

Even Abstract objects can be manipulated as vectors even if we may not conceive them to be. They should satisfy 8 funda properties. Symbol: $|a\rangle$

1. ✓ Addition b/w 2 objects ~~should~~^{should} exist
Notion of $|a\rangle + |b\rangle$ shd yield a vector
2. $\alpha |a\rangle \Rightarrow$ Multiplication with complex no.
~~should~~ yield a vector.
3. \exists a null element $|0\rangle$ such that $|a\rangle + |0\rangle = |a\rangle$
4. $\forall |a\rangle \in S$, \exists an inverse vector $|a'\rangle$, such [reverse]
that $|a\rangle + |a'\rangle = |0\rangle$
5. $|a\rangle + |b\rangle = |b\rangle + |a\rangle$
6. $1|a\rangle = |a\rangle$
7. $\alpha(\beta|a\rangle) = (\alpha\beta)|a\rangle$
8. $(\alpha + \beta)|a\rangle = \alpha|a\rangle + \beta|a\rangle$
 $\alpha(\alpha|a\rangle + |b\rangle) = \alpha|a\rangle + \alpha|b\rangle$

If a set S satisfies the above properties it forms a vector field.

If $\alpha, \beta \in R$: Real vector field.

else : complex vector field.

Eg: Set of n -dimensional column complex matrices: They form a vector field.

Set of $n \times n$ complex matrices: Yes.

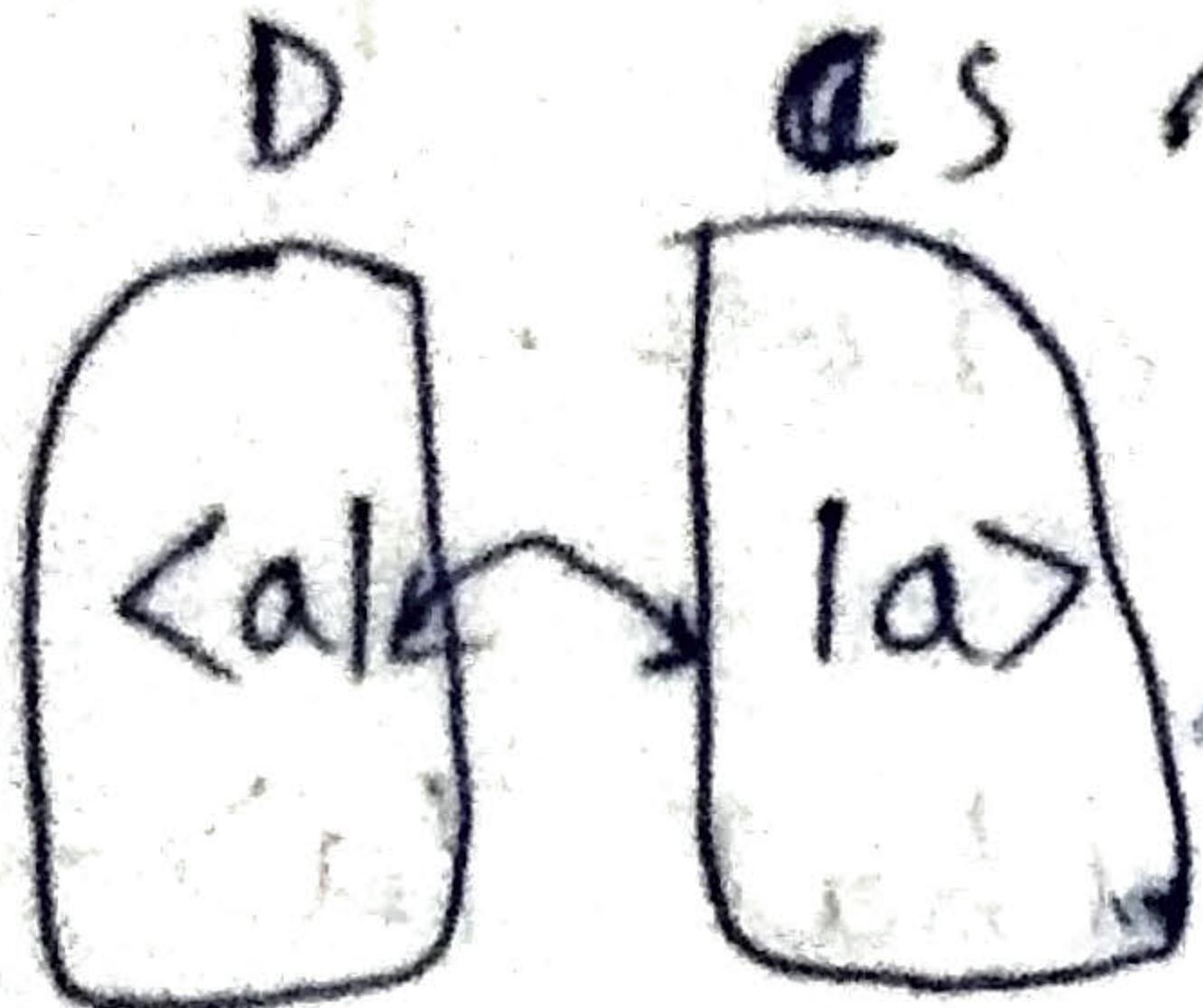
Note: $\langle 1|a \rangle = r e^{i\theta} |a\rangle$

Basically, in the prev. example they form a set of Matrices space in the vector space.

Polynomials: form a vector space.

set of all functions form a vector space.

Ket, Bra Sets



Duals
of each other

One - One mapping.

for every element in D,

there is ~~an image~~ ^{a copy} in S.

For scalar product:

$$1. \quad \langle b|a \rangle = \langle a|b \rangle^*$$

$$2. \quad \langle c|(\alpha|a\rangle + \beta|b\rangle) \rangle = \alpha \langle c|a\rangle + \beta \langle c|b\rangle$$

$$3. \quad \langle a|a \rangle \geq 0 \quad \text{equality appears only if } |a\rangle = 0.$$

vector spaces

Any operation D, S which satisfies the above conditions is called ~~an~~ ^{are eligible for} some under scalar product.

E.g.: for column Matrix, Generalise (Real Matrix) dot product.

$D \rightarrow$ Column matrices $S: P$ Transpose of D .

Take product.

Eg: For complex column matrix:

S:

D: Take ~~conjugate~~ Transpose of S and then take conjugate.

$$\text{if } |z\rangle_S = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \xrightarrow{\text{X}} |z\rangle_D = (a_1^*, a_2^*, a_3^*)^T$$

$$\text{If: } \langle y|x\rangle = \alpha \langle y|a\rangle + \beta \langle y|b\rangle$$

$$\text{then } \langle x|y\rangle = \alpha^* \langle a|y\rangle + \beta^* \langle b|y\rangle$$

Note: $\vec{A} = a_1, a_2, a_3$ $\vec{B} = b_1, b_2, b_3$

$\vec{A} \cdot \vec{B}$ need not only be

$$a_1 b_1 + a_2 b_2 + a_3 b_3.$$

Linear Combination

Linear Independence:

$$\sum_{i=1}^n \alpha_i |a_i\rangle = 0 \quad \text{then } \alpha_1 = \alpha_2 = \dots = \alpha_n = 0$$

$$\Rightarrow \alpha_i = 0 \forall i$$

Given 2 vectors, one can't be expressed as a sum of others multiplied by a constant.

Lec-7

In the complex vector space formed by complex nos; $\langle z_1 | z_2 \rangle = z_1^* z_2$

\rightarrow ~~conjugate~~ conjugate

Cauchy-Schwarz theorem

$$|A \cdot B| \geq |A \cdot B| \quad \xrightarrow{z \in \mathbb{R}}$$

$$\text{Let } |c\rangle = |a\rangle - z\langle b|a\rangle |b\rangle$$

$$|\langle c|c\rangle| = |\langle a| - z\langle ab\rangle \langle b|b\rangle|$$

$$|\langle c|c\rangle| \geq 0$$

$$\Rightarrow z^2 \langle b|a\rangle \langle a|b\rangle \langle b|b\rangle$$

$$- 2z \langle b|a\rangle \langle a|b\rangle + \frac{\langle a|a\rangle \langle b|b\rangle}{\langle a|b\rangle \langle b|a\rangle} - 1 \geq 0$$

$$(1 - z \langle b|b\rangle)^2 + \left(\frac{\langle a|a\rangle \langle b|b\rangle}{\langle a|b\rangle \langle b|a\rangle} - 1 \right) \geq 0$$

$$\text{If } z = \frac{1}{\langle b|b\rangle},$$

$$\langle a|a\rangle \langle b|b\rangle \geq \langle a|b\rangle \langle b|a\rangle$$

Generally when we speak about vectors we generally talk about distance. Is there a notion of dist in this abstract notation?
Yes; metric.

$$1) p(a, b) = p(b, a)$$

$$2) p(a, b) = 0 \Rightarrow a, b \text{ are same vectors, } |a\rangle = |b\rangle$$

$$3. p(a, b) + p(b, c) \geq p(a, c) \text{ Triangle Inequality}$$

$$\text{Good Standard: } \Delta_{AB}^2 = |\vec{A} - \vec{B}|^2$$

$$e(a, b)^2 = (\langle a| - \langle b|)(|a\rangle - |b\rangle)$$

In n -dimensional vector space, there are only n vectors which are independent. You can't find one more vector which is independent of all the others.

The n -vectors form a basis;

given a basis and another vector, we can express it in terms of all others with unique constants:

Orthonormal basis: Vectors such that

$$\langle e_i | \cdot e_j \rangle = \delta_{ij}$$

example: $\hat{i}, \hat{j}, \hat{k}$

Given n -dimensions there will always be an orthonormal basis;

Procedure for finding the Orthonormal basis:
 (Gram Schmidt)

① Given $\{|\alpha_1\rangle, |\alpha_2\rangle, \dots, |\alpha_n\rangle\}$

$$|e_1\rangle = \frac{|\alpha_1\rangle}{\sqrt{\langle \alpha_1 | \alpha_1 \rangle}}$$

② Take 2nd vector; if it is \perp to e_1 , return.

$$\text{else } |e_2\rangle = \frac{|\alpha_2\rangle - \langle e_1 | \alpha_2 \rangle |e_1\rangle}{\sqrt{\text{magnitude of numerator}}}$$

$$\text{③ } |e_3\rangle = (|\alpha_3\rangle - \langle e_1 | \alpha_3 \rangle |e_1\rangle - \langle e_2 | \alpha_3 \rangle |e_2\rangle)$$

Questions

1. 3D position space.

$$\vec{A} = \hat{i} + 2\hat{j}$$

$$\vec{B} = -\hat{j} + \hat{k}$$

$$\vec{C} = \hat{i} - \hat{j} + \hat{k}$$

$$a\hat{i} + 2a\hat{j} + b\hat{k} + ai - bj + ck = 0$$

$$a=0 \quad b=0 \quad c=0$$

$$\text{Independent.} \quad D = 2(\hat{j} - \hat{k})$$

$$2ai + (2a-2b)\hat{j} + (b+c)\hat{k} = 2\hat{j} - 2\hat{k}$$

$$a=0 \quad b=-1 \quad c=-1$$

2. Gram Schmidt of A, B, C

$$\hat{a}_1 = \frac{1}{\sqrt{5}} (\hat{i} + 2\hat{j})$$

($\cancel{\hat{j} + \hat{k}}$) ~~Age~~

$$-\hat{j} + \hat{k} = \left(\frac{-2}{\sqrt{5}} \right) \left[\frac{1}{\sqrt{5}} (\hat{i} + 2\hat{j}) \right] + \hat{a}_2$$

$$-\frac{2}{5}\hat{i} - \frac{4}{5}\hat{j} + \hat{a}_2$$

$$\hat{a}_2 = \frac{2}{5}\hat{i} + -\frac{1}{5}\hat{j} + \hat{k}$$

$$\hat{a}_2 \Rightarrow \cancel{\frac{1}{\sqrt{5}}} (2\hat{i} - \hat{j} + \hat{k})$$

$$\hat{a}_2 = \frac{\vec{B} - (a \cdot b) \hat{a}_1}{1} \quad \frac{2}{5}\hat{i} - \frac{1}{5}\hat{j} + \hat{k}$$

$$(-\hat{j} + \hat{k}) + \left(\frac{-2}{\sqrt{5}} \right) \left(\frac{1}{\sqrt{5}} \right) (\hat{i} + 2\hat{j})$$

$$\hat{e}_3 = (\lambda - j + k) - \frac{1}{\sqrt{5}} (-1) \left(\frac{1}{\sqrt{5}} (\bar{\epsilon} + 2\hat{j}) \right)$$

$$= \frac{1}{\sqrt{5}} \frac{1}{\sqrt{5}} (2\lambda - j + 5k)$$

$$\lambda - j + k + \frac{i}{5} + \frac{2}{5}\hat{j} - \frac{8}{15}\bar{\epsilon} + \frac{4}{15}\hat{k} - \frac{20}{15}\frac{4}{3}k$$

$$\Rightarrow \frac{2\lambda - j + 5k}{\frac{1}{3}\sqrt{6}} = \frac{1}{\sqrt{5}} (2\lambda - j - k)$$

3. Show that the fall. + Matrices are linearly
ind:

$$M_1 = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad M_2 = \begin{bmatrix} 0 & 1-5i \\ 1+5i & 0 \end{bmatrix} \quad M_3 = \begin{bmatrix} 6 & 2-4i \\ 2+4i & -6 \end{bmatrix}$$

$$M_4 = \begin{bmatrix} 7 & 9 \\ 0 & 7 \end{bmatrix}$$

$$6c + 7d = 0$$

$$4a + b - 5bi + 2\bar{c} - 4\bar{d}i = 0$$

$$4a + b + 5bi + 2\bar{c} + 4\bar{d}i = 0$$

$$-6c + 7d = 0$$

$$c = 0, d = 0$$

$$\rightarrow 4a + b = 0 \quad b = 0 \quad a = 0$$

Scalar product of a Matrix:

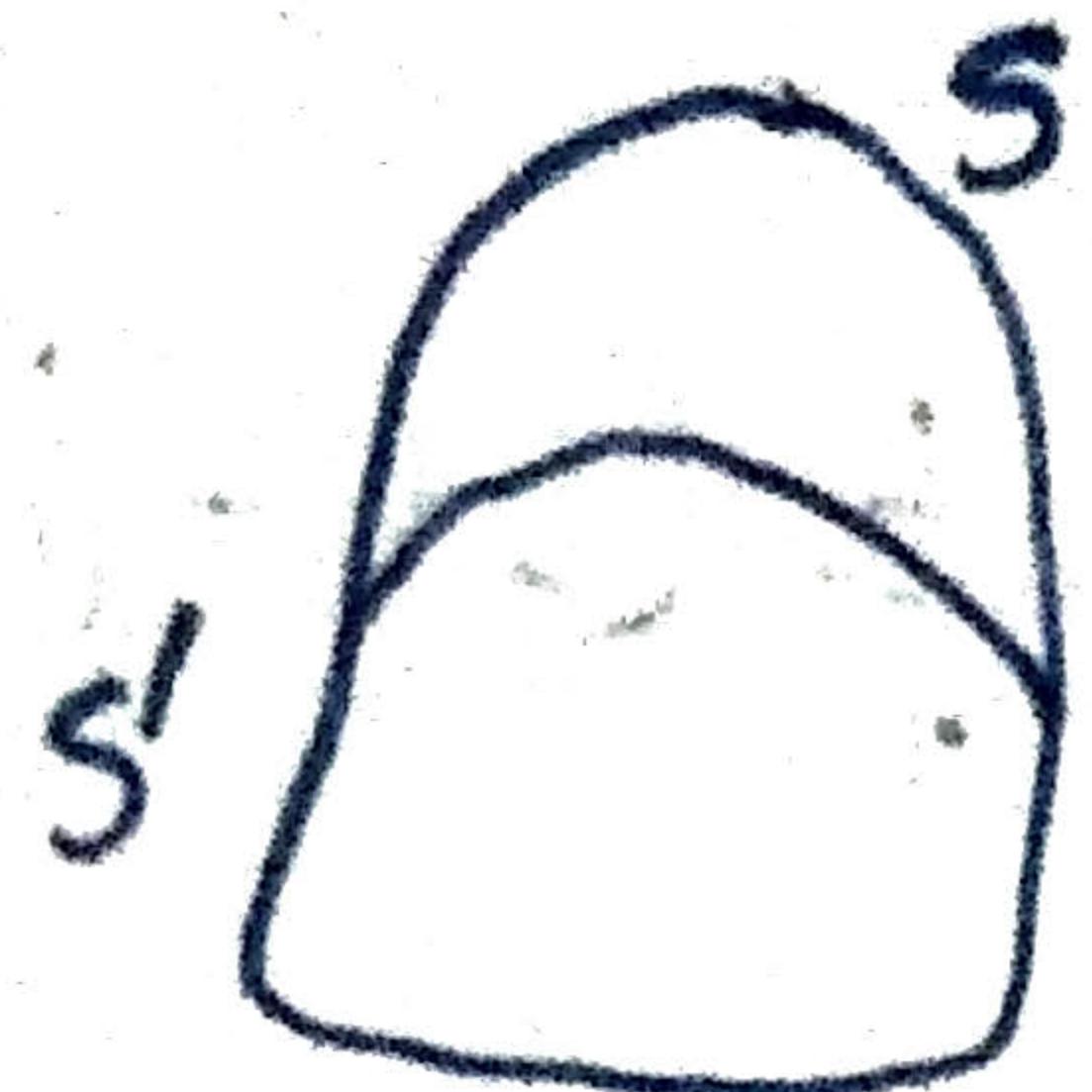
$$\langle M_i | M_j \rangle = \frac{1}{2} \text{Trace}(M_i^+ M_j)$$

$$M_i^+ = M_i \quad \langle M_i | M_i \rangle = \frac{1}{2} \text{Trace}$$

$$\hat{e}_i = \frac{M_i}{\|M_i\|} = \left(\begin{array}{cc} 0 & 2 \\ 4 & 0 \end{array} \right) \cdot \frac{1}{\sqrt{16}}$$

Subset of a Vector Space: [Subspace]

It should be a subset of the original space and this set by itself should form a vector space.



$$(1) |x\rangle, |y\rangle \in S', \quad |x\rangle + |y\rangle \in S'$$

$$(2) |x\rangle \in S', \quad \langle |x\rangle \in S'.$$

If S is the vector spaces and $S_1, S_2 \dots S_n$ are the subspaces of S .

$$\text{if: } (1) S_i \cap S_j = \{0\}$$

$$(2) |x\rangle = \underbrace{|x_1\rangle + |x_2\rangle + \dots + |x_n\rangle}_{\text{can be unique way expressed}}$$

can be unique way
expressed

They form the direct sum:

$$S = S_1 \oplus S_2 \oplus S_3 \oplus \dots \oplus S_n$$

$$\text{dimension}(S) = \sum_{i=1}^n \dim(S_i)$$

If S_1, S_2 form subspaces does $S_1 \cup S_2$ form a subspace? No

$$\text{eg: } S_1: \vec{x} \quad S_2: \vec{y}$$

$S_1 \cup S_2$: Vectors along \vec{x}, \vec{y} not $\vec{x} + \vec{y}$; Closure is not satisfied

If at all they form a subspace, one of the following must be true:

$$S_1 \subseteq S_2 \text{ or } S_2 \subseteq S_1.$$

→ polynomials of degree $\leq n$ form a vector space.

Even polynomials: Subspace

All the odd degree polynomials form an orthogonal space to even polynomials.

Linear Operators

If A is an operator:

$A|z\rangle = |y\rangle$, where $|z\rangle, |y\rangle$ are vectors in S.

example: $S_3 \rightarrow P_2(x)$ $A = \frac{d}{dx}$
↓
Polynomials with degree ≤ 2 .

Properties:

1. $A = B$ iff $A|x\rangle = B|x\rangle \forall |x\rangle$
2. $(A + B)|x\rangle = A|x\rangle + B|x\rangle$
3. $(A \cdot B)|x\rangle = A(B|x\rangle)$ | generally $AB \neq BA$
4. $A^m|x\rangle = \underbrace{A \cdot A \cdots}_{m \text{ times}}|x\rangle$

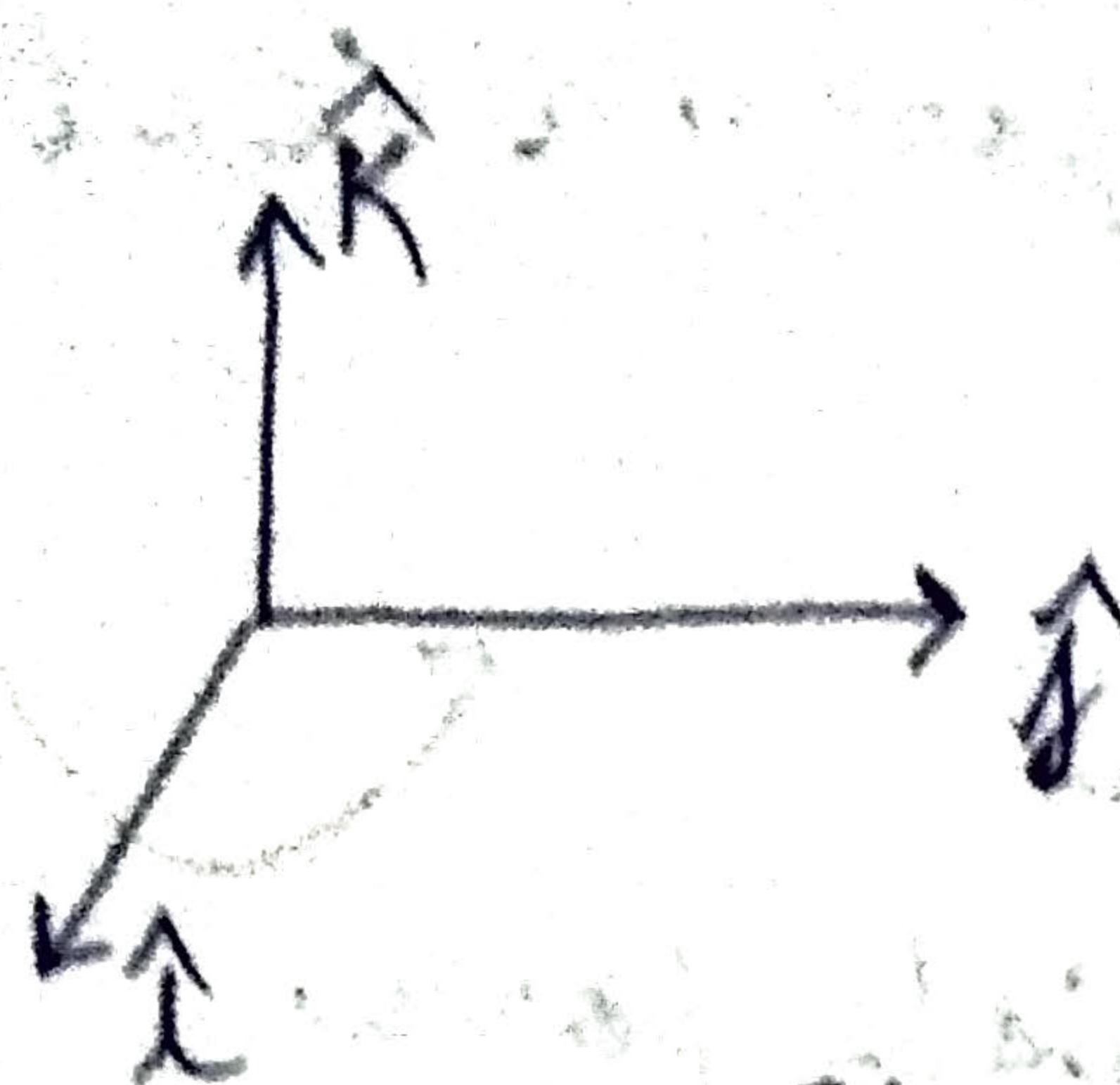
ex $P_2(x)$ $A = \frac{d}{dx}$ $B = x \frac{d^2}{dx^2}$

$$AB = \frac{d^2}{dx^2} + x \frac{d^3}{dx^3} P(x)$$

$$BA = x \frac{d^3}{dx^3} P(x).$$

$$A^3 P_2(x) = 0.$$

Note: This doesn't mean A^3 is null.
 $P_2(x)$ is null.



R_1 = rotation by $\pi/2$ about z-axis

R_2 = rotation by $\pi/2$ by x axis.

Clockwise : +ve

$$R_1 \hat{z} = \hat{y}$$

$$R_1 \hat{y} = -\hat{x}$$

$$\boxed{R_1 \hat{x} = \hat{z}}$$

$$R_2 \hat{z} = \hat{x}$$

$$R_2 \hat{x} = \hat{y}$$

$$R_2 \hat{y} = -\hat{z}$$

Invariant

$$R_1 \cdot R_2 \Rightarrow \begin{array}{l} \hat{z} \rightarrow \hat{y} \\ \hat{y} \rightarrow \hat{z} \\ \hat{x} \rightarrow -\hat{x} \end{array}$$

$$R_2 \cdot R_1 \Rightarrow \begin{array}{l} \hat{x} \rightarrow \hat{z} \\ \hat{y} \rightarrow -\hat{x} \\ \hat{z} \rightarrow -\hat{y} \end{array}$$

Reverse
order

Invariant:
 $\hat{x} + \hat{y} + \hat{z}$

Inverse of an operator:

(Right Inverse, Left Inverse).

$$A A^{-1} |x\rangle = \mathbb{I} |x\rangle = |x\rangle$$

$$A^{-1} A |x\rangle = \mathbb{I} |x\rangle = |x\rangle$$

$$A \cdot A^{-1} = I$$

$$A^{-1} A = I$$

The left inverse can't exist
in the full ~~property~~^{case}:

$$\begin{cases} A|e_n\rangle = |e_{n-1}\rangle \\ A|e_1\rangle = 0 \end{cases}$$

Proof Let there be A_l^{-1} (left right inverse).

$$A_l^{-1} A|e_n\rangle = |e_n\rangle$$

$$\text{Put } n=1.$$

$A_l^{-1}(0)$ which is not equal
to e_{n-1} .

In the full case, right inverse
doesn't exist:

$$A_r^{-1}|e_n\rangle = |e_{n+1}\rangle$$

$$A \cdot A_r^{-1}|e_n\rangle = |e_n\rangle.$$

If both left, right inverse exists, they are
same and unique.

If left inverse is unique and it exists, right inverse
exists and is same as right inverse.

In the dual space:

if in normal $A|x\rangle = |y\rangle$
space

dual space: $\langle x|A^+ = \langle y|$.

We know $\langle z|x\rangle = \langle x|z\rangle^*$

then $\langle z|A^+|x\rangle = \langle x|A|z\rangle^*$

Any Operator can be expressed as.

$$A = |y\rangle\langle x|$$

suppose $A|w\rangle = |z\rangle$

$$|y\rangle\langle x|w\rangle = |z\rangle$$

Complex Number

vector along $|y\rangle$ times
the complex no.

then $A^+ = \cancel{|x\rangle\langle y|}$

Theorem $\langle \cancel{a} | A^+ | \cancel{b} \rangle = \langle \cancel{y} | A | \cancel{x} \rangle^*$

$\langle \cancel{a} | y \rangle^* \langle x | \cancel{b} \rangle^*$

$\langle y | a \rangle \langle b | x \rangle$

reverse the
order

$\langle a | A^+ | b \rangle$.

Unitary Matrices : $U^+ U = I = U U^+$

Hermitian Matrix : $H^\dagger = H$

↳ symmetric matrices in
Real space.

If $|y\rangle = U|x\rangle$ then $\langle y| = \langle x|U^+$

$$\begin{aligned}\langle y | y \rangle &= \langle x | U^+ U | x \rangle \\ &= \langle x | x \rangle\end{aligned}$$

Unitary Operators do not change
the length of a vector.

If $\{ |e_1\rangle, |e_2\rangle, \dots, |e_n\rangle \}$
is an orthonormal basis,

The projection operator is :

$$P_i = |e_i\rangle \langle e_i|$$

Let $|x\rangle = x_1 |e_1\rangle + \dots + x_n |e_n\rangle$

$$\begin{aligned} P_i |x\rangle &= |e_i\rangle \langle e_i| (x_1 |e_1\rangle + \dots) \\ &\Rightarrow x_1 |e_1\rangle \end{aligned}$$

Identity operators : $\sum_{i=1}^N |e_i\rangle \langle e_i| = I$

$$P_i P_j = \delta_{ij} P_j$$

$$P_i^2 = P_i$$

$$P_i^3 = P_i$$

Because of this property, Inverse of a
projection doesn't exist

10th March

$$|x\rangle = \sum |e_i\rangle \langle e_i| x = \sum_i \langle x | e_i \rangle$$

\downarrow

$$\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad A \rightarrow (a_{ji})$$

$$a_{ji} = \langle e_j | A | e_i \rangle$$

$$\text{Eg: } f(x) = a_0 + a_1 x + a_2 x^2$$

$$A = \frac{d}{dx} \cdot |e_0\rangle = x^\circ \quad |e_2\rangle$$

$$|e_1\rangle = x'$$

Now after finding a_{ij} for each
 $i, j = 0, 1, 2$

Operation A is $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$

Now check:

$$\frac{d}{dx} (5 + 5x + 3x^2) \quad [\text{Ans: } 5 + 6x]$$

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 5 \\ 5 \\ 3 \end{pmatrix} = \begin{pmatrix} 5 \\ 6 \\ 0 \end{pmatrix}$$

Even the rotation problem, linear equations etc
 can be done by considering the operation
 as a matrix.

To check whether $AB|e_1\rangle = c|e_1\rangle$.
 (product of $A \cdot B$)

Now we need to prove matrix(A) · matrix
 (B)
 $= \text{matrix}(C)$

$$c|e_i\rangle = \sum_{j=1}^n |e_j\rangle \underbrace{\langle e_j|}_{\text{identity}} \overbrace{\langle c|e_i\rangle}^{\downarrow c_{ji}}$$

$$AB|e_i\rangle = \sum_{j,k=1}^n |e_j\rangle \underbrace{\langle e_j|}_{a_{jk}} \underbrace{A|e_k\rangle}_{\langle e_k|B|e_i\rangle} \underbrace{\langle e_k|}_{b_{ki}} e_i$$

$$\text{So } c_{ji} = \sum_k a_{jk} \cdot b_{ki}$$

Eigen Vector

$$A|x\rangle = \lambda|x\rangle$$

operating A on $|x\rangle$ will give back
vector in the same direction
scaled to a factor.

$|x\rangle$ is the Eigen vector of A .

λ → Eigen value.

$$\frac{d}{dx}(e^{ikx}) = ik e^{ikx}$$

Spectrum: $A \Rightarrow (\lambda_1, \lambda_2 \dots \lambda_{n-1})$.

$$\Rightarrow \text{If } A|x_1\rangle = \lambda_1|x_1\rangle$$

$$A|x_2\rangle = \lambda_2|x_2\rangle$$

prove that if $\lambda_1 \neq \lambda_2$ they are independent

$$\text{if } x_1 = t x_2$$

$$A|x_1\rangle = \cancel{\lambda_1} \cancel{|x_1\rangle} A|tx_2\rangle$$

$$\cancel{\lambda_1} \cancel{|x_1\rangle} \Rightarrow \cancel{\lambda_1}$$

$$\Rightarrow \lambda_1|x_1\rangle \Rightarrow \lambda_2(t|x_2\rangle)$$

$$\Rightarrow \boxed{\lambda_1 = \lambda_2}$$

$$\Rightarrow \text{if } A \{ \lambda_1, \lambda_2 \dots \lambda_n \}$$

$$A^m \{ \lambda_1^m, \lambda_2^m \dots \lambda_n^m \}$$

$$A|x\rangle = \lambda|x\rangle$$

$$A^2|x\rangle = \lambda A(A|x\rangle)$$

$$\Rightarrow A(\lambda|x\rangle)$$

$$\Rightarrow \lambda^2|x\rangle.$$

and so on.

\Rightarrow Eigen values of hermitian operator : Real

If $\lambda_1 \neq \lambda_2$; x_1, x_2 are

$$H|x_1\rangle = \lambda_1|x_1\rangle$$

~~$$H|x_2\rangle = \lambda_2|x_2\rangle$$~~

$$\langle x_1|H^+ = \lambda_1^* \langle x_1|$$

$$\Rightarrow \langle x_1|H = \lambda_1^* \langle x_1|$$

$$(\langle x_1|H)(H|x_1\rangle) \Rightarrow \cancel{\lambda_1^*} \cancel{\langle x_1|H|x_1\rangle}$$

$$\langle x_1|H|x_1\rangle = \langle x_1|H^+|x_1\rangle$$

$$\hookrightarrow A = A^T$$

\Rightarrow real

~~$$\langle \lambda_1 | x_1 \rangle$$~~

$$\langle x_1 | H^+ | H_1 | x_2 \rangle = \langle \lambda_1^* x_1 | \lambda_2 x_2 \rangle$$

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