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CPE 301-1001  
Lab #7  
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## **Assignment Description:**

In this lab we were to learn how to use serial communication and timers to control the input to a speaker. We were supposed to generate frequencies of different notes using this speaker. We could get extra credit if we did the sharp (#) frequencies as well.

## **Problems Encountered:**

My one problem was easily solved by fixing the address I was writing data port b to. I had it set wrong, but somehow I could still faintly hear out of the speaker. After some debugging and help from the lab TAs we diagnosed the simple issue.

## **Lessons Learned:**

I for some reason did not know how simple it was to make a speaker play a sound. I don't claim to know how that speaker was built, but I didn't know it was as simple as running a certain frequency through a wire directly to the speaker. It was interesting to learn how this is done.

# Description of Completed Lab: (compiled code below)

```
ANSI-C_Lab_7

volatile unsigned char *myTCCR1A = (unsigned char *) 0x80; // Timer/Counter Control Register A
volatile unsigned char *myTCCR1B = (unsigned char *) 0x81; // Timer/Counter Control Register B
volatile unsigned char *myTCCR1C = (unsigned char *) 0x82; // Timer/Counter Control Register C
volatile unsigned char *myTIMSK1 = (unsigned char *) 0x6F; // Timer/Counter Interrupt Mask Register
volatile unsigned int *myTCNT1 = (unsigned int *) 0x84; // Timer/Counter Count Register (low & high)
volatile unsigned char *myTIFR1 = (unsigned char *) 0x36; // Timer/Counter Interrupt Flag Register
volatile unsigned char *portDDRB = (unsigned char *) 0x24;
volatile unsigned char *portB = (unsigned char *) 0x25;
volatile byte byteRead = 0;

void myDelayFor(int);

void setup() {
    /* Initialize Timer1 for NORMAL mode */
    *myTCCR1A = 0;
    *myTCCR1B = 0;
    *myTCCR1C = 0;
    *myTIMSK1 = 0; // Timer 1 should have no interrupts

    *portDDRB |= 0x40; // Initialize GPIO PortB as output

    Serial.begin(115200);
}

// the loop function runs over and over again forever
void loop() {

    /* check if data has been sent from the computer: */
    if (Serial.available()) {
        /* read the most recent byte */
        byteRead = Serial.read();
    }

    switch(byteRead) {
        case 'a':
            myDelayFor(18182);
            break;
        case 'A':
            myDelayFor(17167); // A#
            break;
        case 'b':
            myDelayFor(16194);
            break;
        case 'c':
            myDelayFor(15296);
            break;
        case 'C':
            myDelayFor(14440); // C#
            break;
        case 'd':
            myDelayFor(13629);
            break;
        case 'D':
            myDelayFor(12821); // D#
            break;
        case 'e':
            myDelayFor(12140);
            break;
        case 'f':
            myDelayFor(11461);
            break;
        case 'F':
            myDelayFor(10811); // F#
            break;
        case 'g':
            myDelayFor(10204);
            break;
        case 'G':
            myDelayFor(9627); // G#
            break;
        default:
            Serial.write(byteRead);
            myDelayFor(18182);
    }
}

void myDelayFor(int numTicks) {
    *myTCCR1B &= 0xF8; // turn timer to OFF
    *myTCNT1 = (unsigned int) (65536 - numTicks); // for A
    *myTCCR1B |= 0x01; // turn timer ON with prescaler of 1
    while(!(*myTIFR1 & 0x01)); // once overflow flag is 1, we will stop
    *myTCCR1B &= 0xF8; // turn timer to OFF (prof. Egbert says this is optional)
    *myTIFR1 |= 0x01; // clear overflow flag bit (by setting to 1 for some reason)

    *portB ^= 0x40;
}
```

Basically to achieve what the lab was asking for I had to create a timer function, pass into that function the amount of ticks to subtract from 65536 for the timer, then run a loop to see if anything changed in the serial communication. In my setup() i just set up the timer in normal mode and started the Serial at a baud of 115200 (I could have used 9600 but a TA had me change it). I also initialized the Port B as output. Then I could use the loop() to read the byte from the serial terminal. Once that byte was read I could use it in the switch statement to decide what frequency I had to generate.

I used a pre-scalar of 1 as suggested by Frank in the lab because that way I didn't have to change the math for each frequency I wanted to generate.

My circuit was simply the arduino portB pin 6 hooked up to a resistor then alligator clips to a speaker. Of course that speaker was grounded as well, to finish the circuit.