

3D Image Restoration using Machine Learning

Master Thesis Defense

Sönke Ziemer

5.11.2018

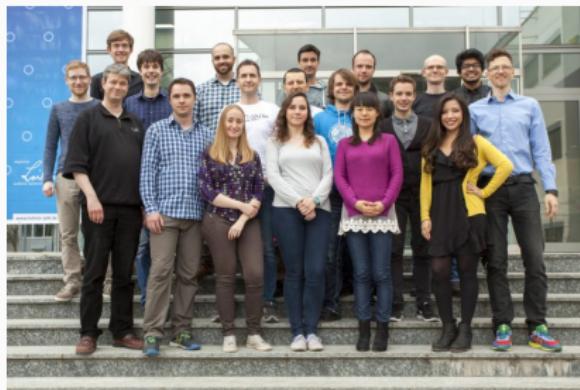


Thank You

Supervisors: Rainer Heintzmann, Christian Karras, Benedict Diederich

Proofreaders: Dina Ratsimandresy, Elsie Quansah

The Bio-Nanoimaging Group

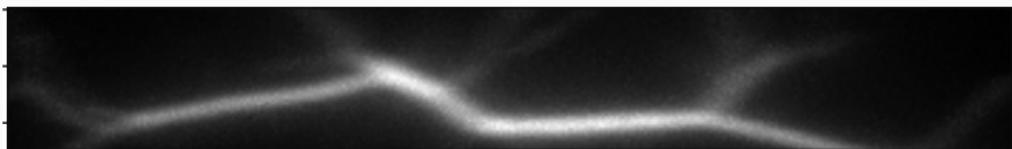


Introduction

3D Microscopic Imaging: $\text{obj} \mapsto \text{img}$

Investigated ways to recover obj

img



↓?

obj



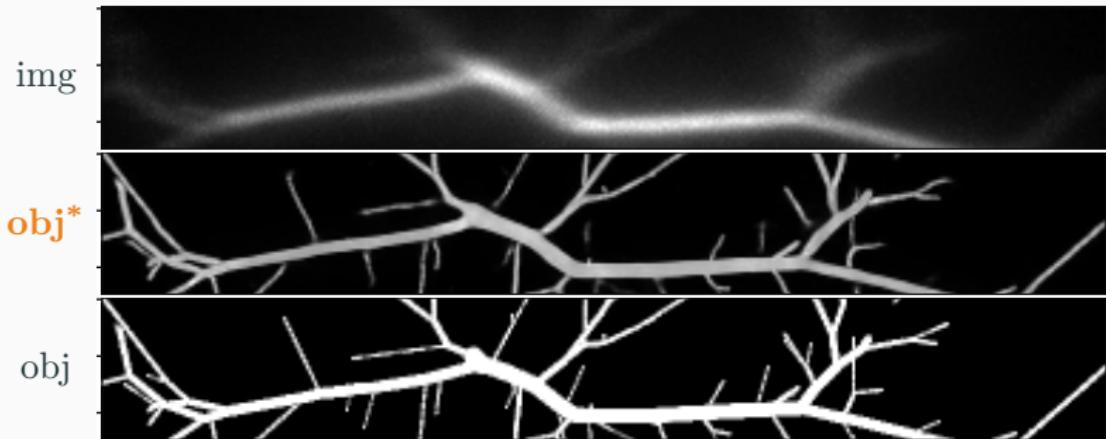
Shown are Maximum Projections

Introduction

3D Microscopic Imaging: $\text{obj} \mapsto \text{img}$

Investigated ways to recover obj

Using a Convolutional Neural Network:



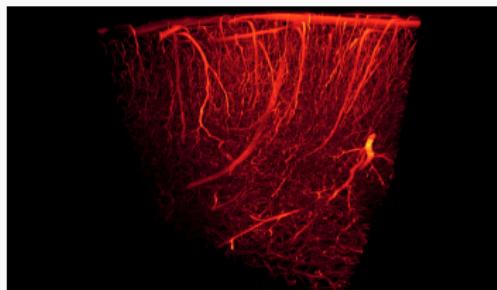
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1. Dataset Generation
2. Cost Function Approach to Deconvolution
3. Convolutional Neural Network (CNN) for Deconvolution

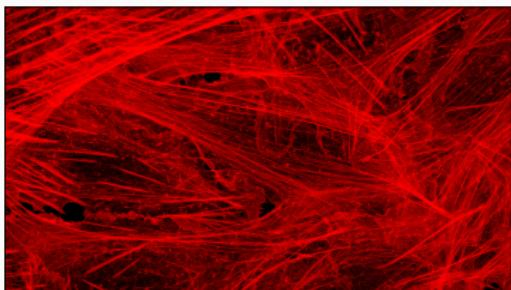
Dataset Generation: VascuSynth

Software to simulate blood vessels

Assume similarity to actin or microtubules



Blood Vessels, By Antonino Paolo Di Giovanna [CC BY-SA 4.0], from Wikimedia Commons



Actin, adapted from Howard Vindin [CC BY-SA 4.0], from Wikimedia Commons

Related: [1, 2]

Dataset Generation: Imaging

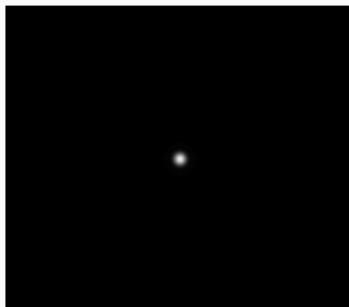
$$\text{img} = \mathcal{N}_{\text{Poisson}}(\text{obj} \otimes \text{PSF} + \text{b})$$

Dataset Generation: Imaging

$$\text{img} = \text{N}_{\text{Poisson}}(\text{obj} \otimes \text{PSF} + b)$$



\otimes_{3D}

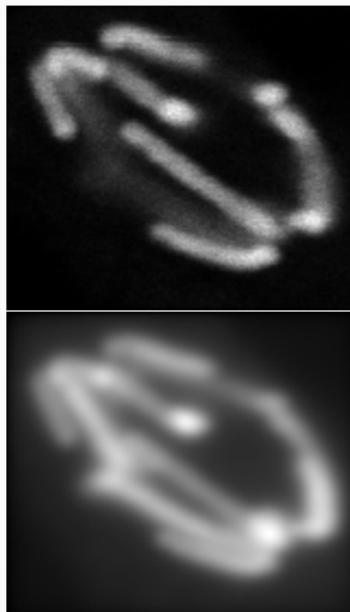


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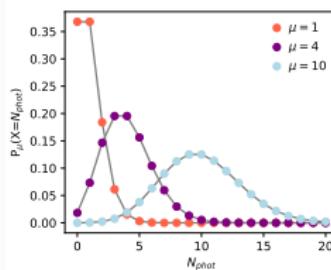
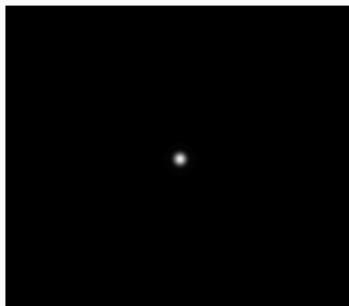


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\otimes_{3D}

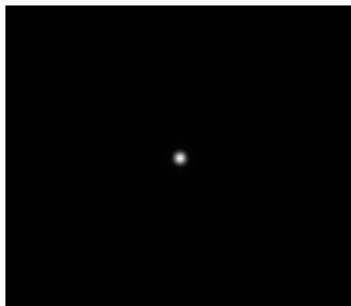


Dataset Generation: Scaling blur and noise

Blur: Vary wavelength $\lambda = 520 \text{ nm}$, $N_{\text{phot}} = 1000$



\otimes_{3D}



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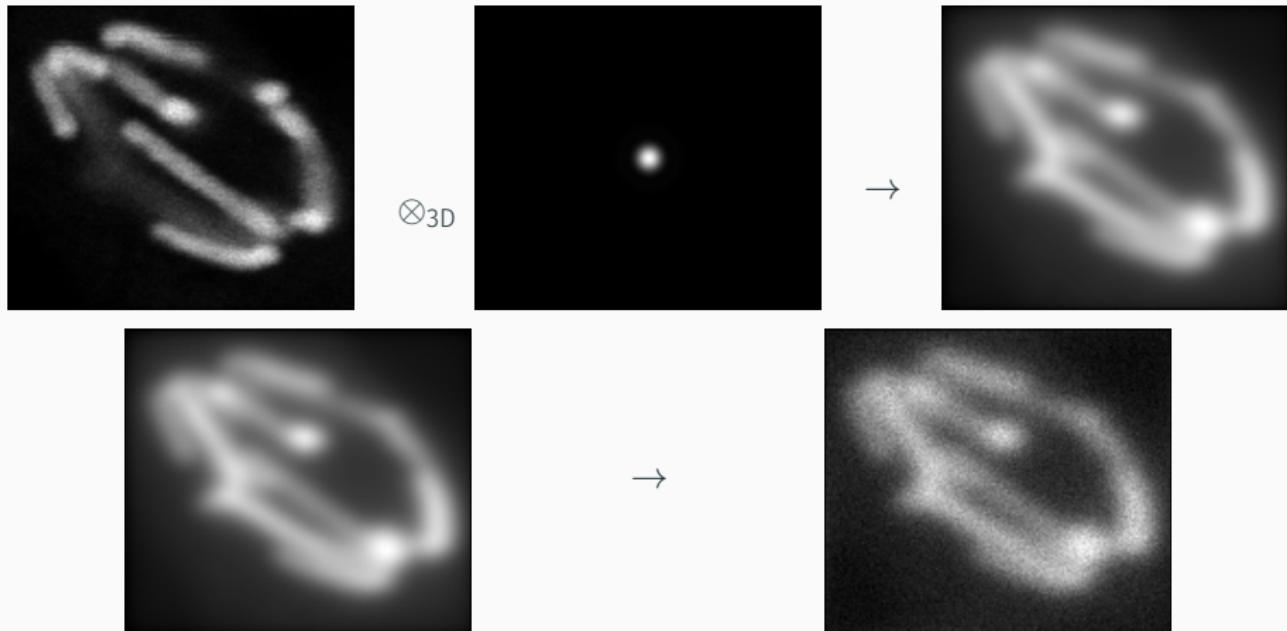


→



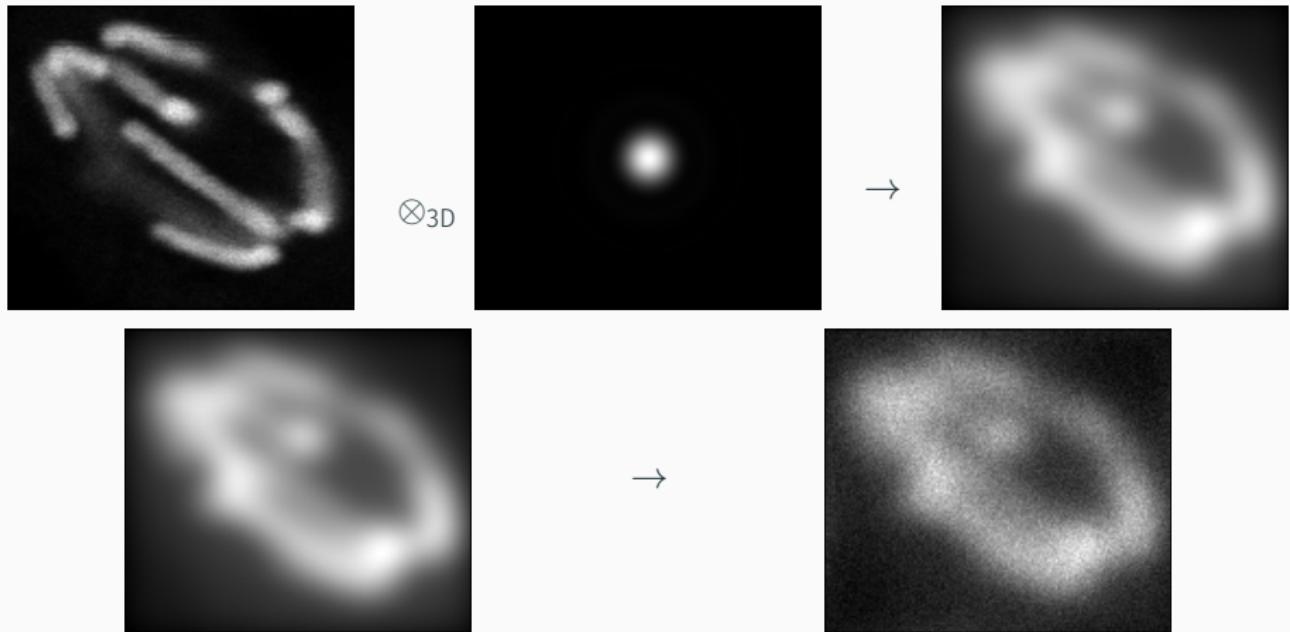
Dataset Generation: Scaling blur and noise

Blur: Vary wavelength $\lambda = 1040 \text{ nm}$, $N_{\text{phot}} = 1000$



Dataset Generation: Scaling blur and noise

Blur: Vary wavelength $\lambda = 2080 \text{ nm}$, $N_{\text{phot}} = 1000$

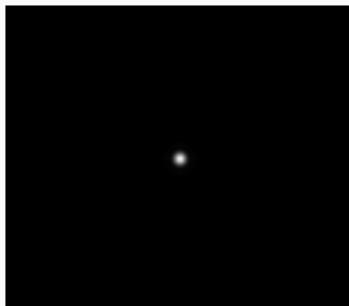


Dataset Generation: Scaling blur and noise

Blur: Vary number of photons $\lambda = 520 \text{ nm}$, $N_{\text{phot}} = 10\,000$



\otimes_{3D}



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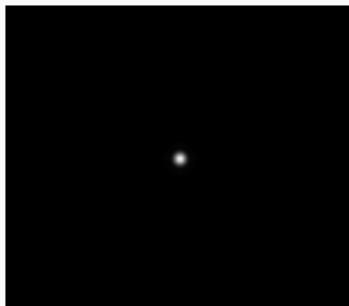


Dataset Generation: Scaling blur and noise

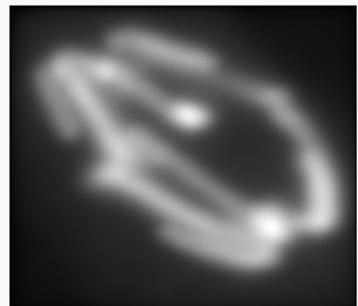
Blur: Vary number of photons $\lambda = 520 \text{ nm}$, $N_{\text{phot}} = 1000$



\otimes_{3D}



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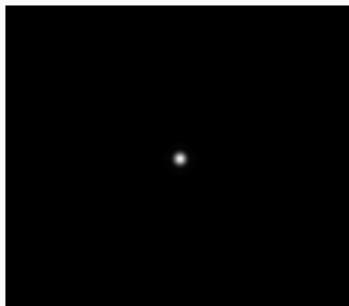


Dataset Generation: Scaling blur and noise

Blur: Vary number of photons $\lambda = 520$ nm, $N_{\text{phot}} = 100$



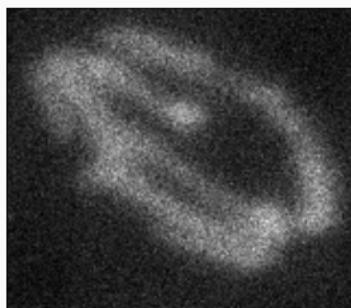
\otimes_{3D}



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Deconvolution: Approaches

Direct inversion / Wiener Deconvolution:

→ one step, but limited results

Cost Function Approach:

→ minimize cost

$$\text{obj}^* = \underset{\text{est}}{\operatorname{argmin}} \text{cost}_{\text{img}}(\text{est})$$

→ gradient descent:

$$\text{est}_i^{(n+1)} = \text{est}_i^{(n)} + \alpha^{(n)} \frac{d\text{cost}_{\text{img}}}{d\text{est}_i}(\text{est}_i^{(n)})$$

Related: [3]

Deconvolution: Cost Function Approach

$$\text{cost}_{\text{img}}(\text{est}) = \text{fid}_{\text{img}}(\text{est}) + \alpha \cdot \text{Reg}(\text{est})$$

Cost Function Approach: Data Fidelity

$$\text{cost}_{\text{img}}(\text{est}) = \text{fid}_{\text{img}}(\text{est}) + \alpha \cdot \text{Reg}(\text{est})$$

Reason for data fidelity:

→ estimate should be related to image

Examples:

$$\text{MSE}_{\text{img}}[\text{blur}(\text{est})] = \frac{1}{N} \sum_{i=0}^{N-1} [\text{blur}(\text{est}_i) - \text{img}_i]^2$$

$$\text{Poi}_{\text{img}}[\text{blur}(\text{est})] = \sum_{i=0}^{N-1} [\text{blur}(\text{est}_i) + \ln \text{img}_i! - \text{img}_i \cdot \ln \text{blur}(\text{est}_i)]$$

Cost Function Approach: Regularization

$$\text{cost}_{\text{img}}(\text{est}) = \text{fid}_{\text{img}}(\text{est}) + \alpha \cdot \text{Reg}(\text{est})$$

Reasons for Regularization:

- Statistical Estimate from a single measurement
- Break ambiguity of estimate

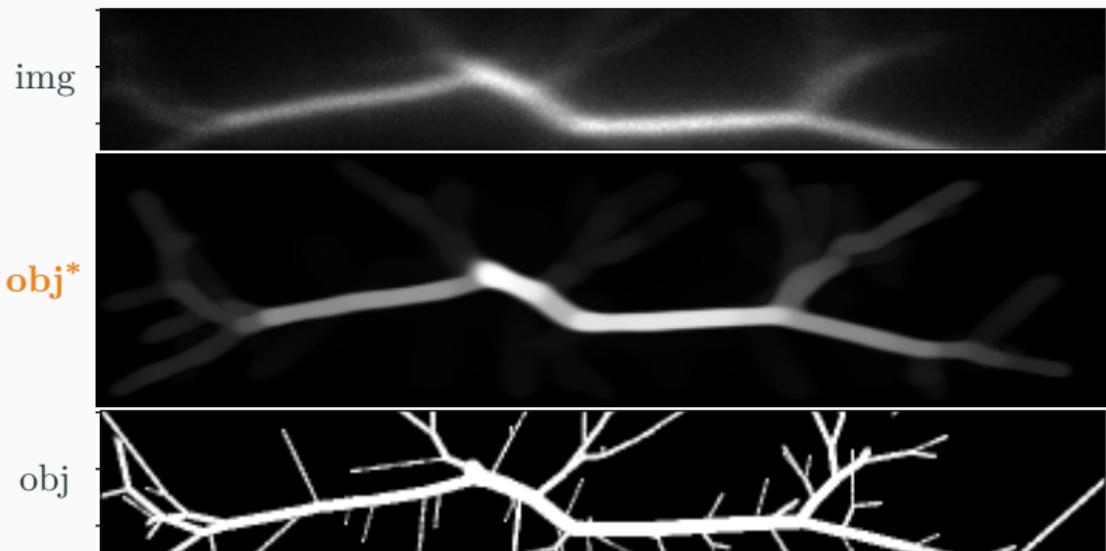
Example:

$$\text{TV}(\text{est}) = \sum_{i=0}^{N-1} \sqrt{(\partial_x \text{est}_i)^2 + (\partial_y \text{est}_i)^2 + (\partial_z \text{est}_i)^2}$$

Related: [4]

Result: Cost Function Approach

$$\text{cost}_{\text{img}}(\text{est}) = \sum_{i=0}^{N-1} [\text{blur}(\text{est}_i) + \ln |\text{img}_i| - \text{img}_i \cdot \ln \text{blur}(\text{est}_i)] + \text{TV}(\text{est})$$



Deconvolution using a Convolutional Neural Network

Before: Cost was function of est with respect to **one** img

Now: Define a cost as a function of CNN-parameters $\vec{\theta}$ with respect to **all** images in a dataset \mathcal{D}

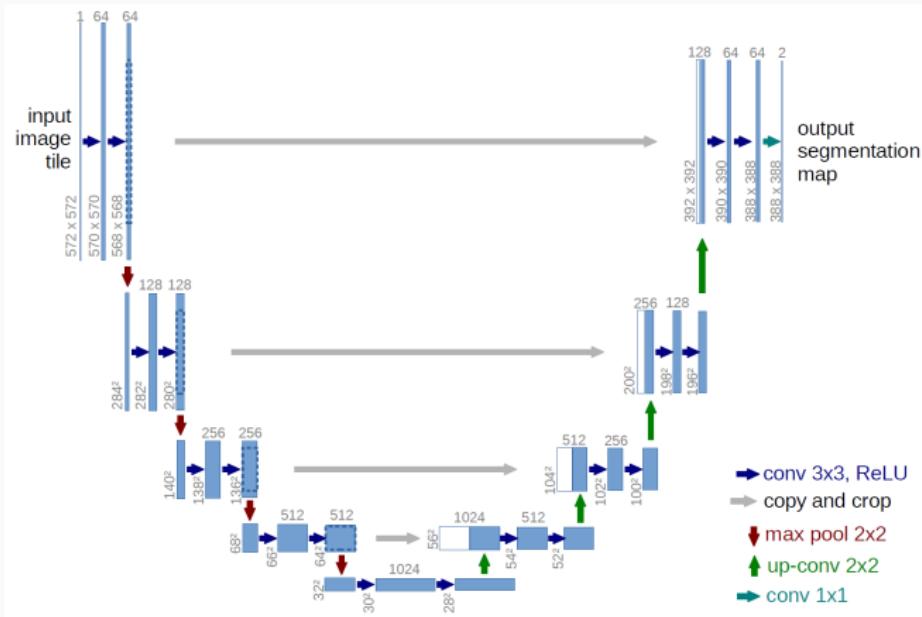
→ 2 Steps:

1. Train CNN on dataset: $\vec{\theta}^* = \operatorname{argmin}_{\vec{\theta}} \text{cost}_{\mathcal{D}}(\vec{\theta})$
2. Test CNN on unknown images: $\text{obj}^* = \text{CNN}_{\vec{\theta}^*}(\text{img})$

Related: [3]

Deconvolution using a CNN

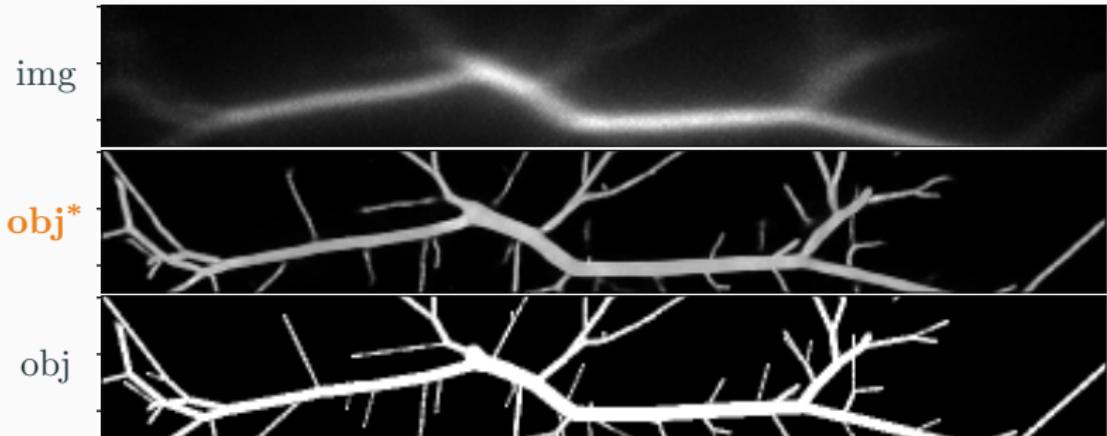
network architecture: U-Net



Related: [5, 6]

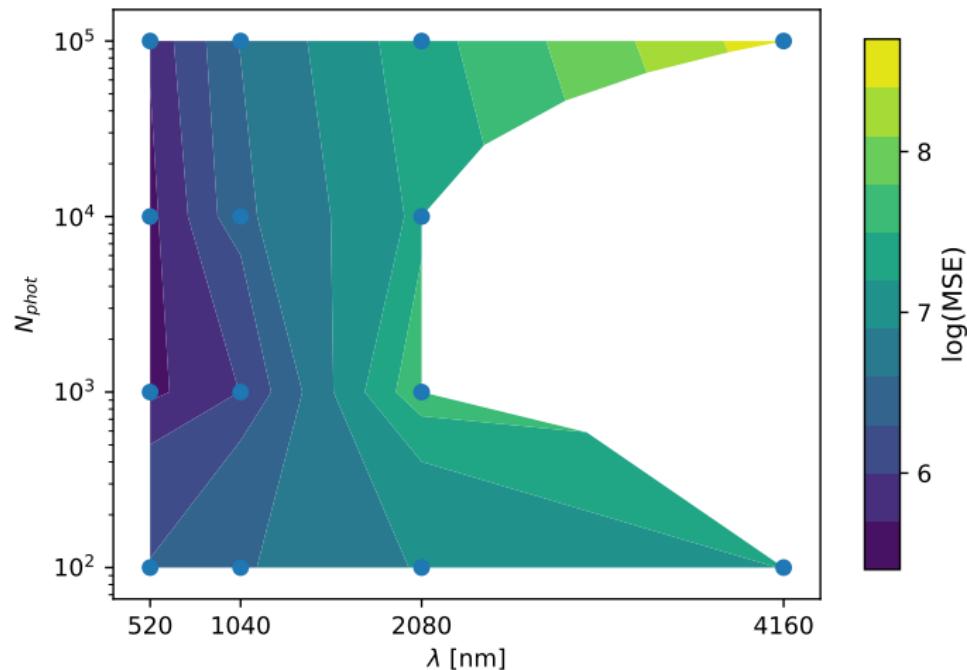
Results: CNN - Proof of Principle

$$\text{cost}_{\mathcal{D}}(\vec{\theta}) = \frac{1}{N_{\mathcal{D}}} \sum_{(\text{obj}, \text{img}) \in \mathcal{D}} \text{MSE}_{\text{obj}, \text{img}}(\text{CNN}_{\vec{\theta}}(\text{img}_i), \text{obj}_i)$$



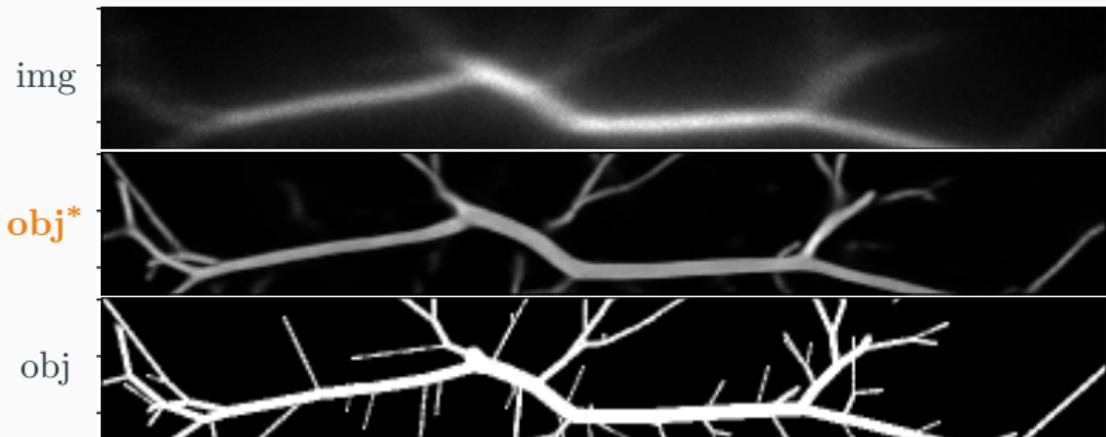
$\lambda = 520 \text{ nm}, N_{\text{phot}} = 10\,000$

Results: CNN - Application Limits



Results: CNN - Application Limits

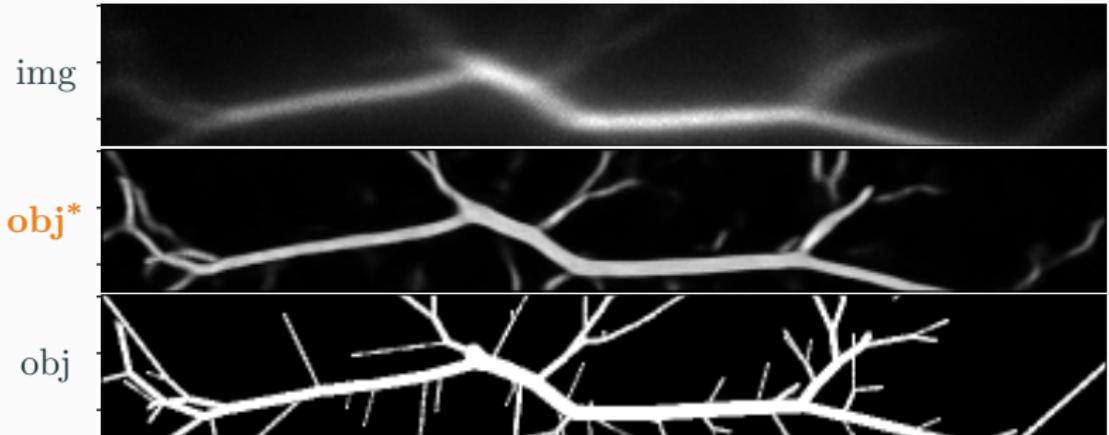
$$\text{cost}_{\mathcal{D}}(\vec{\theta}) = \frac{1}{N_{\mathcal{D}}} \sum_{(\text{obj}, \text{img}) \in \mathcal{D}} \text{MSE}_{\text{obj}, \text{img}}(\text{CNN}_{\vec{\theta}}(\text{img}_i), \text{obj}_i)$$



$\lambda = 1040 \text{ nm}$, $N_{\text{phot}} = 10\,000$

Results: CNN - Application Limits

$$\text{cost}_{\mathcal{D}}(\vec{\theta}) = \frac{1}{N_{\mathcal{D}}} \sum_{(\text{obj}, \text{img}) \in \mathcal{D}} \text{MSE}_{\text{obj}, \text{img}}(\text{CNN}_{\vec{\theta}}(\text{img}_i), \text{obj}_i)$$



$\lambda = 520 \text{ nm}, N_{\text{phot}} = 100$

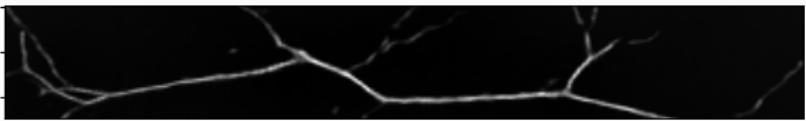
Results: CNN - Transferability

Transfer to a different blur level did not work well.

Transfer to a different noise level:

training	testing	Result
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1000	1000	
------	------	--

100 000	1000	
---------	------	--

100	1000	
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$\lambda = 520 \text{ nm}$, N_{phot} varies

Conclusion and Outlook

Proof of Principle ✓

Applicability of models (✓)

Transfer of models ×

Conclusion and Outlook

Proof of Principle ✓

- Poisson cost for CNN
- Unsupervised Training
- Architecture and Hyperparameter

Applicability of models (✓)

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Conclusion and Outlook

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Applicability of models (✓)

- Collect more data points
- Quantify image quality

Transfer of models ×

Conclusion and Outlook

Proof of Principle ✓

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- Architecture and Hyperparameter

Applicability of models (✓)

- Collect more data points
- Quantify image quality

Transfer of models ×

- Identify reasons
- Countermeasures

Thank you for your attention

References

- [1] G. Hamarneh and P. Jassi. "VascuSynth: Simulating vascular trees for generating volumetric image data with ground-truth segmentation and tree analysis." In: *Computerized Medical Imaging and Graphics* 34.8 (Dec. 2010), p. 605. doi: 10.1016/j.compmedimag.2010.06.002.
- [2] P. Jassi and G. Hamarneh. "VascuSynth: Vascular Tree Synthesis Software." In: *Insight Journal* January-June (Apr. 2011), p. 1. URL: <http://hdl.handle.net/10380/3260>.
- [3] M. T. McCann, K. H. Jin, and M. Unser. "Convolutional Neural Networks for Inverse Problems in Imaging: A Review." In: *IEEE Signal Processing Magazine* 34.6 (Nov. 2017), p. 85. doi: 10.1109/msp.2017.2739299.
- [4] U. S. Kamilov et al. "Optical Tomographic Image Reconstruction Based on Beam Propagation and Sparse Regularization." In: *IEEE Transactions on Computational Imaging* 2.1 (Mar. 2016), p. 59. doi: 10.1109/tci.2016.2519261.
- [5] O. Ronneberger, P. Fischer, and T. Brox. "U-Net: Convolutional Networks for Biomedical Image Segmentation." In: *Medical Image Computing and Computer-Assisted Intervention – MICCAI 2015*. Ed. by N. Navab, J. Hornegger, W. M. Wells, and A. F. Frangi. Cham: Springer International Publishing, May 18, 2015, p. 234. doi: 10.1007/978-3-319-24574-4_28.
- [6] M. Weigert et al. "Content-Aware Image Restoration: Pushing the Limits of Fluorescence Microscopy." In: *bioRxiv* (pre-print) (Dec. 2017). doi: 10.1101/236463.

Appendix



