

COZMO VS COZMO TIC-TAC-TOE

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ABOUT

- This project consists of two cozmos that play each other in a game of tic-tac-toe
- Our cosmos use:
 - **Markers** to orient themselves and map the board
 - **Parameterized AI** to plan moves
 - **Optimized path planner** to used to move chips
 - **Communication** over wifi

DIFFICULTIES

- Path planning to the intended location with the chips
- Specifically:
 - The marker's orientation was not reliable, so positions were not reliable.
 - Path planner did not account for objects being pushed.
 - Limited communication capability - cannot share world maps.



INTERESTING SOLUTIONS

- Standardizing playing field
 - initial chip positions
 - start pose
- Self-correcting chip locations
- Using wifi connection to synchronize world-maps. Cozmos wait on each other for new:
 - states of the board (moves made)
 - corrections



FURTHER WORK

- Using computer vision to detect and avoid chips
- Shared world map
- Path planner that places objects in the correct position
- More landmarks for accurate positions and orientations
- Non-standardized board