

APPENDIX G  
POLYNOMIAL ZONOTOPE ARITHMETIC

We introduce several useful operations on polynomial zonotopes: interval conversions, set addition and multiplication, slicing, computing bounds, and set-valued function evaluation.

1) *Interval Arithmetic*: Let  $\mathbb{IR}^n$  be the set of all real-valued  $n$ -dimensional interval vectors. The Minkowski sum and difference of  $[x]$  and  $[y]$  are

$$[x] \oplus [y] = [\underline{x} + \underline{y}, \bar{x} + \bar{y}], \quad (104)$$

$$[x] \ominus [y] = [\underline{x} - \bar{y}, \bar{x} - \underline{y}]. \quad (105)$$

The product of  $[x]$  and  $[y]$  is

$$[x][y] = [\min(\underline{x}\underline{y}, \underline{x}\bar{y}, \bar{x}\underline{y}, \bar{x}\bar{y}), \max(\underline{x}\underline{y}, \underline{x}\bar{y}, \bar{x}\underline{y}, \bar{x}\bar{y})]. \quad (106)$$

The  $i^{\text{th}}$  and  $j^{\text{th}}$  entry of the product of an interval matrix  $[Y]$  multiplied by an interval matrix  $[X]$  is

$$([X][Y])_{ij} = \bigoplus_{k=1}^n ([X]_{ik}[Y]_{kj}), \quad (107)$$

where  $n$  is the number of columns of  $[X]$  and number of rows of  $[Y]$ . Given interval vectors  $[x], [y] \subset \mathbb{R}^3$ , their cross product is

$$[x] \otimes [y] = [x]^\times [y], \quad (108)$$

where  $[x]^\times$  is the skew-symmetric matrix representation of  $[x]$ .

2) *Interval Conversion*: Intervals can also be written as polynomial zonotopes. For example, let  $[z] = [\underline{z}, \bar{z}] \subset \mathbb{R}^n$ , then one can convert  $[z]$  to a polynomial zonotope  $\mathbf{z}$  using

$$\mathbf{z} = \frac{\bar{z} + \underline{z}}{2} + \sum_{i=1}^n \frac{\bar{z}_i - \underline{z}_i}{2} x_i, \quad (109)$$

where  $x \in [-1, 1]^n$  is the indeterminate vector.

3) *Set Addition and Multiplication*: The Minkowski Sum of two polynomial zonotopes  $\mathbf{P}_1 \subset \mathbb{R}^n = \mathcal{PZ}(g_i, \alpha_i, x)$  and  $\mathbf{P}_2 \subset \mathbb{R}^n = \mathcal{PZ}(h_j, \beta_j, y)$  follows from polynomial addition:

$$\mathbf{P}_1 \oplus \mathbf{P}_2 = \left\{ z \in \mathbb{R}^n \mid z = \sum_{i=0}^{n_g} g_i x^{\alpha_i} + \sum_{j=0}^{n_h} h_j y^{\beta_j} \right\}. \quad (110)$$

Similarly, we may write the matrix product of two polynomial zonotopes  $\mathbf{P}_1$  and  $\mathbf{P}_2$  when the sizes are compatible. Letting  $\mathbf{P}_1 \subset \mathbb{R}^{n \times m}$  and  $\mathbf{P}_2 \subset \mathbb{R}^{m \times k}$ , we obtain  $\mathbf{P}_1 \mathbf{P}_2 \subset \mathbb{R}^{n \times k}$ :

$$\mathbf{P}_1 \mathbf{P}_2 = \left\{ z \in \mathbb{R}^{n \times k} \mid z = \sum_{i=0}^{n_g} g_i \left( \sum_{j=0}^q h_j y^{\beta_j} \right) x^{\alpha_i} \right\}. \quad (111)$$

When  $\mathbf{P}_1 \subset \mathbb{R}^{n \times n}$  is square, exponentiation  $\mathbf{P}_1^m$  may be performed by multiplying  $\mathbf{P}_1$  by itself  $m$  times. Furthermore, if  $\mathbf{P}_1 \subset \mathbb{R}^3$  and  $\mathbf{P}_2 \subset \mathbb{R}^3$ , we implement a set-based cross product as matrix multiplication. We create  $\mathbf{P}_1^\times \subset \mathbb{R}^{3 \times 3}$  as

$$\mathbf{P}_1^\times = \left\{ A \in \mathbb{R}^{3 \times 3} \mid A = \sum_{i=0}^{n_g} \begin{bmatrix} 0 & -g_{i,3} & g_{i,2} \\ g_{i,3} & 0 & -g_{i,1} \\ -g_{i,2} & g_{i,1} & 0 \end{bmatrix} x^{\alpha_i} \right\} \quad (112)$$

where  $g_{i,j}$  refers to the  $j^{\text{th}}$  element of  $g_i$ . Then, the set-based cross product  $\mathbf{P}_1 \otimes \mathbf{P}_2 = \mathbf{P}_1^\times \mathbf{P}_2$  is well-defined.

4) *Slicing*: One can obtain subsets of polynomial zonotopes by plugging in values of known indeterminates. For instance, if a polynomial zonotope  $\mathbf{P}$  represented a set of possible positions of a robot arm operating near an obstacle. It may be beneficial to know whether a particular choice of  $\mathbf{P}$ 's indeterminates yields a subset of positions that could collide with the obstacle. To this end, "slicing" a polynomial zonotope  $\mathbf{P} = \mathcal{PZ}(g_i, \alpha_i, x)$  corresponds to evaluating an element of the indeterminate  $x$ . Given the  $j^{\text{th}}$  indeterminate  $x_j$  and a value  $\sigma \in [-1, 1]$ , slicing yields a subset of  $\mathbf{P}$  by plugging  $\sigma$  into the specified element  $x_j$ :

$$\text{slice}(\mathbf{P}, x_j, \sigma) \subset \mathbf{P} = \left\{ z \in \mathbf{P} \mid z = \sum_{i=0}^{n_g} g_i x^{\alpha_i}, x_j = \sigma \right\}. \quad (113)$$

5) *Bounding a PZ*: Our algorithm requires a means to bound the elements of a polynomial zonotope. We define the  $\sup$  and  $\inf$  operations which return these upper and lower bounds, respectively, by taking the absolute values of generators. For  $\mathbf{P} \subseteq \mathbb{R}^n$  with center  $g_0$  and generators  $g_i$ ,

$$\sup(\mathbf{P}) = g_0 + \sum_{i=1}^{n_g} |g_i|, \quad (114)$$

$$\inf(\mathbf{P}) = g_0 - \sum_{i=1}^{n_g} |g_i|. \quad (115)$$

Note that for any  $z \in \mathbf{P}$ ,  $\sup(\mathbf{P}) \geq z$  and  $\inf(\mathbf{P}) \leq z$ , where the inequalities are taken element-wise. These bounds may not be tight, but they are quick to compute.

6) *Set-Valued Function Evaluation*: One can overapproximate any analytic function evaluated on a polynomial zonotope using a Taylor expansion, which itself can be represented as a polynomial zonotope [60, Sec 4.1], [2, Prop. 13]. Consider an analytic function  $f: \mathbb{R} \rightarrow \mathbb{R}$  and  $\mathbf{P}_1 = \mathcal{PZ}(g_i, \alpha_i, x)$ , with each  $g_i \in \mathbb{R}$ , then  $f(\mathbf{P}_1) = \{y \in \mathbb{R} \mid y = f(z), z \in \mathbf{P}_1\}$ . We generate  $\mathbf{P}_2$  such that  $f(\mathbf{P}_1) \subseteq \mathbf{P}_2$  using a Taylor expansion of degree  $d \in \mathbb{N}$ , where the error incurred from the finite approximation is overapproximated using a Lagrange remainder. The method follows the Taylor expansion found in the reachability algorithm in [2], which builds on previous work on conservative polynomialization found in [60]. Recall that the Taylor expansion about a point  $c \in \mathbb{R}$  is

$$f(z) = \sum_{n=0}^{\infty} \frac{f^{(n)}(c)}{n!} (z - c)^n, \quad (116)$$

where  $f^{(n)}$  is the  $n^{\text{th}}$  derivative of  $f$ . The error incurred by a finite Taylor expansion can be bounded using the Lagrange remainder  $r$  [61, p. 7.7]:

$$|f(z) - \sum_{n=0}^d \frac{f^{(n)}(c)}{n!} (z - c)^n| \leq r, \quad (117)$$

where

$$r = \max_{\delta \in [c, z]} \frac{(|f^{(d+1)}(\delta)|) |z - c|^{d+1}}{(d+1)!}. \quad (118)$$

For a polynomial zonotope, the infinite dimensional Taylor expansion is given by

$$f(\mathbf{P}_1) = \sum_{n=0}^{\infty} \frac{f^{(n)}(c)}{n!} (\mathbf{P}_1 - c)^n. \quad (119)$$

In practice, only a finite Taylor expansion of degree  $d \in \mathbb{N}$  can be computed. Letting  $c = g_0$  (i.e., the center of  $\mathbf{P}_1$ ), and noting that  $(z - c) = \sum_{i=1}^{n_g} g_i x^{\alpha_i}$  for  $z \in \mathbf{P}_1$ , we write

$$\mathbf{P}_2 := \left\{ z \in \mathbb{R} \mid z \in \sum_{n=0}^d \left( \frac{f^{(n)}(g_0)}{n!} \left( \sum_{i=1}^{n_g} g_i x^{\alpha_i} \right)^n \right) \oplus [r] \right\}, \quad (120)$$

and the Lagrange remainder  $[r]$  is computed using interval arithmetic as

$$[r] = \frac{[f^{(d+1)}(\mathbf{P}_1)][(\mathbf{P}_1 - c)^{d+1}]}{(d+1)!} \quad (121)$$

where  $[(\mathbf{P}_1 - c)^{d+1}] = [\inf((\mathbf{P}_1 - c)^{d+1}), \sup((\mathbf{P}_1 - c)^{d+1})]$  is an overapproximation of  $(\mathbf{P}_1 - c)^{d+1}$ .  $\mathbf{P}_2$  can be expressed as a polynomial zonotope because all terms in the summation are polynomials of  $x$ , and the interval  $[r]$  can be expressed as a polynomial zonotope as in (109). We denote the polynomial zonotope overapproximation of a function evaluated on a zonotope using bold symbols (i.e.,  $\mathbf{f}(\mathbf{P}_1)$  is the polynomial zonotope overapproximation of  $f$  applied to  $\mathbf{P}$ ).