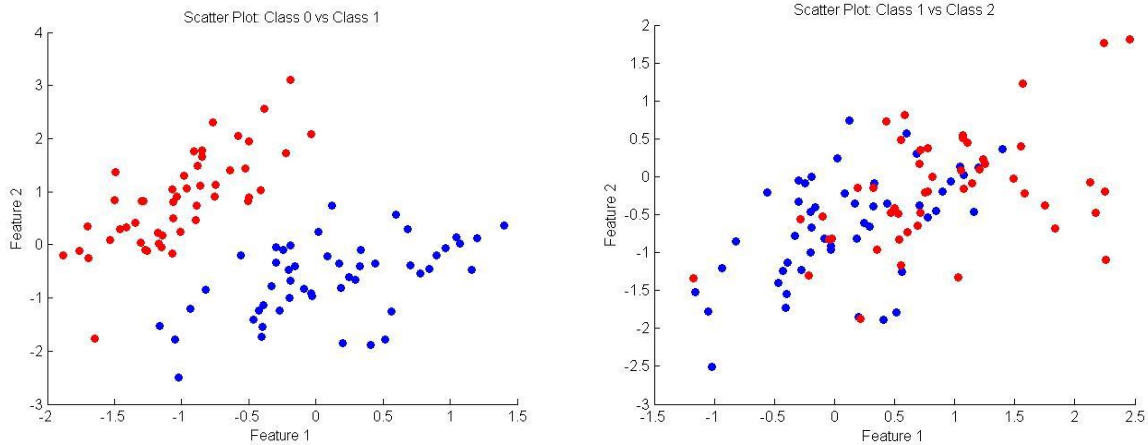


Problem 1

PART A: Show two classes in a scatter plot and verify that one is linearly separable while the other is not.



According to the plots above, “Class 0 vs Class 1” is linearly separable while “Class 1 vs Class 2” is not.

Code:

```
%Class 0 vs 1
figure (1)
XA_1 = X(Y==1, :);
XA_0 = X(Y==0, :);
hold on;
scatter(XA_1(:,1),XA_1(:,2),'b','filled')
scatter(XA_0(:,1),XA_0(:,2),'r','filled')
title('Scatter Plot: Class 0 vs Class 1')
xlabel('Feature 1')
ylabel('Feature 2')
hold off;

%Class 1 vs 2
figure (2)
XB_1 = X(Y==1, :);
XB_2 = X(Y==2, :);
hold on;
scatter(XB_1(:,1),XB_1(:,2),'b','filled')
scatter(XB_2(:,1),XB_2(:,2),'r','filled')
title('Scatter Plot: Class 1 vs Class 2')
xlabel('Feature 1')
ylabel('Feature 2')
hold off;
```

PART B: Write the function @logisticClassify2/plot2DLinear.m so that it plots the two classes of data in different colors, along with the decision boundary (a line). Boundary is defined as $\text{sign}(0.5 + 1x_1 - 0.25x_2)$.

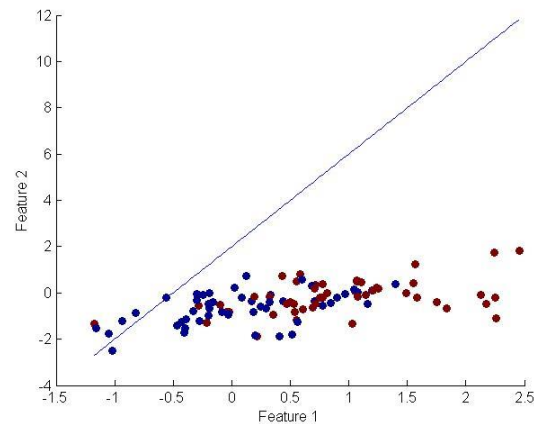
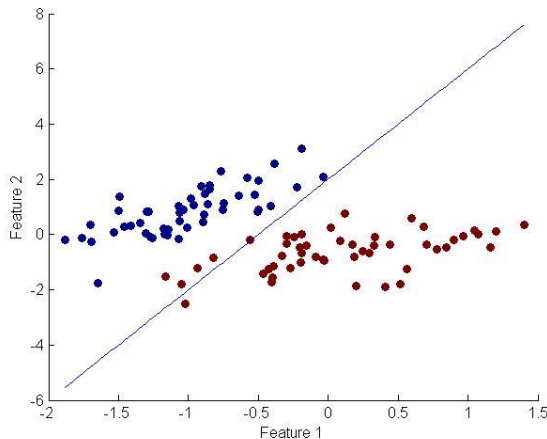
For testing purposes, the following code is written to set up the testing.

```

learner = logisticClassify2(); % Create "blank" learner
learner = setClasses(learner, unique(YA)); % Define class labels using YA or YB
wts = [0.5 1 -0.25]; % [theta0 theta1 theta2];
learner = setWeights(learner,wts); % Set the learner's parameters

plot2DLinear(learner, XA, YA)
plot2DLinear(learner, XB, YB)

```



The image on the left is the output plot when data set A is passed into “plot2DLinear” function while the image on the right shows the output plot when data set B is passed into the function.

Code:

```

%% TODO: Fill in the rest of this function...
figure
hold on;
scatter(X(:,1),X(:,2), [], Y, 'filled');
xlabel('Feature 1')
ylabel('Feature 2')

% Let's plot the decision boundary
% Want to plot wts(0) + wts(1)*x(1) + wts(2)*x(2) = 0
% wts(2)*x(2) = -(wts(0) + wts(1)*x(1))
% x(2) = (-1/wts(2))*(wts(0) + wts(1)*x(1))

x1 = min(X):0.025:max(X);
x2 = (-1/obj.wts(3))*(obj.wts(1) + obj.wts(2)*x1);
plot(x1,x2)
hold off;

```

PART C: Complete the predict.m function to make predictions for your linear classifier. Verify that the function works by computing & reporting the error rate of the classifier in the previous part on both data sets A and B. (The error rate on data set A should be around 0.0505.)

```

Code: % STEP (1) make predictions based on the sign of wts(1) + wts(2)*x(:,1)
+ ...
predict_sign = sign(obj.wts(1) + obj.wts(2)*Xte(:,1) + obj.wts(3)*Xte(:,2));
% STEP (2) convert predictions to saved classes: Yte = obj.classes( [1 or 2] );

```

```
Y_positive = find(predict_sign == 1);  
Y_negative = find(predict_sign == -1);  
  
[n,d]=size(Xte);  
Yte = zeros (n,1);  
  
Yte(Y_positive) = obj.classes(2);  
Yte(Y_negative) = obj.classes(1);  
  
Yte;
```

“PlotClassify2D” processing Data Set A and Data Set B:

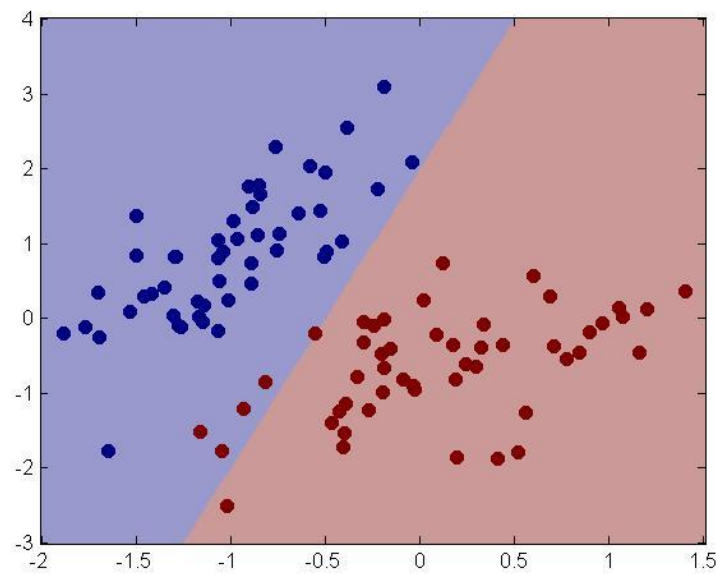


Figure 1 PlotClassify2D(XA) Data Set A

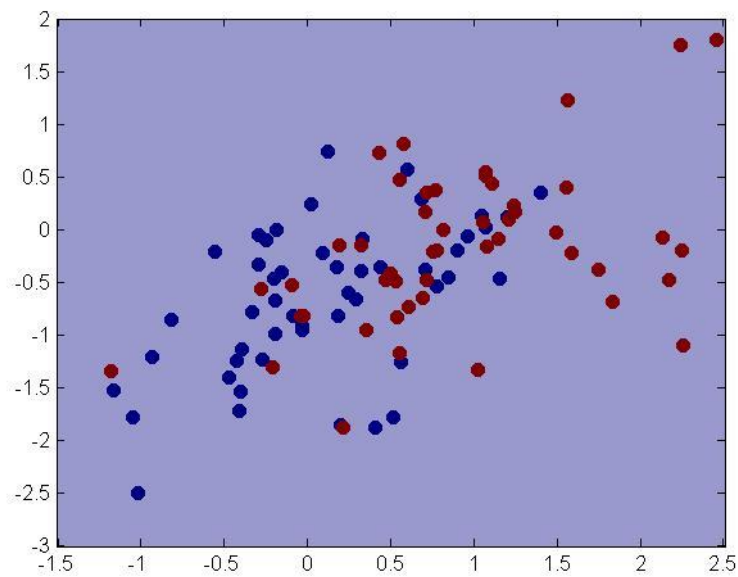


Figure 2 PlotClassify2D(XB) Data Set B

Error Calculation:

error_A =

0.0505

error_B =

0.5455

The calculated error of data set A matches with the error given in the problem; therefore, I believe the predict.m function is working properly.

PART D:

Linear Response of Perceptron: $z = \theta x^{(j)}$.

$\sigma \Rightarrow$ Standard Logistic function.

$$\sigma(z) = (1 + \exp(-z))^{-1}$$

\hookrightarrow Regularized Logistic Negative log likelihood loss for a single data point j

$$\Rightarrow J_j(\theta) = -y^{(j)} \log \sigma(\theta x^{(j)T}) - (1 - y^{(j)}) \log(1 - \sigma(\theta x^{(j)T})) + \frac{\alpha}{2} \sum_i \theta_i^2$$

$y^{(j)} \Rightarrow$ either 0 or 1.

\rightarrow Derive the gradient of the regularized negative log likelihood J_j for logistic regression.

$$\frac{\partial J_j(\theta)}{\partial \theta} = \frac{\partial}{\partial \theta} \left[-y^{(j)} \log \sigma(\theta x^{(j)T}) - (1 - y^{(j)}) \log(1 - \sigma(\theta x^{(j)T})) \right] + \alpha \frac{\partial}{\partial \theta} \left[\sum_i \theta_i^2 \right]$$

$$= -y^{(j)} \left[\frac{1}{\sigma(\theta x^{(j)T})} \frac{\partial \sigma(\theta x^{(j)T})}{\partial \theta} \right] x^{(j)} - (1 - y^{(j)}) \left[\frac{1}{1 - \sigma(\theta x^{(j)T})} \frac{\partial (1 - \sigma(\theta x^{(j)T}))}{\partial \theta} \right] x^{(j)} + 2\alpha \theta$$

$$\text{Let } \theta = [\theta_0, \theta_1, \theta_2, \dots, \theta_k] \quad x^{(j)T} = \begin{bmatrix} x_0^{(j)} \\ x_1^{(j)} \\ \vdots \end{bmatrix}$$

$$\theta \cdot x^{(j)T} = \theta_0 x_0^{(j)} + \theta_1 x_1^{(j)} + \dots$$

$$\begin{aligned}
 & \frac{\partial}{\partial \theta} [\zeta(\underline{\theta} \cdot \underline{x}^{(j)T})] \\
 & \zeta(\underline{\theta} \cdot \underline{x}^{(j)T}) = \frac{1}{1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T})} \\
 & \frac{\partial}{\partial \theta} (1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T})) \\
 & = -(1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}))^{-2} \cdot \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}) \cdot \frac{\partial}{\partial \theta} (-\underline{\theta} \cdot \underline{x}^{(j)T}) \\
 & = (1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}))^{-2} \cdot \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}) \cdot \underline{x}^{(j)} \\
 & \frac{\partial}{\partial \theta} [(1 - \zeta(\underline{\theta} \cdot \underline{x}^{(j)T}))] = \frac{\partial}{\partial \theta} - \frac{\partial}{\partial \theta} [\zeta(\underline{\theta} \cdot \underline{x}^{(j)T})] \\
 & = - \left[(1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}))^{-2} \cdot \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}) \cdot \underline{x}^{(j)} \right] \\
 \Rightarrow \frac{\partial J_j(\theta)}{\partial \theta} &= -y^{(j)} (1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T})) \left[(1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}))^{-2} \cdot \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}) \cdot \underline{x}^{(j)} \right] \\
 &+ (1 - y^{(j)}) \frac{1}{1 - \frac{1}{1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T})}} \left[(1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}))^{-2} \cdot \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}) \cdot \underline{x}^{(j)} \right] \\
 &+ 2\alpha \theta \quad \hookrightarrow \frac{1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T})}{1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T}) - 1} \\
 \Rightarrow \frac{\partial J_j(\theta)}{\partial \theta} &= -y^{(j)} \frac{\exp(-\underline{\theta} \cdot \underline{x}^{(j)T})}{1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T})} \underline{x}^{(j)} + (1 - y^{(j)}) \frac{1}{1 + \exp(-\underline{\theta} \cdot \underline{x}^{(j)T})} \underline{x}^{(j)} \\
 &+ 2\alpha \theta
 \end{aligned}$$

PART E:

```

% Training loop (SGD):
iter=1; Jsur=zeros(1,stopIter); J01=zeros(1,stopIter); done=0;
while (~done)
    step = stepsize/iter; % update step-size and evaluate current
    loss values
    %% TODO: compute surrogate (neg log likelihood) loss
    for i=1:n
        z = obj.wts*X1(i,:)';

```

```

        sigma = 1/(1+exp(-z));
        Jsurr(iter) = Jsurr(iter)-Y(i,:)*log(sigma)-(1-Y(i,:))*(log(1-sigma))+
reg*(sum((obj.wts).^2));    %%% TODO: compute surrogate (neg log likelihood)
    loss
    end
    J01(iter) = err(obj,X,Yin);

for j=1:n,
    % Compute linear responses and activation for data point j
    %%% TODO ^^^
        z = obj.wts*X1(j,:);
        sigma = 1/(1+exp(-z));
        % Compute gradient:
        %%% TODO ^^^
        grad = -Y(j,:)*(1-sigma)*X1(j,:)+(1-Y(j,:))*sigma*X1(j,:)+ 2*reg*obj.wts
        %grad = -Y(j,:)*sigma*exp(-z)*X1(j,:)+(1-Y(j,:))*sigma*X1(j,:)+
2*reg*obj.wts;
        obj.wts = obj.wts - step * grad;    % take a step down the gradient
    end;

done = false;

%% TODO: Check for stopping conditions
norm(obj.wts-wtsold)
    if (stopIter == iter || norm(obj.wts-wtsold)<stopTol)
        done = true;
    end;

    wtsold = obj.wts;
    iter = iter + 1;
end;

```

PART F:

I run the train function with Data Set A, train function allows it to update the weight for better classification. Numbers shows the gradient function value at a specific data point and iteration and the changes of the gradient function. The train function stop when the changes of the weight function drop less than 0.02.

Testing Code:

```

% % Part E & F: Train Function
% Please comment or uncomment either one for data set A and data set B
train(learner, XA, YA, 'stopiter', 200, 'stoptol', 0.02);
%train(learner, XB, YB, 'stopiter', 200, 'stoptol', 0.02);

```

Result:

grad =

0.0661 -0.0328 0.0590

ans =

0.0196

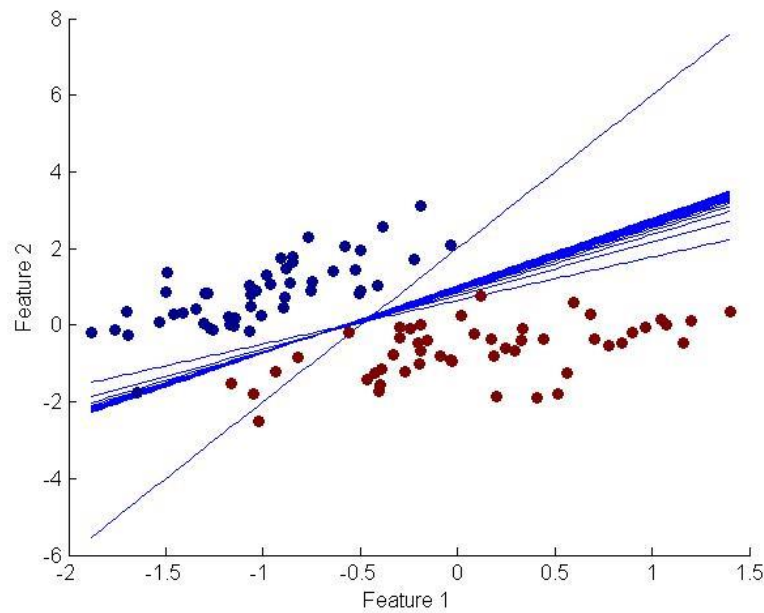


Figure 3 TrainFucntion (XA)

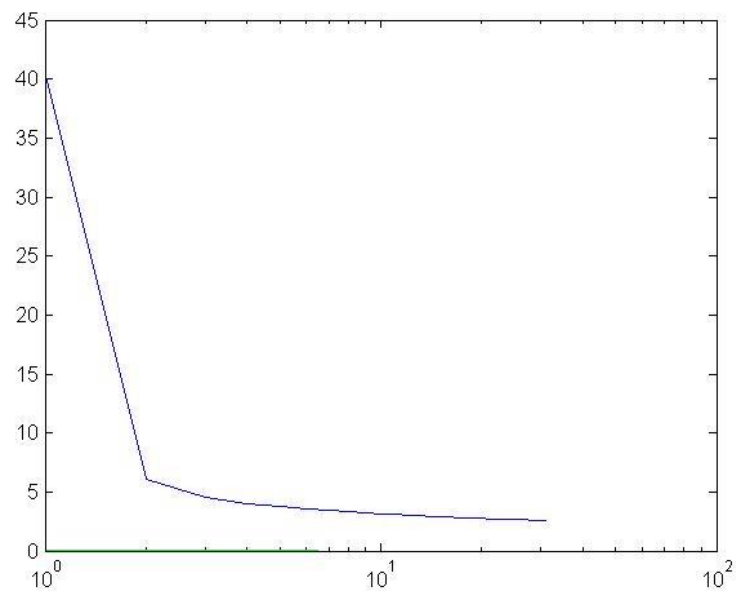


Figure 4 TrainFunction_Change of Gradient Function (XA)

For Data Set B, it is not a linearly separable data set. Therefore, the train function can not calculate a classifier that separate Data Set B no matter how small does “`norm(obj.wts-wtsold)`” (i.e. Change of weight function). In this testing set up, the stoptol is set to 0.001 in the test case with 200 iteration.

Test Code:

```
train(learner, XB, YB, 'stopiter', 200, 'stoptol', 0.001);
```

Result:

grad =

-0.5066 -0.2383 0.2389

ans =

9.8418e-04

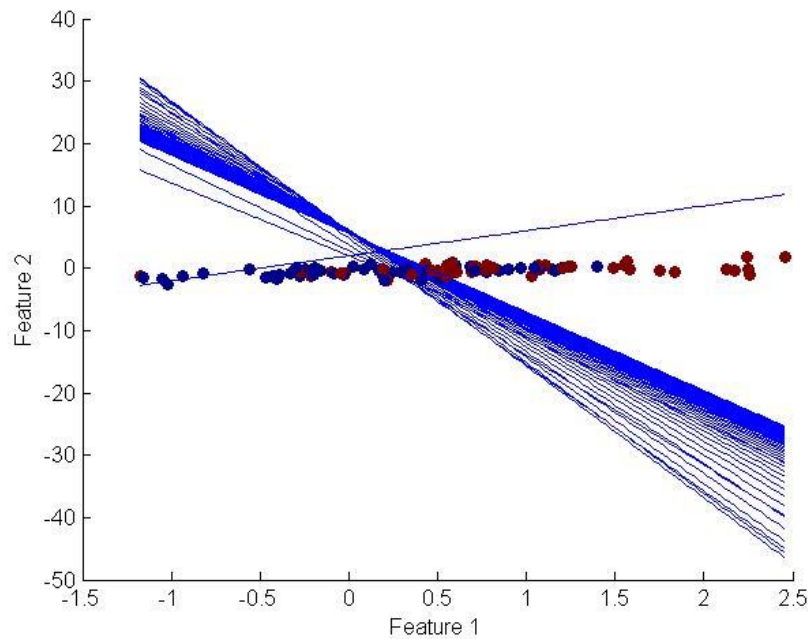


Figure 5 TestFunction(XB)

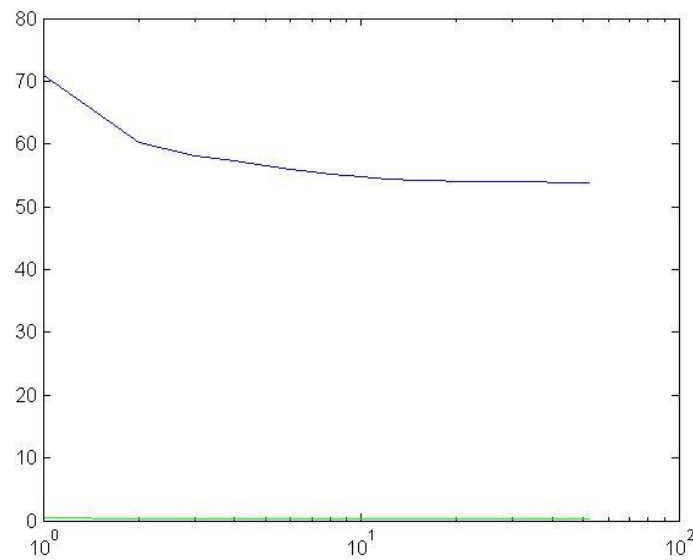


Figure 6 TestFunction Error (XB)

Problem 2

Determine which of the four set of Data points can be shattered by each learner. Explanation / Justification and use the result to guess the VC dimension of the classifier

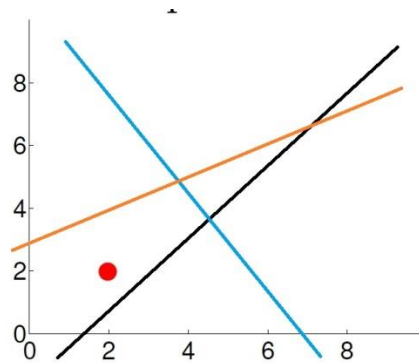


Figure 7: Data Set 1

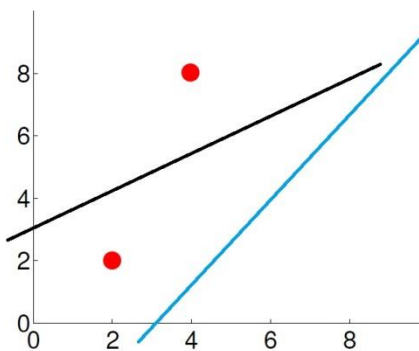


Figure 8: Data Set 2

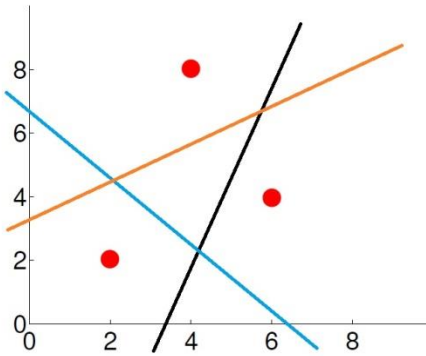


Figure 9: Data Set 3

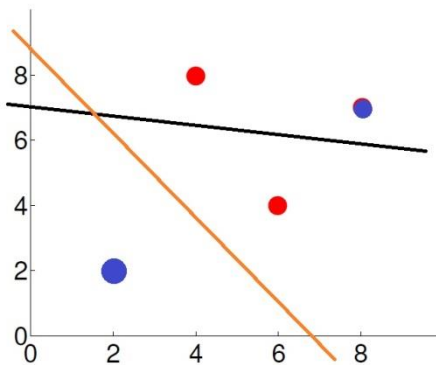


Figure 10: Data Set 4

As shown above, Data set 1 to 3 can be shattered but not Data Set 4.

a) $T(a+bx_1)$

Function: $a+bx_1$ is a linear function; therefore, it can shatter Data set 1 to 3 as shown above. In other words, VC dim = 3 as it can at most shatter 3 data points.

b) $T((x_1-a)^2 + (x_2-b)^2 + c)$

Function: $(x_1-a)^2 + (x_2-b)^2 + c$ is a circular function center at point (a,b) . The VC dim for this function is 3. It is because if the circles locates at $(4,8)$ with increasing radius, it cannot includes at $(4,8)$ and $(2,2)$ while not including $(4,6)$.

c) $T((a*b)x_1 + (c/a)x_2)$

Function: $(a*b)x_1 + (c/a)x_2$ is also a linear function; therefore, the VC dim is the same as the function in part A. VC dim = 3