

Quadruped Robot			
S. no	Body Part	Count	
1	body_d	1	
2	body_u	1	
3	coxa_l	2	
4	coxa_r	2	
5	tibia_r_update	2	
6	tibia_l_update	2	
7	femur_1	4	
8	tip	4	
9	s_hold	8	
	Total parts	26	
Contacts:			
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