

Nokia Bell Labs Project

A Middleware path for ROS-NonROS map

Nokia Chennai Factory

The project aims to build a middleware layer connecting ROS with non ROS robots.

This project acts as a building block to utilize ROS algorithms and functionalities with robots that do not natively support ROS.

The main aim of this project is providing support for exploration algorithms and autonomous mapping for non ROS robots.

The above project was done in collaboration between Nokia BELL Labs and Manipal Institute of Technology, Manipal.