

continuous_time_PID
int = set_PID(Kp, Ki, Kd, p, **kwargs)

continuous_time_LTI
discretization_period
continuous_time_LTI_list
set_discretization_period(float)
int = set_LTI(system, **kwargs)
system, system = get_LTI(index)

discrete_time_LTI
discrete_time_LTI_list
int = set_LTI(system)
system = get_LTI(index)
float = LTI_compute(index, u)

periodic_controller
signal_period
set_signal_period(period)
bool = control_signal()

setpoint_abs_1	temperature_heater_2	tecolab_controller
setpoint_abs_2	temperature_ambient	
setpoint_rel_1	actuator_heater_1	
setpoint_rel_2	actuator_heater_2	
temperature_heater_1	actuator_fan	
		_control_compute()

Module's name
Attributes
'Public' methods
'Private' methods