1. The Huber Loss [15 pts]

In statistics, we frequently encounter data sets containing outliers, which are bad data points arising from experimental error or abnormally high noise. Consider for example the following data set consisting of 15 pairs (x, y).

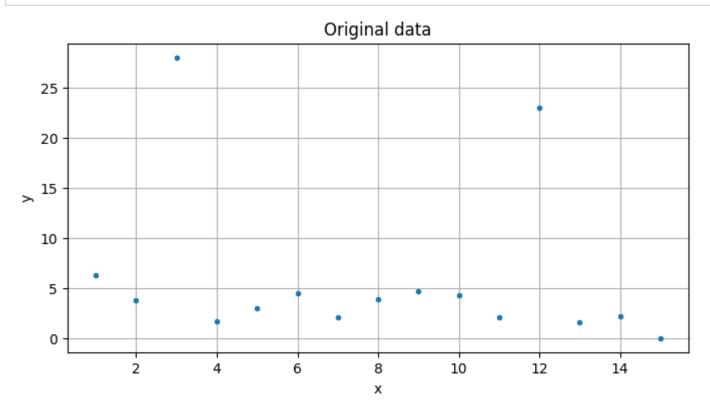
x	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
у	6.31	3.78	28.0	1.71	2.99	4.53	2.11	3.88	4.67	4.25	2.06	23.0	1.58	2.17	0.02

The y values corresponding to x=3 and x=12 are *outliers* because they are far outside the expected range of values for the experiment.

```
In [1]: x = [1:15;]
y = [6.31, 3.78, 28.0, 1.71, 2.99, 4.53, 2.11, 3.88, 4.67, 4.25, 2.06, 23.0, 1.58, 2.17, 0.02]

using PyPlot

figure(figsize=(8,4))
title("Original data")
plot(x, y, ".")
xlabel("x")
ylabel("x")
ylabel("y")
grid("on")
```



a) Compute the best linear fit to the data using an l_2 cost (least squares). In other words, we are looking for the a and b that minimize the expression:

$$\ell_2 \text{ cost:} \qquad \sum_{i=1}^{15} (y_i - ax_i - b)^2$$

Repeat the linear fit computation but this time exclude the outliers from your data set. On a single plot, show the data points and both linear fits. Explain the difference between both fits.

```
In [2]: # without removing outliers, using L_2
        # order of polynomial to use
         k = 1
        # fit using a function of the form f(x) = u1 \times k + u2 \times (k-1) + ... + uk \times u\{k+1\}
        n = length(x)
        A = zeros(n,k+1)
         for i = 1:n
             for j = 1:k+1
                 A[i,j] = x[i]^{(k+1-j)}
             end
         end
        using JuMP, Gurobi, Mosek
        m = Model(solver=MosekSolver(LOG=0))
         @variable(m, u[1:k+1])
        @objective(m, Min, sum((y - A*u).^2))
         status = solve(m)
         uopt = getvalue(u)
         println(status)
         println(uopt)
```

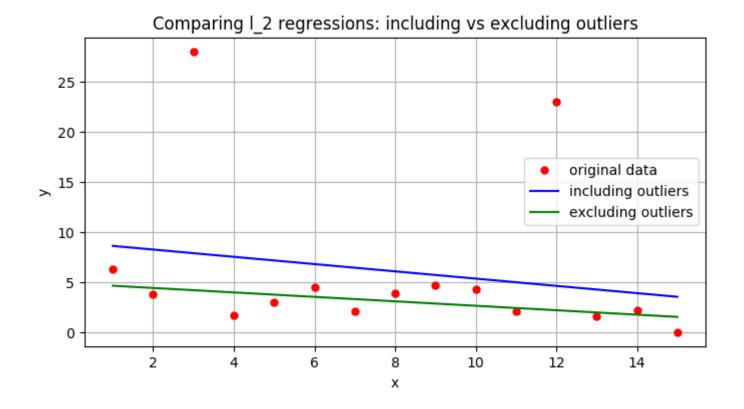
```
Optimal [-0.362214,8.96838]
```

```
In [3]: # with removed outliers using L 2
       x1 = [1:13;]
       y1 = [6.31, 3.78, 1.71, 2.99, 4.53, 2.11, 3.88, 4.67, 4.25, 2.06, 1.58, 2.17, 0.02]
       # order of polynomial to use
       k = 1
       n1 = length(x1)
       A1 = zeros(n1,k+1)
       for i = 1:n1
          for j = 1:k+1
              A1[i,j] = x1[i]^{(k+1-j)}
          end
       end
       using JuMP, Gurobi, Mosek
       m1 = Model(solver=MosekSolver(LOG=0))
       @variable(m1, u1[1:k+1])
       @objective(m1, Min, sum( (y1 - A1*u1).^2 ) )
       status1 = solve(m1)
       uopt1 = getvalue(u1)
       println(status1)
       println(uopt1)
```

Optimal

[-0.258791,4.89308]

```
In [4]: using PyPlot
        npts = 100
        xfine = linspace(x[1], x[end], npts)
        xfine1 = linspace(x1[1], x1[end], npts)
        ffine = ones(npts)
        ffine1 = ones(npts)
        for j = 1:k
            ffine = [ffine.*xfine ones(npts)]
            ffine1 = [ffine1.*xfine1 ones(npts)]
        end
        yfine = ffine * uopt
        yfine1 = ffine1 * uopt1
        figure(figsize=(8,4))
        title("Comparing l_2 regressions: including vs excluding outliers")
        plot( x, y, "r.", markersize=10)
        plot( xfine, yfine, "b-")
        plot( xfine, yfine1, "g-")
        legend(["original data", "including outliers", "excluding outliers"], loc="right")
        xlabel("x")
        ylabel("y")
        grid()
```



The outliers included in the first regression line essentially shifted the true regression line upwards. We notice a slight change of the gradient too, but for this data set, the effect could be considered negligible.

In the second regression line, we see that the line touches some of the plotted data, making it a btter line of best fit, because it minimizes the error in y at each x

b) It's not always practical to remove outliers from the data manually, so we'll investigate ways of automatically dealing with outliers by changing our cost function. Find the best linear fit again (including the outliers), but this time use the l_1 cost function:

$$\ell_1 \text{ cost:} \qquad \sum_{i=1}^{15} |y_i - ax_i - b|$$

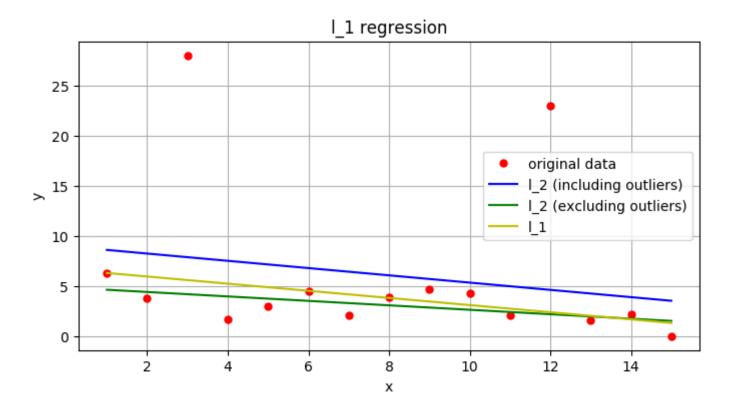
Include a plot containing the data and the best l_1 linear fit. Does the l_1 cost handle outliers better or worse than least squares? Explain why.

```
In [5]: using JuMP, Gurobi
        import JuMP: GenericAffExpr
         function abs_array{V<:GenericAffExpr}(v::Array{V})</pre>
         m = first(first(v).vars).m
         @variable(m, aux[1:length(v)] >= 0)
         @constraint(m, aux .>= v)
         @constraint(m, aux .>= -v)
         return aux
         end:
In [6]: # order of polynomial to use
        k = 1
        # fit using a function of the form f(x) = u1 x^k + u2 x^k + u2 x^k + \dots + uk x + uk + uk
        n2 = length(x)
        A2 = zeros(n2,k+1)
         for i = 1:n2
            for j = 1:k+1
                 A2[i,j] = x[i]^{(k+1-j)}
             end
         end
         using JuMP, Gurobi, Mosek
        m2 = Model(solver=MosekSolver(LOG=0))
        @variable(m2, u2[1:k+1])
         #@variable(m2, t)
        \#@constraint(m2, -t \le y - A2*u2 \le t)
        #@objective(m, Min, t)
        @objective(m2, Min, sum( abs_array(y - A2*u2) ) )
         status2 = solve(m2)
         uopt2 = getvalue(u2)
         println(status)
```

Optimal [-0.356,6.666]

println(uopt2)

```
In [7]: using PyPlot
        npts = 100
        xfine2 = linspace(x[1], x[end], npts)
        ffine2 = ones(npts)
        for j = 1:k
            ffine2 = [ffine2.*xfine2 ones(npts)]
        end
        yfine2 = ffine2 * uopt2
        figure(figsize=(8,4))
        title("l_1 regression")
        plot( x, y, "r.", markersize=10)
        plot( xfine, yfine, "b-")
        plot( xfine, yfine1, "g-")
        plot( xfine2, yfine2, "y-")
        legend(["original data", "l_2 (including outliers)", "l_2 (excluding outliers)", "l_1"], loc="right")
        xlabel("x")
        ylabel("y")
        grid()
```



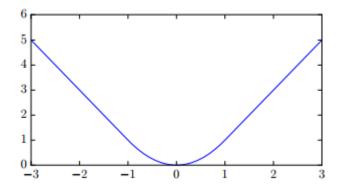
```
In [8]: println("error in m1 (l_2): ", getobjectivevalue(m1))
println("error in m2 (l_1): ", getobjectivevalue(m2))
```

error in m1 (l_2): 21.681303296703305 error in m2 (l_1): 58.03000000020826

- I_2 handles the line of best fit better, simply because the data isn't distorted *at all* by the outliers, whereas I_1 still faces some of the distortion due to them.
- c) Another approach is to use an l_2 penalty for points that are close to the line but an l_1 penalty for points that are far away. Specifically, we'll use something called the Huber loss, defined as:

$$\phi(x) = \begin{cases} x^2 & \text{if } -M \le x \le M \\ 2M|x| - M^2 & \text{otherwise} \end{cases}$$

Here, M is a parameter that determines where the quadratic function transitions to a linear function. The plot below shows what the Huber loss function looks like for M=1.



The formula above is simple, but not in a form that is useful for us. As it turns out, we can evaluate the Huber loss function at any point x by solving the following convex QP instead:

$$\phi(x) = \begin{cases} \underset{v,w}{\text{minimize}} & w^2 + 2Mv \\ \text{subject to:} & |x| \le w + v \\ & v \ge 0, \ w \le M \end{cases}$$

Verify this fact by solving the above QP (with M=1) for many values of x in the interval $-3 \le x \le 3$ and reproducing the plot above. Finally, find the best linear fit to our data using a Huber loss with M=1 and produce a plot showing your fit. The cost function is:

Huber loss:
$$\sum_{i=1}^{15} \phi(y_i - ax_i - b)$$

```
In [9]: using JuMP, PyPlot, Mosek
function getY(x, M)

m3 = Model(solver=MosekSolver(LOG=0))

@variable(m3, v >= 0)
    @variable(m3, w <= M)

@constraint(m3, abs(x) <= w + v)

@objective(m3, Min, w^2 + 2*M*v)

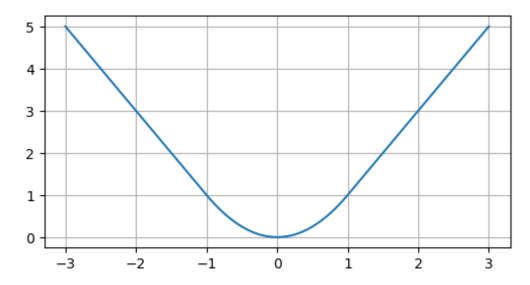
solve(m3)

return getobjectivevalue(m3)
end;</pre>
```

```
In [10]: M = 1
    x_h = linspace(-3, 3, 100)

y_h = zeros(length(x_h))
    for i = 1:length(x_h)
        y_h[i] = getY(x_h[i], M)
    end

figure(figsize=(6,3))
    plot(x_h,y_h)
    grid();
```



```
In [11]: # order of polynomial to use
        k = 1
        n4 = length(x)
        A4 = zeros(n4,k+1)
        for i = 1:n4
           for j = 1:k+1
               A4[i,j] = x[i]^{(k+1-j)}
           end
        end
        using JuMP, Gurobi, Mosek
        m4 = Model(solver=MosekSolver(LOG=0))
        M = 1
        @variable(m4, u4[1:k+1])
        @variable(m4, v[1:n4] >= 0)
        @variable(m4, w[1:n4] <= M)</pre>
        @constraint(m4, abs_array(y - A4*u4) .<= w + v)
        @objective(m4, Min, sum(w[i]^2 + 2*M*v[i] for i in 1:n4))
        status4 = solve(m4)
        uopt4 = getvalue(u4)
        println(status4)
        println(uopt4)
```

Optimal [-0.281108,5.73812]

```
In [13]: figure(figsize=(8,4))
    title("Final Regression Comparison")
    plot( x, y, "r.", markersize=10)
    plot( xfine, yfine, "b-")
    plot( xfine, yfine1, "g-")
    plot( xfine2, yfine2, "y-")
    plot( x, A*uopt4, "m-")
    legend(["original data", "l_2 (including outliers)", "l_2 (excluding outliers)", "l_1", "Huber"], loc="top")
    xlabel("x")
    ylabel("y")
    grid()
```

Final Regression Comparison

