

CSCI 5451 Fall 2015

Week 11 Notes

Professor Ellen Gethner

November 2, 2015

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- ▶ **FFT Application:** Polynomial multiplication (keyword=**convolution** for other applications).

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- ▶ That is, if $p(x) = a_{n-1}x^{n-1} + \dots + a_1x + a_0$ and $q(x) = b_{n-1}x^{n-1} + \dots + b_1x + b_0$ then the straightforward multiplication would require $O(n^2)$ multiplications.

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- ▶ The above method is more than adequate, but there are many applications that require real-time dynamic computations (such as interactive rendering of 3D graphics, for example)
- ▶ and thus any reduction we can make in the complexity will be quite useful.

A Different Approach to Polynomial Multiplication

- **Representing a Polynomial.** The typical representation of $p(x)$ would be as a $1 \times n$ array $[a_{n-1}, a_{n-2}, \dots, a_1, a_0]$.

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- ▶ instead we could represent $\ell(x)$ by any two distinct points on $\ell(x)$.
- ▶ Another way of making the above point (no pun intended) is to remember that **two points uniquely determine a line.**"

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- ▶ **Example.** Suppose $p(x) = a_2x^2 + a_1x + a_0$ and that points $(3, 65)$, $(1, 41)$, and $(2, 57)$ are all on the curve determined by $p(x)$.

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- ▶ We have $67 = a_23^2 + a_13 + a_0$, $51 = a_21^2 + a_11 + a_0$, and $57 = a_22^2 + a_12 + a_0$, and thus we have three equations in three unknowns.

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```
In[25]:= Clear[matrixA]; matrixA = {{9, 3, 1}, {1, 1, 1}, {4, 2, 1}};
matrixA // MatrixForm

Out[26]//MatrixForm=

$$\begin{pmatrix} 9 & 3 & 1 \\ 1 & 1 & 1 \\ 4 & 2 & 1 \end{pmatrix}$$


In[27]:= Clear[vectorOfAnswers]; vectorOfAnswers = {65, 51, 57};
vectorOfAnswers // MatrixForm

Out[28]//MatrixForm=

$$\begin{pmatrix} 65 \\ 51 \\ 57 \end{pmatrix}$$


In[29]:= LinearSolve[matrixA, vectorOfAnswers]

Out[29]= {1, 3, 47}
```

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- Thus $p(x) = x^2 + 3x + 47$.

Another Example and the FFT Journey Continued

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- ▶ **Quick Check:**

```
In[34]:= p[x_] := x^2 + 3 x + 1
```

```
In[35]:= p[1] == 5
```

```
Out[35]= True
```

```
In[36]:= p[2] == 11
```

```
Out[36]= True
```

```
In[37]:= p[3] == 19
```

```
▶ Out[37]= True
```

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- ▶ Why?

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- ▶ But $p(x)q(x) = 2x^4 + 5x^3 + 2x^2 + 8x + 3$ and so is **not** uniquely determined by the three points above.

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- ▶ In particular, we must represent the above polynomial of degree four by five points.

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- ▶ And we'll add $(0,3)$ and $(-1,6)$ to the set of points representing $q(x)$.
- ▶ Thus the five points that we'll use to represent $p(x)q(x)$ are $(1,20)$, $(2,99)$, $(3,342)$, $(0,3)$, and $(-1,-6)$.

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- ▶ **Our insight thus far:** We need an efficient method both for converting from points on a curve representing a polynomial
- ▶ **and** of evaluating polynomials at those points.
- ▶ The ideas above are the foundations of the FFT: it accomplishes both tasks efficiently.

Restatement of the Problem

- **Problem (again).** How can we evaluate two polynomials $p(x)$ and $q(x)$ of degree $n - 1$, each at $2n - 1$ distinct x -values so that the coefficients of the product polynomial $p(x)q(x)$ can be determined?

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- ▶ In fact, by the same reasoning, our polynomials of degree $n - 1$ can be viewed as polynomials of degree $2n - 2$.
- ▶ **One more restatement.** Evaluate an arbitrary polynomial $p(x) = \sum_{i=1}^{n-1} a_i x^i$ of degree $n - 1$ at n distinct points.

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- ▶ The matrix equation that represents the evaluation is:

$$\begin{bmatrix} 1 & x_0 & x_0^2 & \cdots & x_0^{n-1} \\ 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ \vdots & & & \ddots & \\ 1 & x_{n-1} & x_{n-1}^2 & \cdots & x_{n-1}^{n-1} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_{n-1} \end{bmatrix} = \begin{bmatrix} p(x_0) \\ p(x_1) \\ \vdots \\ p(x_{n-1}) \end{bmatrix} \quad (*)$$

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- ▶ Then $x_0 = -x_{\frac{n}{2}}, x_1 = -x_{\frac{n}{2}+1}, \dots, x_{\frac{n}{2}-1} = -x_{n-1}$.
- ▶ We will use the above set of **functional equations** to reduce the problem to two subproblems.

Reduction to two subproblems

- ▶ Rewrite matrix equation (*) on the previous slide using the functional equations as shown next:

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$$\begin{aligned}
 & \text{► } (**) \begin{bmatrix} 1 & x_0 & x_0^2 & \cdots & x_0^{n-1} \\ 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{\frac{n}{2}-1} & x_{\frac{n}{2}-1}^2 & \cdots & x_{\frac{n}{2}-1}^{n-1} \\ 1 & -x_0 & (-x_0^2) & \cdots & (-x_0^{n-1}) \\ 1 & -x_1 & (-x_1^2) & \cdots & (-x_1^{n-1}) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & (-x_{\frac{n}{2}-1}) & (-x_{\frac{n}{2}-1}^2) & \cdots & (-x_{\frac{n}{2}-1}^{n-1}) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_{\frac{n}{2}-1} \\ a_{\frac{n}{2}} \\ a_{\frac{n}{2}+1} \\ \vdots \\ a_{n-1} \end{bmatrix} = \\
 & \begin{bmatrix} p(x_0) \\ p(x_1) \\ \vdots \\ p(x_{n-1}) \end{bmatrix}
 \end{aligned}$$

Similarities in the red and black parts of (**)

$$\begin{bmatrix} 1 & x_0 & x_0^2 & \cdots & x_0^{n-1} \\ 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ \vdots & & & \ddots & \\ 1 & x_{\frac{n}{2}-1} & x_{\frac{n}{2}-1}^2 & \cdots & x_{\frac{n}{2}-1}^{n-1} \\ 1 & -x_0 & (-x_0^2) & \cdots & (-x_0^{n-1}) \\ 1 & -x_1 & (-x_1^2) & \cdots & (-x_1^{n-1}) \\ \vdots & & & \ddots & \\ 1 & (-x_{\frac{n}{2}-1}) & (-x_{\frac{n}{2}-1}^2) & \cdots & (-x_{\frac{n}{2}-1}^{n-1}) \end{bmatrix}$$

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- **Observation 1.** The coefficients of the even powers of x are the same in both the red and the black submatrices.

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- **Observation 1.** The coefficients of the even powers of x are the same in both the red and the black submatrices.
- **Observation 2.** The coefficients of the odd powers of x in the red submatrix are the negatives of the corresponding odd powers of x in the black submatrix.

Red versus black; even powers versus odd powers of x

► **Notation.** Let $P(x) =$

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- ▶ The cost is $\frac{n}{2}$ additions, $\frac{n}{2}$ subtractions, and n multiplications.
- ▶ **So Far.** We now have two subproblems of size $\frac{n}{2}$ and $O(n)$ additional computations. Sound familiar?

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- ▶ **The Point.** We've significantly reduced the complexity from the naive $O(n^2)$ -time algorithm!!

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- ▶ Geometrically, the complex numbers $\omega^0, \omega^1, \omega^2, \dots, \omega^{n-1}$ are all vectors of length one spaced evenly around the unit circle centered at the origin of the complex plane.
- ▶ The vector ω^1 has polar coordinates $(1, \frac{2\pi}{n})$ and to move on to the next vector on the list, we simply add $\frac{2\pi}{n}$ to the current angle: ω^2 has polar coordinates $(1, \frac{4\pi}{n})$, and so on.

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- ▶ **Observation.** Every primitive n th root of unity has a multiplicative inverse since $\omega^k \omega^{n-k} = 1$.

Toolbox: Cancellation Property

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- ▶ Altogether, we have $1 + \omega^{\frac{n}{2}} = 0 \Rightarrow \omega^{\frac{n}{2}} = -1$. **QED**

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- ▶ That is, substitute ω^2 for ω and repeat the procedure.

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- ▶ evaluate an arbitrary polynomial of degree $n - 1$ at n points
- ▶ FFT accomplishes this in time $O(n \log n)$
- ▶ recover coefficients of product polynomial with **inverse FFT**¹ in time $O(n \log n)$.

¹<http://mathworld.wolfram.com/FourierTransform.html> 

Next Week

NP-Completeness