a_i, b_i \in \mathbb{R} \\ f \text{ and } g \text{ do not have common roots} \\ g \text{ is of higher degree than } f \ (r > p) \end{cases}$$

Factor F(s) in linear factors  $(s-a)^m$  and quadratic factors  $(s^2+ps+q)^n$ .

$$H = \frac{A_1}{s-a} + \frac{A_2}{(s-a)^2} + \cdots + \frac{A_m}{(s-a)^m} + \frac{B_1 s + C_1}{s^2 + ps + q} + \frac{B_2 s + C_2}{(s^2 + ps + q)^2} + \cdots + \frac{B_n s + C_n}{(s^2 + ps + q)^n}$$

Solve for  $A_i$ ,  $B_i$   $C_i$ 

#### Remark:

$$as^{2} + bs + c = a(s+k)^{2} + h^{2}$$
  $k = \frac{b}{2a}$   $h = \sqrt{c - b^{2}/4a}$ 

$$as^{2} + bs + c = a(s+k)^{2} + h^{2} \qquad k = \frac{b}{2a} \quad h = \sqrt{c - b^{2}/4a}$$

$$Ex: \mathcal{L}^{-1} \left\{ \frac{1}{s^{2} - 2s + 9} \right\} = \frac{1}{(s-1)^{2} + \sqrt{8}^{2}} = \frac{1}{\sqrt{8}} \frac{\sqrt{8}}{(s-1)^{2} + \sqrt{8}^{2}} = \frac{1}{\sqrt{8}} e^{x} \sin \sqrt{8}x$$

Ex: Avoid imaginary factors:  $\mathcal{L}^{-1}\left\{\frac{1}{s^2 + 2s + 2}\right\} = \frac{1}{(s+1)^2 + 1} = e^{-x} \sin x$ 

### **Step Function**

$$u(t) = \begin{cases} 0 & t < 0 \\ 1 & t > 0 \end{cases} \mathcal{L}\{u(t)\} = \frac{1}{s}$$

$$u(t) = \begin{cases} 0 & t < 0 \\ 1 & t \ge 0 \end{cases} \quad \mathcal{L}\{u(t)\} = \frac{1}{s}$$

$$u(t-a) = \begin{cases} 0 & 0 \le t < a \\ 1 & t \ge a \end{cases} \quad \mathcal{L}\{u(t-a)\} = \frac{e^{-as}}{s}, \ a > 0$$

$$\mathcal{L}\{f(t-a)u(t-a)\} = e^{-as}F(s)$$

$$\mathcal{L}{f(t) u(t-a)} = e^{-as} \mathcal{L}{f(t+a)}$$

# **Impulse Function**

$$\delta(t) = \begin{cases} \infty & t = 0 \\ 0 & t \neq 0 \end{cases} \mathcal{L}\{\delta(t)\} = 1$$

$$\delta(t-a) = \begin{cases} \infty & t = a \\ 0 & t \neq a \end{cases} \mathcal{L}\{\delta(t-a)\} = e^{-as}$$

#### Convolution

$$\mathcal{L}{F.G} = f * g = \int_0^t f(u)g(t-u)du$$

$$f * g = g * f$$

Ex: 
$$\mathcal{L}^{-1}\left\{\frac{1}{s^2(s-a)}\right\} \mathcal{L}^{-1}\left\{\frac{1}{s^2}\right\} = t \mathcal{L}^{-1}\left\{\frac{1}{s-a}\right\} = e^{at} \mathcal{L}^{-1}\left\{\frac{1}{s^2}\frac{1}{s-a}\right\} = \int_0^t u e^{a(t-u)} du = \frac{1}{a^2}(e^{at} - at - 1)$$

## **Polynomial coefficients**

$$\mathcal{L}\lbrace t^n. f(t)\rbrace = (-1)^n F^{(n)}(s) \quad n \in \mathbb{N}$$

Let 
$$y(0) = y_0$$
 and  $y'(0) = w_0$ 

$$\mathcal{L}\{ty'\} = -\frac{d}{ds}\mathcal{L}\{y'\} = -\frac{d}{ds}[sY - y_0] = -Y - sY' + y_0'$$

$$\mathcal{L}\{ty''\} = -\frac{d}{ds}\mathcal{L}\{y''\} = -\frac{d}{ds}[s^2Y - sw_0 - y_0] = -2sY - s^2Y' + sw'_0 + w_0 + y'_0$$

$$\mathcal{L}\{t^2y'\} = \frac{d^2}{ds^2}\mathcal{L}\{y'\} = \frac{d^2}{ds^2}[sY - y_0] = 2Y' + sY'' - y_0''$$

Ex: 
$$y'' + 2ty' - 4y = 1$$
  $y(0) = y'(0) = 0$   $s^2Y - 2Y - 2sY' - 4Y = \frac{1}{s}$  New linear DE! Solve with Integration Factor to find  $Y(s)$ .

### Systems of DE using Laplace Transforms

Ex: 
$$\begin{cases} \frac{dx}{dt} = 2x - 3y & x(0) = 8\\ \frac{dy}{dt} = y - 2x & y(0) = 3 \end{cases} \begin{cases} sX - x(0) = 2X - 3Y\\ sY - y(0) = Y - 2X \end{cases}$$

Solve for X and Y. Invert to find x(t) and y(t)

#### Integral by parts:

LAPLACE

$$\int_{a}^{b} u dv = uv|_{a}^{b} - \int_{a}^{b} v du$$

$$\begin{split} \int_{t_0}^{t_1} e^{-st} \cos(at) \, dt &= ? \\ u &= e^{-st} \to du = -se^{-st} dt & dv = \cos(at) \to v = \frac{1}{a} \sin{(at)} \\ \int_{t_0}^{t_1} e^{-st} \cos(at) \, dt &= \frac{1}{a} \left[ e^{-st} \sin(at) \right]_{t_0}^{t_1} + \frac{s}{a} \int_{t_0}^{t_1} e^{-st} \sin(at) \, dt \\ u &= e^{-st} \to du = -se^{-st} dt & dv = \sin(at) \to v = \frac{-1}{a} \cos{(at)} \\ \int_{t_0}^{t_1} e^{-st} \cos(at) \, dt &= \frac{1}{a} \left[ e^{-st} \sin(at) \right]_{t_0}^{t_1} + \frac{s}{a^2} \left[ e^{-st} \sin(at) \right]_{t_0}^{t_1} - \frac{s^2}{a^2} \int_{t_0}^{t_1} e^{-st} \cos(at) \, dt \\ \int_{t_0}^{t_1} e^{-st} \cos(at) \, dt &= \frac{a}{a^2 + s^2} \left[ e^{-st} \sin(at) \right]_{t_0}^{t_1} + \frac{s}{a^2 + s^2} \left[ e^{-st} \sin(at) \right]_{t_0}^{t_1} \end{split}$$

$$\int t \cos t \, dt = t \sin t + \cos t \quad u = t \; ; \; du = dt \; ; \; dv = \cos t \, dt \; ; \; v = \sin t$$

# **Euler**

$$e^{\pm ix} = \cos x \pm i \sin x \qquad \cos x = \frac{e^{ix} + e^{-ix}}{2} \quad \sin x = \frac{e^{ix} - e^{-ix}}{2i}$$

#### Baskhara

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\int \frac{x \, dx}{ax+b} \, dx = \frac{1}{2} \ln |x^2 + a^2|$$

$$\int \frac{dx}{ax+bx+c} = \frac{2}{\sqrt{aa-b^2}} \, atan \frac{2ax+b}{\sqrt{4ac-b^2}}$$

$$\int \frac{x \, dx}{(x+a)^2+b^2} = \frac{1}{2} \ln |(x+a)^2 + b^2| - \frac{a}{b} \, atan \frac{x+a}{b}$$

$$\int \frac{x \, dx}{x^2+a^2} = \frac{1}{a} \, atan \frac{x}{a}$$

$$\int \frac{dx}{x^2+a^2} = \frac{1}{a} \, atan \frac{x}{a}$$

$$\int \frac{dx}{x^2-a^2} = \int \frac{dx}{(x+a)(x-a)} = \frac{1}{2a} \left[ \int \frac{dx}{x-a} - \int \frac{dx}{x+a} \right] = \frac{1}{2a} \ln \left| \frac{x-a}{x+a} \right|$$

$$\int (x+a)^n \, dx = \frac{(x+a)^{n+1}}{n+1}$$

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$$\int \frac{x^2}{x^2+a^2} \, dx = x - a \left( atan \frac{x}{a} \right)$$

$$\int \frac{x^3}{x^2+a^2} \, dx = \frac{1}{2} x^2 - \frac{1}{2} a^2 \ln |a^2 + x^2|$$

$$\int \frac{dx}{(x+a)(x+b)} = \frac{1}{b-a} \ln \left( \frac{a+x}{b+x} \right) \quad a \neq b$$

$$\int \frac{x \, dx}{(x^2+a)(x+b)} = \frac{1}{b-a} \ln |ax^2 + bx + c| - \frac{b}{a} \frac{1}{\sqrt{4ac-b^2}} \, atan \frac{2ax+b}{\sqrt{4ac-b^2}}$$

$$\int \sqrt{x-a} \, dx = \frac{2}{3} (x-a)^{3/2}$$

$$\int \frac{dx}{\sqrt{x+a}} = 2\sqrt{x \pm a}$$

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$$\int \frac{dx}{\sqrt{x+a}} = 2\sqrt{x} \, dx = \frac{1}{2a} (ax+b)^{5/2}$$

$$\int \frac{x}{\sqrt{x+a}} \, dx = -\sqrt{x(a-x)} - a \, atan \left( \frac{\sqrt{x(a-x)}}{x-a} \right)$$

$$\int \int \frac{x}{\sqrt{a-x}} \, dx = -\sqrt{x(a-x)} - a \, atan \left( \frac{\sqrt{x(a-x)}}{x-a} \right)$$

$$\int \sqrt{x^2 + a^2} \, dx = \frac{1}{2} x \sqrt{x^2 + a^2} \, dx + 3 a^2 x^2 \sqrt{ax + b}$$

$$\int \sqrt{x^2 + a^2} \, dx = \frac{1}{2} x \sqrt{x^2 + a^2} + \frac{1}{2} a^2 a \, tan \frac{x}{\sqrt{a^2 - x^2}}$$

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$$\int \frac{dx}{\sqrt{a^2 - x^2}} \, dx = -\sqrt{a^2 - x^2}$$

$$\int \ln ax \, dx = x \ln |ax - x|$$

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$$\int \ln ax \, dx = x \ln |ax$$

 $\int \frac{\ln ax}{x} dx = \frac{1}{2} (\ln ax)^2$ 

 $\int \frac{\ln ax}{x^2} dx = -\frac{1}{x} - \frac{\ln x}{x}$ 

$$\int \ln(ax+b) \, dx = \left(x + \frac{b}{a}\right) \ln(ax+b) - x \qquad a \neq 0$$

$$\int x \ln(ax+b) \, dx = \frac{bx}{2a} - \frac{1}{4}x^2 + \frac{1}{2}(x^2 - \frac{b^2}{a^2}) \ln(ax+b)$$

$$\int \ln(x^2 + a^2) \, dx = x \ln(x^2 + a^2) + 2a \tan \frac{x}{a} - 2x$$

$$\int \ln(x^2 - a^2) \, dx = x \ln(x^2 - a^2) + a \ln \frac{x+a}{x-a} - 2x$$

$$\int \ln(ax^2 + bx + c) \, dx = \frac{1}{\sqrt{4ac-b^2}} \arctan \frac{2ax+b}{\sqrt{4ac-b^2}} - 2x + \left(\frac{b}{2a} + x\right) \ln(ax^2 + bx + c)$$

$$\int (\ln x)^2 \, dx = 2x - 2x \ln x + x(\ln x)^2$$

$$\int xe^{ax} \, dx = \left(\frac{x}{a} - \frac{1}{a^2}\right) e^{ax}$$

$$\int x^2 e^{ax} \, dx = \left(\frac{x^2}{a} - \frac{2x}{a^2} + \frac{2}{a^2}\right) e^{ax}$$

$$\int x^n e^{ax} \, dx = \frac{x^n - a^n}{a} - \frac{\pi}{a} \int x^{n-1} e^{ax} \, dx$$

$$\int \sin ax \, dx = \frac{1}{a} \cos ax$$

$$\int \cos ax \, dx = \frac{1}{a} \sin ax$$

$$\int \sin^2 ax \, dx = \frac{x}{2} - \frac{\sin 2ax}{4a}$$

$$\int \cos^3 ax \, dx = \frac{x + \sin 2ax}{4a}$$

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$$\int \sec^2 ax \, dx = \frac{1}{a} \tan ax$$

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$$\int \sec^2 x \, dx = \frac{1}{a} \tan ax$$

$$\int x \cos ax \, dx = \frac{1}{a^2} \cos ax + \frac{x}{a} \sin ax$$

$$\int x^2 \cos ax \, dx = \frac{1}{a^2} \cos ax + \frac{x}{a} \sin ax$$

$$\int x^2 \sin ax \, dx = \frac{-x \cos ax}{a^2} + \frac{x^2 \sin ax}{a^2}$$

$$\int x^2 \sin ax \, dx = \frac{-x \cos ax}{a^2} + \frac{x^2 \sin ax}{a^2}$$

$$\int x^2 \sin ax \, dx = \frac{(2a^2 - x^2)}{a^2} \cos ax + \frac{2x \sin ax}{a^2}$$

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