HW9

November 29, 2023

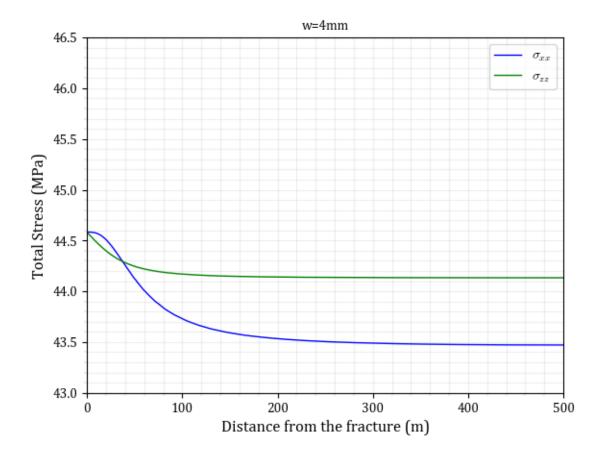
Exercise 1

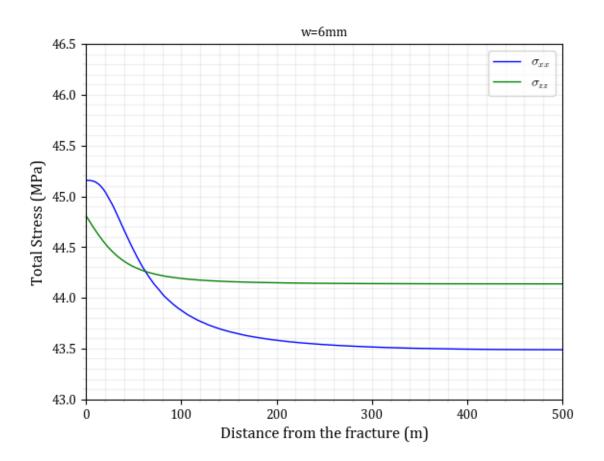
 $\# d_syy = nu * (d_sxx + d_szz)$

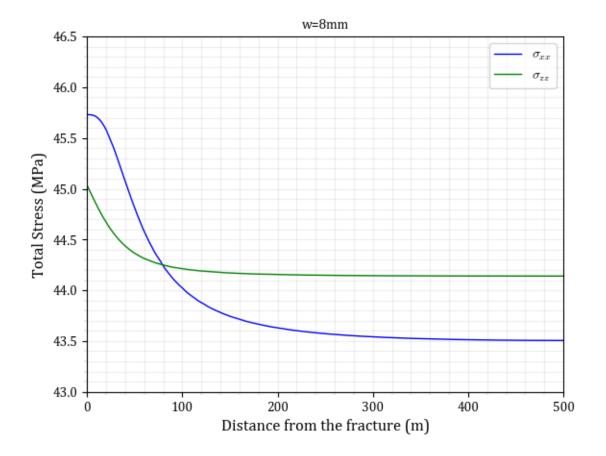
```
3]: E_psi = 7.3e6
   E = 6894.76 * E_psi
    c_{ft} = 150
    c = 150 * 0.3048
   nu = 0.2
    w = 4e-3
   P_{net} = E / (1 - nu**2) / 4 / c * w
   SH_psi = 6400
    SH = SH_psi * 6894.76
    Sh_psi = 6300
    Sh = Sh_psi * 6894.76
    print(f"Pnet={P_net / 1e6} MPa")
   print(f"E={E / 1e9} GPa")
    print(f"c={c}m")
    print(f"SH={SH/1e6} MPa")
    print(f"Sh={Sh/1e6} MPa")
    # Net pressure for each farcture width
    w = 4e-3
    P_net = E / (1 - nu**2) / 4 / c * w
    print(f"w={w} => P_net={P_net/1e6:.4f}")
    w = 6e-3
    P_{net} = E / (1 - nu**2) / 4 / c * w
    print(f"w={w} => P_net={P_net/1e6:.4f}")
    w = 8e-3
   P_{net} = E / (1 - nu**2) / 4 / c * w
    print(f"w={w} => P_net={P_net/1e6:.4f}")
    w = 4e-3
   P_{net} = E / (1 - nu**2) / 4 / c * w
   print(f"w={w} => P_net={P_net/1e6:.4f}")
   Pnet=1.1467389362787985 MPa
   E=50.331748 GPa
   c=45.72m
  SH=44.126464 MPa
   Sh=43.436988 MPa
  w=0.004 \Rightarrow P_net=1.1467
   w=0.006 => P_net=1.7201
   w=0.008 \Rightarrow P_net=2.2935
  w=0.004 \Rightarrow P_net=1.1467
3]: import pandas as pd
    import matplotlib.pyplot as plt
    plt.style.use('default') ## reset!
    plt.style.use('paper.mplstyle')
    def find_xcross (df, title) :
        df['sxx_tot'] = Sh - df.sigxx
        df['sigzz'] = nu * ( df.sigxx + df.sigyy )
        df['szz_tot'] = SH - df.sigzz
```

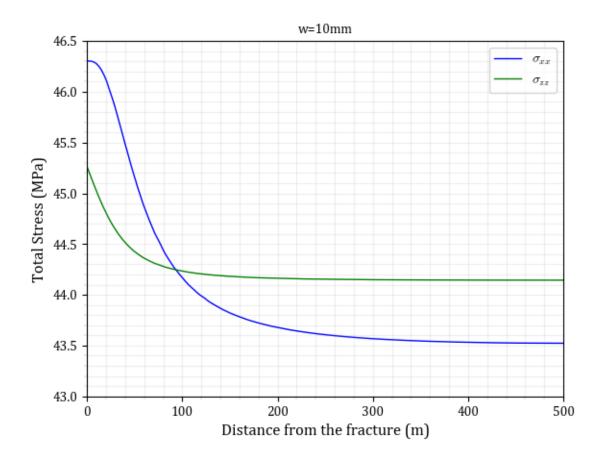
```
from scipy.interpolate import make_interp_spline, PPoly
    import matplotlib.pyplot as plt
    spline = make_interp_spline(df.x, df.sxx_tot - df.szz_tot, k=1) # Create a cubic spline from the data
    curve = PPoly.from_spline(spline)
                                         # Create a piecewise polynomial object; in essence, y = curve(x)
    width = curve.solve(y=0)
    width = width[ width > 20 ]
    df["spline"] = spline( df.x )
    fig, ax = plt.subplots()
    ax.plot( df.x, df.sxx_tot/1e6, label='\sl_x' )
    ax.plot( df.x, df.szz_tot/1e6, label='$\sigma_{zz}$' )
    \#ax.plot(df.x, df.szz\_tot, label='$\sigma_{zz}$')
    ax.set_title( title )
    ax.set_xlabel("Distance from the fracture (m)")
    ax.set_ylabel("Total Stress (MPa)")
    ax.set_xlim(0,500)
    ax.set_ylim(43,46.5)
    ax.legend()
    #fig, ax = plt.subplots()
    #ax.plot( df.x, df.sxy_tot, label='sxy' )
    #ax.plot( df.x, df.szz_tot, label='szz' )
    #ax.legend()
    #fig, ax = plt.subplots()
    #ax.scatter( df.x, df.sxx_tot - df.syy_tot, label='Sxx - Syy', marker='x', alpha=0.3 )
    #ax.plot( df.x, df.spline, label='Spline', c='r' )
    print( width )
    return width[0]
w = [4, 6, 8, 10]
xc = []
df = pd.read_csv( "FractureCenter_w4.dat", sep=",")
xc.append ( find_xcross( df, "w=4mm" ) )
df = pd.read_csv( "FractureCenter_w6.dat", sep=",")
xc.append ( find_xcross( df, "w=6mm" ) )
df = pd.read_csv( "FractureCenter_w8.dat", sep=",")
xc.append ( find_xcross( df, "w=8mm" ) )
df = pd.read_csv( "FractureCenter_w10.dat", sep=",")
xc.append ( find_xcross( df, "w=10mm" ) )
fig, ax = plt.subplots()
ax.scatter( w, xc, marker='x' )
ax.set_xlabel("Fracture width $w_0$ (mm)")
ax.set_ylabel("Distance of the isotropic point (m)")
[37.28153309]
[62.35566458]
```

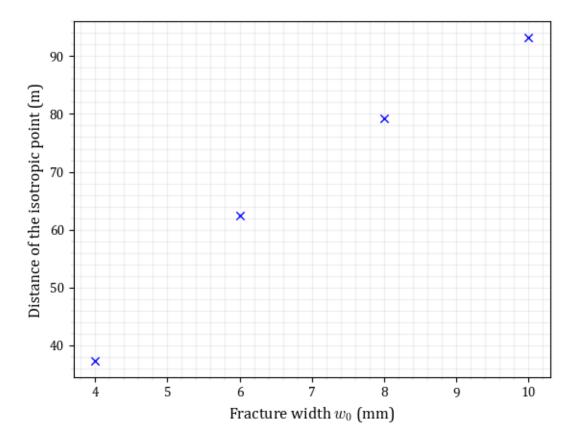
[79.30553238]











Exercise 2

```
fight numpy as np
hf_ft = 170
hf = hf_ft * 0.3048 # m

E__psi = 8.9e6
E_ = E__psi * 6894.76 # Pa

Q_bbl_min = 50 # bbl/min
Q = 50 / 377.3884 # m3/s

mu_cp = 2 #cp
mu = 2 * 1e-3 # Pa.S

def PKN(t):
    global Q, E_, mu, hf
    xf = 0.524 * ( Q**3 * E_ / mu / hf**4 ) ** 0.2 * t**(4/5)
    w0 = 3.04 * ( Q**2 * mu / E_ / hf ) **0.2*t**0.2
    Pnet = 1.52 * ( E_**4 * Q**2 * mu / hf**6 ) ** 0.2 * t**0.2
    return xf, w0, Pnet
```

```
T_hour = 1
t = 1 * 60 * 60 # sec

xf, w0, Pnet = PKN(t)

print( f"xf={xf:.2f} m" )
print( f"w0={w0*1e3:.2f} mm" )
print( f"Pnet={Pnet/1e6:.2f} MPa" )
```

xf=2309.33 m w0=6.35 mm Pnet=3.76 MPa

```
Z]: T = np.linspace( 0, 2*60*60, 100 ) #seconds
T_h = T/60/60

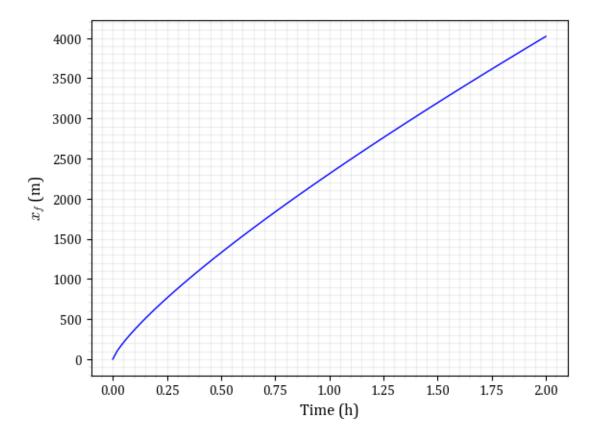
xf, w0, Pnet = PKN(T)

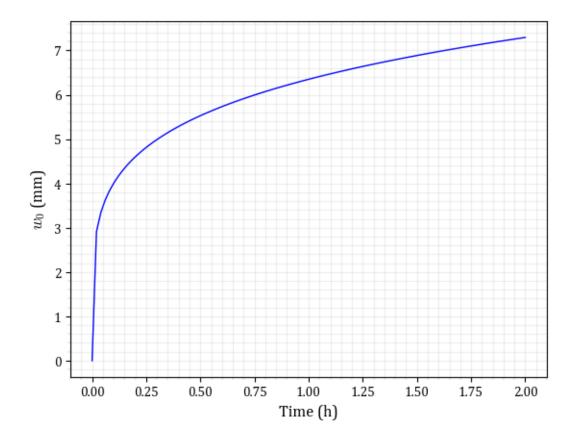
import pandas as pd
import matplotlib.pyplot as plt
plt.style.use('default') ## reset!
plt.style.use('paper.mplstyle')

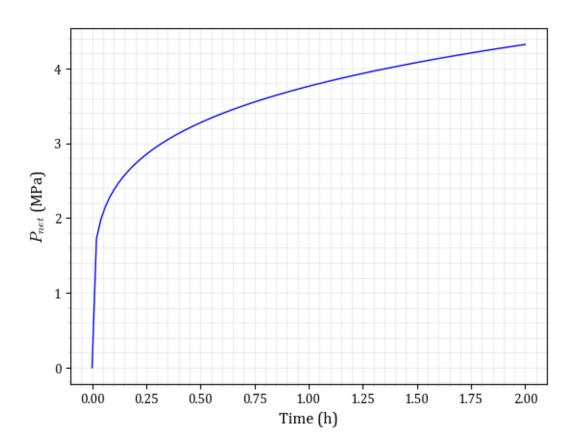
fig, ax = plt.subplots()
ax.plot(T_h,xf)
ax.set_ylabel("$x_f$ (m)")
ax.set_ylabel("$x_f$ (m)")
fig, ax = plt.subplots()
ax.plot(T_h,w0*1e3)
ax.set_ylabel("$w_0$ (mm)")
ax.set_ylabel("$w_0$ (mm)")
ax.set_xlabel("Time (h)")

fig, ax = plt.subplots()
ax.plot(T_h,p0*1e3)
ax.set_ylabel("$y_f* (MPa)")
ax.set_ylabel("$P_f* (MPa)")
ax.set_ylabel("$P_f* (MPa)")
ax.set_xlabel("Time (h)")
```

2]: Text(0.5, 0, 'Time (h)')







3. What should you do to your solution in order to consider leak-off? Justify and explain briefly the algorithm to calculate x_f , $w_{w,0}$, and p_n . The leakoff would reduce the effective rate of fluid inside the fracture (namely, the i parameter in the equation), and the energy aviailable to open the fracture.

The algorithm would probably be iterative, as the leakoff model would depend tightly on the x_f , P_{net} and w_0 parameters, and vice-versa. So I believe we would need to calculate the solution by stepping, to deal with such tight coupling.

```
B]: with open('Fracture.edp', 'r') as file:
      data = file.read().rstrip()
   print(">> ----")
   print(">> FreeFem++ input - Fracture.edp")
   print(">> ----\n\n")
   print(data)
  >> -----
  >> FreeFem++ input - Fracture.edp
  load "iovtk"
  //-----
  // Dimensions
  real xa = 0.;
  real xb = 500.; // x-size of the domain
  real ya = -300.;
  real yb = 300.; // y-size of the domain
  real xSize = xb - xa ;
  real ySize = yb - ya ;
  // Elastic constants
  real E = 50.33e9;
                     // Young's modulus
  real nu = 0.2 ;  // Poisson's ratio
  real G = E/(2*(1+nu)); // shear modulus
  real lambda = E*nu/((1+nu)*(1-2*nu)); // Lame constant
  //Stresses
  real Pfrac = 2.8668e6;
  // w=0.004 => P_net=1.1467e6
  // w=0.006 => P_net=1.7201e6
  // w=0.008 => P_net=2.2935e6
  // w=0.01 => P_net=2.8668e6
  // FRACTURE
  real xf = 45.72; // fracture half-length
  real fw = .000; // fracture half-width
  //-----
  // First define boundaries
  border Right(t=ya, yb){x=xb;y=t;}
  border Top(t=xb, xa){x=t;y=yb;}
  border Left1(t=yb,(ya+ySize/2+xf)){x=xa;y=t;}
  border Frac(t = -pi/2, pi/2) {x = fw*cos(t); y = xf*sin(-t);}
  border Left2(t=(ya+ySize/2-xf), ya){x=xa;y=t;}
  border Bottom(t=xa,xb){x=t;y=ya;}
  //SHOW DOMAIN
  plot( Right(10)+Top(10)+Left1(10), Left2(10) +Bottom(10) +Frac(40), wait=true);
  //-----
  // Create mesh
  int n = 30; // number of mesh nodes on the outer borders
  int nfrac = 30; // number of mesh nodes on wellbore
  mesh Omega = buildmesh
  (\texttt{Right(n)} + \texttt{Top(n)} + \texttt{Left1(n/2)} + \texttt{Left2(n/2)} + \texttt{Bottom(n)} + \texttt{Frac(nfrac))};
  plot(Omega, wait=true);
  fespace Displacement(Omega, P2); // linear shape functions
  fespace Stress(Omega, P2); // piecewise constants
  Displacement u1, u2, v1, v2;
  Stress sigmaxx, sigmayy, sigmaxy;
  //-----
```

// definition of 2 macros :

```
// macro for strain
macro e(u1,u2)
       Γ
               dx(u1),
               (dy(u1)+dx(u2))/2,
               (dx(u2)+dy(u1))/2,
               dy(u2)
       ]//eps_xx, eps_xy , eps_yx , eps_yy
// macro for stress
macro sigma(u1,u2)
               (lambda+2.*G)*e(u1,u2)[0]+lambda*e(u1,u2)[3],
               2.*G*e(u1,u2)[1],
               2.*G*e(u1,u2)[2],
               lambda*e(u1,u2)[0]+(lambda+2.*G)*e(u1,u2)[3]
       ] //stress s_xx, s_xy, s_yx, s_yy
       // Define system of equations
problem Elasticity([u1,u2], [v1,v2]) =
   int2d(Omega) ( sigma(u1,u2)'*e(v1,v2) )
       + on(Left1,u1=0)
                            // Dirichlet boundary conditions
       + on(Left2,u1=0)
                                  // Dirichlet boundary conditions
       + on(Bottom,u2=0)
       + on(Right,u1=0)
       + on(Top,u2=0)
  // Boundary conditions
  // condition only on one component
  + int1d(Omega, Frac) (Pfrac*(N.x*v1))
//-----
       Solve system
Elasticity;
// Stresses
sigmaxx = sigma(u1,u2)[0];
sigmayy = sigma(u1,u2)[3];
sigmaxy = sigma(u1,u2)[1];
                           // we could use [2] as
                                                                 well
//-----
// plot on the deformed surface
mesh Th=movemesh(Omega, [x+10*u1,y+10*u2]);
plot(Th,cmm="Deformed configuration",wait=1);
// plot the deformation field and stress
plot([u1,u2],coef=10,cmm="Displacement field",wait=1,value=true);
plot(sigmaxx,fill=1, cmm="Stress sigmaxx",wait=1,value=true);
plot(sigmayy,fill=1, cmm="Stress sigmayy",wait=1,value=true);
plot(sigmaxy,fill=1, cmm="Stress sigmaxy",wait=1,value=true);
// Write stress field
ofstream ff("FractureShadow.dat");
for(int i=0;i<100;i++) {
for(int j=0;j<100;j++) {
       // x, y, Sxx, Syy, Sxy
              real xline = xa + xSize*i/100.;
               real yline = ya + ySize*j/100.;
       // Analytical solution
       //write file numerical and analytical solution
       ff<< xline <<", "<< yline
               <<", "<< sigmaxx(xline,yline)
               <<", "<< sigmayy(xline,yline)
               <<", "<< sigmaxy(xline,yline)
               <<endl;
// Write horizontal line from the fracture center
ofstream fc("FractureCenter_w10.dat");
fc << "x,y,sigxx,sigyy,sigxy" << endl;</pre>
for(int i=0;i<1000;i++) {
 real xline = xa + xSize*i/1000.;
 real yline = 0;
 fc<< xline <<", "<< yline
   <<", "<< sigmaxx(xline,yline)
```

```
<<", "<< sigmayy(xline,yline)
<<", "<< sigmaxy(xline,yline)
<<endl;
```