# Distributed Systems Principles and Paradigms

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## Chapter 01: Introduction

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## Distributed System: Definition A distributed system is a collection of autonomous computing elements that appears to its users as a single coherent system Two aspects: (1) independent computing elements and (2) single system $\Rightarrow$ middleware. Same interface everywhere Computer 1 Computer 2 Computer 3 Computer 4 Appl. A Application B Appl. C Distributed-system layer (middleware) Local OS 2 Network

Introduction 1.2 Goals	Introduction 1.2 Goals
Goals of Distributed Systems	
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Making resources available	
Distribution transparency	
<ul><li>Openness</li></ul>	
Scalability	
Godiability	

#### Distribution transparency Transp. Description Hide differences in data representation and how an Access object is accessed Location Hide where an object is located Relocation Hide that an object may be moved to another location while in use Migration Hide that an object may move to another location Replication Hide that an object is replicated Hide that an object may be shared by several Concurrency independent users Failure Hide the failure and recovery of an object Distribution transparency is a nice a goal, but achieving it is a different story.

Introduction 1.2 Goals

Degree of transparency

Light Space of transparency

Light Space of transparency

Observation
Aiming at full distribution transparency may be too much:

• Users may be located in different continents

Languages

- Completely hiding failures of networks and nodes is (theoretically and practically) impossible
  - You cannot distinguish a slow computer from a failing one
  - You can never be sure that a server actually performed an operation before a crash
- Full transparency will cost performance, exposing distribution of the system
  - Keeping Web caches exactly up-to-date with the master
  - Immediately flushing write operations to disk for fault tolerance

Introduction 1.2 Goals	Introduction 1.2 Goals
Openness of distributed systems	
Open distributed system	
Be able to interact with services from other open systems, irrespective	
of the underlying environment:	
Systems should conform to well-defined interfaces	
Systems should support portability of applications	
Systems should easily interoperate	
Achieving openness	
At least make the distributed system independent from heterogeneity	
of the underlying environment:	
Hardware	
Platforms	

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Introduction 1.2 Goals	Introduction 1.2 Goals
Policies versus mechanisms	
Implementing openness	
Requires support for different policies:	
What level of consistency do we require for client-cached data?	
Which operations do we allow downloaded code to perform?	
Which QoS requirements do we adjust in the face of varying bandwidth?	
What level of secrecy do we require for communication?	
Involve of the second	
Implementing openness	
Ideally, a distributed system provides only mechanisms:	
Allow (dynamic) setting of caching policies	
Support different levels of trust for mobile code	
Provide adjustable QoS parameters per data stream	
Offer different encryption algorithms	
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Scale in distributed systems	<u> </u>
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Observation	
Many developers of modern distributed system easily use the adjective "scalable" without making clear why their system actually scales.	
Scalability	
At least three components:	
<ul> <li>Number of users and/or processes (size scalability)</li> </ul>	
Maximum distance between nodes (geographical scalability)	
Number of administrative domains (administrative scalability)	
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Observation	
Most systems account only, to a certain extent, for size scalability. The (non)solution: powerful servers. Today, the challenge lies in geographical and administrative scalability.	

Introduction 1.2 Goals	Introduction 1.2 Goals
Techniques for scaling	
Hide communication latencies	_
Avoid waiting for responses; do something else:	
Make use of asynchronous communication	
<ul> <li>Have separate handler for incoming response</li> <li>Problem: not every application fits this model</li> </ul>	
Problem. Not every application his this model	

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Introduction 1.2 Goals	Introduction 1.2 Goals
Techniques for scaling	
Distribution	
Partition data and computations across multiple machines:	
<ul> <li>Move computations to clients (Java applets)</li> <li>Decentralized naming services (DNS)</li> </ul>	
Decentralized information systems (WWW)	
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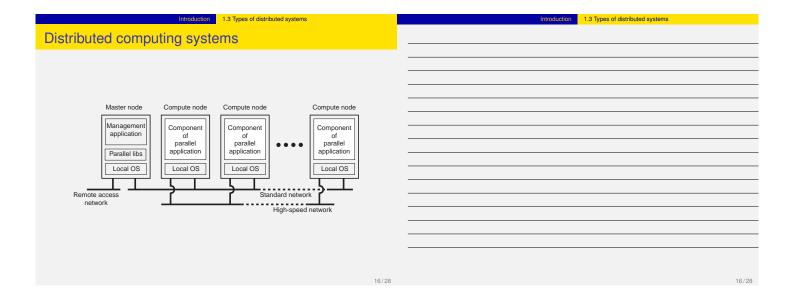
Introduction 1.2 Goals	Introduction 1.2 Goals
Techniques for scaling	
Replication/caching	
Make copies of data available at different machines:	
Replicated file servers and databases	
Mirrored Web sites	
Web caches (in browsers and proxies)	
File caching (at server and client)	

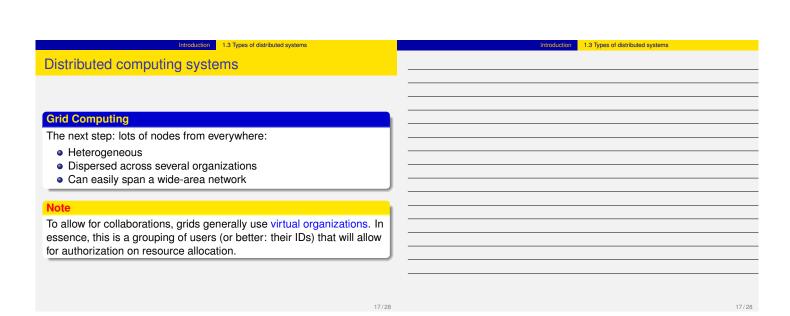
Introduction 1.2 Goals	Introduction 1.2 Goals
Scaling – The problem	
Observation	
Applying scaling techniques is easy, except for one thing:	
<ul> <li>Having multiple copies (cached or replicated), leads to inconsistencies: modifying one copy makes that copy different from the rest.</li> <li>Always keeping copies consistent and in a general way requires global synchronization on each modification.</li> <li>Global synchronization precludes large-scale solutions.</li> </ul>	
Observation	
If we can tolerate inconsistencies, we may reduce the need for global synchronization, but tolerating inconsistencies is application dependent.	
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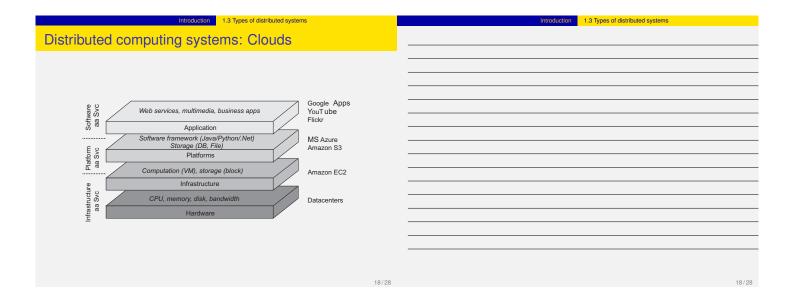
Introduction 1.2 Goals	Introduction 1.2 Goals
Developing distributed systems: Pitfalls	
Developing distributed systems: Pitfalls  Observation  Many distributed systems are needlessly complex caused by mistakes that required patching later on. There are many false assumptions:  The network is reliable The network is secure The network is homogeneous The topology does not change Latency is zero Bandwidth is infinite Transport cost is zero	
There is one administrator	
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Introduction 1.3 Types of distributed systems	Introduction 1.3 Types of distributed systems
Types of distributed systems	
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<ul> <li>Distributed computing systems</li> </ul>	
<ul> <li>Distributed information systems</li> </ul>	
Distributed pervasive systems	
Distributed pervasive systems	
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Introduction 1.3 Types of distributed systems	Introduction 1.3 Types of distributed systems
Distributed computing systems	·
Distributed computing systems	
Observation	
Many distributed systems are configured for High-Performance	
Computing	
Cluster Computing	<u> </u>
Essentially a group of high-end systems connected through a LAN:	
Homogeneous: same OS, near-identical hardware	
Single managing node	
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Introduction 1.3 Types of distributed systems	Introduction 1.3 Types of distributed systems
Distributed computing systems: Clouds	
Cloud computing	
Make a distinction between four layers:	
<ul> <li>Hardware: Processors, routers, power and cooling systems.         Customers normally never get to see these.</li> <li>Infrastructure: Deploys virtualization techniques. Evolves around allocating and managing virtual storage devices and virtual servers.</li> <li>Platform: Provides higher-level abstractions for storage and such. Example: Amazon S3 storage system offers an API for (locally created) files to be organized and stored in so-called buckets.</li> <li>Application: Actual applications, such as office suites (text processors, spreadsheet applications, presentation applications). Comparable to the suite of apps shipped with OSes.</li> </ul>	

Introduction 1.3 Types of distributed systems	Introduction 1.3 Types of distributed systems
Distributed Information Systems	<mark> </mark>
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Observation	h
The vast amount of distributed systems in use today are forms of	
traditional information systems, that now integrate legacy systems.	
Example: Transaction processing systems.	
Example: Transaction processing systems.	)
BEGIN_TRANSACTION(server, transaction)	
READ(transaction, file-1, data)	
<pre>WRITE(transaction, file-2, data) newData := MODIFIED(data)</pre>	
IF WRONG (newData) THEN ABORT_TRANSACTION (transaction)	
ELSE	
<pre>WRITE(transaction, file-2, newData) END_TRANSACTION(transaction)</pre>	
END IF	
	-

Transactions form an atomic operation.

Distributed information systems: Transactions

Model

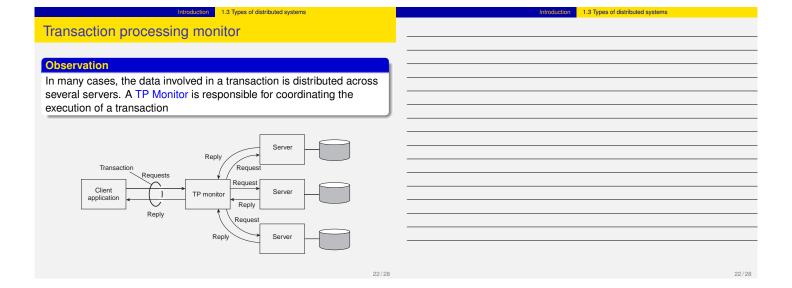
A transaction is a collection of operations on the state of an object (database, object composition, etc.) that satisfies the following properties (ACID)

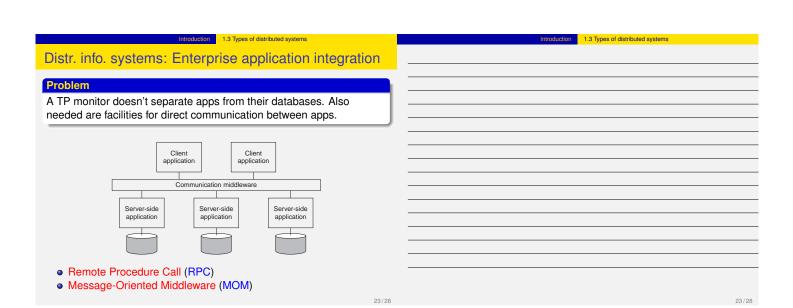
Atomicity: All operations either succeed, or all of them fail. When the transaction fails, the state of the object will remain unaffected by the transaction.

Consistency: A transaction establishes a valid state transition. This does not exclude the possibility of invalid, intermediate states during the transaction's execution.

Isolation: Concurrent transactions do not interfere with each other. It appears to each transaction T that other transactions occur either before T, or after T, but never both.

Durability: After the execution of a transaction, its effects are made permanent: changes to the state survive failures.





Introduction 1.3 Types of distributed systems	Introduction 1.3 Types of distributed systems
Distributed pervasive systems	
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Observation	
Emerging next-generation of distributed systems in which nodes are	
small, mobile, and often embedded in a larger system, characterized	
by the fact that the system naturally blends into the user's environment.	
Three (overlapping) subtypes	
<ul> <li>Ubiquitous computing systems: pervasive and continuously</li> </ul>	
present, i.e., there is a continous interaction between system and	
user.	
Mobile computing systems: pervasive, but emphasis is on the fact	<u>-</u>
that devices are inherently mobile.	
Sensor (and actuator) networks: pervasive, with emphasis on the	
actual (collaborative) sensing and actuation of the environment.	
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introduction 1.3 types of distributed systems	introduction 1.3 types of distributed systems
Ubiquitous computing systems	
Basic characteristics	
(Distribution) Devices are networked, distributed, and accessible	
in a transparent manner	
(Interaction) Interaction between users and devices is highly	
unobtrusive	
(Context awareness) The system is aware of a user's context in	
order to optimize interaction	
(Autonomy) Devices operate autonomously without human	
intervention, and are thus highly self-managed	
(Intelligence) The system as a whole can handle a wide range of	
dynamic actions and interactions	
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Mobile computing systems	
Observation	
Mobile computing systems are generally a subclass of ubiquitous	
computing systems and meet all of the five requirements.	
Twicel shows to victics	
Typical characteristics	
Many different types of mobile divices: smart phones, remote     anticle or agricultural and as an	
controls, car equipment, and so on  Wireless communication	
<ul> <li>Devices may continuously change their location ⇒</li> </ul>	
<ul> <li>setting up a route may be problematic, as routes can change</li> </ul>	
frequently	
<ul> <li>devices may easily be temporarily disconnected ⇒ disruption-tolerant networks</li> </ul>	
dioraption tolorant networks	

Introduction 1.3 Types of distributed systems

Introduction 1.3 Types of distributed systems

Sensor networks  1.3 Types of distributed systems		Introduction 1.3 Types of distributed systems
Characteristics The nodes to which sensors are attached are:  • Many (10s-1000s)		
<ul> <li>Simple (small memory/compute/communication capacity)</li> <li>Often battery-powered (or even battery-less)</li> </ul>		
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