Trust Prediction using Temporal Dynamics

SMAI Project

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Social trust Relation

- In open society based applications, we assume there are dependencies between users.
- Any user's preference depends on the user's trust on other users.
- Initial attempts assumes trust relations to be static.
- In real scenario, trust relations are dynamic and change with time.

Social Trust Prediction Model

A trust prediction framework is proposed based on low rank matrix factorization as:

$$\min_{U,V} || \boldsymbol{G} - \boldsymbol{U}\boldsymbol{V}\boldsymbol{U}^{\mathsf{T}} ||_F^2$$

where $G = \sum_{i,j} U \in \mathbb{R}^{n^*d}$ is the user preference matrix and d is the number of facets of user preference. $V \in \mathbb{R}^{d^*d}$ captures the more compact correlations among U, such as G(i,j) as U(i,:) V $U^T(j,:)$,

Temporal Weight Matrix Factorization in trust prediction

- Social trust relation depend on time distance between the current time and the time on which trust relation was established.
- These trust relations decay with time.
- The rates of decay may be different for different for different users.
- Prediction error is related to the time distance.
- In prediction error we want to incorporate the effect of time on trust relations.

Continued...

- Let $g_{i,j}^{t}$ be the first timestamp when u_i trusted u_j .
- Earlier trust relations reflect users' previous preferences and should have less influence on the current trust prediction.
- Exponential time function $e^{-\eta (m-g_0)}$ is added. 'm' is current time.

In the error term, we multiply the time decay factor, the error in prediction of a trust relation from user u_i to u_j be.

$$e^{-\eta_i(m-g_{ij}^t)} \| \boldsymbol{G}(i,j) - \boldsymbol{U}(i,:)\boldsymbol{V}\boldsymbol{U}^{\mathrm{T}}(j,:) \|_2^2$$

Update Rule Derivation:

$$L = \|\mathbf{X} - \mathbf{U}\mathbf{V}^T\|_F^2 + \alpha \|\mathbf{U}\|_F^2 + \beta \|\mathbf{V}\|_F^2 - Tr(\Lambda_1\mathbf{U}^T) - Tr(\Lambda_2\mathbf{V}^T).$$

We have the following KKT condition,

$$\Lambda_1 \circ \mathbf{U} = \mathbf{0},$$

 $\Lambda_2 \circ \mathbf{V} = \mathbf{0},$

where o denotes the Hadamard product. We then have

$$\frac{\partial L}{\partial \mathbf{U}} = \frac{\partial Tr(\mathbf{V}\mathbf{U}^T\mathbf{U}\mathbf{V}^T - 2\mathbf{X}^T\mathbf{U}\mathbf{V}^T) + \alpha Tr(\mathbf{U}^T\mathbf{U}) - Tr(\Lambda_1\mathbf{U}^T)}{\partial \mathbf{U}}
= 2(\mathbf{U}\mathbf{V}^T\mathbf{V} - \mathbf{X}\mathbf{V} + \alpha \mathbf{U}) - \Lambda_1,
\frac{\partial L}{\partial \mathbf{V}} = \frac{\partial Tr(\mathbf{V}\mathbf{U}^T\mathbf{U}\mathbf{V}^T - 2\mathbf{X}^T\mathbf{U}\mathbf{V}^T) + \beta Tr(\mathbf{V}^T\mathbf{V}) - Tr(\Lambda_2\mathbf{V}^T)}{\partial \mathbf{V}}
= 2(\mathbf{V}\mathbf{U}^T\mathbf{U} - \mathbf{X}^T\mathbf{U} + \beta \mathbf{V}) - \Lambda_2.$$

Let $\frac{\partial L}{\partial \mathbf{U}} = 0$ and $\frac{\partial L}{\partial \mathbf{V}} = 0$ as another KKT condition, we have

$$\Lambda_1 = 2(\mathbf{U}\mathbf{V}^T\mathbf{V} - \mathbf{X}\mathbf{V} + \alpha\mathbf{U}),$$

$$\Lambda_2 = 2(\mathbf{V}\mathbf{U}^T\mathbf{U} - \mathbf{X}^T\mathbf{U} + \beta\mathbf{V}).$$

Now we combine Eq. 8 and Eq. 10, we have

Continuation:

An auxiliary function $G(\mathbf{U}, \mathbf{U}^t)$ of function $L(\mathbf{U})$ is a function that satisfies

$$G(\mathbf{U}, \mathbf{U}) = L(\mathbf{U}), \ G(\mathbf{U}, \mathbf{U}^t) \ge L(\mathbf{U}).$$
 (13)

Then, if we take \mathbf{U}^{t+1} such that

$$\mathbf{U}^{t+1} = \underset{U}{\operatorname{arg \, min}} \ G(\mathbf{U}, \mathbf{U}^t), \tag{14}$$

we have

$$L(\mathbf{U}^{t+1}) \le G(\mathbf{U}^{t+1}, \mathbf{U}^t) \le G(\mathbf{U}^t, \mathbf{U}^t \le L(\mathbf{U}^t)). \tag{15}$$

This proves that L(U) is monotonically decreasing.

Step 1 - Finding an appropriate auxiliary function needs to take advantage of two inequalities,

$$z \ge 1 + \log z, \, \forall z > 0,\tag{16}$$

$$\sum_{i=1}^{m} \sum_{j=1}^{k} \frac{(\mathbf{AS'B})(i,j)\mathbf{S}(i,j)^2}{\mathbf{S'}(i,j)} \ge Tr(\mathbf{S}^T \mathbf{ASB}),$$

$$\forall \mathbf{A} \in \mathbb{R}_{+}^{m \times m}, \mathbf{B} \in \mathbb{R}_{+}^{k \times k}, \mathbf{S}' \in \mathbb{R}_{+}^{m \times k}, \mathbf{S} \in \mathbb{R}_{+}^{m \times k}. \tag{17}$$

The proof for Eq. T can be found in [5] (Proposition 6).

After removing irrelevant terms, the objective function Eq. 5 in terms of U can be written as

$$Tr(\mathbf{V}\mathbf{U}^{T}\mathbf{U}\mathbf{V}^{T} - 2\mathbf{X}^{T}\mathbf{U}\mathbf{V}^{T}) + \alpha Tr(\mathbf{U}^{T}\mathbf{U})$$

$$=Tr(\mathbf{U}^{T}\mathbf{U}\mathbf{V}^{T}\mathbf{V} - 2\mathbf{U}^{T}\mathbf{X}\mathbf{V}) + \alpha Tr(\mathbf{U}^{T}\mathbf{U})$$
(18)

We now propose an auxiliary function

$$G(\mathbf{U}, \mathbf{U}^{t}) = -2 \sum_{i,j} (\mathbf{X}\mathbf{V})(i,j) \mathbf{U}^{t}(i,j) (1 + \log \frac{\mathbf{U}(i,j)}{\mathbf{U}^{t}(i,j)})$$

$$+ \sum_{i,j} \frac{(\mathbf{U}^{t}\mathbf{V}^{T}\mathbf{V})(i,j) \mathbf{U}(i,j)^{2}}{\mathbf{U}^{t}(i,j)} + \alpha \sum_{i,j} \frac{\mathbf{U}^{t}(i,j) \mathbf{U}(i,j)^{2}}{\mathbf{U}^{t}(i,j)}.$$
(19)

Combining the two inequalities Eq. 16, 17, it is straightforward to see that Eq. 19 is a legal auxiliary function for Eq. 18, i.e., the two conditions in Eq. 13 are satisfied. Now we proceed to find \mathbf{U}^{t+1} that satisfies condition Eq. 14.

Step 2 - Finding U^{t+1} can be achieved by obtaining the *global minima* of Eq. 19. First, we have

$$\frac{\partial G(\mathbf{U}, \mathbf{U}^t)}{\partial \mathbf{U}(i, j)} = -2(\mathbf{X}\mathbf{V})(i, j)\frac{\mathbf{U}^t(i, j)}{\mathbf{U}(i, j)} + 2\frac{(\mathbf{U}^t\mathbf{V}^T\mathbf{V})(i, j)\mathbf{U}(i, j)}{\mathbf{U}^t(i, j)} + 2\alpha\mathbf{U}(i, j).$$
(20)

Let $\frac{\partial G(\mathbf{U}, \mathbf{U}^t)}{\partial \mathbf{U}(i, j)} = 0$ we have

$$(\mathbf{X}\mathbf{V})(i,j)\frac{\mathbf{U}^{t}(i,j)}{\mathbf{U}^{t+1}(i,j)} = (\frac{(\mathbf{U}^{t}\mathbf{V}^{T}\mathbf{V})(i,j)}{\mathbf{U}^{t}(i,j)} + \alpha)\mathbf{U}^{t+1}(i,j), \tag{21}$$

from which we directly have

$$\mathbf{U}^{t+1}(i,j) = \mathbf{U}^{t}(i,j) \sqrt{\frac{(\mathbf{X}\mathbf{V})(i,j)}{(\mathbf{U}^{t}\mathbf{V}^{T}\mathbf{V} + \alpha\mathbf{U}^{t})(i,j)}},$$
(22)

>) V(i, k) = V(i, k) | B(i,k) B= E & Dig G(i)) UT(i)

C= E E Bij UT(i,)U(j.)

2 G UTU

Algorithm:

Algorithm 1 TWMF for Trust Prediction

Input:
$$\{G_1, G_2, \dots, G_m\}$$
, α, β and γ .

Output: G

$$1: \boldsymbol{G} = \sum_{i=1}^{m} \boldsymbol{G}_{i}$$

- Initialize V randomly;
- Initialize η, randomly;
- 4: Initialize U(i,:) randomly
- 5: while not reach convergence or the maximal iteration

6: Update
$$\eta_i \leftarrow \eta_i \sqrt{\frac{\sum_{j=1}^{n} c_{ij} e^{-\eta_i (w - g'_{ij})}}{2\alpha \eta_i + \sum_{j=1}^{n} c_{ij} e^{-\eta_i (w - g'_{ij})}}}$$
;

7: Update
$$U(i,k) \leftarrow U(i,k) \sqrt{\frac{a_i^T(k)}{[U(i,:)A_i](k)}}$$

$$8: V(i,k) \leftarrow V(i,k) \sqrt{\frac{B(i,k)}{C(i,k)}}$$

9: end while

10:
$$\hat{G} = UVU^T$$

where a_i and A_i are defined as follows:

$$\mathbf{a}_{t} = \sum_{j=1}^{n} b_{ij}^{t} \mathbf{G}(i, j) \mathbf{V} \mathbf{U}^{\mathrm{T}}(j, :) + \sum_{j=1}^{n} b_{ji}^{t} \mathbf{G}(j, i) \mathbf{V}^{\mathrm{T}} \mathbf{U}^{\mathrm{T}}(j, :)$$

$$\mathbf{A}_{t} = \sum_{j=1}^{n} b_{ij}^{t} \mathbf{V} \mathbf{U}^{\mathrm{T}}(j, :) \mathbf{U}(j, :) \mathbf{V}^{\mathrm{T}}]$$

$$+ \sum_{j=1}^{n} b_{ji}^{t} \mathbf{V}^{\mathrm{T}} \mathbf{U}(j, :)^{\mathrm{T}} \mathbf{U}(j, :) \mathbf{V} + \beta \mathbf{I}$$

where B and C are defined as

$$B = \sum_{i=1}^{n} \sum_{j=1}^{n} b_{ij}^{t} G(i, j) U^{T}(i, :) U(j, :)$$

$$C = \sum_{i=1}^{n} \sum_{t=1}^{n} b_{ij}^{t} \boldsymbol{U}^{\mathrm{T}}(i,:) \boldsymbol{U}(j,:) \boldsymbol{V}^{\mathrm{T}} \boldsymbol{U}^{\mathrm{T}}(i,:) \boldsymbol{U}(j,:) + \gamma \boldsymbol{V}$$

where $c_{ij} = \| \boldsymbol{G}(i,j) - \boldsymbol{U}(i,:)\boldsymbol{V}\boldsymbol{U}^{T}(j,:) \|_{2}^{2}$

$$b_{ij}^{t} = e^{-\eta_{t}(m-g_{ij}^{t})}$$
 and $b_{ji}^{t} = e^{-\eta_{j}(m-g_{ji}^{t})}$,

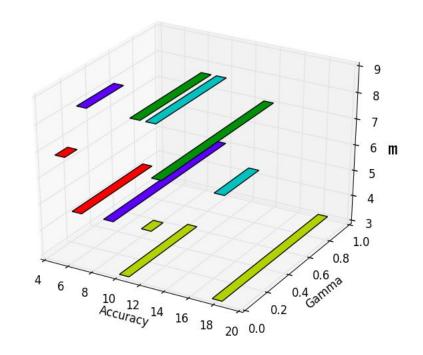
Experiment Settings

- Used dataset generated by <u>www.epinions.com</u>.
- We choose trust relations from t_i to t_{l+i-1} t as old trust relations 'O' with the time window size 'i'.
- 'N' is the new trust relations established at t_{l+i}.
- 'A' is the trust relation predicted excluding 'O'.
- We sort values in A and take top N pairs as C.

Prediction Accuracy (PA) = $|N \cap C|/|N|$

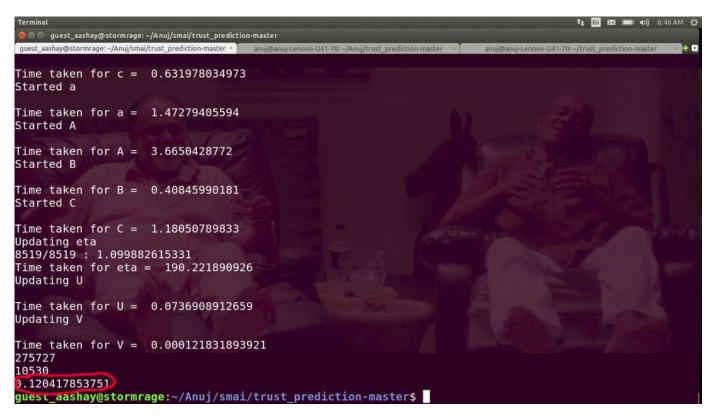
Results

- The following is the graph of The obtained results (accuracy) with varying values of m (time till which the trust relation is known) and gamma (varied from 0.1 to 1).
- The bars of same colors are shows the results obtained with same number of epochs.
- The average time taken for one epoch is about 210 seconds.



(Epocs,colour) - (10 - Red), (5,blue), (6,green), (4,Yellow), (3,Cyan)

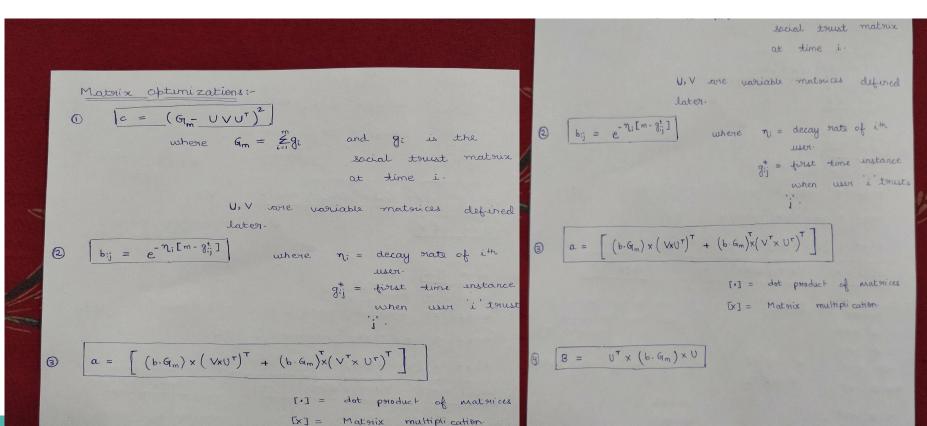
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```
Terminal
                                                                                                  11 En ₩ № 40) 6:20 AM 😃
guest_aashay@stormrage: ~/Anuj/smai/trust_prediction-master
quest aashay@stormrage: ~/Anuj/smai/trust prediction-master ×
                                          anui@anui-Lenovo-U41-70: ~/Anui/trust_prediction-master ×
                                                                                  anui@anui-Lenovo-U41-70: ~/trust prediction-master
Time taken for V = 0.000141143798828
epochs # 2
Started c
Time taken for c = 0.648800849915
Started a
Time taken for a = 1.4781460762
Started A
Time taken for A = 3.63032507896
Started B
Time taken for B = 0.429671049118
Started C
Time taken for C = 1.22097206116
Updating eta
8519/8519 : 1.099882615331
Time taken for eta = 196.742071867
Updating U
Time taken for U = 0.0756840705872
Updating V
Time taken for V = 0.000118017196655
epochs # 3
```

Implementation (Matrix optimizations)



Continuation ...

```
= [i] I gmt
             UETJ X VETJ
   tmp2 = 91eshaped tmp1 [ (n)x(d)x(d) \rightarrow (n)x(dxd)]
   tmp 3[i]= [(b[i]) x tmp2], neshape ([d, d])
                          where d = no of faceits
                                             features
  C+= (VIUII × UII) × tmp3[i] + i
  C+= {V
                             of a variable that is
                                    varied in our model
                           B => fixed variable
  tmpicij = Ucij X Ucij
  tmp2 = sreshaped tmp1 [(n) x (d) x (d) \longrightarrow (n) x (dxd)]
  +mp3 = (b x +mp2) Heshaped [ d,d])
  tmp + = (b.x +mp2) Heshaped ([d,d])
 A[i] + = V x tmp3[i]xV + V x tmp4[i] x V \ \tag{i}
Dimensions of matrices:-
                                m - the al usems
```

```
C+= {V
                             of a variable that is
                                   varied in our model
                             B => fixed variable
   A = BI
   tmpilli] = Ulij X Ulij
   tmp2 = oreshaped tmp1 [ (n) x (d) x (d) \longrightarrow (n) x (dxd)]
   tmp3 = (b x tmp2) reshaped ([d,d])
   tmp + = (b.x +mp2) Heshaped ([d,d])
  A[i] + = V x +mp3[i]xV + V x +mp4[i] x V \ \ti
 Dumensions of matrices:
                                   n = # of Usens
                                   m = time till which
 c => nxn
                                        trust matrices are
 b => nxn
                                        known
               # i=[1, n]
 a(i) dx1
                                    d = # of faceit features
               + i=[,n]
ACE STA
                                11= nxd
 B = dxd
                                V=> dxd
 c = dxd
                         Predicted torust matrix:
 g = D nxn
                                G'= UVUT
```

References:

- https://tcs.epfl.ch/files/content/sites/tcs/files/Lec2-Fall14-Ver2.pdf
- https://www.cse.msu.edu/~tangjili/publication/hTrust.pdf
- https://link.springer.com/content/pdf/10.1007%2Fs11859-014-1027-z.pdf
- https://arxiv.org/pdf/1507.00333.pdf

Minimizing the Error in prediction

Given the error function mentioned before, we write its lagrange to minimize the error as follows.

$$\min_{U,V,\eta_{i}} \sum_{i=1}^{n} \sum_{j=1}^{n} e^{-\eta_{i}} (m - g_{ij}^{t}) \| G(i,j) - U(i,:)VU^{T}(j,:) \|_{2}^{2} + \alpha \sum_{i=1}^{n} \| \eta_{i} \|_{2}^{2} + \beta \| U \|_{F}^{2} + \gamma \| V \|_{F}^{2} \qquad s.t. \ U, V \ge 0, \quad \eta_{i} \ge 0, \ \forall i \in [1,n]$$

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Github: https://github.com/amanshahi/trust_prediction

Thank You!