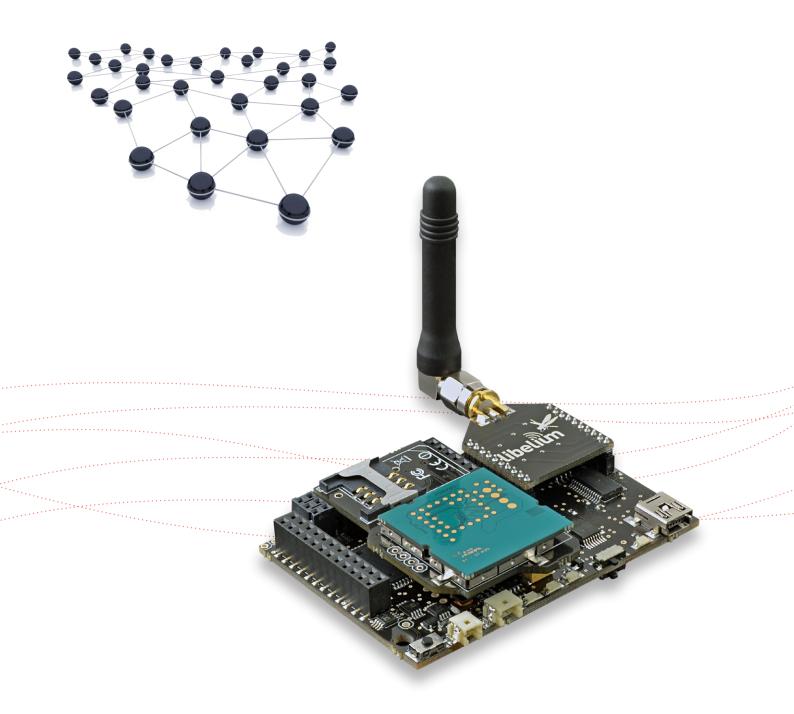
Waspmote Utilities Programming Guide









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1. Introduction

Waspmote provides some libraries to manage USB interaction and other general tasks (blinking LEDs, some string conversions, etc).

To manage these tasks, some functions have been developed and two libraries have been created: 'USB Library' and 'Utils Library'.

2. USB Library

2.1. Waspmote Libraries

2.1.1. Waspmote USB Files

WaspUSB.h; WaspUSB.cpp

2.1.2. Constructor

To start using Waspmote USB library, an object from class 'WaspUSB' must be created. This object, called 'USB', is created inside the Waspmote USB library and it is public to all libraries. It is used through the guide to show how the Waspmote USB library works.

When creating this constructor, one variable is initialized. This variable specifies the number of the UART that USB is going to use (UART0 in this case).

2.1.3. Pre-Defined Constants

There are some constants defined in 'WaspUSB .h' related with the different kind of numbers that can be printed on the screen.

2.2. Initialization

Two functions have been created to open and close the UART used to communicate via USB.

Example of use

```
{
   USB.ON(); // Opens the UART at 115200 bps by default
   USB.OFF(); // Closes the UART
}
```

2.3. Reading data

Two functions have been developed for reading data or checking if data is available in the UART. One more function has been developed to free the UART buffer.

Example of use

```
{
  int data_read=0;
  if(USB.available())
  {
     // If data is available '1' is returned
     data_read=USB.read(); // Reads data from UART0
  }
  USB.flush(); // Frees the UART buffer. All the data unread are lost.
}
```

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2.4. Printing data

Some functions have been created to write data to the UART.

Example of use:

```
Print a character
        char charac='a';
        USB.print(charac); // Writes the char 'a' to the UART
        USB.println(charac); // Writes the char 'a' to the UART adding an EOL
        USB.println(); // Writes an EOL
Print a string
     {
        char* string="Hello";
        USB.print(string); // Writes a string to the UART
        USB.println(string); // Writes a string to the UART adding an EOL
     }
Print uint8_t (1 Byte)
        uint8 t unsigned=3;
        USB.print(unsigned); // Writes the number '3' to the UART
        USB.println(unsigned); // Writes the number '3' to the UART adding an EOL
     }
Print int (2 Bytes)
        int integer=54345;
        USB.print(integer); // Writes the number '54345' to the UART
        USB.println(integer); // Writes the number '54345' to the UART adding an EOL
     }
Print long (4 Bytes)
     {
        long long_int=1234567;
        USB.print(long_int); Writes the number '1234567' to the UART
        USB.println(long_int); Writes the number '1234567' to the UART adding an EOL
     }
Print float (4 Bytes)
        float float num=1,23456;
        USB.print(float_num); Writes the number '1.23456' to the UART
        USB.println(float_num); Writes the number '1.23456' to the UART adding an EOL
     }
Print hexadecimal number (1 Byte)
        uint8_t num = 0x14;
        USB.printHex(num); // Writes the number 0x14 in base 16
```

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Print **numbers** in different formats

```
USB.println(78);  // Writes 78 in integer format: '78'
USB.println(78, BIN); // Writes 78 in binary format: '1001110'
USB.println(78, OCT); // Writes 78 in octal format: '116'
USB.println(78, DEC); // Writes 78 in integer format: '78'
USB.println(78, HEX); // Writes 78 in hexadecimal format: '4E'
}
```

Print formatted data

```
int var1=0xABCD;
int var2=3.1416;
int var3=32767; //max signed int
int var4=32768; //overflows signed int range
long var5=2147483647;  //max signed long int
long var6=2147483648;  //overflows signed long range
unsigned long var7=4294967295; //max unsigned long
USB.printf("%s\n", "Hello world");
                                                 // Writes "Hello World" with EOL
USB.printf("millis: %lu\n", millis()); // Writes "millis: 356" with EOL
USB.printf("hexadecimal: %x\n", var1); // Writes "hexadecimal: abcd" with EOL
USB.printf("decimal: %d\n", var1);
                                               // Writes "decimal: -21555" with EOL
USB.printf("unsigned int: %u\n", var1);// Writes "unsigned int: 43981" with EOL
USB.printf("float: %f\n", var2);
                                                // It is not possible to print floats this way
USB.printf("int: %d\n", var3);  // Writes "int: 32767" with EOL USB.printf("'32768' overflows: %d\n", var4); // Writes "'32768' overflows: -32768"
USB.printf("signed long: %ld\n", var5);// Writes "signed long: 2147483647" with EOL
USB.printf("'2147483648' overflows: %ld\n", var6); Writes "'2147483648' overflows: -2147483648" USB.printf("unsigned long: %lu\n", var7); // Writes "unsigned long: 4294967295"
```

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• USB function example:

http://www.libelium.com/development/waspmote/examples/usb-01-usb-functions

• Formatted print function example:

http://www.libelium.com/development/waspmote/examples/usb-02-usb-printf-function

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3. Utilities Library

3.1. Waspmote Libraries

3.1.1. Waspmote Utilities Files

WaspUtils.h; WaspUtils.cpp

3.1.2. Constructor

To start using the Waspmote Utilities library, an object from class 'WaspUtils' must be created. This object, called 'Utils', is created inside the Waspmote Utilities library and it is public to all libraries. It is used through the guide to show how the Waspmote Utilities library works.

When creating this constructor, no variables are initialized.

3.1.3. Pre-Defined Constants

There are some constants defined in 'WaspUtils.h' used to make it easier the understanding of the code.

3.2. Using LEDs

These functions are capable of changing the state of the LEDs. It is possible to change their state, to get their state and to blink both LEDs for a specific time.

Example of use

```
{
    // 1. set LEDs ON
    Utils.setLED( LED1, LED_ON); // Sets the green LED ON
    Utils.setLED( LED0, LED_ON); // Sets the red LED ON

    // 2. set LEDs OFF
    Utils.setLED( LED1, LED_OFF); // Sets the green LED OFF
    Utils.setLED( LED0, LED_OFF); // Sets the red LED OFF

    // 3. Get LEDs state
    uint8_t state1=Utils.getLED(LED1); // Gets the state of LED1
    uint8_t state0=Utils.getLED(LED0); // Gets the state of LED0

    // 4. Blink LEDs
    Utils.blinkLEDs(1000); // Blink LEDs using a delay of 1000ms for blinking
}
```

· Using LEDs example:

http://www.libelium.com/development/waspmote/examples/ut-02-using-leds

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3.3. Using EEPROM

This is the microcontroller's EEPROM (4KB) non-volatile memory. EEPROM addresses from 0 to 1023 are reserved by Waspmote API to save important data, so they must not be over-written. Thus, the available storage addresses go from 1024 to 4095.

| | RESERVED | AVAILABLE |
|---|----------|-----------|
| 0 | 1023 | 1024 4095 |

The function that writes the EEPROM is Utils.writeEEPROM. This function does not permit to write reserved EEPROM addresses.

Example of use

```
{
   Utils.writeEEPROM(1024,'B'); // Write the value 'B' in the address 1024
   uint8_t data=Utils.readEEPROM(1024); // Reads the value stored in the address 1024
}
```

• Using EEPROM example:

http://www.libelium.com/development/waspmote/examples/ut-01-using-eeprom

3.4. Reading Serial ID

This function reads the Waspmote unique serial identifier. This identifier is composed by 8 bytes.

Example of use:

```
{
  unsigned long id = 0;
  id = Utils.readSerialID();
}
```

Using EEPROM example:

http://www.libelium.com/development/waspmote/examples/ut-03-reading-serial-id

3.5. Converting types

Convert from long int to string

```
{
  char number[20];
  Utils.long2array(1356, number); // Gets the number '1356' into the string
}
```

Convert from **float** to **string**

```
{
  char number[20];
  Utils.float2String(134.54342, number, 3); // Convert 134.54342 to string (3 decimals)
}
```

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AVR Libc Library allows the user to convert between different variable types. This is a list with some supported function prototypes:

Convert **string** to **int** (2 Bytes):

```
{
  int number = atoi("2341");
}
```

Convert from **string** to long **integer** (4 Bytes):

```
{
   long int number = atol("143413");
}
```

• Converting types example:

http://www.libelium.com/development/waspmote/examples/ut-04-convert-types

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4. Input/Output pins

Waspmote can communicate with other external devices using different input/output ports.

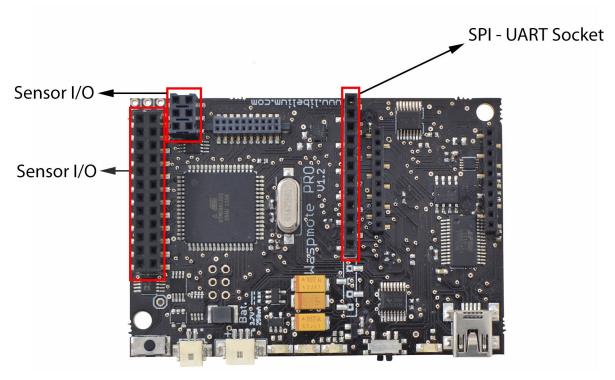


Figure: I/O sockets in Waspmote

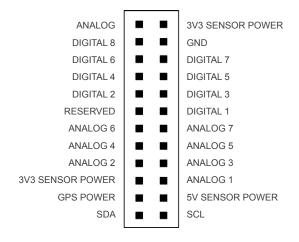


Figure: Description of sensor socket pins

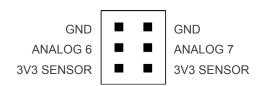


Figure: Description of sensor socket pins

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4.1. Reading ANALOG inputs

It gets the value read by the corresponding analog input. Waspmote has 7 analog inputs in the sensor connector. Each input is directly connected to the microcontroller. The microcontroller uses a 10-bit analog to digital converter (ADC). The reference voltage value for the inputs is 0V (GND). The maximum value of input voltage is 3.3V. To obtain input values, the function analogRead is used. The value read from this function will be an integer number between 0 and 1023 bits, where 0 corresponds to 0 V and 1023 to 3.3 V.

Example of use

```
int val1 = analogRead(ANALOG1); // Read the input ANALOG1 and store its value in val1
int val2 = analogRead(ANALOG2); // Read the input ANALOG2 and store its value in val2
int val3 = analogRead(ANALOG3); // Read the input ANALOG3 and store its value in val3
int val4 = analogRead(ANALOG4); // Read the input ANALOG4 and store its value in val4
int val5 = analogRead(ANALOG5); // Read the input ANALOG5 and store its value in val5
int val6 = analogRead(ANALOG6); // Read the input ANALOG6 and store its value in val6
int val7 = analogRead(ANALOG7); // Read the input ANALOG7 and store its value in val7
}
```

4.2. Digital I/O

4.2.1. Setting DIGITAL pin mode

It configures the specified pin as an input or an output.

It returns nothing.

```
Example of use
```

```
{
   pinMode(DIGITAL1, INPUT); // Sets DIGITAL1 as an input
   pinMode(DIGITAL4,OUTPUT); // Sets DIGITAL4 as an output
}
```

4.2.2. Reading DIGITAL Inputs

It reads the value from the specified digital pin.

```
It returns '0' or '1'.
```

```
Example of use
```

```
{
   int val=0;
   pinMode(DIGITAL1, INPUT); // Sets DIGITAL1 as an input
   val=digitalRead(DIGITAL1); // Reads the value from Digital 1
}
```

4.2.3. Writing DIGITAL Outputs

It writes a 'HIGH' or 'LOW' value to a digital pin.

Its voltage will be set to 3.3V for a 'HIGH' value, and 0V for a 'LOW' value.

Example of use

```
{
   pinMode(DIGITAL4, OUTPUT); // Sets DIGITAL4 as an output
   digitalWrite(DIGITAL4, HIGH); // Writes 'High' to Digital 4
}
```

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4.2.4. DIGITAL1 pin as PWM output

There is one pin that can be used as an analog or digital pin.

This pin is called DIGITAL1.

It returns nothing.

Example of use

```
{
   analogWrite(DIGITAL1, 128); // Writes a value comprised between [0-255] in DIGITAL1
}
```

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5. Getting Free RAM Memory

5.1. Waspmote Files

Inside the Core directory we can find both MemoryFree.cpp and MemoryFree.h which develop the function that allows the user to get the available free memory in Waspmote's RAM memory.

5.2. freeMemory function

This is the function that returns the Waspmote's available memory in Bytes.

| Waspmote RAM | | | | |
|--------------------|-------------------|--------|-------------|---------|
| .data Variables | .bss Variables | Heap → | Free Memory | ← Stack |

Figure: RAM Memory spaces

The different sections in RAM memory are explained below:

.data variables/.bss variables: Memory space for initialized and uninitialized variables

Heap: Memory space for dynamic memory allocation.

Stack: Memory space used for calling subroutines and storing local (automatic) variables. This memory space grows downwards.

Example of use

```
{
   USB.print("free Memory (Bytes):");
   USB.println(freeMemory()); // prints free RAM
}
```

• Getting free memory example:

http://www.libelium.com/development/waspmote/examples/ut-05-get-free-memory

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6. Reading basic sensors

There are some basic sensors that can be plugged directly to Waspmote except for the light sensor which needs some hardware modifications.



Figure: Basic sensors

6.1. Temperature Sensor

The temperature sensor **MCP9700A** can be plugged directly to the secondary I/O Sensor socket. The sensor pins are described below indicating where they have to be plugged to:

```
Pin1: Vcc (3V3 SENSOR)
Pin2: Vout (ANALOG6)
Pin3: GND
```

Example of use:

```
{
  float temperature;
  temperature = Utils.readTemperature();
}
```

• Reading temperature sensor example:



Figure: MCP9700A Temperature sensor

http://www.libelium.com/development/waspmote/examples/bs-01-reading-temperature

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6.2. Light Sensor

The **LDR** sensor needs a simple hardware modification so as to be connected directly to Waspmote. This sensor is connected to the main I/O sensor socket. The modification is presented below:

The sensor pins are connected this way:

Pin Vcc (3V3 SENSOR POWER)
Pin Vout (ANALOG5)
Pin GND (GND)





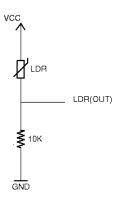


Figure: LDR sensor hardware modification

Example of use:

```
{
  int light;
  light = Utils.readLight();
}
```

• Reading light sensor example:

http://www.libelium.com/development/waspmote/examples/bs-02-reading-light

6.3. Humidity

The humidity sensor **808H5V6** can be plugged directly to the secondary I/O Sensor socket. The sensor pins are described below indicating where they have to be plugged to:

```
Pin1: Vcc (3V3 SENSOR)
Pin2: Vout (ANALOG7)
Pin3: GND

Example of use:

{
    int humidity;
    humidity = Utils.readHumidity();
}
```



Figure: 808H5V6 Humidity sensor

• Reading humidity sensor example:

http://www.libelium.com/development/waspmote/examples/bs-03-reading-humidity

• Reading all sensors at the same time:

http://www.libelium.com/development/waspmote/examples/bs-04-reading-sensors

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6.4. DS18B20 Temperature Sensor

This temperature sensor also needs a simple hardware modification to be directly plugged to Waspmote. Three pins come out of the sensor: Red (3V3), Black (GND) and White (Output pin). A 4K7 resistor must be connected between the red and white pins. The Sensor output can be plugged in any Waspmote digital pin. When reading the sensor the output pin is selected as input parameter:

Example of use:

```
{
  // temperature sensor plugged to DIGITAL8 pin
  float temp;
  temp = Utils.readTempDS1820(DIGITAL8);
}
```

• Reading DS18B20 temperature sensor example:

http://www.libelium.com/development/waspmote/examples/bs-05-reading-ds18b20

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7. Code examples and extended information

In the Waspmote Development section you can find complete examples:

http://www.libelium.com/development/waspmote/examples



8. API changelog

| Function / File | Changelog | Version |
|--|--|--------------|
| WaspUtils::getBootVersion | New Function | v007 → v008 |
| WaspUtils::readTempDS1820 | Internal change in function | v004 → v005 |
| WaspUtils::checkNewProgram | Internal change in function | v004 → v005 |
| MUX0 | Definition changed to MUX_0 | v004 → v005 |
| MUX1 | Definition changed to MUX_1 | v004 → v005 |
| WaspUtils::setMux | Internal change in function | v004 → v005 |
| WaspUtils::setMuxGPS | Internal change in function | v004 → v005 |
| WaspUtils::setMuxSocket1 | Internal change in function | v004 → v005 |
| WaspUtils::setMuxAux1 | Internal change in function | v004 → v005 |
| WaspUtils::setMuxAux2 | Internal change in function | v004 → v005 |
| WaspUtils::str2hex | New function to convert a hexadecimal ASCII string to hexadecimal values array | v004 → v005 |
| MAX_ARGS | This definition has been deleted | V0.31 → v001 |
| MAX_ARG_LENGTH | This definition has been deleted | V0.31 → v001 |
| EEPROM_START | This definition has been created | V0.31 → v001 |
| SD_SELECT | This definition has been created | V0.31 → v001 |
| SRAM_SELECT | This definition has been created | V0.31 → v001 |
| SOCKETO_SELECT | This definition has been created | V0.31 → v001 |
| SOCKET1_SELECT | This definition has been created | V0.31 → v001 |
| ALL_DESELECTED | This definition has been created | V0.31 → v001 |
| <pre>char arguments[MAX_ARGS][MAX_ARG_LENGTH];</pre> | This attribute has been deleted | V0.31 → v001 |
| WaspUtils::setMuxGPRS | This function has been renamed to setMuxSocket1 | V0.31 → v001 |
| WaspUtils::setMuxUSB | New function created | V0.31 → v001 |
| WaspUtils::muxOFF | New function created | V0.31 → v001 |
| WaspUtils::setMuxSocket0 | New function created | V0.31 → v001 |
| WaspUtils::parse_decimal | Function deleted | V0.31 → v001 |
| WaspUtils::parse_degrees | Function deleted | V0.31 → v001 |
| WaspUtils::gpsatol | Function deleted | V0.31 → v001 |
| WaspUtils::gpsisdigit | Function deleted | V0.31 → v001 |
| WaspUtils::parse_latitude | Function deleted | V0.31 → v001 |
| WaspUtils::Dec2hex | Function deleted | V0.31 → v001 |
| WaspUtils::array2long | Function deleted | V0.31 → v001 |
| WaspUtils::setID | New function created | V0.31 → v001 |
| WaspUtils::setAuthKey | New function created | V0.31 → v001 |
| WaspUtils::readSerialID | New function created | V0.31 → v001 |
| WaspUtils::readTempDS1820 | New function created | V0.31 → v001 |
| WaspUtils::readTemperature | New function created | V0.31 → v001 |
| WaspUtils::readHumidity | New function created | V0.31 → v001 |
| WaspUtils::readLight | New function created | V0.31 → v001 |
| WaspUtils::strtolong | Function deleted | V0.31 → v001 |
| WaspUtils::sizeOf | Function deleted | V0.31 → v001 |
| WaspUtils::strCmp | Function deleted | V0.31 → v001 |
| WaspUtils::strCp | Function deleted | V0.31 → v001 |
| WaspUtils::setSPISlave | New function created | V0.31 → v001 |

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9. Document changelog

From v4.1 to v4.2:

API changelog updated

From v4.0 to v4.1:

- API changelog update
- AVR libc reference added
- Document changelog added

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