# (Pseudo-Bayesian) Inference for Complex Survey Data

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## Thank you!

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- Christine Task (Knexus) and Gary Howarth (NIST) for keeping me in the loop over the years!
- ► To you all for your time and energy!

## Bio

#### 1. Work

- 2 years as senior research statistician at RTI: National Survey on Drug Use and Health (SAMHSA) and Model-based early estimates (NCHS)
- ▶ 10 years as mathematical statistical for federal government: USDA, HHS, NSF
- Sample design, weighting, imputation, estimation, disclosure limitation (production and methods development)

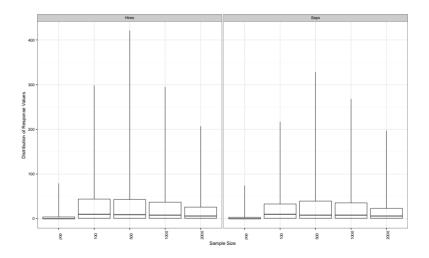
#### 2. Consulting

- International surveys for agricultural production (USAID) and vaccination knowledge, attitudes, and behaviors (UNICEF)
- 3. Research (ORCID: 0000-0001-8894-1240)
  - Constrained Optimization for Survey Applications (weight adjustment, benchmarking model estimates)
  - Applying Bayesian inference methods to data from complex surveys.
  - Bayesian synthetic data for privacy protection.

## Outline

- 1 Informative Sampling (Savitsky and Toth, 2016)
- 2 Consistency (Williams and Savitsky, 2020)
- 3 Variance Estimation
- 4 Related Works

# Distributions of ${\bf y}$ in Informative Samples



## Population Inference from Informative Samples

- ▶ Goal: perform inference about a finite population generated from an unknown model,  $\mathbb{P}_{\theta_0}(\mathbf{y})$ .
- lacktriangle Data: from under a complex sampling design distribution,  $\mathbb{P}_{
  u}(\delta)$ 
  - Probabilities of inclusion  $\pi_i = Pr(\delta_i = 1|\mathbf{y})$  are often associated with the variable of interest (purposefully)
  - Sampling designs are "informative": the balance of information in the sample ≠ balance in the population.
- ▶ Biased Estimation: estimate  $\mathbb{P}_{\theta_0}(\mathbf{y})$  without accounting for  $\mathbb{P}_{\nu}(\delta)$ .
  - Use inverse probability weights  $w_i = 1/\pi_i$  to mitigate bias.
- ► Incorrect Uncertainty Quantification:
  - Failure to account for dependence induced by  $\mathbb{P}_{\nu}(\delta)$  leads to standard errors and confidence intervals that are the wrong size.

#### Pseudo Posterior

$$p^{\pi}\left(oldsymbol{ heta}|\mathbf{y}, ilde{\mathbf{w}}
ight) \propto \left[\prod_{i=1}^{n} p\left(y_{i}|oldsymbol{ heta}
ight)^{ ilde{w}_{i}}
ight] p\left(oldsymbol{ heta}
ight) \ rac{w_{i}}{w_{i}} := rac{1}{\pi_{i}} \ rac{ ilde{w}_{i}}{\sum_{i=1}^{n} w_{i}}, \ i = 1, \ldots, n$$

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# Frequentist Consistency of a (Pseudo) Posterior

- Estimated distribution  $p^{\pi}(\boldsymbol{\theta}|\mathbf{y}, \tilde{\mathbf{w}})$  collapses around generating parameter  $\theta_0$  with increasing population  $N_{\nu}$  and sample  $n_{\nu}$  sizes.
  - Evaluated with respect to joint distribution of population generation  $\mathbb{P}_{\theta_0}(\mathbf{y})$  and the sample inclusion indicators  $\mathbb{P}_{\nu}(\delta)$ .
- ightharpoonup Conditions on the model  $\mathbb{P}_{\theta_0}(\mathbf{y})$  (standard)
  - Complexity of the model limited by sample size
  - Prior distribution not too restrictive (e.g. point mass)
- lacktriangle Conditions on the sampling design  $\mathbb{P}_{
  u}(\delta)$  (new-ish)
  - Every unit in population has non-zero probability of inclusion finite weights
  - ▶ Dependence restricted to countable blocks of bounded size ⇒ arbitrary dependence within clusters, but approximate independence between clusters.

# Simulation Example: Three-Stage Sample

Area (PPS), Household (Systematic, sorting by Size), Individual (PPS)

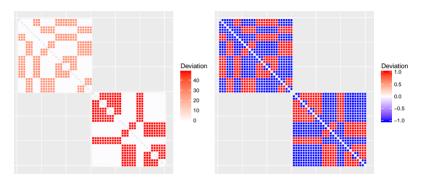


Figure: Factorization matrix  $(\pi_{ij}/(\pi_i\pi_j)-1)$  for two PSU's. Magnitude (left) and Sign (right). Systematic Sampling  $(\pi_{ij}=0)$ . Clustering and PPS sampling  $(\pi_{ij}>\pi_i\pi_j)$ . Independent first stage sample  $(\pi_{ij}=\pi_i\pi_j)$ 

# Simulation Example: Three-Stage Sample (Cont)

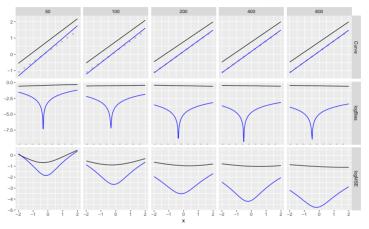


Figure: The marginal estimate of  $\mu = f(x_1)$ . population curve, sample with equal weights, and inverse probability weights. Top to bottom: estimated curve, log of BIAS, log MSE. Left to right: sample size (50 to 800).

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#### Variance Estimation

- ► The de-facto approach:
  - ▶ approximate sampling independence of the primary sampling units (Heeringa et al., 2010).
  - within-cluster dependence treated as nuisance
- ► Two common methods:
  - ► Taylor linearization and replication based methods.
  - A variety of implementations are available (Binder, 1996; Rao et al., 1992).

# **Taylor Linearization**

Let  $y_{ij}$  and  $w_{ij}$  be the observed data for individual i in cluster j of the sample. Assume the parameter  $\theta$  is a vector of dimension d with population model value  $\theta_0$ .

- 1. Approximate an estimate  $\hat{\theta}$ , or a 'residual'  $(\hat{\theta} \theta_0)$ , as a weighted sum:  $\hat{\theta} \approx \sum_{i,j} w_{ij} z_{ij}(\theta)$  where  $z_{ij}$  is a function evaluated at the current values of  $y_{ij}$ , and  $\hat{\theta}$  (e.g.  $z_i(\hat{\theta}) = H_{\theta_0}^{-1} \dot{\ell}_{\hat{\theta}}(\mathbf{y}_i)$ ).
- 2. Compute the weighted components for each cluster (e.g., primary sampling units (PSUs)):  $\hat{\theta}_j = \sum_i w_{ij} z_{ij}(\theta)$ .
- 3. Compute the variance between clusters:

$$\widehat{Var(\hat{ heta})} = rac{1}{J-d} \sum_{j=1}^{J} (\hat{ heta} - \hat{ heta}_j) (\hat{ heta} - \hat{ heta}_j)^T$$

4. For stratified designs, compute  $\hat{\theta}_s$  and  $\widehat{Var}(\hat{\theta}_s)$  within strata and sum  $\widehat{Var}(\hat{\theta}) = \sum_s \widehat{Var}(\hat{\theta}_s)$ .

# Replication

Let  $y_{ij}$  and  $w_{ij}$  be the observed data for individual i in cluster j of the sample. Assume the parameter  $\theta$  is a vector of dimension d with population model value  $\theta_0$ .

- 1. Through randomization (bootstrap), leave-one-out (jackknife), or orthogonal contrasts (balanced repeated replicates), create a set of K replicate weights  $(w_i)_k$  for all  $i \in S$  and for every  $k = 1, \ldots, K$ .
- 2. Each set of weights has a modified value (usually 0) for a subset of clusters, and typically has a weight adjustment to the other clusters to compensate:  $\sum_{i \in S} (w_i)_k = \sum_{i \in S} w_i$  for every k.
- 3. Estimate  $\hat{\theta}_k$  for each replicate  $k \in 1, ..., K$ .
- 4. Compute the variance between replicates:  $\widehat{Var(\hat{\theta})} = \frac{C}{K-d} \sum_{k=1}^{K} (\hat{\theta} \hat{\theta}_k) (\hat{\theta} \hat{\theta}_k)^T.$
- 5. For stratified designs, generate replicates such that each strata is represented in every replicate.

## Challenges

There are two notable trade-offs associated with these methods:

- ► Taylor linearization: value  $\hat{\theta}$  computed once then used in a plug in for  $z_i(\theta)$ .
  - ▶ Replication methods: estimate  $\hat{\theta}_k$  computed K times.
  - Sizable differences in computational effort
- Replication methods: no derivatives are needed.
  - ► Taylor linearization: requires the calculation of a gradient to derive the analytical form of the first order approximation  $z_i(\theta)$ .
  - This poses significant analytical challenges for all but the simplest models.

## Some Improvements

- Abstraction of Derivatives (less analytic work for Taylor Linearization)
  - ► Recent advances in algorithmic differentiation (Margossian, 2018), allows us to specify the model as a log density but only treat the gradient in the abstract without specifying it analytically.
  - ► Implemented in Stan and Rstan (Carpenter, 2015; Stan Development Team, 2016)
- ► Hybrid Approach or Taylor Linearization for replicate designs (less computation for Replication approaches)
  - Survey package (Lumley, 2016) to calculate replication variance of gradient  $\dot{\ell}_{\theta}$
  - Use plug in for  $\theta$ , only estimate once

$$(\hat{\psi} - \psi_0) = H_{\theta_0}(\hat{\theta} - \theta_0) \approx \sum_{i \in S} w_i \dot{\ell}_{\hat{\theta}}(\mathbf{y}_i) = \sum_{i \in S} w_i z_i(\hat{\theta}),$$

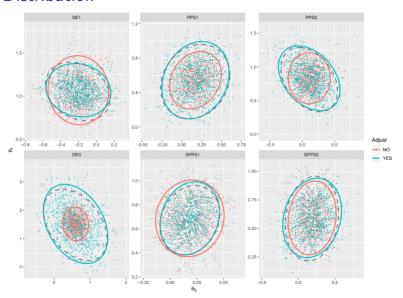
with 
$$\operatorname{Var}_{P_{\theta_0},P_{\nu}}(\hat{\psi}-\psi_0)=J_{\theta_0}^{\pi}$$
.

# Example: Design Effect for Survey-Weighted Bayes

$$p^{\pi}\left(oldsymbol{ heta}|\mathbf{y}, \mathbf{ ilde{w}}
ight) \propto \left[\prod_{i=1}^{n} p\left(y_{i}|oldsymbol{ heta}
ight)^{ ilde{w}_{i}}
ight] p\left(oldsymbol{ heta}
ight)$$

- ► Variances Differ:
  - Weighted MLE:  $H_{\theta_0}^{-1}J_{\theta_0}^{\pi}H_{\theta_0}^{-1}$  (Robust)
  - Weighted Posterior:  $H_{\theta_0}^{-1}$  (Model-Based)
- ► Adjust for Design Effect:  $R_2^{-1}R_1$ 
  - $lackbox{}\hat{ heta}_m \equiv$  sample pseudo posterior for  $m=1,\ldots,M$  draws with mean  $ar{ heta}$
  - $\hat{\theta}_m^a = \left(\hat{\theta}_m \bar{\theta}\right) R_2^{-1} R_1 + \bar{\theta}$
  - where  $R'_1 R_1 = H_{\theta_0}^{-1} J_{\theta_0}^{\pi} H_{\theta_0}^{-1}$
  - $ightharpoonup R_2'R_2 = H_{\theta_0}^{-1}$

## Joint Distribution



# Related Papers

- Consistency of the Pseudo-Posterior (Savitsky and Toth, 2016)
- Uncertainty Quantification (Williams and Savitsky, 2021)
- Extension to multistage surveys (Williams and Savitsky, 2020; Han and Wellner, 2021)
- Extension to pairwise weights and outcomes (Williams and Savitsky, 2018)
- Extension to Divide and Conquer computational methods (Savitsky and Srivastava, 2018)
- Correction of asymptotic coverage (Williams and Savitsky, 2021)
- Joint modeling of Outcome and Weights (León-Novelo and Savitsky, 2019; Leon-Novelo and Savitsky, 2021)

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