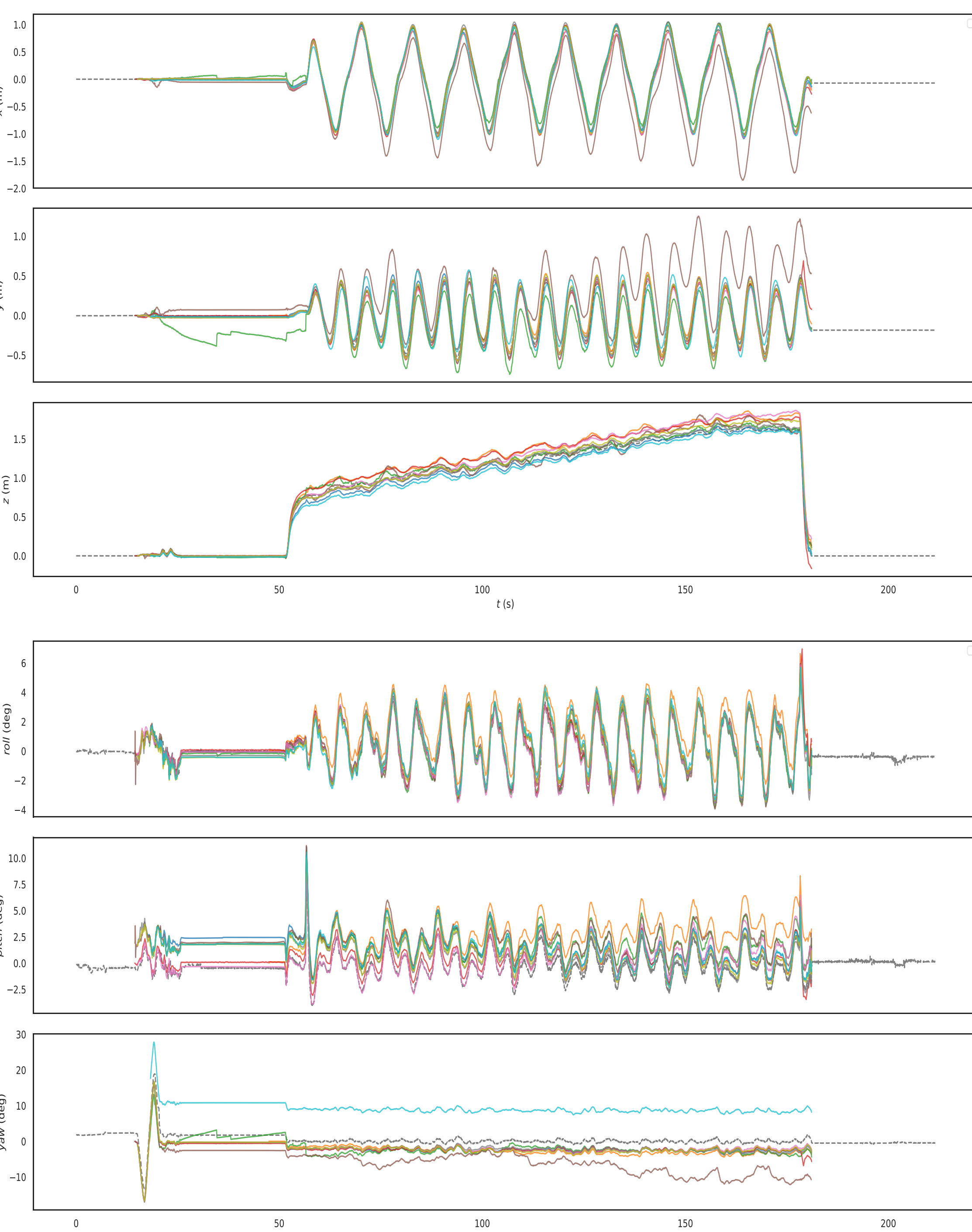
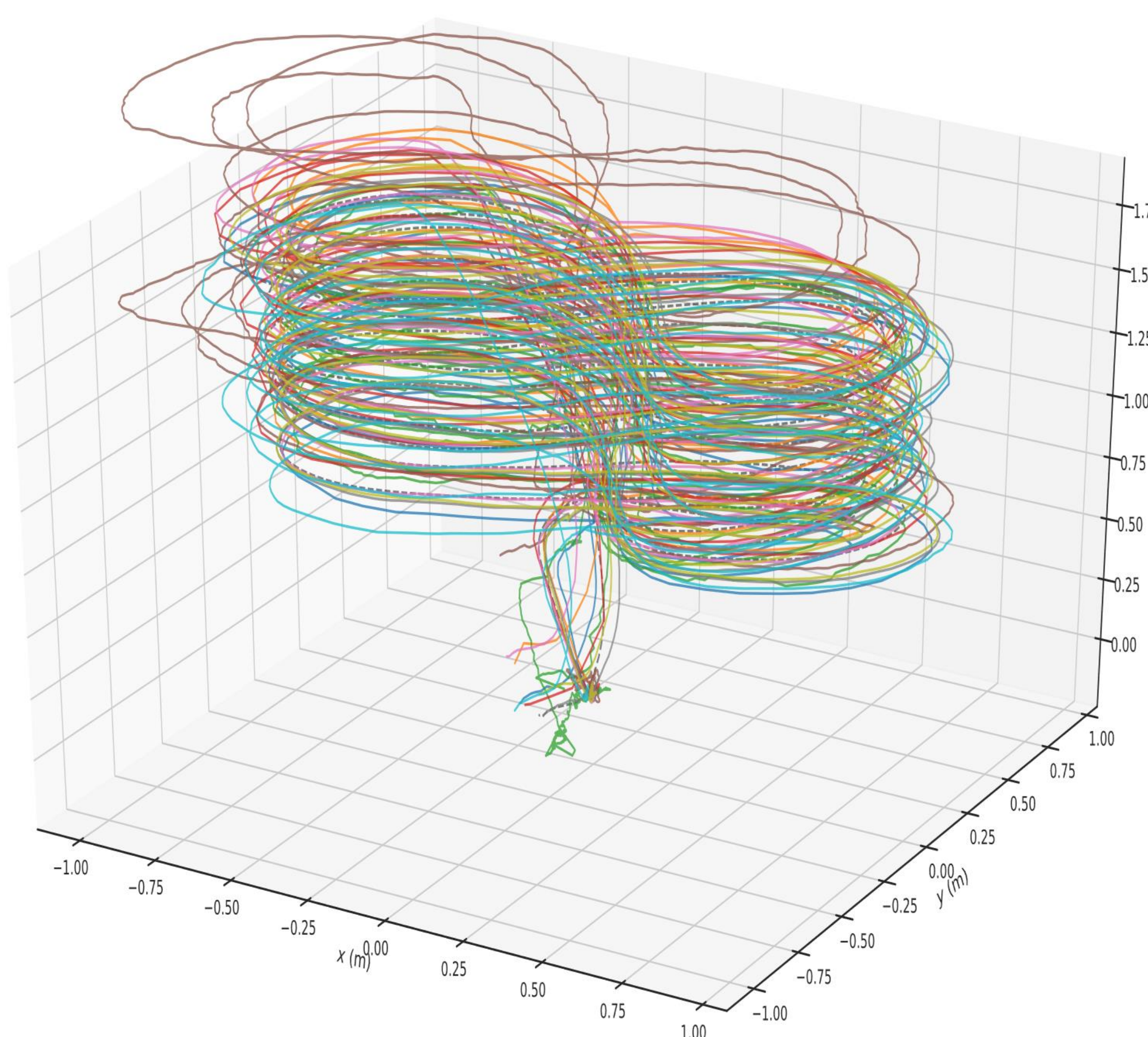
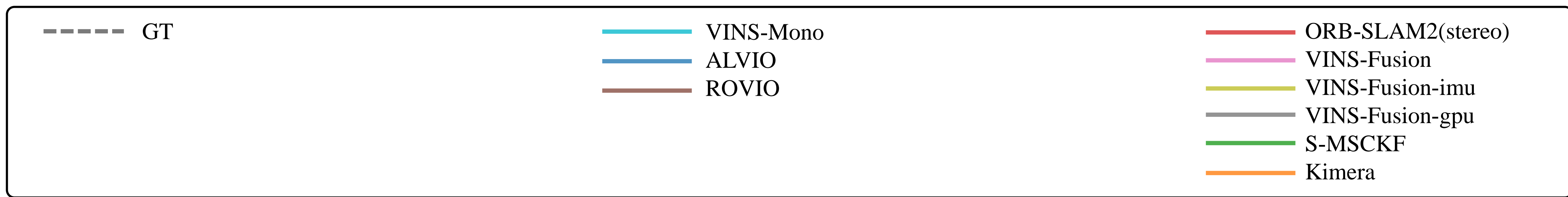


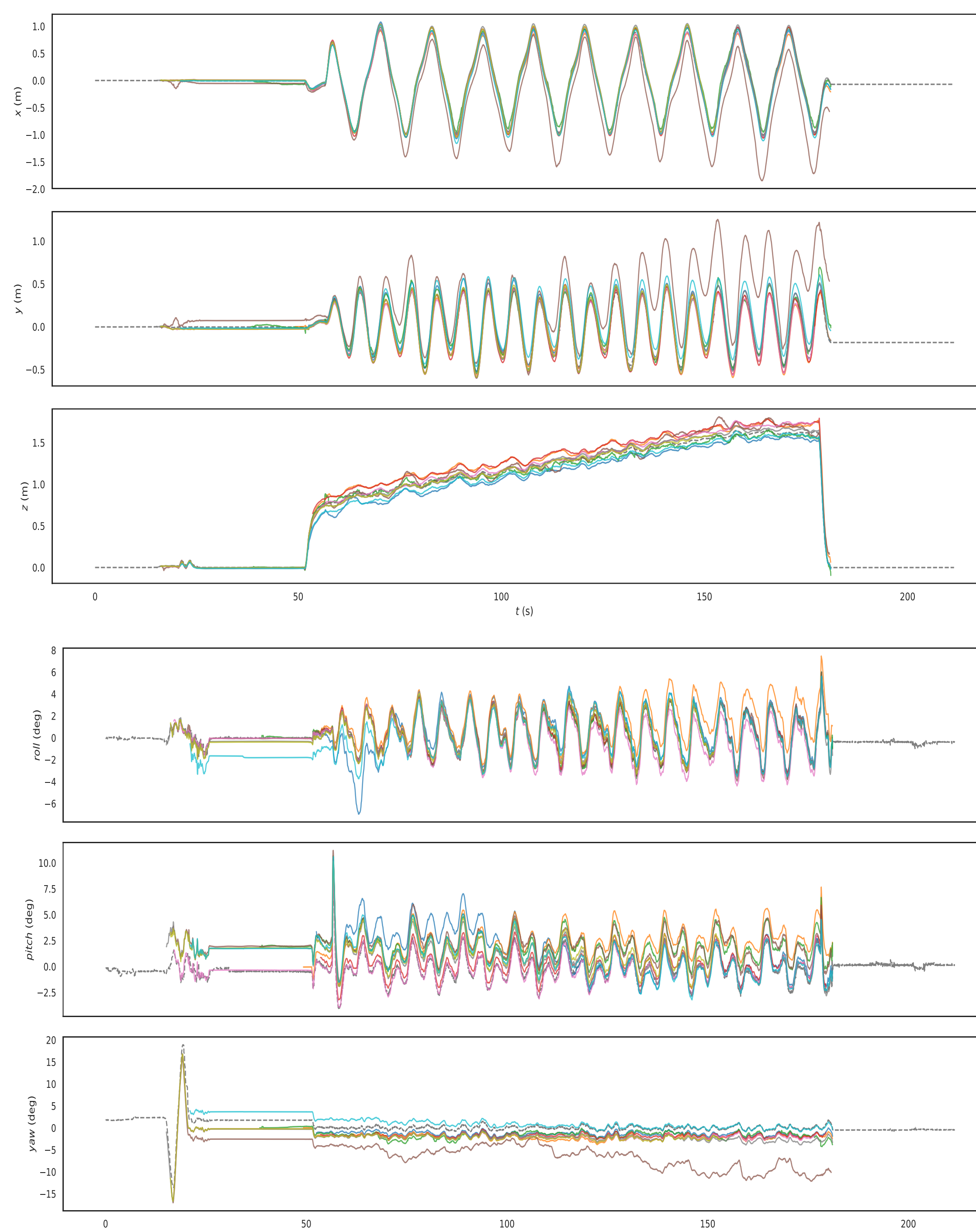
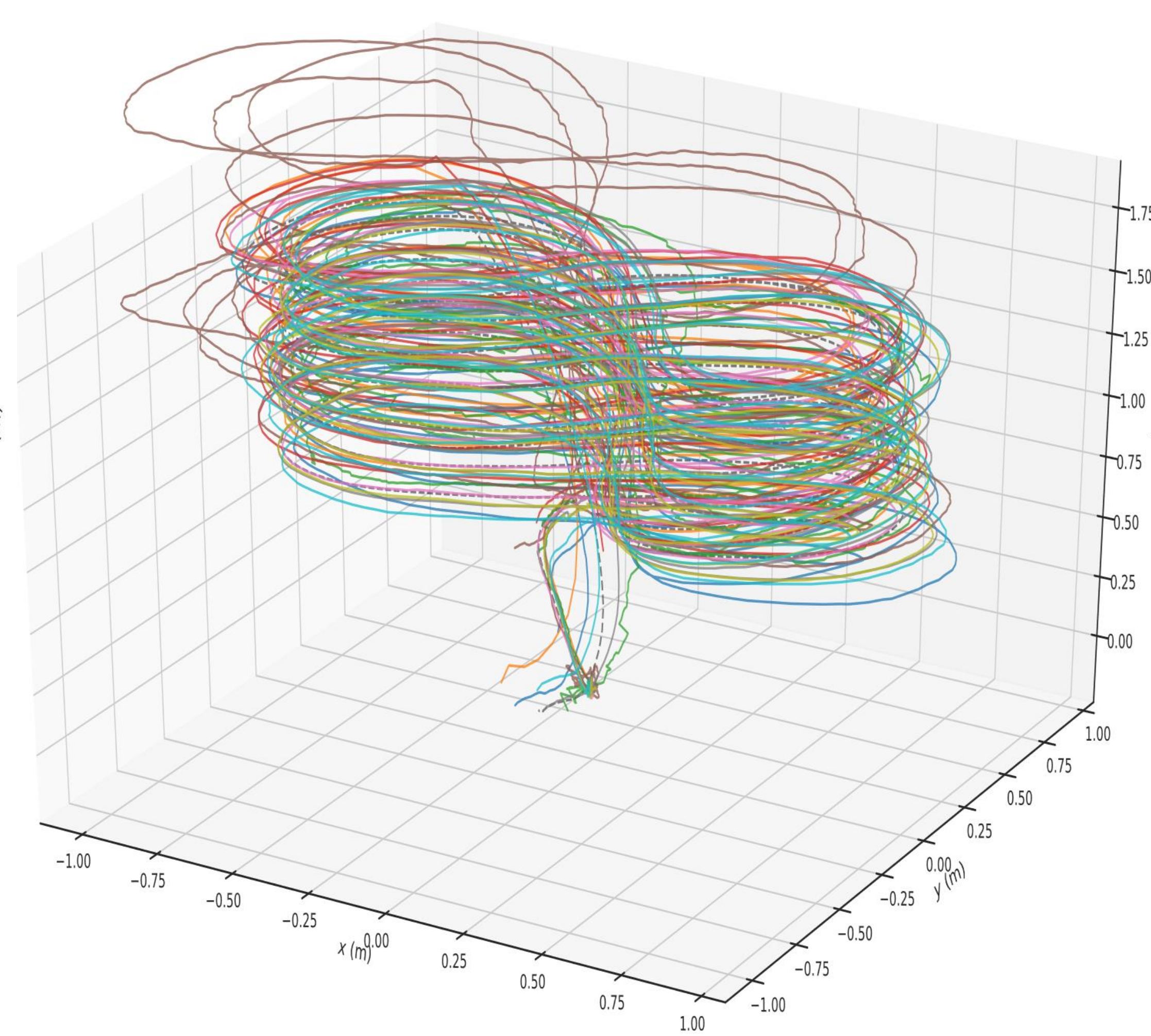
(a) TX2

trajectory view (top) / xyz view (middle) / rpy view (bottom)



(b) Xavier NX

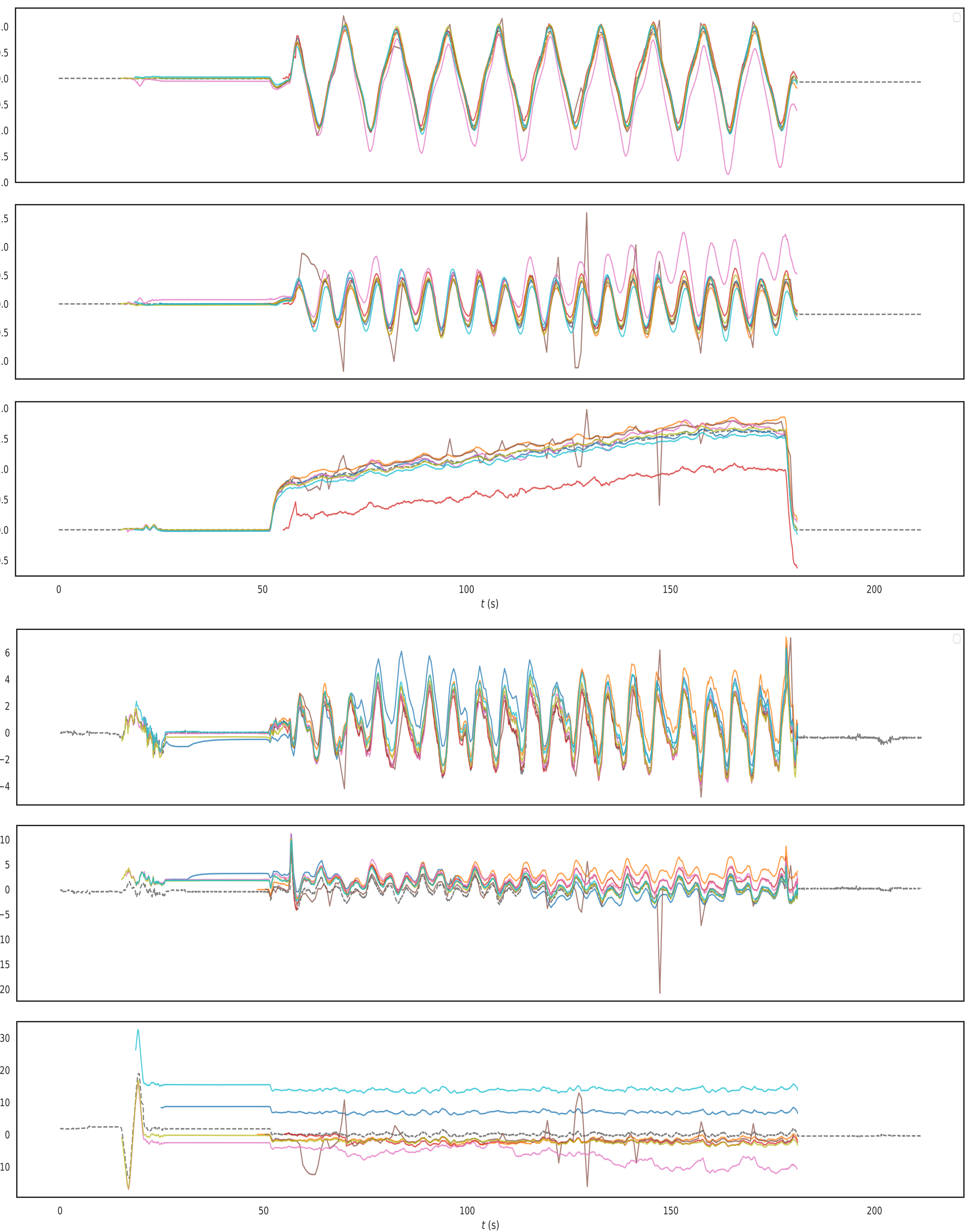
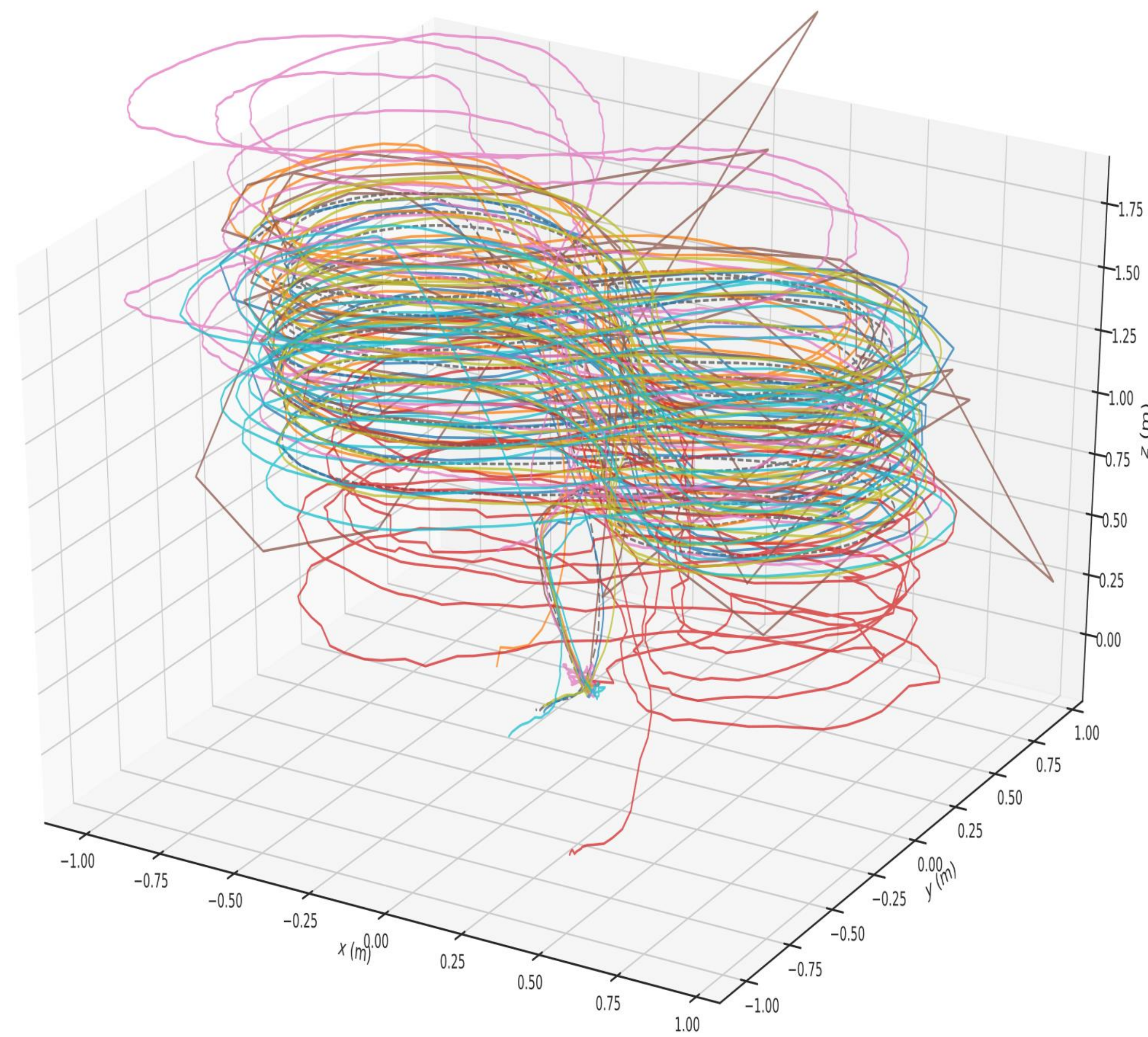
trajectory view (top) / xyz view (middle) / rpy view (bottom)



(c) Xavier

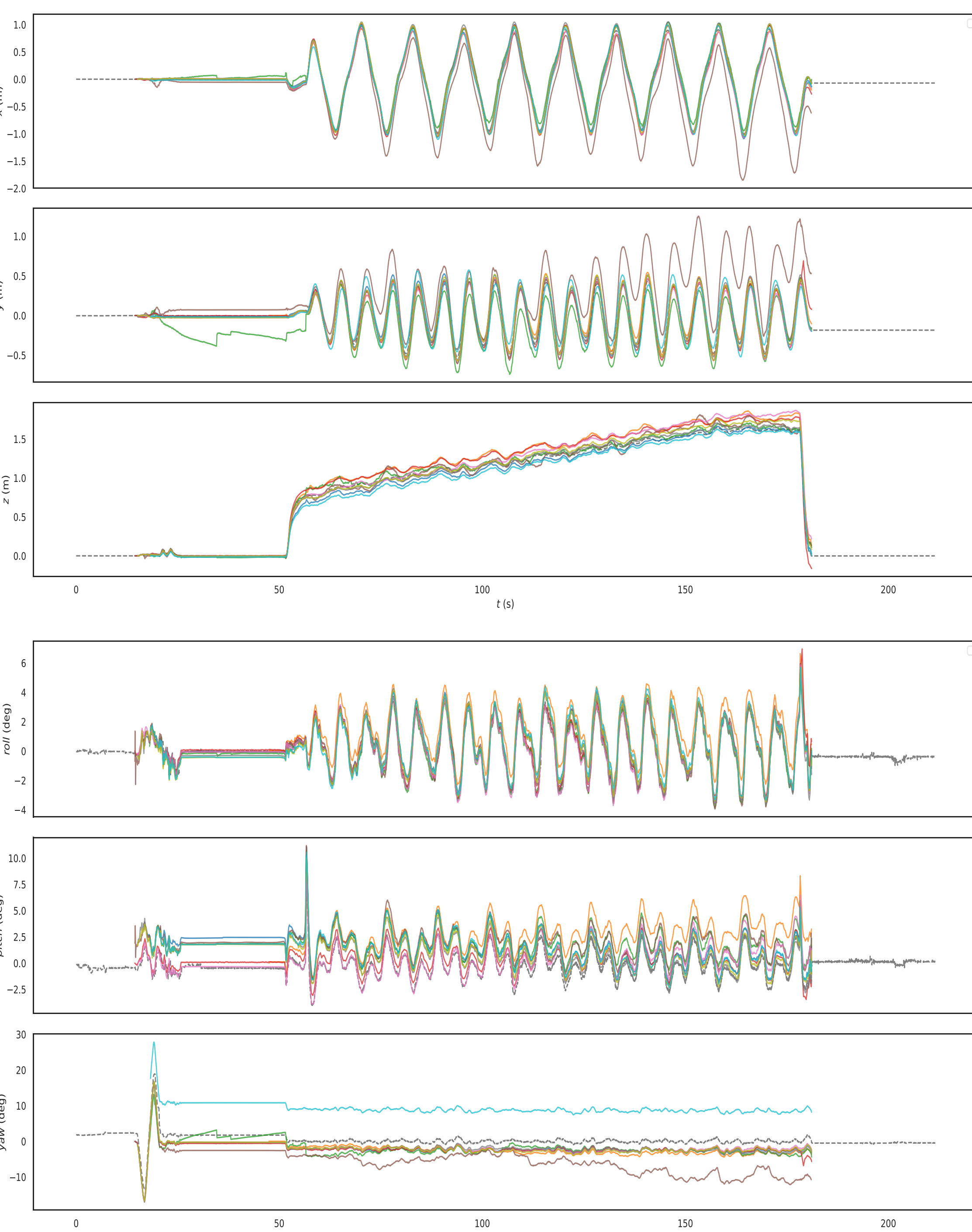
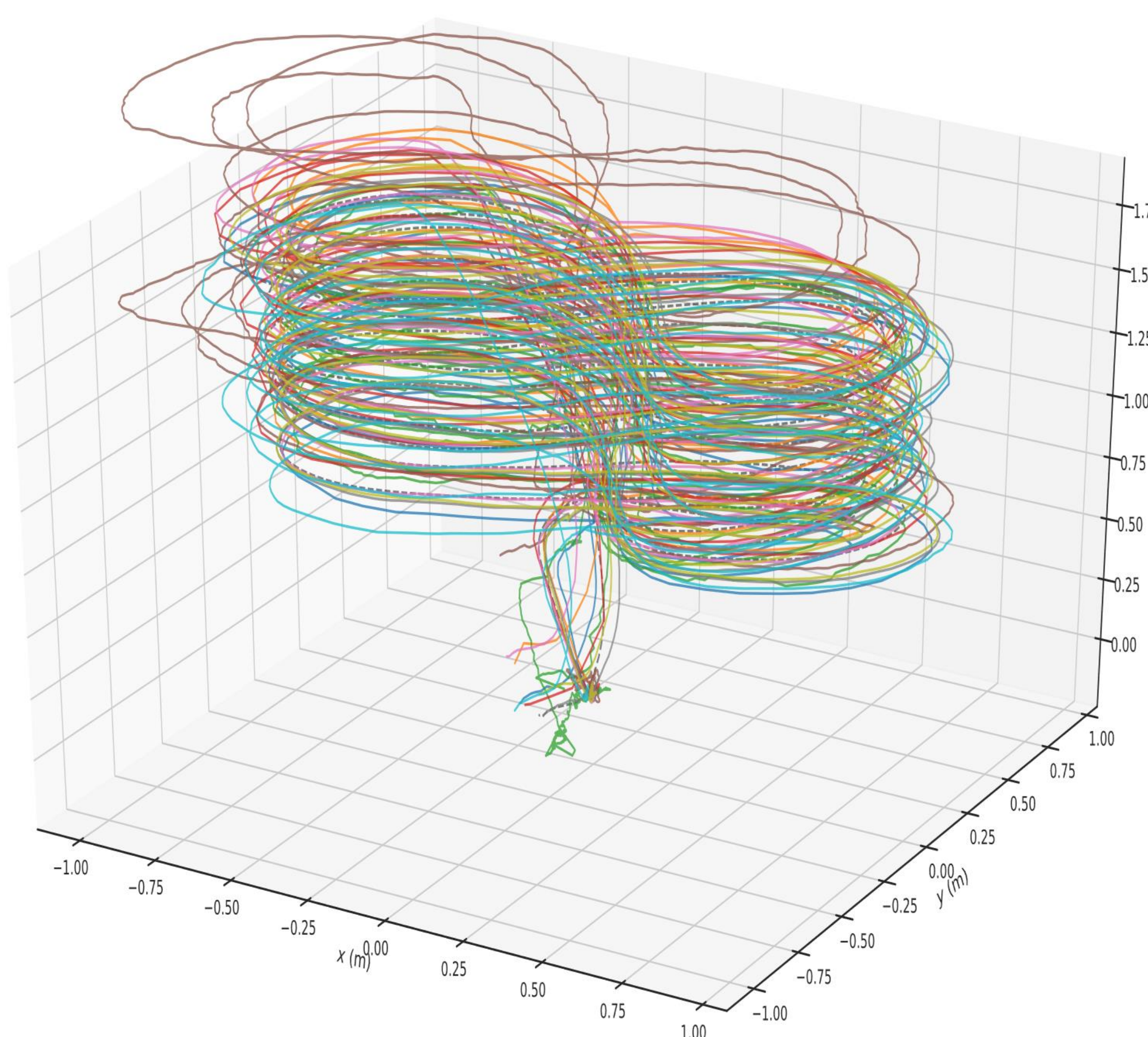
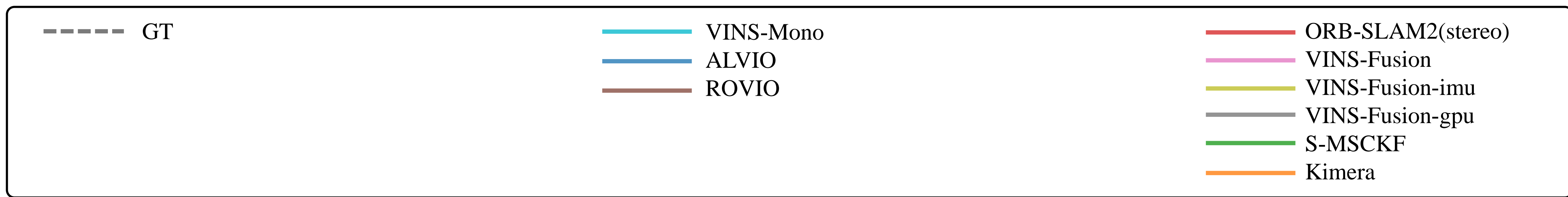
trajectory view (top) / xyz view (middle) / rpy view (bottom)





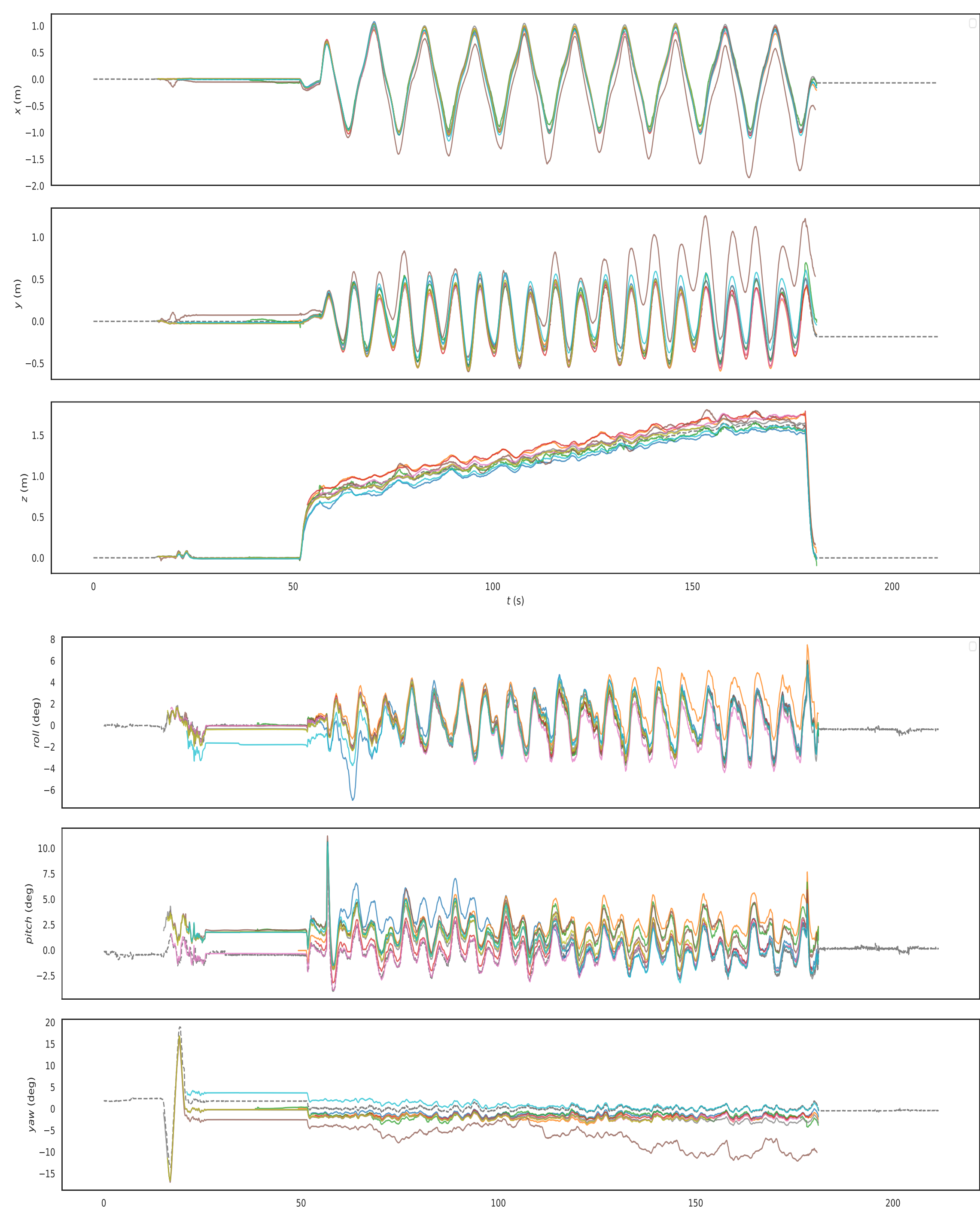
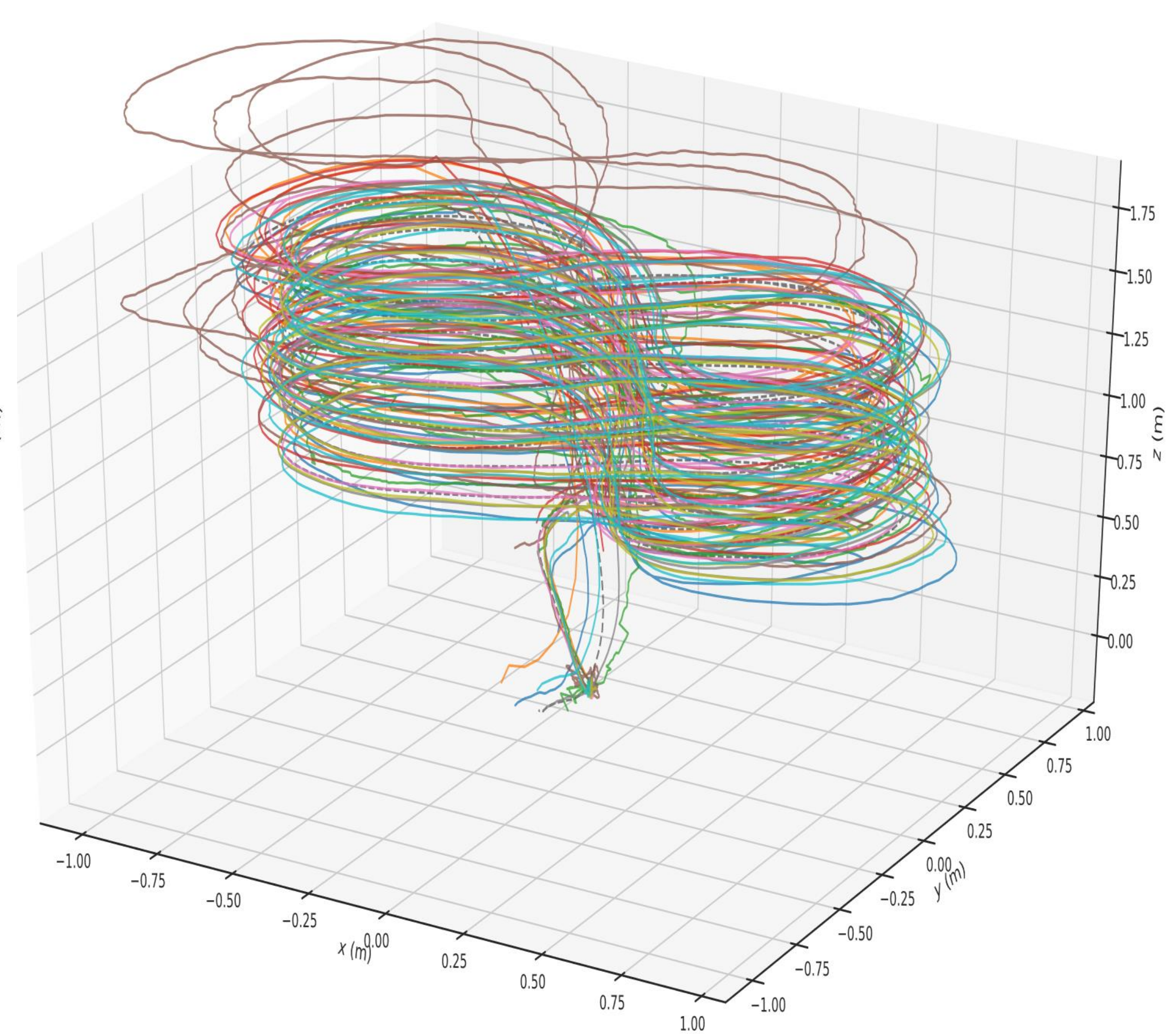
(a) TX2

trajectory view (top) / xyz view (middle) / rpy view (bottom)



(b) Xavier NX

trajectory view (top) / xyz view (middle) / rpy view (bottom)



(c) Xavier

trajectory view (top) / xyz view (middle) / rpy view (bottom)