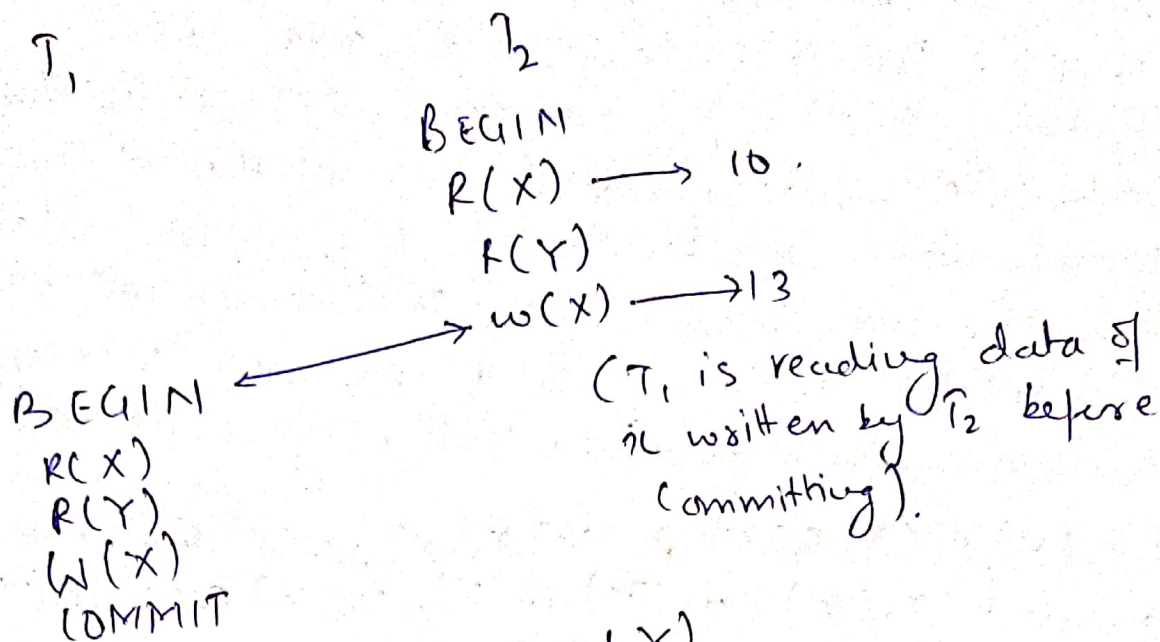


Q.1  
(i)  $T_1$  ?



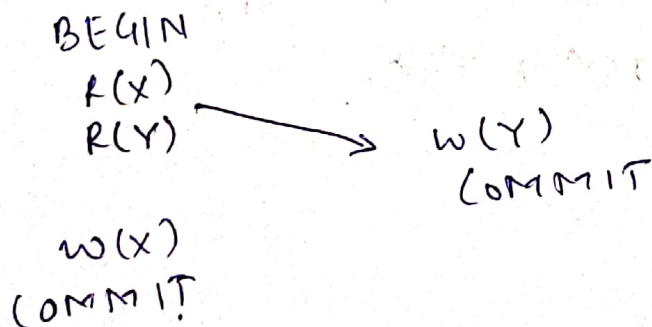
$w(Y)$   
ABORT.

$T_2$

```

    BEGIN
    R(X)
    R(Y)
    W(X)
  
```

(ii)  $T_1$

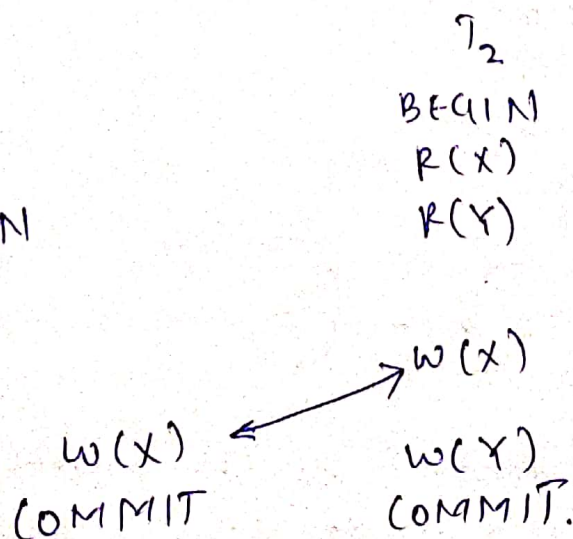


(iii)  $T_1$

$T_1$

```

    BEGIN
    R(X)
    R(Y)
  
```



iv) If we use strict 2PL the locking and unlocking will be done in 2 phases and all exclusive locks will have held till the transaction commits or aborts and shared locks can be released anytime during the second phase. If we apply ~~the~~ strict 2PL, only ~~stable~~ serializable schedule write be allowed and all the schedule listed above will be shared by S. and release of lock by U, and commit by C. So following will be execution of schedules where strict 2PL will ensure stability by not granting locks which may create conflicts.

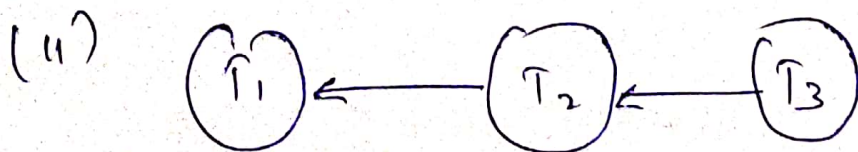
(i)  $S_2(X), R_2(X), S_2(Y), R_2(Y), X_2(X), W_2(X), S_1(X)$  - request not granted,  $X_2(Y), W_2(Y), U_2(X), U_2(Y), S_1(X), R_1(X), S_1(Y), R_1(Y), X_1(X), W_1(X), U_1(X), U_1(Y), C_1$

(ii)  $S_2(X), R_2(X), S_2(Y), R_2(Y), X_2(X), W_2(X), S_1(X)$  - request not granted,  $X_2(Y), W_2(Y), U_2(X), U_2(Y), C_2, S_1(X), R_1(X), S_1(Y), R_1(Y), X_1(X), W_1(X), U_1(X), U_1(Y), C_1$

(iii)  $S_2(X), R_2(X), R_2(Y), S_1(X)$  - request not granted,  $X_2(X), W_2(X), X_2(Y), W_2(Y), U_2(X), U_2(Y), C_2, S_1(X), R_1(X), S_1(Y), R_1(Y), X_1(X), W_1(X), U_1(X), U_1(Y), C_1$

U:2 — — — — ?

(i) -  $S(A)$  at  $t_2 : g$   
 $S(B)$  at  $t_3 : g$   
 $S(C)$  at  $t_4 : g$   
 $X(B)$  at  $t_5 : b$   
 $S(A)$  at  $t_6 : b$   
 $S(C)$  at  $t_1 : g$



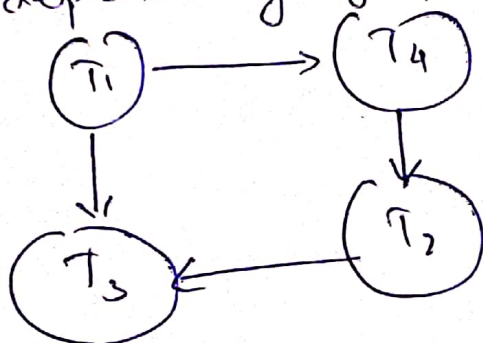
(iii) A deadlock does not exist because there is no cycle in the dependency graph.



Q.3

- (1)
- $X(A)$  at  $t_2 : g$
  - $S(C)$  at  $t_3 : g$
  - $S(A)$  at  $t_4 : b$
  - $X(D)$  at  $t_5 : g$
  - $X(C)$  at  $t_6 : b$
  - $X(B)$  at  $t_1 : b$
  - $S(D)$  at  $t_8 : b$

(II) A deadlock exists because there is a cycle in the dependency graph.



- (III)
- $X(A)$  at  $t_2 : g$
  - $S(C)$  at  $t_3 : g$
  - $S(A)$  at  $t_4 : a(T_1 \text{ aborts})$
  - $X(D)$  at  $t_5 : g$
  - $X(C)$  at  $t_6 : a(T_2 \text{ aborts})$

- $X(B)$  at  $t_7 : g$  (No locks held on B since  $t_1$  was aborted)
- $S(D)$  at  $t_8 : g$  (No locks held on D since  $t_2$  was aborted)

- (IV)
- $V(A)$  at  $t_2 : g$
  - $S(C)$  at  $t_3 : g$
  - $S(A)$  at  $t_4 : b$
  - $X(D)$  at  $t_5 : g$
  - $X(C)$  at  $t_6 : b$
  - $X(B)$  at  $t_7 : g$  ( $T_1$  Aborts)
  - $S(D)$  at  $t_8 : g$  ( $T_2$  Aborts)

Q.4

(a) (iii) ~~X(A) at t<sub>2</sub>: g~~

~~S(C) at t<sub>3</sub>: g~~

~~S(A) at t<sub>4</sub>: a (T<sub>1</sub> aborted)~~

~~X(B) at t<sub>5</sub>: g~~

~~X(C) at t<sub>6</sub>: a (T<sub>2</sub> aborted)~~

~~X(B) at t<sub>7</sub>: g (No lock held on B since T<sub>1</sub> was~~

~~S(B) at t<sub>8</sub>: g (No lock held on B since T<sub>2</sub> was aborted).~~

(iv) ~~X(A) at t<sub>2</sub>: g~~

~~S(C) at t<sub>3</sub>: g~~

~~S(A) at t<sub>4</sub>: b~~

~~X(B) at t<sub>5</sub>: g~~

~~X(C) at t<sub>6</sub>: b~~

~~X(B) at t<sub>7</sub>~~

Q.4

(a) B tree.

Insert 1 

1		
---	--	--

Insert 3 

1	3	
---	---	--

Insert 5 

1	3	5
---	---	---

Insert 7

```

graph TD
    Root["3 | | "] --> L["1 | | "]
    Root --> R["5 | 7 | "]
  
```

Insert 9

```

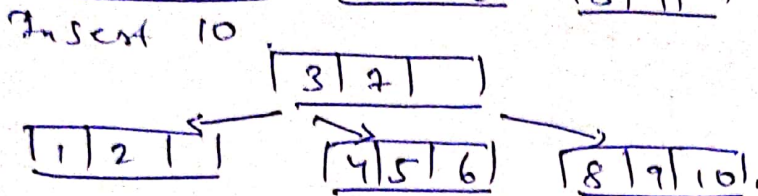
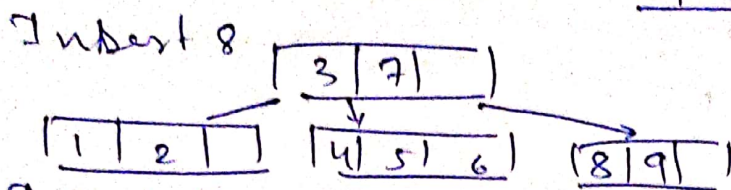
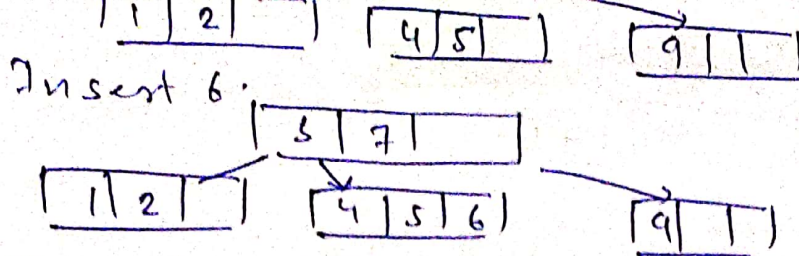
graph TD
    Root["3 | | "] --> L["1 | | "]
    Root --> R["5 | 7 | 9"]
  
```

Insert 2

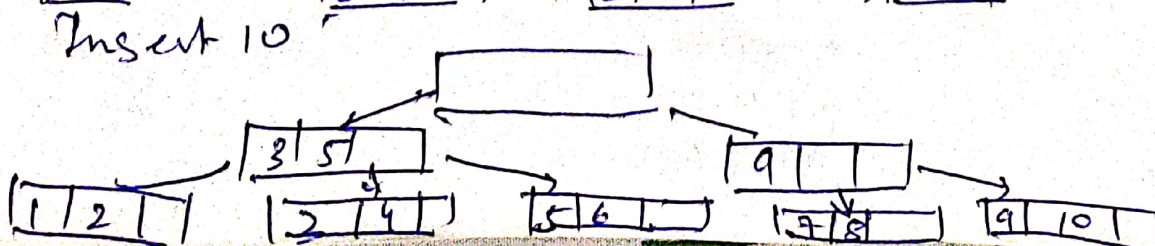
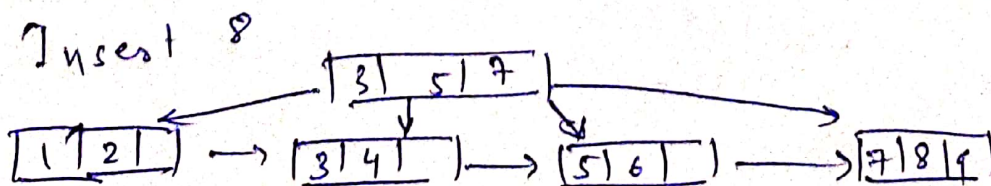
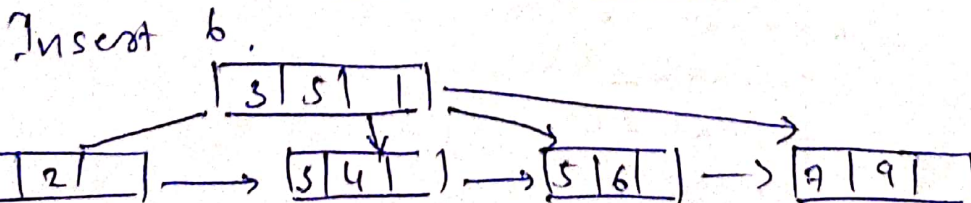
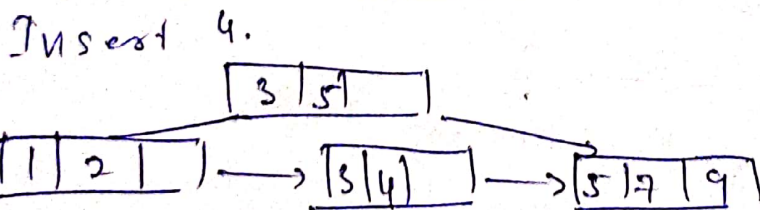
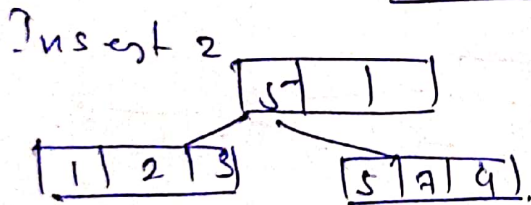
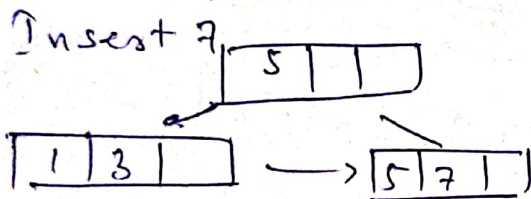
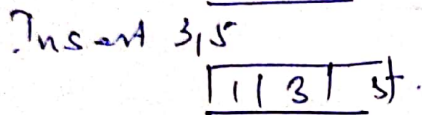
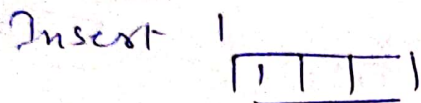
```

graph TD
    Root["3 | | "] --> L["1 | 2 | "]
    Root --> R["5 | 7 | 9"]
  
```





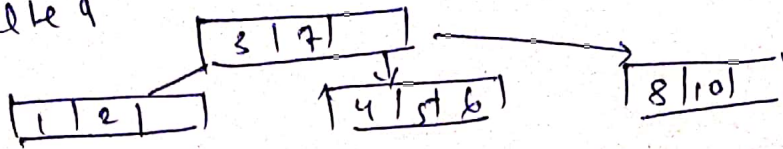
B+ tree.



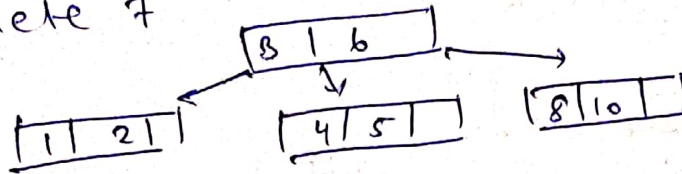
6) Delete 9, 7, 8

B tree

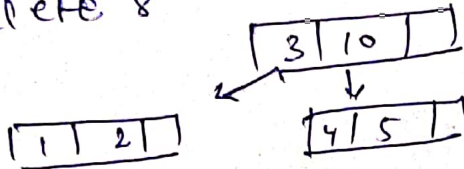
Delete 9



Delete 7

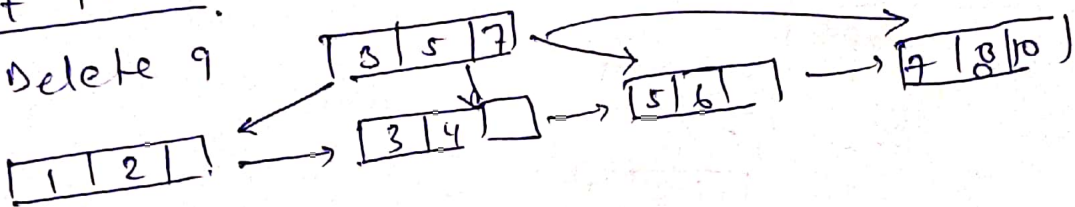


Delete 8

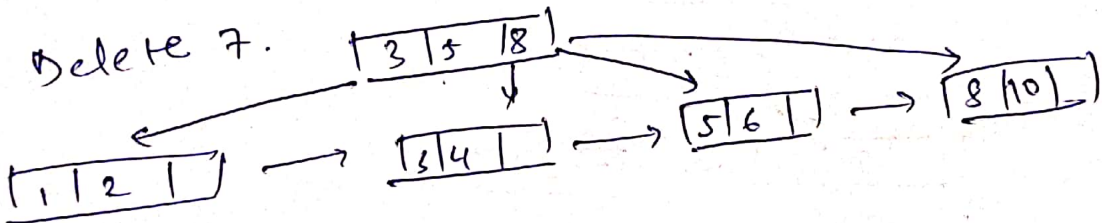


B+ tree

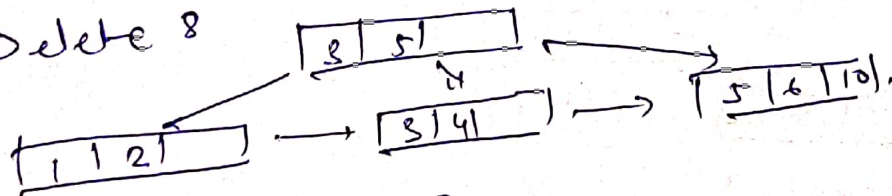
Delete 9



Delete 7



Delete 8

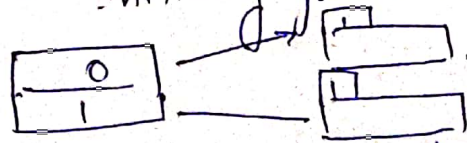


CO-5 (ii) — — — ?  
converting into binary form.

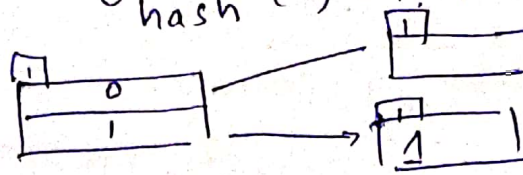
000001 → 1  
101000 → 40  
111101 → 61  
000010 → 2  
000100 → 4  
001111 → 15  
011110 → 30  
010001 → 9  
010100 → 20  
011010 → 26



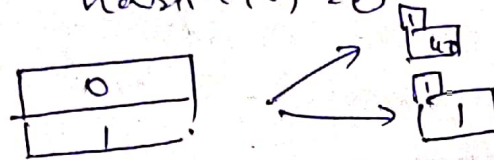
Initially global and local depth is 1.



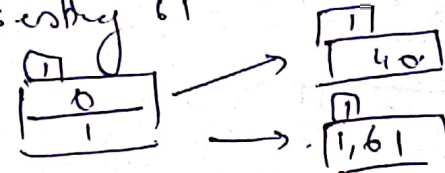
Inserting 1, global depth is 1  
 $\text{hash}(1) = 1$



Inserting 40  
 $\text{hash}(40) = 0$



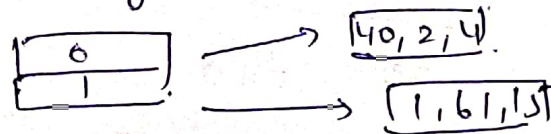
Inserting 61



Inserting 2,  $\text{hash}(2) = 0$

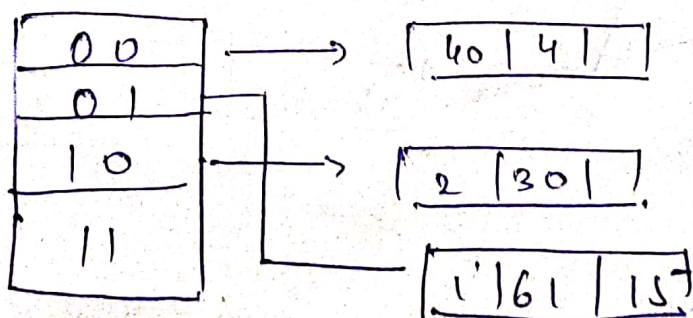


Inserting 15  $\text{hash}(15) = 1$

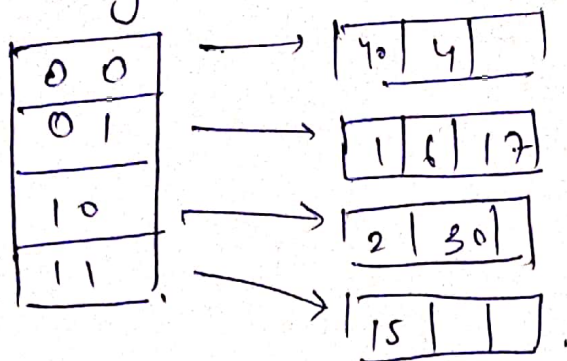


Inserting 30,  $\text{hash}(30) = 0 \Rightarrow$  overflow!  
 Directly expansion. (Rehashing) all the numbers inserted upto now occurs.

global depth =  $(1 + 1) = 2$ .  
 $\text{hash}(1) = 01$ ,  $\text{hash}(61) = 01$   
 $\text{hash}(40) = 00$ ,  $\text{hash}(2) = 10$ ,  $\text{hash}(4) = 00$   
 $\text{hash}(15) = 11$ ,  $\text{hash}(30) = 10$

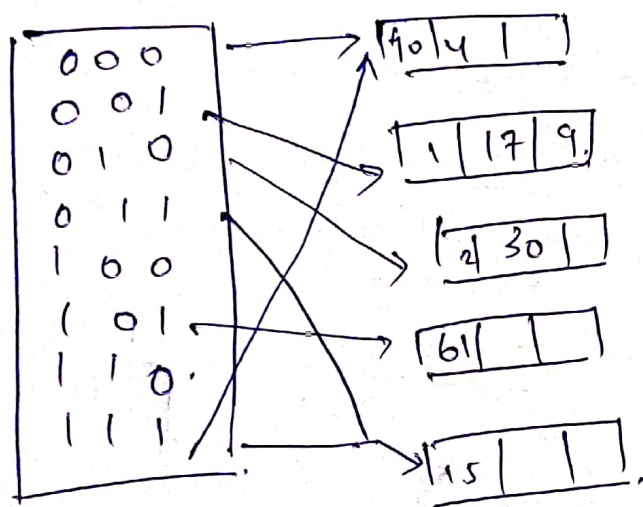


Inserting 17  $\text{hash}(17) = 01$  OVERFLOW!

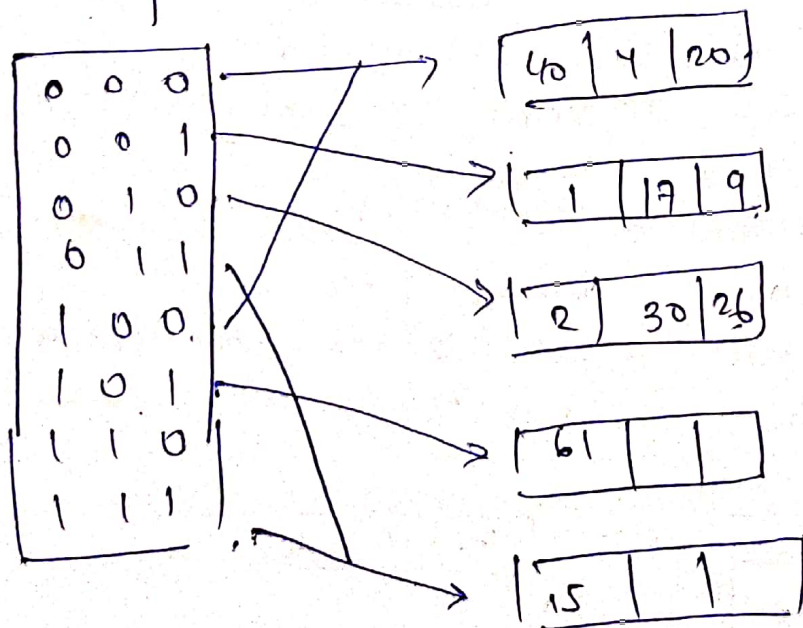


Inserting 9  $\text{hash}(9) = 01$  OVERFLOW.  
 local Depth = global depth.

⇒ directory expansion & rehashing  
 $\text{hash}(1) = 001, \text{hash}(6) = 101, \text{hash}(17) = 001, \text{hash}(9) = 001$



Inserting 26  $\text{hash}(26) = 010$ .





Q.8. — — — ?

(a) In DBMS, Hashing a technique to directly search the location and desired data disk without using index structure. Data is stored in form of data block whose address is generated by applying a hash function in memory location where the records are stored known as data block or data bucket.

(b) 1) chaining  
It is a method in which additional field with which data is introduced.

2) linear probing  
In this, collision can be solved by placing the second record linearly down, whenever empty place is found.

3) quadratic probing  
$$\text{hash}(\text{key}, i) = (\text{hash}(k) + i^2) \text{ mod } m$$

(c) STATIC HASHING

A HASHING technique that allow users to perform lookups on a finalized dictionary (all objects in dictionary are final and not changing).

Resultant data bucket address is always the same.

less efficient.

DYNAMIC HASHING

A hashing technique in which data buckets are added and removed dynamically and on demand.

Data buckets change depending on the record.

more efficient.