## SUPPLEMENT A POLYNOMIAL ZONOTOPE ARITHMETIC

We introduce several useful operations on polynomial zonotopes: interval conversions, set addition and multiplication, slicing, computing bounds, and set-valued function evaluation.

1) Interval Arithmetic: Let  $\mathbb{IR}^n$  be the set of all real-valued *n*-dimensional interval vectors. The Minkowski sum and difference of [x] and [y] are

$$[x] \oplus [y] = [x + y, \overline{x} + \overline{y}], \tag{S.1}$$

$$[x] \ominus [y] = [\underline{x} - \overline{y}, \overline{x} - y].$$
 (S.2)

The product of [x] and [y] is

$$[x][y] = \left[\min\left(\underline{x}y, \underline{x}\overline{y}, \overline{x}y, \overline{x}\overline{y}\right), \max\left(\underline{x}y, \underline{x}\overline{y}, \overline{x}y, \overline{x}\overline{y}\right)\right]. \tag{S.3}$$

The  $i^{th}$  and  $j^{th}$  entry of the product of an interval matrix [Y] multplied by an interval matrix [X] is

$$([X][Y])_{ij} = \bigoplus_{k=1}^{n} ([X]_{ik}[Y]_{kj}), \tag{S.4}$$

where *n* is the number of columns of [X] and number of rows of [Y]. Given interval vectors  $[x], [y] \subset \mathbb{R}^3$ , their cross product is

$$[x] \otimes [y] = [x]^{\times}[y], \tag{S.5}$$

where  $[x]^{\times}$  is the skew-symmetric matrix representation of [x].

2) Interval Conversion: Intervals can also be written as polynomial zonotopes. For example, let  $[z] = [\underline{z}, \overline{z}] \subset \mathbb{R}^n$ , then one can convert [z] to a polynomial zonotope **z** using

$$\mathbf{z} = \frac{\overline{z} + \underline{z}}{2} + \sum_{i=1}^{n} \frac{\overline{z}_i - \underline{z}_i}{2} x_i, \tag{S.6}$$

where  $x \in [-1,1]^n$  is the indeterminate vector.

3) Set Addition and Multiplication: The Minkowski Sum of two polynomial zonotopes  $\mathbf{P}_1 \subset \mathbb{R}^n = \mathcal{PZ}(g_i, \alpha_i, x)$  and  $\mathbf{P}_2 \subset \mathbb{R}^n = \mathcal{PZ}(h_i, \beta_i, y)$  follows from polynomial addition:

$$\mathbf{P}_1 \oplus \mathbf{P}_2 = \left\{ z \in \mathbb{R}^n \mid z = \sum_{i=0}^{n_g} g_i x^{\alpha_i} + \sum_{i=0}^{n_h} h_j y^{\beta_j} \right\}. \tag{S.7}$$

Similarly, we may write the matrix product of two polynomial zonotopes  $\mathbf{P}_1$  and  $\mathbf{P}_2$  when the sizes are compatible. Letting  $\mathbf{P}_1 \subset \mathbb{R}^{n \times m}$  and  $\mathbf{P}_2 \subset \mathbb{R}^{m \times k}$ , we obtain  $\mathbf{P}_1 \mathbf{P}_2 \subset \mathbb{R}^{n \times k}$ :

$$\mathbf{P}_{1}\mathbf{P}_{2} = \left\{ z \in \mathbb{R}^{n \times k} \mid z = \sum_{i=0}^{n_{g}} g_{i} (\sum_{j=0}^{q} h_{j} y^{\beta_{j}}) x^{\alpha_{i}} \right\}.$$
 (S.8)

When  $\mathbf{P}_1 \subset \mathbb{R}^{n \times n}$  is square, exponentiation  $\mathbf{P}_1^m$  may be performed by multiplying  $\mathbf{P}_1$  by itself m times. Furthermore, if  $\mathbf{P}_1 \subset \mathbb{R}^3$  and  $\mathbf{P}_2 \subset \mathbb{R}^3$ , we implement a set-based cross product as matrix multiplication. We create  $\mathbf{P}_1^{\times} \subset \mathbb{R}^{3 \times 3}$  as

$$\mathbf{P}_{1}^{\times} = \left\{ A \in \mathbb{R}^{3 \times 3} \mid A = \sum_{i=0}^{n_{g}} \begin{bmatrix} 0 & -g_{i,3} & g_{i,2} \\ g_{i,3} & 0 & -g_{i,1} \\ -g_{i,2} & g_{i,1} & 0 \end{bmatrix} x^{\alpha_{i}} \right\}$$
 (S.9)

where  $g_{i,j}$  refers to the  $j^{\text{th}}$  element of  $g_i$ . Then, the set-based cross product  $\mathbf{P}_1 \otimes \mathbf{P}_2 = \mathbf{P}_1^{\times} \mathbf{P}_2$  is well-defined.

4) Slicing: One can obtain subsets of polynomial zonotopes by plugging in values of known indeterminates. For instance, if a polynomial zonotope  $\mathbf{P}$  represented a set of possible positions of a robot arm operating near an obstacle. It may be beneficial to know whether a particular choice of  $\mathbf{P}$ 's indeterminates yields a subset of positions that could collide with the obstacle. To this end, "slicing" a polynomial zonotope  $\mathbf{P} = \mathcal{PZ}(g_i, \alpha_i, x)$  corresponds to evaluating an element of the indeterminate x. Given the  $j^{\text{th}}$  indeterminate  $x_j$  and a value  $\sigma \in [-1, 1]$ , slicing yields a subset of  $\mathbf{P}$  by plugging  $\sigma$  into the specified element  $x_j$ :

$$slice(\mathbf{P}, x_j, \sigma) \subset \mathbf{P} = \left\{ z \in \mathbf{P} \mid z = \sum_{i=0}^{n_g} g_i x^{\alpha_i}, x_j = \sigma \right\}.$$
 (S.10)

5) Bounding a PZ: Our algorithm requires a means to bound the elements of a polynomial zonotope. We define the sup and inf operations which return these upper and lower bounds, respectively, by taking the absolute values of generators. For  $\mathbf{P} \subseteq \mathbb{R}^n$  with center  $g_0$  and generators  $g_i$ ,

$$\sup(\mathbf{P}) = g_0 + \sum_{i=1}^{n_g} |g_i|, \qquad (S.11)$$

$$\inf(\mathbf{P}) = g_0 - \sum_{i=1}^{n_g} |g_i|.$$
 (S.12)

Note that for any  $z \in \mathbf{P}$ ,  $\sup(\mathbf{P}) \ge z$  and  $\inf(\mathbf{P}) \le z$ , where the inequalities are taken element-wise. These bounds may not be tight, but they are quick to compute.

6) Set-Valued Function Evaluation: One can overapproximate any analytic function evaluated on a polynomial zonotope using a Taylor expansion, which itself can be represented as a polynomial zonotope [1, Sec 4.1],[2, Prop. 13]. Consider an analytic function  $f: \mathbb{R} \to \mathbb{R}$  and  $\mathbf{P}_1 = \mathfrak{PZ}(g_i, \alpha_i, x)$ , with each  $g_i \in \mathbb{R}$ , then  $f(\mathbf{P}_1) = \{y \in \mathbb{R} \mid y = f(z), z \in \mathbf{P}_1\}$ . We generate  $\mathbf{P}_2$  such that  $f(\mathbf{P}_1) \subseteq \mathbf{P}_2$  using a Taylor expansion of degree  $d \in \mathbb{N}$ , where the error incurred from the finite approximation is overapproximated using a Lagrange remainder. The method follows the Taylor expansion found in the reachability algorithm in [2], which builds on previous work on conservative polynomialization found in [1]. Recall that the Taylor expansion about a point  $c \in \mathbb{R}$  is

$$f(z) = \sum_{n=0}^{\infty} \frac{f^{(n)}(c)}{n!} (z - c)^n,$$
 (S.13)

where  $f^{(n)}$  is the  $n^{th}$  derivative of f. The error incurred by a finite Taylor expansion can be bounded using the Lagrange remainder r [3, p. 7.7]:

$$|f(z) - \sum_{n=0}^{d} \frac{f^{(n)}(c)}{n!} (z - c)^n| \le r,$$
 (S.14)

where

$$r = \max_{\delta \in [c,z]} \frac{(|f^{d+1}(\delta)|)|z - c|^{d+1}}{(d+1)!}.$$
 (S.15)

For a polynomial zonotope, the infinite dimensional Taylor expansion is given by

$$f(\mathbf{P}_1) = \sum_{n=0}^{\infty} \frac{f^{(n)}(c)}{n!} (\mathbf{P}_1 - c)^n.$$
 (S.16)

In practice, only a finite Taylor expansion of degree  $d \in \mathbb{N}$  can be computed. Letting  $c = g_0$  (i.e., the center of  $\mathbf{P}_1$ ), and noting that  $(z-c) = \sum_{i=1}^{n_g} g_i x^{\alpha_i}$  for  $z \in \mathbf{P}_1$ , we write

$$\mathbf{P}_{2} := \left\{ z \in \mathbb{R} \, | \, z \in \sum_{n=0}^{d} \left( \frac{f^{(n)}(g_{0})}{n!} (\sum_{i=1}^{n_{g}} g_{i} x^{\alpha_{i}})^{n} \right) \oplus [r] \right\}, \quad (S.17)$$

and the Lagrange remainder [r] is computed using interval arithmetic as

$$[r] = \frac{[f^{(d+1)}([\mathbf{P}_1])][(\mathbf{P}_1 - c)^{d+1}]}{(d+1)!}$$
 (S.18)

where  $[(\mathbf{P}_1 - c)^{d+1}] = [\inf((\mathbf{P}_1 - c)^{d+1}), \sup((\mathbf{P}_1 - c)^{d+1})]$  is an overapproximation of  $(\mathbf{P}_1 - c)^{d+1}$ .  $\mathbf{P}_2$  can be expressed as a polynomial zonotope because all terms in the summation are polynomials of x, and the interval [r] can be expressed as a polynomial zonotope as in (S.6). We denote the polynomial zonotope overapproximation of a function evaluated on a zonotope using bold symbols (i.e.,  $\mathbf{f}(\mathbf{P}_1)$  is the polynomial zonotope overapproximation of f applied to  $\mathbf{P}$ ).