



# 280823 - Mooring Systems

## Lesson 3 - Line Modelling - Finite Element Analysis

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- 1 Finite Element Analysis
  - Strong Form
  - Weak Form



## Conservation of Mass:

$$\frac{DM}{Dt} = \frac{d}{dt} \int \rho dV = 0$$

$$\frac{D\rho}{Dt} + \rho \nabla \cdot \dot{\mathbf{x}} = 0 \quad (1)$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \dot{\mathbf{x}}) = 0$$



## Material Derivative

$$\gamma(x(t), t) \quad (2)$$
$$\frac{D\gamma}{Dt} = \frac{\partial \gamma}{\partial t} + \dot{x} \nabla(\gamma)$$



Reynolds transport theorem

$$\frac{D}{Dt} \int_{\Omega} \gamma \, d\Omega = \int_{\Omega} \frac{\partial \gamma}{\partial t} \, d\Omega + \int_{\partial\Omega} (\dot{\mathbf{x}} \cdot \mathbf{n}) \gamma \, d\Gamma \quad (3)$$



## Divergence theorem

$$\int_{\Omega} \nabla \cdot \gamma \, d\Omega = \int_{\partial\Omega} (\gamma \cdot n) \, d\Gamma \quad (4)$$



## Conservation of Linear Momentum

$$\sum F = \sum_i m_i a_i = \sum F_{\text{body}} + \sum F_{\text{boundary}} = 0$$

$$\frac{DM\dot{x}}{Dt} = \frac{d}{dt} \int (\rho \dot{x}) dV = 0 \quad (5)$$

$$\rho \frac{D\dot{x}}{Dt} = \nabla \cdot \sigma + \rho b$$

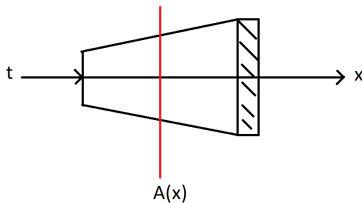


## Conservation of Angular Momentum

$$\sigma = \sigma^T \quad (6)$$



## Conservation of Linear Momentum



$$\sum F = t + R + b = 0 \quad (7)$$

Figure 1: Schematic of a rod.

## Conservation of Linear Momentum

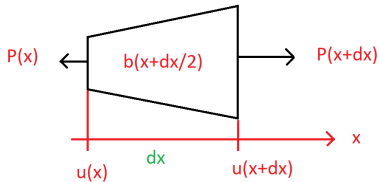


Figure 2: Differential element



## 1 Equilibrium of forces.

$$-f(x) + b(x + \frac{dx}{2})dx + f(x + dx) = 0$$

$$\frac{f(x + dx) - f(x)}{dx} + b(x + \frac{dx}{2}) = 0 \quad (8)$$

$$\lim(dx) \rightarrow 0$$

$$df(x) + b(x) = 0$$



## 2 Constitutive Law.

$$\sigma(x) = \frac{f(x)}{A(x)} \rightarrow f(x) = \sigma(x) \cdot A(x) \quad (9)$$



## 3 Notation of Strain and Stress-Strain relationship:

$$\varepsilon = \frac{l(f)}{l_0}$$

$$\varepsilon \approx \frac{u(x + dx) - u(x)}{dx}$$

$$\lim(dx) \rightarrow 0 \quad (10)$$

$$\varepsilon := \frac{du}{dx}$$

$$\sigma := E \cdot \varepsilon$$

Equilibrium Equation:

$$\frac{d}{dx}\left(AE\frac{du}{dt}\right) + b = 0 \quad \forall x \in \Omega := [0, l_0] \quad (11)$$

Boundary Conditions:

$$\begin{cases} \sigma(x=0) = E\frac{du}{dt}|_{x=0} = \frac{p(x=0)}{A(x=0)} = -t \\ u(x=l_0) = \bar{u} = 0 \end{cases} \quad (12)$$



# Strong Form



Finite  
Element  
Analysis

**Strong Form**  
Weak Form

$$\left\{ \begin{array}{ll} \frac{d}{dx} \left( AE \frac{du}{dt} \right) + b = 0 & , \forall x \in \Omega \\ E \frac{du}{dt} = -t & , \forall x \in \partial\Omega_N \\ u = \bar{u} & , \forall x \in \partial\Omega_D \end{array} \right. \quad (13)$$

# Weak Form

We constrain the function  $u(x)$  and a test function  $v(x)$  to reside in the space :

$$u, v \in \mathcal{L}_2 := \left[ \|f(x)\|_{\mathcal{L}_2} \equiv \left( \int_{\Omega} |f|^2 \right)^{\frac{1}{2}} < \infty \right] \quad (14)$$

Assume integrals  $\int_{\gamma}$  are respect  $d\gamma$ :

$$\begin{cases} \int_{\Omega} v \cdot (\nabla \cdot (AE \nabla(u)) + b) = 0 & , \forall v \in \Omega \\ v \cdot A(E \nabla(u) + t) = 0 & , \forall x \in \partial\Omega_N \\ v = 0 & , \forall v \in \partial\Omega_D \end{cases} \quad (15)$$





Expanding, using integral by parts and divergence theorem:

$$\left\{ \begin{array}{l} \int_{\Omega} v \cdot \nabla \cdot (AE \nabla(u)) + \int_{\Omega} v \cdot b = 0 \quad , \forall v \in \Omega \\ \\ - \int_{\Omega} \nabla(v) \cdot (AE \nabla(u)) \\ + \int_{\Omega} \nabla \cdot (v \cdot (AE \nabla(u))) + \int_{\Omega} v \cdot b = 0 \quad , \forall v \in \Omega \\ \\ - \int_{\Omega} \nabla(v) \cdot (AE \nabla(u)) \\ + \int_{\partial\Omega} (n \cdot (v \cdot (AE \nabla(u)))) + \int_{\Omega} v \cdot b = 0 \quad , \forall v \in \Omega \end{array} \right. \quad (16)$$



Expanding and using integral by parts:

$$\left\{ \begin{array}{l} - \int_{\Omega} \nabla(v) \cdot (AE \nabla(u)) \\ + \left[ (n \cdot (v \cdot (AE \nabla(u)))) \right] \Big|_{x=0}^{x=l_0} + \int_{\Omega} v \cdot b = 0 \end{array} \right. , \forall v \in \Omega$$
$$\left\{ \begin{array}{l} - \int_{\Omega} \nabla(v) \cdot (AE \nabla(u)) \\ - v \cdot (A\sigma)|_{x=0} + \int_{\Omega} v \cdot b = 0 \end{array} \right. , \forall v \in \Omega$$

(17)



Dirichlet (prescribed) boundary conditions on  $v(x = l_0) = 0$

$$-\int_{\Omega} \nabla(v) \cdot (AE \nabla(u)) = v \cdot t + \int_{\Omega} v \cdot b, \forall v \in \Omega \quad (18)$$



# THE END



Carlos Agelet and Javier Olivella.

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Authors, first edition, 2016.

URL: [https:](https://www.researchgate.net/publication/308650155_Continuum_Mechanics_for_Engineers_Theory_and_Problems_First_edition_September_2016)

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doi:10.13140/RG.2.2.25821.20961.