

A generalized entropy ftn.,
or a mathematical, entropy
ftn.

$$1. H(U) \in \mathbb{R}^+$$

2. \exists scalar val ftns called
entropy ftns $\sigma_i(U)$

$$\Rightarrow H_{,U} A_i^\vee = \sigma_{i,U}$$

$$\begin{aligned} \text{So } H_{,t} + \sigma_{i,i} &= H_{,U} U_{,t} + \sigma_{i,U} U_{,i} \\ &= H_{,U} (U_{,t} + A_i U_{,i}) \end{aligned}$$

$$\text{Choose } H = \int g \, \omega \leftarrow, \text{ with } \sigma_i = H u_i$$

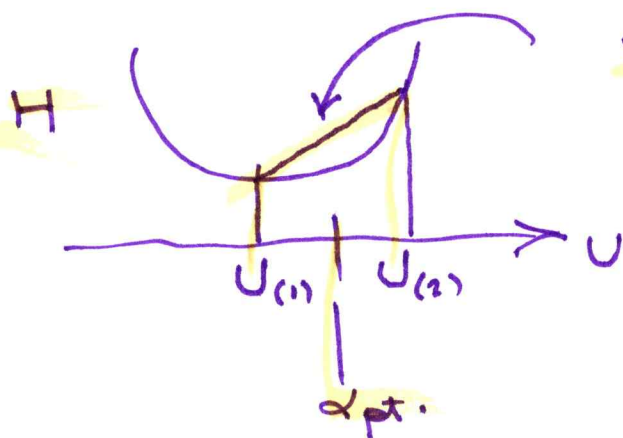
$$\omega \uparrow \Leftrightarrow H \downarrow$$

Note: H is a convex ftn of U .

$$\forall \alpha \in [0, 1]$$

$$\alpha H(U_{(1)}) + (1-\alpha) H(U_{(2)})$$

$$\geq H(\alpha U_{(1)} + (1-\alpha) U_{(2)})$$



We ^{have} a well-defined change of variables: (140.)

$$V = \frac{\partial H}{\partial U} \quad V(U), \quad U(V)$$

by convex of $H(U)$ $V = \text{"entropy variables"}$

Convexity can also be expressed as

$$\underbrace{H_{,UU}}_{5 \times 5} \text{ pos. def.}$$

Why is V important? Let's see.

$$0 = R(U) = U_{,t} + \underbrace{A_i(U)}_{\tilde{A}_i(U)} U_{,i} - \underbrace{(K_{ij}(U) U_{,j})_{,i}}_{\tilde{K}_{ij}(U)} - \underline{F(U)}$$

$$0 = \tilde{R}(V) = R(\underbrace{U(V)}_{\uparrow})$$

$$= \underbrace{U_{,V}}_{\tilde{A}_0(V)} V_{,t} + \boxed{\underbrace{A_i(U(V)) U_{,V}}_{\tilde{A}_0(V)} V_{,i}}$$

symm. > 0 .

$$- \underbrace{(K_{ij}(U(V)) U_{,V} V_{,j})_{,i}}_{\tilde{K}_{ij}(V)} - \underbrace{F(U(V))}_{\tilde{F}(V)}$$

$$0 = \tilde{R}(V) = \underbrace{\tilde{A}_0(V)}_{\text{symm}, > 0} V_{,t} + \underbrace{\tilde{A}_i(V)}_{\text{symm}, > 0} V_{,i} - \underbrace{\left(\tilde{K}_{ij}^{\text{diff}}(V) V_{,j} \right)}_{\text{diff}} V_{,i} - \tilde{f}(V)$$

Properties 1. \tilde{A}_0 symm, pos def

2. Each \tilde{A}_i is symm.

and $\tilde{A}_i k_i$ has real eigenvalues for all $k_i \in \mathbb{R}, i=1,2,3$.

$$3. \tilde{K} = \begin{bmatrix} \tilde{K}_{11} & \tilde{K}_{12} & \tilde{K}_{13} \\ \tilde{K}_{21} & \tilde{K}_{22} & \tilde{K}_{23} \\ \tilde{K}_{31} & \tilde{K}_{32} & \tilde{K}_{33} \end{bmatrix}$$

15x15

is symm.,
pos-semi-def.

$$4. V \cdot \tilde{R}(V) = 0.$$

$$H = -p\omega = -g \frac{\mathcal{M}}{c_w}$$

can be shown $= \left(H_{,t} + (H u_i)_{,i} - \left(\frac{q_i}{c_w \theta} \right)_{,i} + \frac{g r}{c_w \theta} + \underbrace{(V_{,i})^T \tilde{K}_{ij}(V) V_{,j}}_{\geq 0} \right) = 0$

$$\Rightarrow H_{,t} + (H u_i)_{,i} - \left(\frac{q_i}{c_w \theta} \right)_{,i} + \frac{g r}{c_w \theta} \leq 0.$$

Euler part is a symm. hyp. sys.

Friedrichs systems.

$$\Rightarrow \left[\frac{\partial(\rho \eta)}{\partial t} + (\rho \eta u_i)_{,i} + \left(\frac{q_i}{\theta} \right)_{,i} - \frac{\rho r}{\theta} \right]$$

$$= c_w \left(\underbrace{V_{,i}^T K_{ij}(V) V_{,j}}_{\geq 0} \right)$$

$$\lambda \geq 0$$

Clausius - Duhem ineq.
 entropy prod. "
 2nd law of thermo.

Toward our weak form.

$$0 = \int_{Q \times [t_n, t_{n+1}]} W^{h,T}(\tilde{R}(V^h)) dQ \quad \xrightarrow{\text{int-by-parts}} \quad \text{Clausius - Duhem ineq.}$$

$$\begin{aligned} \neq & \int_{Q \times [t_n, t_{n+1}]} \left(-W^{h,T}_{,t} U(V^h) - W^{h,T}_{,i} \tilde{F}_i(V^h) \right. \\ & \left. + W^{h,T}_{,i} \tilde{F}_i^{\text{diff}}(V^h, \nabla V^h) - \tilde{F}(V^h) \right) dQ. \end{aligned}$$

= bndy terms :

$$\begin{aligned} & \int_{\partial \Omega \times [t_n, t_{n+1}]} W^{h,T} \tilde{A}_0 V^h d\Omega + \int_{\partial \Omega \times [t_n, t_{n+1}]} W^{h,T} \tilde{A}_i n_i V^h dP \\ & + \int_{\Omega \times \{t_{n+1}\}} W^{h,T} \tilde{A}_0 V^h d\Omega - \int_{\Omega \times \{t_n\}} W^{h,T} \tilde{A}_0 V^h d\Omega \end{aligned}$$

$\left\{ \begin{array}{l} 0 \\ 1 \\ h \cdot u_i + h_u \end{array} \right\}$

heat source

pos real eigen's
 zero out the
 neg real
 eigen's.

discretize U^h

U^h

↑
as a possible weighting fn
but you need V^h , so?

(143)

$$\begin{aligned} & \underbrace{V^h}_{\substack{\uparrow \\ \text{entropy}}} + \underbrace{\left(\cancel{P} - V^h + \cancel{U^h(V^h)} \right)}_{P(V^h) : \text{conc. var.}} \\ & \quad \quad \quad \underbrace{\left(P(V^h) - V^h \right)}_{\text{entropy error.}} \\ & \quad \quad \quad + \underbrace{P(V(U^h)) - V(U^h)}_{\text{entropy error.}} \end{aligned}$$

X