

UC&NL

Underwater Communication
and Navigation Laboratory

<http://unavlab.com>

support@unavlab.com

uWAVE underwater communication
system interfacing protocol
specification

uWAVE

Interfacing protocol specification

version 2.0 rev. b

28-02-2019

Content

1 Introduction.....	3
1.1 Physical layer.....	3
1.2 NMEA0183 Protocol standard.....	3
2 UUV sentences.....	5
2.1 Sentence IC_D2H_ACK - device reaction.....	5
2.2 IC_H2D_SETTINGS_WRITE - writing new settings.....	5
2.3 IC_H2D_RC_REQUEST - code request to a remote subscriber.....	6
2.4 IC_D2H_RC_RESPONSE - answer of remote subscriber.....	6
2.5 IC_D2H_RC_TIMEOUT - remote subscriber timeout.....	7
2.6 IC_D2H_RC_ASYNC_IN - incoming message from a remote subscriber.....	7
2.7 IC_H2D_AMB_DTA_CFG - ambient parameters and supply voltage configuration	8
2.8 IC_H2D_AMB_DTA - ambient parameters and supply voltage.....	9
2.9 IC_H2D_DINFO_GET - request device information.....	9
2.10 IC_D2H_DINFO - device information.....	10
3 Command mode.....	10
4 Identifiers.....	12
4.1 Error codes.....	12
4.2 Remote commands.....	13

1 Introduction

1.1 Physical layer

uWAVE hydroacoustic modems support data pairing using the RS-232 physical layer standard for asynchronous interface (UART) with a 3.3V data line voltage.

The connection is made using a four-wire cable with Tx (transmitter), Rx (receiver), Vcc (power) and GND (ground) wires.

Without the use of additional repeaters and interface converters, the maximum cable length, for which the correct operation of the interface is guaranteed, is no more than 2 meters.

Default connection port settings¹:

Baudrate: 9600 bit/s

Data bits: 8

Stop bits: 1

Parity: No

Hardware flow control: No

WARNING!

The modems are powered by a 5 or 12 Volt DC source, while the data line voltage is 3.3 V.

1.2 NMEA0183 Protocol standard

The NMEA0183 standard describes the format of text (ASCII) messages at the interactive level.

Sentence example: \$PUWV0,1,0*hh<CR><LF>

¹ Specified parameters can be changed by the request

Parts of a message (sentence) NMEA0183:

- '\$' - sentence start,
- 'P' - Proprietary
- 'UVW' - manufacturer identifier
- '0' - sentence identifier
- ',' - parameters separator
- '*' - checksum separator
- 'hh' - checksum in hexadecimal format (for example FF, 01). Byte-by-byte XOR for all characters between '\$' and '*'.
- <CR><LF> - end of sentence

2 UWV sentences

WARNING!

If not specified, the format of the parameters should be understood literally: 'xx' means two decimal digits, if the number is less than 10, then the left position is padded with zero: '02', '09' and not '2' and '9'.

The prefix D2H in the name of the message means that it is transmitted from the device (D) to the host system (H).

The H2D prefix in the message name means that it is transmitted from the host system (Host) to the device (Device).

2.1 Sentence IC_D2H_ACK - device reaction

Sentence format \$PUWV0,x,x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'
PUWV	UWV
0	Sentence ID
cmdID	Incoming sentence ID that caused ACK
errCode	Error code (see 4.1)
*	Checksum separator NMEA
hh	Checksum NMEA
<CR><LF>	Sentence end

2.2 IC_H2D_SETTINGS_WRITE - writing new settings

Sentence format \$PUWV1,x,x,x,x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'

PUWV	UWV
1	Sentence ID
txChID	Tx code channel ID
rxChID	Rx code channel ID
STY	Salinity, PSU
isCmdMode	'0' - command mode by pin, '1' - command mode by default (to switch back to transparent channel mode use '0')
*	Chechsum separator
hh	Checksum
<CR><LF>	Sentence end

2.3 IC_H2D_RC_REQUEST - code request to a remote subscriber

Sentence format \$PUWV2,x,x,x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'
PUWV	UWV
2	Sentence ID
txChID	Tx code channel ID
rxChID	Rx code channel ID for the request
rcCmdID	Command ID (see 4.3)
*	Chechsum separator
hh	Checksum
<CR><LF>	Sentence end

2.4 IC_D2H_RC_RESPONSE - answer of remote subscriber

Sentence format \$PUWV3,x,x.x,x.x,x.x,x.x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'

PUWV	UWV
3	Sentence ID
rcCmdID	Command ID (see 4.3)
propTime	Signal propagation time, sec
SNR	Signal to noise ratio, dB
Value	Requested value
Reserved	Reserved
*	Chechsum separator
hh	Checksum
<CR><LF>	Sentence end

2.5 IC_D2H_RC_TIMEOUT - remote subscriber timeout

Sentence format \$PUWV4,x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'
PUWV	UWV
4	Sentence ID
rcCmdID	Command ID (see 4.3)
*	Chechsum separator
hh	Checksum
<CR><LF>	Sentence end

2.6 IC_D2H_RC_ASYNC_IN - incoming message from a remote subscriber

Sentence format \$PUWV5,x,x.x,x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'
PUWV	UWV
5	Sentence ID
rcCmdID	Command ID (см.п. 4.3)

snr	Signal to noise ratio, dB
Reserved	Reserved
*	Chechsum separator
hh	Checksum
<CR><LF>	Sentence end

2.7 IC_H2D_AMB_DTA_CFG - ambient parameters and supply voltage configuration

This message configures the modem's output of the readings of the built-in pressure / temperature sensor and supply voltage. After configuration, the modem can transmit these readings using the IC_D2H_AMB_DTA message (Section 2.8)

Sentence format \$PUWV6,x,x,x,x,x,x*hh <CR><LF>	
Field/Paramter	Description
\$	Sentence start '\$'
PUWV	UWV
6	Sentence identifier
IsSaveToFlash	1 - store settings in internal Flash, 0 - do not store
PeriodMs	IC_D2H_AMB_DTA period in msec., 0 - disabled, 1 - tandem (send immediately after any outcoming message to host system), or value from 500 to 60000 (0.5 - 60 sec.)
IsPressure	1 - pressure output enabled, 0 - disabled
IsTemperature	1 - temperature oputput enabled, 0 - disabled
IsDepth	1 - depth output enabled, 0 - disabled
IsVCC	1 - supply voltage output enabled, 0 - disabled
*	Chechsum separator NMEA

hh	Chechsum NMEA
<CR><LF>	Sentence end

2.8 IC_H2D_AMB_DTA - ambient parameters and supply voltage

Sentence format \$PUWV7,x.x,x.x,x.x,x.x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'
PUWV	UWV
7	Sentence identifier
Pressure_mBar	Pressure in mBar
Temperature_C	Temperature in °C
Depth_m	Depth in meters
VCC_V	Supply voltage in Volts
*	Checksum separator NMEA
hh	Checksum NMEA
<CR><LF>	Sentence end

2.9 IC_H2D_DINFO_GET - request device information

Sentence format \$PUWV?,x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'
PUWV	UWV
?	Sentence ID
Reserved	Reserved
*	Chechsum separator
hh	Checksum
<CR><LF>	Sentence end

2.10 IC_D2H_DINFO - device information

Sentence format \$PUWV!,c--c,c--c,x,c--c,x,x.x,x,x,x*hh <CR><LF>	
Field/Parameter	Description
\$	Sentence start '\$'
PUWV	UWV
!	Sentence ID
Serial number	Device serial number
System moniker	System name
System version	System version
Core moniker	Communication subsystem
Core version	Communication subsystem version
acBaudrate	Data transmission speed, baud
rxChID	Rx code channel ID
txChID	Tx code channel ID
maxChannels	Total number of possible code channel IDs
styPSU	Water salinity, PSU (can be set by the user)
isPTS	"1" - device has a pressure/temperature sensor, "0" - otherwise
isCmdMode	"1" - command mode by default, "0" - command mode by command pin.
*	Checksum separator
hh	Checksum
<CR><LF>	Sentence end

3 Command mode

uWAVE modems provide the user with a so-called "transparent channel", when all data supplied to the input without changes and analysis are transmitted to the hydroacoustic channel, after which they are received by another modem and in unchanged form are given to the user at the receiving side. In this regard, in order to

be able to configure modems, as well as measure the propagation time to remote subscribers, there is a command mode.

Modems analyze input data only in command mode. To switch to the command mode, the “service” core should be pulled to +3.3 V. After that, the “service” core should be pulled to the ground to exit the service mode.

Also, the command mode can be enabled by default using the IC_H2D_SETTINGS_WRITE sentence, when isCmdMode parameter equals to 1. To return to control by “service” core, IC_H2D_SETTINGS_WRITE sentence can be used with isCmdMode parameter equals to 0.

WARNING!

The core "service" is pulled ONLY to 3-5 V or ground, connecting it to a higher voltage will cause a FATAL and NON-GUARANTEE failure of the device.

WARNING!

Before switching on the device, the "service" core should be pulled to the ground, otherwise the device will enter the software update mode.

4 Identifiers

4.1 Error codes

Error	Value	Description
LOC_ERR_NO_ERROR	0	Request accepted
LOC_ERR_INVALID_SYNTAX	1	Syntax error
LOC_ERR_UNSUPPORTED	2	Request not supported
LOC_ERR_TRANSMITTER_BUSY	3	Transmitter is busy
LOC_ERR_ARGUMENT_OUT_OF_RANGE	4	Speified parameter out of range
LOC_ERR_INVALID_OPERATION	5	Invalid request
LOC_ERR_UNKNOWN_FIELD_ID	6	Unknown field identifier
LOC_ERR_VALUE_UNAVAILIBLE	7	Requested parameter is not available at the moment
LOC_ERR_RECEIVER_BUSY	8	Receiver is busy (wating for a remote answer)
LOC_ERR_TX_BUFFER_OVERRUN	9	Transmitter buffer is full
LOC_ERR_CHKSUM_ERROR	10	Checksum error

4.2 Remote commands

Command	Value	Description
RC_PING	0	Ping
RC_PONG	1	Pong
RC_DPT_GET	2	Request a depth value of a remote subscriber
RC_TMP_GET	3	Request a temp. Value of a remote subscriber
RC_BAT_V_GET	4	Request a battery voltage of a remote subscriber
RC_ERR_NSUP	5	Remote subscriber answered - request not supported
RC_ACK	6	Remote subscriber answered - request accepted
RC_USR_CMD_000	7	User command
RC_USR_CMD_001	8	User command
RC_USR_CMD_002	9	User command
RC_USR_CMD_003	10	User command
RC_USR_CMD_004	11	User command
RC_USR_CMD_005	12	User command
RC_USR_CMD_006	13	User command
RC_USR_CMD_007	14	User command
RC_USR_CMD_008	15	User command