Computing derivatives based on surface curvatures

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At a corner the following quantities are known:

- First derivative (S_u)
- First cross-derivative (S_v)
- Normal vector $(n = (S_u \times S_v)/||S_u \times S_v||)$
- Principal directions $(e_{\text{max}}, e_{\text{min}})$
- Principal curvatures $(\kappa_{\text{max}}, \kappa_{\text{min}})$

Based on the above information, we need to compute S_{uu} , S_{vv} and S_{uv} .

Let ϑ_u (ϑ_v) be the oriented angles between S_u (S_v) and e_{\max} . Then, according to Euler's theorem

$$\kappa_u = \kappa_{\text{max}} \cos^2 \vartheta_u + \kappa_{\text{min}} \sin^2 \vartheta_u,
\kappa_v = \kappa_{\text{max}} \cos^2 \vartheta_v + \kappa_{\text{min}} \sin^2 \vartheta_v, \tag{1}$$

where κ_u and κ_v are the normal curvatures in the u and v directions. We also know that

$$L = \kappa_u E, \qquad N = \kappa_v G, \tag{2}$$

or, equivalently,

$$S_{uu}n = \kappa_u ||S_u||^2,$$
 $S_{vv}n = \kappa_v ||S_v||^2,$ (3)

which constrains the "height" of the second derivatives. Similarly, from

$$M^2 = LN - K(EG - F^2),$$
 (4)

or, equivalently,

$$S_{uv}n = \pm \sqrt{(S_{uu}n)(S_{vv}n) - \kappa_{\max}\kappa_{\min}||S_u \times S_v||^2},$$
 (5)

we can determine the height of the twist vector; its position in that plane can be assigned using the parallelogram rule or some other heuristics.

Computing oriented angles

First express both vectors in their common plane, so $v_1=(x_1,y_1)$ and $v_2=(x_2,y_2)$. Then the angle can be computed by

$$\vartheta = \operatorname{atan2}(x_1 y_2 - y_1 x_2, x_1 x_2 + y_1 y_2).$$

But note that we do not really need oriented angles, as all (co)sines are squared.