Mass properties of Frame Configuration: Default Coordinate system: -- default --

The mass properties were copied from an assembly when the assembly was saved as a part.

Jupdate the mass properties, please open the assembly and resave it as a part.

Density = 0.00 grams per cubic millimeter

Mass = 3075.49 grams

Volume = 3075486.83 cubic millimeters

Surface area = 442276.61 square millimeters

Center of mass: (millimeters)

X = -58.51Y = 65.1Z = 23.44

Principal axes of inertia and principal moments of inertia: (grams * square millimeters) Tken at the center of mass.

> Ix = (0.97, 0.23, 0.00)Px = 148042543.34ly = (-0.23, 0.97, 0.00)Py = 161893502.92Iz = (0.00, 0.00, 1.00)Pz = 303840992.05

Moments of inertia: (grams * square millimeters)

Aken at the center of mass and aligned with the output coordinate system.

Lxx = 148770475.66 Lxy = 3090740.32 Lxz = -301.10Lyy = 16**1**65570.60 Lyz = 319.86 Lyx = 3090740.32Lzx = -301.10Lzy = 319.86Lzz = 303840992.05

Moments of inertia: (grams * square millimeters)

Tken at the output coordinate system.

Ixx = 163497044.99 Ixy = -8624775.04 Ixz = -4217254.89lyx = -8624775.04 lyy = 173382353.36 lyz = 4693089.90Izx = -4217254.89 Izy = 4693089.90 Izz = 327406055.80