BioTac® C Library Manual for Cheetah

Version 1.1.0

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Table of Contents

1	Introduction	3
2	General Data Types	3
	Functions	
	tialize Cheetah SPI Device (bt_cheetah_initialize)	
	et BioTac Properties (bt_cheetah_get_properties)	
	nfigure batch command (bt_cheetah_configure_batch)	
	nfigure save-buffer (bt_configure_save_buffer)	
	llect Data (bt_cheetah_collect_batch)	
Pri	nt Error (bt_display_errors)	8
	ve data (bt_save_data)	
	ose Cheetah Device (bt_cheetah_close)	
4	Error Codes	9
5	Code Example	10
OS	Specific Instructions and Known Issues	13
	Linux	13
	Mac OS X	14
	Windows	14
6	Revision History	

1 Introduction

This document describes how to get BioTac data through a Cheetah SPI Host Adapter (Total Phase, Inc.). Some functions therefore use Cheetah API functions. Please refer to Cheetah SPI Host Adapter Datasheet for more details.

BioTac C Library for Cheetah is supported on Linux, Mac OS X, and Windows operating systems. The current Windows version has some restrictions (discussed in Windows section), and we recommend that a user test this on Linux (or Mac OS X).

2 General Data Types

The Cheetah API provides the following data types:

```
typedef unsigned char u08; typedef unsigned short u16; typedef unsigned int u32; typedef unsigned long long u64; typedef signed char s08; typedef signed short s16; typedef signed int s32; typedef signed long long s64;
```

Along with these definitions, BioTac C Library for Cheetah provides the following data types:

as well as structures related to BioTac info (bt_info), properties (bt_property), and data (bt_data) as illustrated in Figure 1.

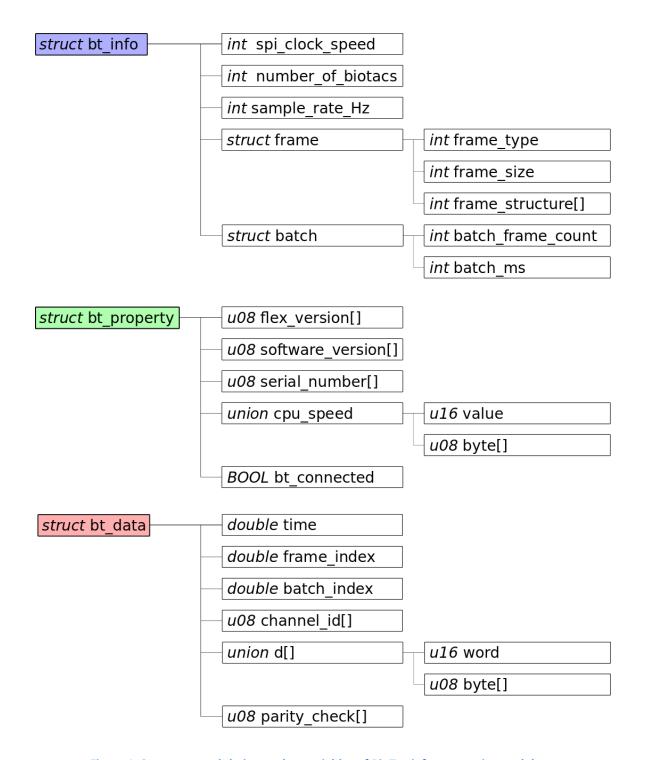


Figure 1: Structures and their member variables of BioTac info, properties, and data.

3 Functions

Initialize Cheetah SPI Device (bt_cheetah_initialize)

```
Cheetah bt cheetah initialize (const bt info *biotac);
```

Open a connection to the Cheetah device and return a Cheetah handle to check errors.

Arguments

biotac pointer to a BioTac information structure

Return Value

This function returns a Cheetah handle, which is guaranteed to be greater than zero if valid.

Specific Error Codes

```
CH_UNABLE_TO_OPEN
```

The specified port is not connected to a Cheetah device or the port is already in use.

CH_INCOMPATIBLE_DEVICE

There is a version mismatch between the DLL and the hardware. The DLL is not of a sufficient version for interoperability with the hardware version or vice versa. See ${\tt ch_open_ext}$ () in the Cheetah Datasheet for more information.

Details

This function may be used to initialize a Cheetah device to communicate with a BioTac. It configures SPI subsystems, sets a clock speed, and clears up the batch queue.

Get BioTac Properties (bt_cheetah_get_properties)

```
BioTac bt_cheetah_get_properties ( Cheetah ch_handle, int bt_select, bt property *property);
```

Receive and print the properties of a selected BioTac.

Arguments

ch handle handle of a Cheetah adapter

bt_select switch to choose a specific BioTac (i.e., 1, 2, ...)

property pointer to a BioTac property structure

Return Value

This function returns a BioTac error code, which is zero if valid.

Specific Error Codes

```
BT WRONG NUMBER ASSIGNED
```

The assigned number exceeds the range, and there is no BioTac assigned to the number.

```
BT_ERROR_UNKNOWN_COMMAND
```

No such command exists. Current version of the BioTac firmware only supports six kinds of properties: Flex version, Firmware version, Serial Number, CPU speed, Sampling speed, and Sampling Pattern.

Details

This function receives and prints BioTac properties such flex circuit version, firmware version, serial number, and CPU speed, and stores those property data in property (the third argument of the function).

Configure batch command (bt_cheetah_configure_batch)

```
BioTac bt_cheetah_configure_batch ( Cheetah ch_handle, bt_info the biotac, int biotac, num_samples);
```

Configure a batch of commands.

Arguments

ch handle handle of a Cheetah adapter

biotac pointer to a BioTac information structure

num samples total number of samples

Return Value

This function returns a BioTac error code, which is zero if valid.

Specific Error Codes

```
BT DATA SIZE TOO SMALL
```

A value assigned to length_of_data_in_second is too small. The value should not be smaller than batch_ms that is 50ms by default.

Details

This function creates a batch of commands that is constructed by a repeated sampling frame. The function uses batch_frame_count, a member variable of bt_info, to setup the number of frames in a batch. A sampling frame is composed sequentially in the order addressed by frame_structure[]. By default, the following 44 sampling commands generate the frame structure:

(BT_FRAME_STRUCTURE_DEFAULT): E1, Pac, E2, Pac, E3, Pac, E4, Pac, E5, Pac, E6, Pac, E7, Pac, E8, Pac, E9, Pac, E10, Pac, E11, Pac, E12, Pac, E13, Pac, E14, Pac, E15, Pac, E16, Pac, E17, Pac, E18, Pac, E19, Pac, Pdc, Pac, Tac, Pac, Tdc, and Pac.

Configure save-buffer (bt_configure_save_buffer)

```
bt data* bt configure save buffer (int num samples);
```

Configure a buffer to save data in a file.

Arguments

```
num_samples total number of samples
```

Return Value

This function returns a pointer to a BioTac data structure.

Specific Error Codes

None.

Details

This function allocates memory for a buffer to store BioTac data and write them in a file later. The function uses the number of samples, which is calculated from <code>length_of_data_in_second</code>. The function has to be called when the save buffer size is changed.

Collect Data (bt_cheetah_collect_batch)

Collect BioTac sampling data in batch unit.

Arguments

ch_handle handle of a Cheetah adapter

biotac pointer to a BioTac information structure

data pointer to data array for storing BioTac sampling data

print flag flag for printing data on Terminal (Linux) or Command Prompt (Windows)

Return Value

This function does not return any value, but stores data in the bt data array.

Specific Error Codes

None.

Details

This function collects a batch of data from a Cheetah SPI device and submits a batch of commands that is configured in the bt_cheetah_get_properties function.

By default, a batch contains 5 frames of raw data (ranging from 0 to 4095) and these data will be decoded in this function. If the result of parity check is wrong, bt parity will be set to 1.

Currently, elapsed time is set to zero for all data by default (DEFAULT_TIMER). If the user is willing to use a timer provided by your computer, MACHINE_TIMER could be enabled (located at the beginning of biotac.c). This feature is currently experimental.

Note: Cheetah SPI device controls the sampling time according to the commands in the memory. By default, the interval timing for each sample of channel is 227µs periodically. However, collecting data would occur only after the Cheetah SPI device has finished collecting a batch of data, which is equal to 50ms of data.

Print Error (bt_display_errors)

```
void bt display errors (BioTac bt err code);
```

Print an error message on the display based on the error code collected in bt_cheetah_setup *function.*

Arguments

```
bt err code variable to store BioTac error information
```

Return Value

This function does not return any value.

Specific Error Codes

None.

Details

```
This function prints out "Wrong BioTac number assigned!" if wrong bt_select number is assigned to the bt_cheetah_get_properties function. For BT_MAX_BIOTACS_PER_CHEETAH = 3, this value should be integer 1, 2, or 3. For BT_MAX_BIOTACS_PER_CHEETAH = 5, this value should be integer 1, 2, 3, 4, or 5.
```

This function prints out "No BioTac detected!" if no BioTac is detected. A physical connection error or wrong timing of SPI sampling commands will cause this error.

This function prints out "Wrong maximum number of BioTacs assigned (should be 3 or 5)!" if BT MAX BIOTACS PER CHEETAH is not 3 or 5. The assigned value should be 3 or 5 only.

This function prints out "The number of samples is too small!" if variable length_of_data_in_second is too small. It should be greater than 50ms.

This function prints out "Something wrong occurred!" if an unknown error has occurred.

Save data (bt_save_data)

Save BioTac data, including batch, frame, and channel ids, raw values, parity check, etc.

Arguments

```
file_name pointer of the string of file name such as "output.txt" data pointer to access the BioTac data num_samples numbers of sampling data saved into the file
```

Return Value

This function does not return any value.

Specific Error Codes

None.

Details

This function saves data in a text file whose name is file_name. By default, a saved data format is as follows (when MAX BIOTACS PER CHEETAH = 3):

```
time, batch_index, frame_index, channel_id, value[0], bt_parity[0],
value[1], bt parity[1], value[2], bt parity[2]
```

Note that channel_id is saved as integer (0-3, 15-35) by default, or can be string (PAC, PDC, TAC, TDC, HAL, E01-E19) as an option. The string name is declared as command name[] in biotac.c.

Close Cheetah Device (bt_cheetah_close)

```
void bt_cheetah_close (Cheetah ch_handle);
```

Disable the SPI output and close the Cheetah Device.

Arguments

ch_handle handle of a Cheetah adapter

Return Value

This function does not return any value.

Specific Error Codes

None.

Details

Disable the outputs. Close the connection of the Cheetah given by the handle.

4 Error Codes

Literal Name	Value
BT_OK	0
BT_WRONG_NUMBER_ASSIGNED	-1
BT_NO_BIOTAC_DETECTED	-2
BT_WRONG_MAX_BIOTAC_NUMBER	-3
BT_DATA_SIZE_TOO_SMALL	-4
BT_ERROR_UNKNOWN_COMMAND	-5

5 Code Example

The code example is compatible with Linux (recommended), Mac OS X, and Windows. Before testing the code, we highly recommend the user try some code examples provided for a Cheetah SPI adapter. Make sure if you have downloaded an appropriate USB driver for your operating system and placed an appropriate Dynamic Linked Library (cheetah. so for Linux and Mac OS X and cheetah.dll for Windows) in a designated directory. Without being able to run Total Phase's detect program, our code example will not run properly.

The cross-platform example package contains seven files:

- biotac.c
- biotac.h
- cheetah.c
- cheetah.h
- example.c
- Makefile
- Makefile-32bit

It is anticipated that the user only modifies example.c. SynTouch LLC does not provide official support for any modifications on biotac.h, biotac.c, cheetah.h, or cheetah.c. Therefore, only example.c is explained below.

```
42
    int main(void)
43
        /************
44
        /* --- Define variables --- */
45
        /****************/
46
47
        bt_info biotac;
48
        bt property biotac property[MAX BIOTACS PER CHEETAH];
        bt data *data;
49
50
        BioTac bt_err_code;
        Cheetah ch handle;
51
52
53
54
        int length_of_data_in_second;
        int number_of_samples;
55
56
        int number_of_loops;
57
        58
        /* --- Initialize BioTac settings (only default values are supported) --- */
59
        /*****************/
60
61
        biotac.spi_clock_speed = BT_SPI_BITRATE_KHZ_DEFAULT;
        biotac.number of biotacs = 0;
62
        biotac.sample_rate_Hz = BT_SAMPLE_RATE_HZ_DEFAULT;
63
64
        biotac.frame.frame type = 0;
        biotac.batch.batch_frame_count = BT_FRAMES_IN_BATCH_DEFAULT;
65
        biotac.batch.batch ms = BT BATCH MS DEFAULT;
66
```

```
67
         // Set the duration of the run time
68
69
         length of data in second = 3;
70
         number_of_samples = (int)(BT_SAMPLE_RATE_HZ_DEFAULT * length_of_data_in_second);
71
72
         // Check if any initial settings are wrong
         if (MAX_BIOTACS_PER_CHEETAH != 3 && MAX_BIOTACS_PER_CHEETAH != 5)
73
74
75
              bt_err_code = BT_WRONG_MAX_BIOTAC_NUMBER;
76
              bt_display_errors(bt_err_code);
77
              exit(1);
         }
78
79
         /***********/
80
81
         /* --- Initialize the Cheetah devices --- */
         /************/
82
83
         ch_handle = bt_cheetah_initialize(&biotac);
84
         /*************/
85
86
         /* --- Get and print out properties of the BioTac(s) --- */
87
88
         for (i = 0; i < MAX_BIOTACS_PER_CHEETAH; i++)
89
90
              bt_err_code = bt_cheetah_get_properties(ch_handle, i+1, &(biotac_property[i]));
91
              if (biotac_property[i].bt_connected == YES)
92
93
94
                  (biotac.number_of_biotacs)++;
95
              }
96
97
              if (bt_err_code)
98
99
                  bt display errors(bt err code);
100
                  exit(1);
101
              }
         }
102
103
         // Check if any BioTacs are detected
104
105
         if (biotac.number_of_biotacs == 0)
106
         {
107
              bt_err_code = BT_NO_BIOTAC_DETECTED;
108
              bt_display_errors(bt_err_code);
              return bt err code;
109
110
         }
         else
111
112
              printf("\n%d BioTac(s) detected.\n\n", biotac.number of biotacs);
113
114
         }
115
         // The programs stops here until it accepts [Enter] key hit
116
         printf("Press [Enter] to continue ...");
117
118
         fflush(stdout);
119
         getchar();
```

```
120
         /***********/
121
122
         /* --- Configure the save buffer --- * /
         /***********************/
123
124
         data = bt_configure_save_buffer(number_of_samples);
125
         /********/
126
127
         /* --- Configure the batch --- */
         /******************/
128
129
         bt_err_code = bt_cheetah_configure_batch(ch_handle, &biotac, number_of_samples);
130
         if (bt err code < 0)
131
132
             bt_display_errors(bt_err_code);
             exit(1);
133
134
         }
135
         else
136
         {
137
             printf("\nConfigured the batch\n");
138
         }
139
         /****************/
140
141
         /* --- Collect the batch and display the data (if desired) --- */
         /**************/
142
         number_of_loops = (int)(number_of_samples / ((double)(biotac.frame.frame_size *
biotac.batch.batch frame count)));
         printf("Start collecting BioTac data for %d second(s)...\n", length_of_data_in_second);
144
         for (i = 0; i < number of loops; i++)
145
146
         {
             // To print out data on Terminal, set the fourth argument to YES (NO by default)
147
             bt cheetah collect batch(ch handle, &biotac, data, NO);
148
         }
149
150
         /***********/
151
152
         /* --- Save data --- */
         /***********/
153
154
         bt_save_buffer_data("output.txt", data, number_of_samples);
155
         /**************/
156
157
         /* --- Close and exit --- */
         /***************/
158
159
         printf("Press [Enter] to close the program");
160
         fflush(stdout);
161
         getchar();
162
163
         free(data);
         bt_cheetah_close(ch_handle);
164
165
166
         return 0;
167 }
```

The main function for the example starts from Line 42. First, several variables are declared (Lines 47-56). Member variables of bt_info biotac are initialized (Lines

61-66). We suggest the user use the default values. On Lines 69-70, the user can change the duration of the run time. The Cheetah initialization function is called on Line 83. In the current version of software, if more than one Cheetah devices are hooked up to a computer, the device opening through port 0 will be detected and other devices will be ignored. Next, properties of the BioTacs such as flex circuit version, software version, serial number, and CPU speed and the number of connected BioTacs are displayed on the display (Lines 88-102). If no BioTac is detected, the program exits (Lines 105-114). The program waits before configuring the batch until it accepts a user input of [Enter] key from a keyboard (Lines 117-119).

After the [Enter] key hit, we allocate memory for a buffer to save data (Line 124), followed by a function to configure batch settings (Lines 129-138). If the user is willing to try the MACHINE_TIMER option, the timer will start here. Thus, pausing after the bt_cheetah_configure_batch function before stopping collecting data is likely to cause an error.

Next, we start collecting the batch of data (Lines 143-149). number_of_loops can be calculated based on number_of_samples, frame_size, and batch_frame_count. During data collection, if the user would like to display real-time data on Terminal, the fourth argument of bt_cheetah_collect_batch can be changed from NO to YES. However, keep in mind that printing data on Terminal makes the program running slower and thus the program might fail to keep up with a specified clock. Instead, you can save data to a text file using the bt_save_data function (Lines 154).

Finally, we close the program by calling bt_cheetah_close and free allocated memory.

OS Specific Instructions and Known Issues

Linux

We have tested our code on Ubuntu 10.04 (32-bit and 64-bit). Makefile is written for a 64-bit kernel. For 32-bit, please delete Makefile (or rename it to Makefile-64bit) and rename Makefile-32bit to Makefile. To run the example program, fist launch Terminal, move to an appropriate directory, build the project, and run the executable file:

```
>> cd /path/to/code_example/
>> make
>> ./bin/example
```

Make sure if you copy an appropriate version of cheetah. so in a designated folder (i.e. where your source files are).

Mac OS X

We have tested our code on Mac OS X 10.7 (64-bit). First, make sure if XCode 4 or higher is installed on your machine to run make. Then, follow the instructions for Linux.

Windows

We have tested our code using Microsoft Visual C++ 2010 Express on Windows 7 Professional (64-bit). First, create a new project (File-> New-> Project...) and choose Empty Project from Visual C++ template. Enter names of the project/solution and set the location, and click OK. After successfully creating the new project, right-click on Header Files on the left menu, choose Add-> Existing item... to import biotac.h and cheetah.h. Similarly, right-click on Sources Files and choose Add-> Existing item... to import biotac.c, cheetah.c, and example.c. Make sure if you copy an appropriate version of cheetah.dll in a designated folder. In our case, we downloaded the 32-bit version of cheetah.dll and copied it to C:\Windows\System32 because Microsoft Visual C++ Express 2010 runs under the 32-bit mode.

We have observed that when print_flag, the fourth argument of the bt_cheetah_collect_batch function, is set to YES, only the first batch collects BioTac data. Thus, it is highly recommended that Windows users turn off the print display feature. A member variable parity_check in bt_data cab be a quick check if collected data are corrupted.

6 Revision History

(V1.1.0) April 5, 2012

- Compatible with BioTac firmware 2.x.x and 3.x.x
- $\bullet \quad {\bf New\ function} \ \ {\tt bt_configure_save_buffer\ created}$
- Due to structure change, bt_property is not a member variable of bt_info

(V1.0.0) December 22, 2011

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