

Backlight's Code Template

Backlight @ CSU

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1 ds

1.1 AVLTree

```

1  #include <bits/stdc++.h>
2  using namespace std;
3
4  #define FOR(i, L, r) for (int i = L; i <= r; ++i)
5  #define ROF(i, r, L) for (int i = r; i >= L; --i)
6  #define REP(i, L, r) for (int i = L; i < r; ++i)
7  #define PER(i, r, L) for (int i = r - 1; i >= L; --i)
8
9  const int N = 1e5 + 5;
10 using ll = long long;
11
12 template<typename T>
13 struct AVLTree {
14     struct node {
15         T v;
16         int sz, h, cnt;
17         node *l, *r;
18         node(T _v) : v(_v)
19         {
20             sz = h = cnt = 1;
21             l = r = nullptr;
22         }
23     };
24     node *root = nullptr;
25     int get_size(node* p)
26     {
27         return p ? p->sz : 0;
28     }
29
30     int get_height(node* p)
31     {
32         return p ? p->h : 0;
33     }
34
35     void push_up(node *p)
36     {
37         if (!p) return;
38         p->sz = get_size(p->l) + p->cnt + get_size(p->r);
39         p->h = 1 + max(get_height(p->l), get_height(p->r));
40     }
41
42     void zig(node* &p)
43     {
44         node* q = p;
45         q = p->r;
46         p->r = q->l;
47         q->l = p;
48         push_up(p);
49         push_up(q);
50         p = q;
51     }
52
53     void zag(node* &p)
54     {
55         node* q = p->l;
56         p->l = q->r;
57         q->r = p;
58         push_up(p);
59         push_up(q);
60         p = q;
61     }

```

```
62
63 void maintain(node* &p)
64 {
65     if (!p) return;
66     if (get_height(p->l) - get_height(p->r) == 2) {
67         if (get_height(p->l->l) < get_height(p->l->r)) {
68             zig(p->l);
69         }
70         zag(p);
71     } else if (get_height(p->l) - get_height(p->r) == -2) {
72         if (get_height(p->r->l) > get_height(p->r->r)) {
73             zag(p->r);
74         }
75         zig(p);
76     }
77 }
78
79 void ins(node* &p, T v)
80 {
81     if (!p) {
82         p = new node(v);
83         return;
84     }
85     if (p->v == v) {
86         ++(p->cnt);
87     } else {
88         if (v < p->v) {
89             ins(p->l, v);
90         } else {
91             ins(p->r, v);
92         }
93     }
94     push_up(p);
95     maintain(p);
96     push_up(p);
97 }
98
99 void del(node* &p, T v)
100 {
101     if (!p) return;
102     if (p->v == v) {
103         if (p->cnt == 1) {
104             if (p->l && p->r) {
105                 node* q = p->r;
106                 while(q->l) q = q->l;
107                 p->cnt = q->cnt, p->v = q->v;
108                 q->cnt = 1;
109                 del(p->r, q->v);
110             } else {
111                 node* q = p;
112                 if (p->l) p = p->l;
113                 else if (p->r) p = p->r;
114                 else p = nullptr;
115                 delete q;
116                 q = nullptr;
117             }
118         } else {
119             --p->cnt;
120         }
121     } else {
122         if (v < p->v) del(p->l, v);
123         else del(p->r, v);
124     }
125     push_up(p);
126     maintain(p);
```

```
127     push_up(p);
128 }
129
130 void ins(T v)
131 {
132     ins(root, v);
133 }
134
135 void del(T v)
136 {
137     del(root, v);
138 }
139
140 int getRank(T v)
141 {
142     node* p = root;
143     int res = 0;
144     while(p) {
145         if (v == p->v) {
146             res += get_size(p->l);
147             break;
148         }
149         if (v < p->v) p = p->l;
150         else {
151             res += get_size(p->l) + p->cnt;
152             p = p->r;
153         }
154     }
155     return res + 1;
156 }
157
158 T getKth(int k)
159 {
160     node *p = root;
161     T res = -1;
162     while(p) {
163         if (k <= get_size(p->l)) p = p->l;
164         else if (k - get_size(p->l) <= p->cnt) {
165             res = p->v;
166             break;
167         } else {
168             k -= get_size(p->l) + p->cnt;
169             p = p->r;
170         }
171     }
172     return res;
173 }
174
175 T getPrev(T v)
176 {
177     T res = numeric_limits<T>::min();
178     node* p = root;
179     while(p) {
180         if (v == p->v) {
181             node *q = p->l;
182             while(q->r) q = q->r;
183             res = q->v;
184             break;
185         }
186
187         if (v < p->v) {
188             p = p->l;
189         } else {
190             if (p->v > res) res = p->v;
191             p = p->r;
```

```
192     }
193 }
194 return res;
195 }
196
197 T getSucc(T v)
198 {
199     T res = numeric_limits<T>::max();
200     node* p = root;
201     while(p) {
202         if (v == p->v) {
203             node *q = p->r;
204             while(q->l) q = q->l;
205             res = q->v;
206             break;
207         }
208
209         if (v < p->v) {
210             if (p->v < res) res = p->v;
211             p = p->l;
212         } else {
213             p = p->r;
214         }
215     }
216     return res;
217 }
218
219 void debug(node* p)
220 {
221     if (!p) return;
222     debug(p->l);
223     cerr << p->v << " ";
224     debug(p->r);
225 }
226
227 void debug()
228 {
229     cerr << "INORDER: " << endl;
230     debug(root);
231     cerr << endl;
232 }
233 };
234
235 void solve(int Case)
236 {
237     int n;
238     scanf("%d", &n);
239     int op, x;
240     AVLTree<int> t;
241     FOR(i, 1, n) {
242         scanf("%d %d", &op, &x);
243         // cerr << op << " " << x << endl;
244         switch(op) {
245             case 1:
246                 t.ins(x);
247                 break;
248             case 2:
249                 t.del(x);
250                 break;
251             case 3:
252                 printf("%d\n", t.getRank(x));
253                 break;
254             case 4:
255                 printf("%d\n", t.getKth(x));
256                 break;
```

```

257         case 5:
258             printf("%d\n", t.getPrev(x));
259             break;
260         case 6:
261             printf("%d\n", t.getSucc(x));
262             break;
263     }
264     // t.debug();
265 }
266 }
267
268 int main()
269 {
270     #ifdef BACKLIGHT
271         freopen("in.txt", "r", stdin);
272     #endif
273     int T = 1;
274     // scanf("%d", &T);
275     for (int _ = 1; _ <= T; ++_) solve(_);
276     return 0;
277 }

```

1.2 BTree

```

1  template <typename K, int BF>
2  class BTree
3  {
4      public:
5          typedef std::pair<K, int> value_type;
6
7      private:
8          struct Node
9          {
10             value_type values[2 * BF - 1];
11             Node *child[2 * BF] = {nullptr};
12             Node *p = nullptr;
13             int keyNum = 0, size = 0;
14             bool isLeaf = true;
15             const K &key(int i) const { return values[i].first; }
16             int &cnt(int i) { return values[i].second; }
17             Node(Node *p = nullptr) : p(p) {}
18         };
19         Node *root = nullptr;
20         static bool pairComp(const value_type &lhs, const K &rhs) { return lhs.first < rhs; }
21         template <typename T>
22         static void shiftBy(T *ptr, int length, int shift) { memmove(ptr + shift, ptr, length * sizeof(T)); }
23         static int calcSize(Node *x)
24         {
25             if (!x)
26                 return 0;
27             int nsz = 0;
28             for (int i = 0; i < x->keyNum; ++i)
29                 nsz += getSize(x->child[i]) + x->cnt(i);
30             nsz += getSize(x->child[x->keyNum]);
31             return nsz;
32         }
33         static int getSize(Node *x)
34         {
35             if (!x)
36                 return 0;
37             return x->size;
38         }
39         //把 where 孩子分成两个节点，都作为 x 的孩子
40         void split(Node *x, int where)

```



```

41 {
42     Node *z = new Node(x);
43     Node *y = x->child[where];
44     z->isLeaf = y->isLeaf;
45     memmove(z->values, y->values + BF, (BF - 1) * sizeof(value_type));
46     if (!y->isLeaf)
47     {
48         memmove(z->child, y->child + BF, BF * sizeof(Node *));
49         for (int i = 0; i < BF; ++i)
50             z->child[i]->p = z;
51     }
52     z->keyNum = y->keyNum = BF - 1;
53     shiftBy(x->child + where + 1, x->keyNum - where, 1); //注意 child 本身 keyNum 多一个
54     x->child[where + 1] = z;
55     shiftBy(x->values + where, x->keyNum - where, 1);
56     new (x->values + where) value_type(y->values[BF - 1]);
57
58     y->size = calcSize(y), z->size = calcSize(z);
59     ++x->keyNum;
60 }
61 void insertEmpty(Node *x, const K &key)
62 {
63     while (true)
64     {
65         int i = lower_bound(x->values, x->values + x->keyNum, key, pairComp) - x->values;
66         if (i != x->keyNum && !(key < x->values[i].first)) //重复插入
67         {
68             ++x->cnt(i);
69             while (x)
70                 ++x->size, x = x->p;
71             return;
72         }
73         if (x->isLeaf)
74         {
75             shiftBy(x->values + i, x->keyNum - i, 1);
76             x->values[i] = {key, 1};
77             ++x->keyNum;
78             while (x)
79                 ++x->size, x = x->p;
80             return;
81         }
82         if (x->child[i]->keyNum == 2 * BF - 1)
83         {
84             split(x, i);
85             if (x->key(i) < key)
86                 ++i;
87             else if (!(key < x->key(i)))
88             {
89                 ++x->cnt(i);
90                 while (x)
91                     ++x->size, x = x->p;
92                 return;
93             }
94         }
95         x = x->child[i];
96     }
97 }
98
99 void merge(Node *x, int i) //将 x 的 i 孩子与 i+1 孩子合并, 用 x 的 i 键作为分隔, 这两个孩子都只有 BF-1 个孩子, 合并后有
100 {
101     Node *y = x->child[i], *z = x->child[i + 1];
102     y->keyNum = 2 * BF - 1;
103     y->values[BF - 1] = std::move(x->values[i]);
104     memmove(y->values + BF, z->values, (BF - 1) * sizeof(value_type));
105     if (!y->isLeaf)

```

```

106     {
107         memmove(y->child + BF, z->child, BF * sizeof(Node *));
108         for (int j = BF; j <= 2 * BF - 1; ++j)
109             y->child[j]->p = y;
110     }
111     shiftBy(x->values + i + 1, x->keyNum - i - 1, -1);
112     shiftBy(x->child + i + 2, x->keyNum - i - 1, -1);
113
114     --x->keyNum;
115     y->size = calcSize(y);
116 }
117 void erase(Node *x, const K &key)
118 {
119     int i = lower_bound(x->values, x->values + x->keyNum, key, pairComp) - x->values;
120     if (i != x->keyNum && !(key < x->values[i].first)) //找到 key 了
121     {
122         if (x->cnt(i) > 1)
123         {
124             --x->cnt(i);
125             while (x)
126                 --x->size, x = x->p;
127             return;
128         }
129         if (x->isLeaf) //x 是叶节点, 直接删除
130         {
131             shiftBy(x->values + i + 1, --x->keyNum - i, -1); //需要移动的内存是 x->keyNum-i-1
132             while (x)
133                 --x->size, x = x->p;
134         }
135         else
136         {
137             if (x->child[i]->keyNum >= BF) //前驱所在孩子有足够的孩子 (以应对它的孩子的需求)
138             {
139                 Node *y = x->child[i];
140                 while (!y->isLeaf)
141                     y = y->child[y->keyNum]; //找前驱
142                 x->values[i] = y->values[y->keyNum - 1];
143                 if (x->cnt(i) != 1) //y 的对应节点 cnt 有多个, 那么沿路减 size; 只有一个的话删除的时候会处理
144                 {
145                     y->cnt(y->keyNum - 1) = 1;
146                     while (y != x)
147                         y->size -= x->cnt(i) - 1, y = y->p;
148                 }
149
150                 erase(x->child[i], x->key(i));
151             }
152             else if (x->child[i + 1]->keyNum >= BF) //后继所在孩子有足够的孩子
153             {
154                 Node *y = x->child[i + 1];
155                 while (!y->isLeaf)
156                     y = y->child[0]; //找后继
157                 x->values[i] = y->values[0];
158                 if (x->cnt(i) != 1)
159                 {
160                     y->cnt(0) = 1;
161                     while (y != x)
162                         y->size -= x->cnt(i) - 1, y = y->p;
163                 }
164
165                 erase(x->child[i + 1], x->key(i));
166             }
167             else //都没有, 那么把这两个节点都合并到 y 中, 并且挪动 x 的孩子和键
168             {
169                 merge(x, i);
170                 if (root->keyNum == 0) //keyNum==0 只是没有键了, 但是还可能有一个孩子, 这时根变成这个孩子

```

```

171         root = x->child[i], root->p = nullptr;
172         erase(x->child[i], key);
173     }
174 }
175 }
176 else if (!x->isLeaf) //没有找到 key, 只要保证 x->child[i]->keyNum 足够多即可无脑递归, 然而很难保证
177 {
178     if (x->child[i]->keyNum == BF - 1)
179     {
180         Node *y = x->child[i];
181         if (i >= 1 && x->child[i - 1]->keyNum >= BF) //左兄弟, 取走它的最大孩子
182         {
183             //找相邻的兄弟借节点, 类似旋转操作, 把 x 的一个键移入要删的 key 所在孩子, 把它的兄弟的一个 key 和孩子移入 x
184             //但是从左还是右借并不完全一样, 所以不能一概处理
185             Node *z = x->child[i - 1];
186             shiftBy(y->values, y->keyNum, 1);
187             //是否需要考虑析构的问题? z 的 keyNum 已经减了, 不可能再去析构 z->values[z->keyNum - 1] 了
188             //所以, value 的构造必须要用 new 不能用 =, 从而避开 = 的资源释放
189             //但是 value 的移动似乎应该是 bitwise 的, 考虑 std::move
190             new (y->values) value_type(std::move(x->values[i - 1]));
191             new (x->values + i - 1) value_type(std::move(z->values[z->keyNum - 1]));
192             if (!y->isLeaf)
193             {
194                 shiftBy(y->child, y->keyNum + 1, 1);
195                 y->child[0] = z->child[z->keyNum], y->child[0]->p = y;
196             }
197
198             --z->keyNum, ++y->keyNum;
199             y->size = calcSize(y), z->size = calcSize(z);
200             erase(y, key);
201         }
202         else if (i < x->keyNum && x->child[i + 1]->keyNum >= BF) //右兄弟, 取走它的最小孩子
203         {
204             Node *z = x->child[i + 1];
205             new (y->values + y->keyNum) value_type(std::move(x->values[i]));
206             new (x->values + i) value_type(std::move(z->values[0]));
207             if (!y->isLeaf) //y 和 z 深度一样, isLeaf 情况相同
208             {
209                 y->child[y->keyNum + 1] = z->child[0], y->child[y->keyNum + 1]->p = y;
210                 shiftBy(z->child + 1, z->keyNum, -1);
211             }
212             shiftBy(z->values + 1, z->keyNum - 1, -1);
213
214             --z->keyNum, ++y->keyNum;
215             y->size = calcSize(y), z->size = calcSize(z);
216             erase(y, key);
217         }
218         else //两个兄弟都没有节点借, 那么将它与随便左右哪个兄弟合并, 然而还是要特判一下
219         {
220             if (i != 0)
221                 --i; //i==0 时, y 与 y+1 合并仍放于 y; 否则 y 与 y-1 合并放于 y-1
222             y = x->child[i];
223             merge(x, i);
224             if (root->keyNum == 0)
225                 root = y, root->p = nullptr;
226             erase(y, key);
227         }
228     }
229     else
230         erase(x->child[i], key);
231 }
232 }
233
234 public:
235     BTree() : root(new Node) {}

```

```

236 void insert(const K &key)
237 {
238     //沿路向下分裂满节点，每次分裂成左右一半，孩子的中间 key 留在父亲节点中用于分隔两个新孩子
239     //insertEmpty 只保证了当前节点有空间（来容纳它的孩子的分裂），不保证 key 需要去的孩子节点也有空间
240     if (root->keyNum == 2 * BF - 1)
241     {
242         Node *x = new Node;
243         x->isLeaf = false, x->child[0] = root, x->size = root->size; //+1 操作由 insertEmpty 来做
244         root->p = x, root = x;
245         split(x, 0); //split 接受参数: node 的满子节点下标
246     }
247     insertEmpty(root, key);
248 }
249 void erase(const K &key) { erase(root, key); }
250 int next(const K &key)
251 {
252     Node *x = root;
253     int ret;
254     while (x)
255     {
256         int i = lower_bound(x->values, x->values + x->keyNum, key, pairComp) - x->values;
257         if (x->values[i].first == key)
258             ++i;
259         if (i != x->keyNum)
260             ret = x->values[i].first;
261         x = x->child[i];
262     }
263     return ret;
264 }
265 int prev(const K &key)
266 {
267     Node *x = root;
268     int ret;
269     while (x)
270     {
271         int i = lower_bound(x->values, x->values + x->keyNum, key, pairComp) - x->values;
272         if (i)
273             ret = x->values[i - 1].first;
274         x = x->child[i];
275     }
276     return ret;
277 }
278 int rank(const K &key)
279 {
280     Node *x = root;
281     int ret = 0;
282     while (x)
283     {
284         if (x->key(x->keyNum - 1) < key)
285         {
286             ret += x->size - getSize(x->child[x->keyNum]);
287             x = x->child[x->keyNum];
288             continue;
289         }
290         for (int i = 0; i < x->keyNum; ++i)
291         {
292             if (x->key(i) < key)
293                 ret += getSize(x->child[i]) + x->cnt(i);
294             else if (x->key(i) == key)
295                 return ret + getSize(x->child[i]) + 1;
296             else
297             {
298                 x = x->child[i];
299                 break;
300             }

```

```

301     }
302 }
303 return ret;
304 }
305 int kth(int k)
306 {
307     Node *x = root;
308     while (true)
309     {
310         for (int i = 0; i <= x->keyNum; ++i)
311         {
312             //const int csz = getSize(x->child[i]) + (i == x->keyNum ? 1 : x->cnt(i));
313             const int lb = getSize(x->child[i]) + 1, ub = getSize(x->child[i]) + (i == x->keyNum ? 1 : x->cnt(i));
314             if (k >= lb && k <= ub)
315                 return x->key(i);
316             if (k < lb)
317             {
318                 x = x->child[i];
319                 break;
320             }
321             k -= ub;
322         }
323     }
324 }
325 };

```

1.3 CaptainMo

```

1 // Captain Mo
2 // 询问 [L, r] 内的元素是否互不相同
3 int Ans, ans[N];
4 int block_sz, block_id[N];
5 struct Query {
6     int l, r, id;
7     Query() {}
8     Query(int _l, int _r, int _id) : l(_l), r(_r), id(_id) {}
9     bool operator < (const Query& q) const {
10         if (block_id[l] == block_id[q.l])
11             return block_id[l] & 1 ? r < q.r : r > q.r;
12         return block_id[l] < block_id[q.l];
13     }
14 } Q[N];
15
16 int n, q, a[N];
17
18 int cnt[N], ge2;
19 inline void add(int p) {
20     ++cnt[a[p]];
21     if (cnt[a[p]] == 2) ++ge2;
22 }
23
24 inline void del(int p) {
25     if (cnt[a[p]] == 2) --ge2;
26     --cnt[a[p]];
27 }
28
29 void CaptainMo() {
30     block_sz = sqrt(n);
31     for (int i = 1; i <= n; ++i) block_id[i] = i / block_sz;
32     sort(Q + 1, Q + 1 + q);
33
34     int l = 1, r = 0;
35     ge2 = 0;
36     for (int i = 1; i <= q; ++i) {

```

```

37     while(r < Q[i].r) ++r, add(r);
38     while(l < Q[i].l) del(l), ++l;
39     while(l > Q[i].l) --l, add(l);
40     while(r > Q[i].r) del(r), --r;
41     ans[Q[i].id] = (ge2 == 0);
42 }
43 }

```

1.4 FenwickTree

```

1  template<typename T>
2  struct FenwickTree {
3      int n;
4      vector<T> c;
5      FenwickTree(int _n) : n(_n), c(n + 1) {}
6      inline int lb(int x) { return x & -x; }
7      void add(int x, T d) { for (; x < n; x += lb(x)) c[x] += d; }
8      T getsum(int x) { T r = 0; for (; x; x -= lb(x)) r += c[x]; return r; }
9      T getsum(int l, int r) { return getsum(r) - getsum(l - 1); }
10     T kth(int k) {
11         T ans = 0, cnt = 0;
12         for (int i = log2(n) + 1; i >= 0; --i) {
13             ans += (1LL << i);
14             if (ans >= n || cnt + c[ans] >= k) ans -= (1LL << i);
15             else cnt += c[ans];
16         }
17         return ans + 1;
18     }
19 };

```

1.5 KDTree

```

1  // KDTree
2  // 平面最近点对
3  template < typename T, int K = 2 >
4  struct KDTree
5  {
6      using node = array< double, K >;
7      int n;
8      node p[ N ], ma[ N ], mi[ N ];
9      double L[ N ], R[ N ], D[ N ], U[ N ];
10     int sd[ N ], lc[ N ], rc[ N ];
11
12     KDTree( int _n ) : n( _n )
13     {
14     }
15
16     double dist( const node& nd1, const node& nd2 )
17     {
18         double res = 0;
19         for ( int j = 0; j < K; ++j )
20         {
21             res += ( nd1[ j ] - nd2[ j ] ) * ( nd1[ j ] - nd2[ j ] );
22         }
23         return res;
24     }
25
26     double dist( int x, int y )
27     {
28         return dist( p[ x ], p[ y ] );
29     }
30 }

```

```

31 double cost( int x, int y )
32 {
33     double res = 0;
34     for ( int j = 0; j < K; ++j )
35     {
36         if ( mi[ y ][ j ] > p[ x ][ j ] )
37             res += ( mi[ y ][ j ] - p[ x ][ j ] ) * ( mi[ y ][ j ] - p[ x ][ j ] );
38         if ( ma[ y ][ j ] < p[ x ][ j ] )
39             res += ( ma[ y ][ j ] - p[ x ][ j ] ) * ( ma[ y ][ j ] - p[ x ][ j ] );
40     }
41     return res;
42 }
43
44 struct cmp
45 {
46     int s;
47     cmp( int _s ) : s( _s )
48     {
49     }
50     bool operator()( const node& nd1, const node& nd2 ) const
51     {
52         return nd1[ s ] < nd2[ s ];
53     }
54 };
55
56 void maintain( int x )
57 {
58     ma[ x ] = mi[ x ] = p[ x ];
59     if ( lc[ x ] )
60     {
61         for ( int j = 0; j < K; ++j )
62         {
63             ma[ x ][ j ] = max( ma[ x ][ j ], ma[ lc[ x ] ][ j ] );
64             mi[ x ][ j ] = min( mi[ x ][ j ], mi[ lc[ x ] ][ j ] );
65         }
66     }
67     if ( rc[ x ] )
68     {
69         for ( int j = 0; j < K; ++j )
70         {
71             ma[ x ][ j ] = max( ma[ x ][ j ], ma[ rc[ x ] ][ j ] );
72             mi[ x ][ j ] = min( mi[ x ][ j ], mi[ rc[ x ] ][ j ] );
73         }
74     }
75 }
76
77 int build( int l, int r )
78 {
79     if ( l >= r )
80         return 0;
81     int mid = ( l + r ) >> 1;
82
83     array< double, K > avg;
84     for ( int i = l; i <= r; ++i )
85         for ( int j = 0; j < K; ++j )
86             avg[ j ] += p[ i ][ j ];
87     for ( int j = 0; j < K; ++j )
88         avg[ j ] /= ( r - l + 1 );
89
90     array< double, K > var;
91     for ( int i = l; i <= r; ++i )
92         for ( int j = 0; j < K; ++j )
93             var[ j ] += ( p[ i ][ j ] - avg[ j ] ) * ( p[ i ][ j ] - avg[ j ] );
94
95     sd[ mid ] = 0;

```

```
96     for ( int j = 0; j < K; ++j )
97         if ( var[ j ] > var[ sd[ mid ] ] )
98             sd[ mid ] = j;
99
100     nth_element( p + 1, p + mid, p + r + 1, cmp( sd[ mid ] ) );
101
102     lc[ mid ] = build( l, mid - 1 );
103     rc[ mid ] = build( mid + 1, r );
104
105     maintain( mid );
106
107     return mid;
108 }
109
110 double min_dist;
111
112 void query( int l, int r, int x )
113 {
114     if ( l > r )
115         return;
116     int mid = ( l + r ) >> 1;
117     if ( mid != x )
118         min_dist = min( min_dist, dist( x, mid ) );
119     if ( l == r )
120         return;
121
122     double dl = cost( x, lc[ mid ] );
123     double dr = cost( x, rc[ mid ] );
124
125     if ( dl < min_dist && dr < min_dist )
126     {
127         if ( dl < dr )
128         {
129             query( l, mid - 1, x );
130             if ( dr < min_dist )
131                 query( mid + 1, r, x );
132         }
133         else
134         {
135             query( mid + 1, r, x );
136             if ( dl < min_dist )
137                 query( l, mid - 1, x );
138         }
139     }
140     else
141     {
142         if ( dl < min_dist )
143             query( l, mid - 1, x );
144         if ( dr < min_dist )
145             query( mid + 1, r, x );
146     }
147 }
148
149 double getMindis() {
150     min_dist = 2e18;
151     for ( int i = 1; i <= n; ++i )
152         query( 1, n, i );
153     min_dist = sqrt(min_dist);
154     return min_dist;
155 }
156 };
```


1.6 LCT

```

1  template <typename T>
2  struct LinkCutTree
3  {
4      #define ls ch[x][0]
5      #define rs ch[x][1]
6      #define SIZE 100005
7
8      int tot, sz[SIZE], rev[SIZE], ch[SIZE][2], fa[SIZE];
9      T v[SIZE], sum[SIZE];
10
11     LinkCutTree() { tot = 0; }
12
13     inline void init() { tot = 0; }
14
15     inline void clear(int x)
16     {
17         ch[x][0] = ch[x][1] = fa[x] = sz[x] = rev[x] = sum[x] = v[x] = 0;
18     }
19
20     inline int get(int x) { return ch[fa[x]][1] == x; }
21
22     inline int isroot(int x) { return ch[fa[x]][0] != x && ch[fa[x]][1] != x; }
23
24     inline int newnode(T val)
25     {
26         ++tot;
27         sz[tot] = 1;
28         ch[tot][0] = ch[tot][1] = fa[tot] = rev[tot] = 0;
29         sum[tot] = v[tot] = val;
30         return tot;
31     }
32
33     inline void reverse(int x)
34     {
35         swap(ls, rs);
36         rev[x] ^= 1;
37     }
38
39     inline void push_up(int x)
40     {
41         sz[x] = sz[ls] + 1 + sz[rs];
42         sum[x] = sum[ls] ^ v[x] ^ sum[rs];
43     }
44
45     inline void push_down(int x)
46     {
47         if (rev[x])
48         {
49             reverse(ls);
50             reverse(rs);
51             rev[x] = 0;
52         }
53     }
54
55     inline void update(int x)
56     {
57         if (!isroot(x))
58             update(fa[x]);
59         push_down(x);
60     }
61
62     inline void rotate(int x)
63     {

```

```

64     int f = fa[x], g = fa[f], i = get(x);
65     if (!isroot(f))
66         ch[g][get(f)] = x;
67     fa[x] = g;
68     ch[f][i] = ch[x][i ^ 1];
69     fa[ch[f][i]] = f;
70     ch[x][i ^ 1] = f;
71     fa[f] = x;
72     push_up(f);
73     push_up(x);
74 }
75
76 inline void splay(int x)
77 {
78     update(x);
79     for (; !isroot(x); rotate(x))
80         if (!isroot(fa[x]))
81             rotate(get(fa[x]) == get(x) ? fa[x] : x);
82 }
83
84 inline void access(int x)
85 {
86     for (int y = 0; x; y = x, x = fa[x]) splay(x), rs = y, push_up(x);
87 }
88
89 inline void makeroot(int x)
90 {
91     access(x);
92     splay(x);
93     reverse(x);
94 }
95
96 inline int findroot(int x)
97 {
98     access(x);
99     splay(x);
100    while (ls) push_down(x), x = ls;
101    return x;
102 }
103
104 inline void link(int x, int y)
105 {
106     makeroot(x);
107     if (findroot(y) != x)
108         fa[x] = y;
109 }
110
111 inline void cut(int x, int y)
112 {
113     makeroot(x);
114     if (findroot(y) == x && fa[x] == y && ch[y][0] == x && !ch[y][1])
115     {
116         fa[x] = ch[y][0] = 0;
117         push_up(y);
118     }
119 }
120
121 inline void split(int x, int y)
122 {
123     makeroot(x);
124     access(y);
125     splay(y);
126 }
127
128 // x--y 路径上节点权值之和

```

```

129 inline int query(int x, int y)
130 {
131     split(x, y);
132     return sum[y];
133 }
134 };
135
136 void solve(int Case)
137 {
138     /* write code here */
139     /* gl & hf */
140     int n, m;
141     rd(n, m);
142     VI a(n + 1);
143     FOR(i, 1, n) rd(a[i]);
144     LinkCutTree<int> t;
145     FOR(i, 1, n) t.newnode(a[i]);
146
147     int op, x, y;
148     FOR(_, 1, m)
149     {
150         rd(op, x, y);
151         debug(op, x, y);
152         if (op == 0)
153         {
154             pln(t.query(x, y));
155         }
156         else if (op == 1)
157         {
158             t.link(x, y);
159         }
160         else if (op == 2)
161         {
162             t.cut(x, y);
163         }
164         else
165         {
166             t.v[x] = y;
167             t.makeroot(x);
168         }
169     }
170 }

```

1.7 LeftistTree

```

1 template <typename V>
2 struct LeftistForest {
3     struct LeftistTree {
4         V v;
5         int dist;
6         int l, r, rt;
7     } t[N];
8     LeftistTree& operator[](int x) { return t[x]; }
9     void init(int n, V* a) {
10         FOR(i, 1, n) {
11             t[i].v = a[i];
12             t[i].l = t[i].r = t[i].dist = 0;
13             t[i].rt = i;
14         }
15     }
16     int find(int x) { return t[x].rt == x ? x : t[x].rt = find(t[x].rt); }
17     int merge(int x, int y) {
18         if (!x) return y;
19         if (!y) return x;

```

```

20     if (t[x].v > t[y].v) swap(x, y); // 小根堆
21     t[x].r = merge(t[x].r, y);
22     t[t[x].r].rt = x;
23     if (t[t[x].l].dist < t[t[x].r].dist) swap(t[x].l, t[x].r);
24     if (!t[x].r)
25         t[x].dist = 0;
26     else
27         t[x].dist = t[t[x].r].dist + 1;
28     return x;
29 }
30 V top(int x) {
31     if (t[x].v == -1) return -1;
32     x = find(x);
33     return t[x].v;
34 }
35 void pop(int x) {
36     if (t[x].v == -1) return;
37     x = find(x);
38     t[t[x].l].rt = t[x].l;
39     t[t[x].r].rt = t[x].r;
40     t[x].rt = merge(t[x].l, t[x].r);
41     t[x].v = -1;
42 }
43 };
44
45 int n, m, a[N];
46 void solve(int Case) {
47     rd(n, m);
48     FOR(i, 1, n) rd(a[i]);
49     LeftistForest<int> T;
50     T.init(n, a);
51
52     int op, x, y;
53     FOR(_, 1, m) {
54         rd(op);
55         debug(op);
56         if (op == 1) {
57             rd(x, y);
58             if (T[x].v == -1 || T[y].v == -1) continue;
59             x = T.find(x);
60             y = T.find(y);
61             if (x == y) continue;
62             T[x].rt = T[y].rt = T.merge(x, y);
63         } else {
64             rd(x);
65             pln(T.top(x));
66             T.pop(x);
67         }
68     }
69 }

```

1.8 PersistentSegmentTree

```

1 struct PersistentSegmentTree
2 {
3     // SIZE = N log N
4     #define SIZE 200005 * 20
5
6     int tot;
7     int c[SIZE];
8     int L[SIZE], R[SIZE];
9
10    PersistentSegmentTree() { tot = 0; }
11

```

```

12  int update(int rt, int l, int r, int p, int d)
13  {
14      int nrt = ++tot;
15      L[nrt] = L[rt];
16      R[nrt] = R[rt];
17      c[nrt] = c[rt] + d;
18
19      if (l != r)
20      {
21          int mid = (l + r) >> 1;
22          if (p <= mid)
23              L[nrt] = update(L[rt], l, mid, p, d);
24          else
25              R[nrt] = update(R[rt], mid + 1, r, p, d);
26      }
27
28      return nrt;
29  }
30
31  // 区间第 k 小
32  int query(int u, int v, int l, int r, int k)
33  {
34      if (l == r)
35          return l;
36      int left_size = c[L[v]] - c[L[u]];
37      int mid = (l + r) >> 1;
38      if (k <= left_size)
39          return query(L[u], L[v], l, mid, k);
40      return query(R[u], R[v], mid + 1, r, k - left_size);
41  }
42  };

```

1.9 rbtrees-1

```

1  //define __REDBLACK_DEBUG
2  template <typename T>
3  class rbtree {
4      #define bro(x) (((x)->ftr->lc == (x)) ? ((x)->ftr->rc) : ((x)->ftr->lc))
5      #define islc(x) ((x) != NULL && (x)->ftr->lc == (x))
6      #define isrc(x) ((x) != NULL && (x)->ftr->rc == (x))
7  private:
8      struct Node;
9
10     Node* _root;
11     Node* _hot;
12
13     void init(T);
14     void checkconnect(Node*);
15     void connect34(Node*, Node*, Node*, Node*, Node*, Node*, Node*);
16     void SolveDoubleRed(Node*);
17     void SolveDoubleBlack(Node*);
18     Node* find(T, const int);
19     Node* rfind(T, const int);
20     Node* findkth(int, Node*);
21     int find_rank(T, Node*);
22     #ifdef __REDBLACK_DEBUG
23         void previs(Node*, int);
24         void invis(Node*, int);
25         void postvis(Node*, int);
26     #endif
27
28 public:
29     struct iterator;
30

```

```

31     rbtree()
32         : _root(NULL)
33         , _hot(NULL)
34     {
35     }
36
37     int get_rank(T);
38     iterator insert(T);
39     bool remove(T);
40     int size();
41     iterator kth(int);
42     iterator lower_bound(T);
43     iterator upper_bound(T);
44     #ifdef __REDBLACK_DEBUG
45         void vis();
46         void correctlyconnected();
47     #endif
48 };
49
50 template <typename T>
51 struct rbtree<T>::Node {
52     T val;
53     bool RBc; ////true : Red ; false : Black .
54     Node* ftr;
55     Node* lc;
56     Node* rc;
57     int s;
58
59     Node(T v = T(), bool RB = true,
60         Node* f = NULL, Node* l = NULL, Node* r = NULL, int ss = 1)
61         : val(v)
62         , RBc(RB)
63         , ftr(f)
64         , lc(l)
65         , rc(r)
66         , s(ss)
67     {
68     }
69
70     Node* succ()
71     {
72         Node* ptn = rc;
73         while (ptn->lc != NULL) {
74             --(ptn->s);
75             ptn = ptn->lc;
76         }
77         return ptn;
78     }
79
80     Node* left_node()
81     {
82         Node* ptn = this;
83         if (!lc) {
84             while (ptn->ftr && ptn->ftr->lc == ptn)
85                 ptn = ptn->ftr;
86             ptn = ptn->ftr;
87         } else
88             while (ptn->lc)
89                 ptn = ptn->lc;
90         return ptn;
91     }
92
93     Node* right_node()
94     {
95         Node* ptn = this;

```

```

96         if (!rc) {
97             while (ptn->ftr && ptn->ftr->rc == ptn)
98                 ptn = ptn->ftr;
99             ptn = ptn->ftr;
100         } else
101             while (ptn->rc)
102                 ptn = ptn->rc;
103         return ptn;
104     }
105
106     void maintain()
107     {
108         s = 1;
109         if (lc)
110             s += lc->s;
111         if (rc)
112             s += rc->s;
113     }
114 };
115
116 template <typename T>
117 void rbtree<T>::connect34(Node* nroot, Node* nlc, Node* nrc,
118     Node* ntree1, Node* ntree2, Node* ntree3, Node* ntree4)
119 {
120     nlc->lc = ntree1;
121     if (ntree1 != NULL)
122         ntree1->ftr = nlc;
123     nlc->rc = ntree2;
124     if (ntree2 != NULL)
125         ntree2->ftr = nlc;
126     nrc->lc = ntree3;
127     if (ntree3 != NULL)
128         ntree3->ftr = nrc;
129     nrc->rc = ntree4;
130     if (ntree4 != NULL)
131         ntree4->ftr = nrc;
132     nroot->lc = nlc;
133     nlc->ftr = nroot;
134     nroot->rc = nrc;
135     nrc->ftr = nroot;
136     nlc->maintain();
137     nrc->maintain();
138     nroot->maintain();
139 }
140
141 #ifdef __REDBLACK_DEBUG
142
143 int blackheight(0);
144
145 template <typename T>
146 void rbtree<T>::previs(Node* ptn, int cnt)
147 {
148     if (ptn == NULL) {
149         if (blackheight == -1)
150             blackheight = cnt;
151         assert(blackheight == cnt);
152         return;
153     }
154     printf("%d %s %d \n", ptn->val, ptn->RBc ? "Red" : "Black", ptn->s);
155     if (!(ptn->RBc))
156         ++cnt;
157     previs(ptn->lc, cnt);
158     previs(ptn->rc, cnt);
159 }
160

```

```

161 template <typename T>
162 void rbtree<T>::invis(Node* ptn, int cnt)
163 {
164     if (ptn == NULL) {
165         if (blackheight == -1)
166             blackheight = cnt;
167         assert(blackheight == cnt);
168         return;
169     }
170     if (!(ptn->RBc))
171         ++cnt;
172     invis(ptn->lc, cnt);
173     printf("%d %s %d \n", ptn->val, ptn->RBc ? "Red" : "Black", ptn->s);
174     invis(ptn->rc, cnt);
175 }
176
177 template <typename T>
178 void rbtree<T>::postvis(Node* ptn, int cnt)
179 {
180     if (ptn == NULL) {
181         if (blackheight == -1)
182             blackheight = cnt;
183         assert(blackheight == cnt);
184         return;
185     }
186     if (!(ptn->RBc))
187         ++cnt;
188     postvis(ptn->lc, cnt);
189     postvis(ptn->rc, cnt);
190     printf("%d %s %d \n", ptn->val, ptn->RBc ? "Red" : "Black", ptn->s);
191 }
192
193 template <typename T>
194 void rbtree<T>::vis()
195 {
196     printf("BlackHeight:\t%d\n", blackheight);
197     printf("-----pre-vis-----\n");
198     previs(_root, 0);
199     printf("-----in-vis-----\n");
200     invis(_root, 0);
201     printf("-----post-vis-----\n");
202     postvis(_root, 0);
203 }
204
205 template <typename T>
206 void rbtree<T>::checkconnect(Node* ptn)
207 {
208     if (!ptn)
209         return;
210     assert(ptn->s > 0);
211     if (ptn->lc && ptn->lc->ftr != ptn) {
212         printf("Oops! %d has a lc %d, but it failed to point its ftr!\n", ptn->val, ptn->lc->val);
213     }
214     if (ptn->rc && ptn->rc->ftr != ptn) {
215         printf("Oops! %d has a rc %d, but it failed to point its ftr!\n", ptn->val, ptn->rc->val);
216     }
217     int sss = ptn->s;
218     if (ptn->lc)
219         sss -= ptn->lc->s;
220     if (ptn->rc)
221         sss -= ptn->rc->s;
222     if (sss - 1) {
223         printf("Fuck it! %d's size is %d, but the sum of its children's size is %d!\n", ptn->val, ptn->s, ptn->s - sss);
224     }
225     checkconnect(ptn->lc);

```



```

226     checkconnect(ptn->rc);
227 }
228
229 template <typename T>
230 void rbtree<T>::correctlyconnected()
231 {
232     checkconnect(_root);
233 }
234
235 #endif
236
237 template <typename T>
238 void rbtree<T>::init(T v)
239 {
240     _root = new Node(v, false, NULL, NULL, NULL, 1);
241 #ifdef __REDBLACK_DEBUG
242     ++blackheight;
243 #endif
244 }
245
246 template <typename T>
247 void rbtree<T>::SolveDoubleRed(Node* nn)
248 {
249     while ((!(nn->ftr)) || nn->ftr->RBc) {
250         if (nn == _root) {
251             _root->RBc = false;
252 #ifdef __REDBLACK_DEBUG
253             ++blackheight;
254 #endif
255             return;
256         }
257         Node* pftr = nn->ftr;
258         if (!(pftr->RBc))
259             return; ////No double-red
260         Node* uncle = bro(nn->ftr);
261         Node* grdftr = nn->ftr->ftr;
262         if (uncle != NULL && uncle->RBc) { ////RR-2
263             grdftr->RBc = true;
264             uncle->RBc = false;
265             pftr->RBc = false;
266             nn = grdftr;
267         } else { ////RR-1
268             if (islc(pftr)) {
269                 if (islc(nn)) {
270                     pftr->ftr = grdftr->ftr;
271                     if (grdftr == _root)
272                         _root = pftr;
273                     else if (grdftr->ftr->lc == grdftr)
274                         grdftr->ftr->lc = pftr;
275                     else
276                         grdftr->ftr->rc = pftr;
277                     connect34(pftr, nn, grdftr, nn->lc, nn->rc, pftr->rc, uncle);
278                     pftr->RBc = false;
279                     grdftr->RBc = true;
280                 } else {
281                     nn->ftr = grdftr->ftr;
282                     if (grdftr == _root)
283                         _root = nn;
284                     else if (grdftr->ftr->lc == grdftr)
285                         grdftr->ftr->lc = nn;
286                     else
287                         grdftr->ftr->rc = nn;
288                     connect34(nn, pftr, grdftr, pftr->lc, nn->lc, nn->rc, uncle);
289                     nn->RBc = false;
290                     grdftr->RBc = true;

```

```

291     }
292     } else {
293         if (islc(nn)) {
294             nn->ftr = grdftr->ftr;
295             if (grdftr == _root)
296                 _root = nn;
297             else if (grdftr->ftr->lc == grdftr)
298                 grdftr->ftr->lc = nn;
299             else
300                 grdftr->ftr->rc = nn;
301             connect34(nn, grdftr, pftr, uncle, nn->lc, nn->rc, pftr->rc);
302             nn->RBc = false;
303             grdftr->RBc = true;
304         } else {
305             pftr->ftr = grdftr->ftr;
306             if (grdftr == _root)
307                 _root = pftr;
308             else if (grdftr->ftr->lc == grdftr)
309                 grdftr->ftr->lc = pftr;
310             else
311                 grdftr->ftr->rc = pftr;
312             connect34(pftr, grdftr, nn, uncle, pftr->lc, nn->lc, nn->rc);
313             pftr->RBc = false;
314             grdftr->RBc = true;
315         }
316     }
317     return;
318 }
319 }
320 }
321
322 template <typename T>
323 void rbtree<T>::SolveDoubleBlack(Node* nn)
324 {
325     while (nn != _root) {
326         Node* pftr = nn->ftr;
327         Node* bthr = bro(nn);
328         if (bthr->RBc) { ///BB-1
329             bthr->RBc = false;
330             pftr->RBc = true;
331             if (_root == pftr)
332                 _root = bthr;
333             if (pftr->ftr) {
334                 if (pftr->ftr->lc == pftr)
335                     pftr->ftr->lc = bthr;
336                 else
337                     pftr->ftr->rc = bthr;
338             }
339             bthr->ftr = pftr->ftr;
340             if (islc(nn)) {
341                 connect34(bthr, pftr, bthr->rc, nn, bthr->lc, bthr->rc->lc, bthr->rc->rc);
342             } else {
343                 connect34(bthr, bthr->lc, pftr, bthr->lc->lc, bthr->lc->rc, bthr->rc, nn);
344             }
345             bthr = bro(nn);
346             pftr = nn->ftr;
347         }
348         if (bthr->lc && bthr->lc->RBc) { ///BB-3
349             bool oldRBc = pftr->RBc;
350             pftr->RBc = false;
351             if (pftr->lc == nn) {
352                 if (pftr->ftr) {
353                     if (pftr->ftr->lc == pftr)
354                         pftr->ftr->lc = bthr->lc;
355                     else

```

```

356         pftr->ftr->rc = bthr->lc;
357     }
358     bthr->lc->ftr = pftr->ftr;
359     if (_root == pftr)
360         _root = bthr->lc;
361     connect34(bthr->lc, pftr, bthr, pftr->lc, bthr->lc->lc, bthr->lc->rc, bthr->rc);
362 } else {
363     bthr->lc->RBc = false;
364     if (pftr->ftr) {
365         if (pftr->ftr->lc == pftr)
366             pftr->ftr->lc = bthr;
367         else
368             pftr->ftr->rc = bthr;
369     }
370     bthr->ftr = pftr->ftr;
371     if (_root == pftr)
372         _root = bthr;
373     connect34(bthr, bthr->lc, pftr, bthr->lc->lc, bthr->lc->rc, bthr->rc, pftr->rc);
374 }
375 pftr->ftr->RBc = oldRBc;
376 return;
377 } else if (bthr->rc && bthr->rc->RBc) { ///BB-3
378     bool oldRBc = pftr->RBc;
379     pftr->RBc = false;
380     if (pftr->lc == nn) {
381         bthr->rc->RBc = false;
382         if (pftr->ftr) {
383             if (pftr->ftr->lc == pftr)
384                 pftr->ftr->lc = bthr;
385             else
386                 pftr->ftr->rc = bthr;
387         }
388         bthr->ftr = pftr->ftr;
389         if (_root == pftr)
390             _root = bthr;
391         connect34(bthr, pftr, bthr->rc, pftr->lc, bthr->lc, bthr->rc->lc, bthr->rc->rc);
392     } else {
393         if (pftr->ftr) {
394             if (pftr->ftr->lc == pftr)
395                 pftr->ftr->lc = bthr->rc;
396             else
397                 pftr->ftr->rc = bthr->rc;
398         }
399         bthr->rc->ftr = pftr->ftr;
400         if (_root == pftr)
401             _root = bthr->rc;
402         connect34(bthr->rc, bthr, pftr, bthr->lc, bthr->rc->lc, bthr->rc->rc, pftr->rc);
403     }
404     pftr->ftr->RBc = oldRBc;
405     return;
406 }
407 if (pftr->RBc) { ///BB-2R
408     pftr->RBc = false;
409     bthr->RBc = true;
410     return;
411 } else { ///BB-2B
412     bthr->RBc = true;
413     nn = pftr;
414 }
415 }
416 #ifdef __REDBLACK_DEBUG
417     --blackheight;
418 #endif
419 }
420

```

```

421 template <typename T>
422 typename rbtree<T>::Node* rbtree<T>::findkth(int rank, Node* ptn)
423 {
424     if (!(ptn->lc)) {
425         if (rank == 1) {
426             return ptn;
427         } else {
428             return findkth(rank - 1, ptn->rc);
429         }
430     } else {
431         if (ptn->lc->s == rank - 1)
432             return ptn;
433         else if (ptn->lc->s >= rank)
434             return findkth(rank, ptn->lc);
435         else
436             return findkth(rank - (ptn->lc->s) - 1, ptn->rc);
437     }
438 }
439
440 template <typename T>
441 int rbtree<T>::find_rank(T v, Node* ptn)
442 {
443     if (!ptn)
444         return 1;
445     else if (ptn->val >= v)
446         return find_rank(v, ptn->lc);
447     else
448         return (1 + ((ptn->lc) ? (ptn->lc->s) : 0) + find_rank(v, ptn->rc));
449 }
450
451 template <typename T>
452 int rbtree<T>::get_rank(T v)
453 {
454     return find_rank(v, _root);
455 }
456
457 template <typename T>
458 typename rbtree<T>::Node* rbtree<T>::find(T v, const int op)
459 {
460     Node* ptn = _root;
461     _hot = NULL;
462     while (ptn != NULL) {
463         _hot = ptn;
464         ptn->s += op;
465         if (ptn->val > v)
466             ptn = ptn->lc;
467         else
468             ptn = ptn->rc;
469     }
470     return ptn;
471 }
472
473 template <typename T>
474 typename rbtree<T>::Node* rbtree<T>::rfind(T v, const int op)
475 {
476     Node* ptn = _root;
477     _hot = NULL;
478     while (ptn != NULL && ptn->val != v) {
479         _hot = ptn;
480         ptn->s += op;
481         if (ptn->val > v)
482             ptn = ptn->lc;
483         else
484             ptn = ptn->rc;
485     }

```

```
486     return ptn;
487 }
488
489 template <typename T>
490 struct rbtree<T>::iterator {
491 private:
492     Node* _real__node;
493
494 public:
495     iterator& operator++()
496     {
497         _real__node = _real__node->right_node();
498         return *this;
499     }
500
501     iterator& operator--()
502     {
503         _real__node = _real__node->left_node();
504         return *this;
505     }
506
507     T operator*()
508     {
509         return _real__node->val;
510     }
511
512     iterator(Node* node_nn = NULL)
513         : _real__node(node_nn)
514     {
515     }
516     iterator(T const& val_vv)
517         : _real__node(rfind(val_vv, 0))
518     {
519     }
520     iterator(iterator const& iter)
521         : _real__node(iter._real__node)
522     {
523     }
524 };
525
526 template <typename T>
527 typename rbtree<T>::iterator rbtree<T>::insert(T v)
528 {
529     Node* ptn = find(v, 1);
530     if (_hot == NULL) {
531         init(v);
532         return iterator(_root);
533     }
534     ptn = new Node(v, true, _hot, NULL, NULL, 1);
535     if (_hot->val <= v)
536         _hot->rc = ptn;
537     else
538         _hot->lc = ptn;
539     SolveDoubleRed(ptn);
540     return iterator(ptn);
541 }
542
543 template <typename T>
544 bool rbtree<T>::remove(T v)
545 {
546     Node* ptn = rfind(v, -1);
547     if (!ptn)
548         return false;
549     Node* node_suc;
550     while (ptn->lc || ptn->rc) {
```

```

551     if (!(ptn->lc)) {
552         node_suc = ptn->rc;
553     } else if (!(ptn->rc)) {
554         node_suc = ptn->lc;
555     } else {
556         node_suc = ptn->succ();
557     }
558     --(ptn->s);
559     ptn->val = node_suc->val;
560     ptn = node_suc;
561 }
562 if (!(ptn->RBc)) {
563     --(ptn->s);
564     SolveDoubleBlack(ptn);
565 }
566 if (ptn->ftr->lc == ptn)
567     ptn->ftr->lc = NULL;
568 else
569     ptn->ftr->rc = NULL;
570 delete ptn;
571 return true;
572 }
573
574 template <typename T>
575 int rbtree<T>::size()
576 {
577     return _root->s;
578 }
579
580 template <typename T>
581 typename rbtree<T>::iterator rbtree<T>::kth(int rank)
582 {
583     return iterator(findkth(rank, _root));
584 }
585
586 template <typename T>
587 typename rbtree<T>::iterator rbtree<T>::lower_bound(T v)
588 {
589     Node* ptn = _root;
590     while (ptn) {
591         _hot = ptn;
592         if (ptn->val < v) {
593             ptn = ptn->rc;
594         } else {
595             ptn = ptn->lc;
596         }
597     }
598     if (_hot->val < v) {
599         ptn = _hot;
600     } else {
601         ptn = _hot->left_node();
602     }
603     return iterator(ptn);
604 }
605
606 template <typename T>
607 typename rbtree<T>::iterator rbtree<T>::upper_bound(T v)
608 {
609     Node* ptn = _root;
610     while (ptn) {
611         _hot = ptn;
612         if (ptn->val > v) {
613             ptn = ptn->lc;
614         } else {
615             ptn = ptn->rc;

```

```

616     }
617 }
618 if (_hot->val > v) {
619     ptn = _hot;
620 } else {
621     ptn = _hot->right_node();
622 }
623 return iterator(ptn);
624 }

```

1.10 RBTREE

```

1  template <typename T>
2  struct rbtree {
3      struct node {
4          T val;
5          int sz, cnt;
6          node *l, *r, *p;
7          bool color;
8      };
9      node buf[N << 3], *s = buf;
10     node* nil = ++s;
11     node* root = nil;
12     node* find_min(node* x)
13     {
14         while (x->l != nil)
15             x = x->l;
16         return x;
17     }
18     node* find_max(node* x)
19     {
20         while (x->r != nil)
21             x = x->r;
22         return x;
23     }
24     node* find_node(const T& val)
25     {
26         node* x = root;
27         while (x != nil) {
28             if (x->val == val)
29                 return x;
30             if (x->val < val)
31                 x = x->r;
32             else
33                 x = x->l;
34         }
35         return NULL;
36     }
37     void zig(node* x)
38     {
39         node* y = x->r;
40         x->r = y->l;
41         if (y->l != nil)
42             y->l->p = x;
43         y->p = x->p;
44         if (x->p == nil)
45             root = y;
46         else if (x == x->p->r)
47             x->p->r = y;
48         else
49             x->p->l = y;
50         y->l = x;
51         x->p = y;
52         y->sz = x->sz;

```

```

53     x->sz = x->l->sz + x->r->sz + x->cnt;
54     return;
55 }
56 void zag(node* x)
57 {
58     node* y = x->l;
59     x->l = y->r;
60     if (y->r != nil)
61         y->r->p = x;
62     y->p = x->p;
63     if (x->p == nil)
64         root = y;
65     else if (x == x->p->l)
66         x->p->l = y;
67     else
68         x->p->r = y;
69     y->r = x;
70     x->p = y;
71     y->sz = x->sz;
72     x->sz = x->l->sz + x->r->sz + x->cnt;
73     return;
74 }
75 void insert_fixup(node* z)
76 {
77     while (z->p->color == 1) {
78         if (z->p == z->p->p->l) {
79             node* y = z->p->p->r;
80             if (y->color == 1) {
81                 y->color = z->p->color = 0;
82                 z->p->p->color = 1;
83                 z = z->p->p;
84             } else {
85                 if (z == z->p->r) {
86                     z = z->p;
87                     zig(z);
88                 }
89                 z->p->color = 0;
90                 z->p->p->color = 1;
91                 zag(z->p->p);
92             }
93         } else {
94             node* y = z->p->p->l;
95             if (y->color == 1) {
96                 y->color = z->p->color = 0;
97                 z->p->p->color = 1;
98                 z = z->p->p;
99             } else {
100                 if (z == z->p->l) {
101                     z = z->p;
102                     zag(z);
103                 }
104                 z->p->color = 0;
105                 z->p->p->color = 1;
106                 zig(z->p->p);
107             }
108         }
109     }
110     root->color = 0;
111     return;
112 }
113 void transplant(node* x, node* y)
114 {
115     y->p = x->p;
116     if (x->p == nil)
117         root = y;

```



```
118     else if (x == x->p->l)
119         x->p->l = y;
120     else
121         x->p->r = y;
122     return;
123 }
124 void delete_fixup(node* x)
125 {
126     while (x != root && x->color == 0) {
127         if (x == x->p->l) {
128             node* w = x->p->r;
129             if (w->color == 1) {
130                 x->p->color = 1;
131                 w->color = 0;
132                 zig(x->p);
133                 w = x->p->r;
134             }
135             if (w->l->color == 0 && w->r->color == 0) {
136                 w->color = 1;
137                 x = x->p;
138             } else {
139                 if (w->r->color == 0) {
140                     w->color = 1;
141                     w->l->color = 0;
142                     zag(w);
143                     w = x->p->r;
144                 }
145                 w->color = x->p->color;
146                 x->p->color = 0;
147                 w->r->color = 0;
148                 zig(w->p);
149                 x = root;
150             }
151         } else {
152             node* w = x->p->l;
153             if (w->color == 1) {
154                 x->p->color = 1;
155                 w->color = 0;
156                 zag(x->p);
157                 w = x->p->l;
158             }
159             if (w->r->color == 0 && w->l->color == 0) {
160                 w->color = 1;
161                 x = x->p;
162             } else {
163                 if (w->l->color == 0) {
164                     w->color = 1;
165                     w->r->color = 0;
166                     zig(w);
167                     w = x->p->l;
168                 }
169                 w->color = x->p->color;
170                 x->p->color = 0;
171                 w->l->color = 0;
172                 zag(w->p);
173                 x = root;
174             }
175         }
176     }
177     x->color = 0;
178     return;
179 }
180 void ins(const T& val)
181 {
182     node* x = root;
```

```
183     node* y = nil;
184     while (x != nil) {
185         y = x;
186         ++y->sz;
187         if (x->val == val) {
188             ++x->cnt;
189             return;
190         }
191         if (x->val < val)
192             x = x->r;
193         else
194             x = x->l;
195     }
196     node* z = ++s;
197     *z = (node) { val, 1, 1, nil, nil, y, 1 };
198     if (y == nil)
199         root = z;
200     else {
201         if (y->val < val)
202             y->r = z;
203         else
204             y->l = z;
205     }
206     insert_fixup(z);
207     return;
208 }
209 void del(const T& val)
210 {
211     node* z = root;
212     node* w = nil;
213     while (z != nil) {
214         w = z;
215         --w->sz;
216         if (z->val == val)
217             break;
218         if (z->val < val)
219             z = z->r;
220         else
221             z = z->l;
222     }
223     if (z != nil) {
224         // delete only one node
225         if (z->cnt > 1) {
226             --z->cnt;
227             return;
228         }
229
230         node* y = z;
231         node* x;
232         bool history = y->color;
233         if (z->l == nil) {
234             x = z->r;
235             transplant(z, z->r);
236         } else if (z->r == nil) {
237             x = z->l;
238             transplant(z, z->l);
239         } else {
240             y = find_min(z->r);
241             history = y->color;
242             x = y->r;
243             if (y->p == z)
244                 x->p = y;
245             else {
246                 node* w = y;
247                 while (w != z) {
```

```

248         w->sz -= y->cnt;
249         w = w->p;
250     }
251     transplant(y, y->r);
252     y->r = z->r;
253     y->r->p = y;
254 }
255 transplant(z, y);
256 y->l = z->l;
257 y->l->p = y;
258 y->color = z->color;
259 y->sz = y->l->sz + y->r->sz + y->cnt;
260 }
261 if (history == 0)
262     delete_fixup(x);
263 } else
264     while (w != nil) {
265         ++w->sz;
266         w = w->p;
267     }
268 return;
269 }
270 T getKth(int k)
271 {
272     T res = 0;
273     node* x = root;
274     while (x != nil) {
275         if (x->l->sz + 1 <= k && x->l->sz + x->cnt >= k) {
276             res = x->val;
277             break;
278         } else if (x->l->sz + x->cnt < k) {
279             k -= x->l->sz + x->cnt;
280             x = x->r;
281         } else {
282             x = x->l;
283         }
284     }
285     return res;
286 }
287 int getRank(const T& val)
288 {
289     int rk = 0;
290     node* x = root;
291     while (x != nil) {
292         if (x->val < val) {
293             rk += x->l->sz + x->cnt;
294             x = x->r;
295         } else {
296             if (x->val == val)
297                 ++rk;
298             x = x->l;
299         }
300     }
301     return rk;
302 }
303 T getSucc(const T& val)
304 {
305     ins(val);
306     T res = INT_MAX;
307     node* x = find_node(val);
308     if (x->r != nil) {
309         res = find_min(x->r)->val;
310     } else {
311         while (x->p->r == x)
312             x = x->p;

```

```

313         if (x->p != nil)
314             res = x->p->val;
315     }
316     del(val);
317     return res;
318 }
319 T getPrev(const T& val)
320 {
321     ins(val);
322     T res = INT_MIN;
323     node* x = find_node(val);
324     if (x->l != nil)
325         res = find_max(x->l)->val;
326     else {
327         while (x->p->l == x)
328             x = x->p;
329         if (x->p != nil)
330             res = x->p->val;
331     }
332     del(val);
333     return res;
334 }
335 };

```

1.11 RMQ

```

1  const int LG = log2(N) + 1;
2  int mi[N][LG], lg[N];
3  void init_rmq(int n) {
4      lg[1] = 0;
5      for (int i = 2; i <= n; ++i) lg[i] = lg[i >> 1] + 1;
6  }
7
8  void build_rmq(int n, int* a) {
9      for (int i = 1; i <= n; ++i) mi[i][0] = a[i];
10     for (int j = 1; j <= lg[n]; ++j) {
11         for (int i = 1; i + (1 << (j - 1)) <= n; ++i) {
12             mi[i][j] = min(mi[i][j - 1], mi[i + (1 << (j - 1))][j - 1]);
13         }
14     }
15 }
16
17 int rmqMin(int l, int r) {
18     int k = lg[r - l + 1];
19     return min(mi[l][k], mi[r - (1 << k) + 1][k]);
20 }

```

1.12 RollBackCaptainMo

```

1  // Roll Back Captain Mo
2  // 询问 [L, r] 内值相同的元素的最远距离
3  int Ans, ans[N];
4  int block_sz, block_cnt, block_id[N], L[N], R[N];
5  struct Query {
6      int l, r, id;
7      Query() {}
8      Query(int _l, int _r, int _id) : l(_l), r(_r), id(_id) {}
9      bool operator < (const Query& q) const {
10         if (block_id[l] == block_id[q.l]) return r < q.r;
11         return block_id[l] < block_id[q.l];
12     }
13 } Q[N];

```

```

14
15 int n, m, q, a[N], b[N];
16
17
18 int nums[N], cn;
19 int mi[N], ma[N];
20 int __mi[N];
21
22 int brute_force(int l, int r) {
23     int res = 0;
24     for (int i = l; i <= r; ++i) __mi[a[i]] = 0;
25     for (int i = l; i <= r; ++i) {
26         if (__mi[a[i]]) res = max(res, i - __mi[a[i]]);
27         else __mi[a[i]] = i;
28     }
29     return res;
30 }
31
32 inline void addl(int p) {
33     if (ma[a[p]]) Ans = max(Ans, ma[a[p]] - p);
34     else ma[a[p]] = p;
35 }
36
37 inline void addr(int p) {
38     ma[a[p]] = p;
39     if (!mi[a[p]]) mi[a[p]] = p, nums[++cn] = a[p];
40     Ans = max(Ans, p - mi[a[p]]);
41 }
42
43 inline void dell(int p) {
44     if (ma[a[p]] == p) ma[a[p]] = 0;
45 }
46
47 inline void delr(int p) {
48
49 }
50
51 inline void clear() {
52     for (int i = 1; i <= cn; ++i) mi[nums[i]] = ma[nums[i]] = 0;
53 }
54
55 void RollBackCaptainMo() {
56     block_sz = sqrt(n); block_cnt = n / block_sz;
57
58     for (int i = 1; i <= block_cnt; ++i) L[i] = R[i - 1] + 1, R[i] = i * block_sz;
59     if (R[block_cnt] < n) { ++block_cnt; L[block_cnt] = R[block_cnt - 1] + 1; R[block_cnt] = n; }
60
61     for (int i = 1; i <= block_cnt; ++i)
62         for (int j = L[i]; j <= R[i]; ++j)
63             block_id[j] = i;
64
65     sort(Q + 1, Q + 1 + q);
66
67     for (int i = 1, j = 1; j <= block_cnt; ++j) {
68         int l = R[j] + 1, r = R[j];
69         Ans = 0; cn = 0;
70         for (; block_id[Q[i].l] == j; ++i) {
71             if (block_id[Q[i].l] == block_id[Q[i].r]) ans[Q[i].id] = brute_force(Q[i].l, Q[i].r);
72             else {
73                 while(r < Q[i].r) ++r, addr(r);
74                 int tmp = Ans;
75                 while(l > Q[i].l) --l, addl(l);
76                 ans[Q[i].id] = Ans;
77                 while(l <= R[j]) dell(l), ++l;
78                 Ans = tmp;

```

```

79         }
80     }
81     clear();
82 }
83 }

```

1.13 SegmentTree

```

1  class segtree {
2  public:
3      struct node {
4          // 声明变量, 记得设置初始值
5          // ie. 最大值: int mx = INT_MIN;
6
7          ...
8
9          void apply(int l, int r, ll addv) {
10             // 更新节点信息
11             // ie. 最大值 + 区间加: mx = mx + addv
12
13             ...
14         }
15     };
16
17     friend node operator + (const node& t1, const node& tr) {
18         node t;
19         // 合并两个区间的信息
20         // ie. 区间和: t.sum = t1.sum + t2.sum;
21
22         ...
23
24         return t;
25     }
26
27     inline void push_down(int x, int l, int r) {
28         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
29         // 标记下传
30         // ie. 区间加法
31         // if (tr[x].add != 0) {
32         //     tr[lc].apply(l, mid, tr[x].add);
33         //     tr[rc].apply(mid + 1, r, tr[x].add);
34         //     tr[x].add = 0;
35         // }
36
37         ...
38     }
39
40     /*****
41     inline void push_up(int x) {
42         int lc = x << 1, rc = lc | 1;
43         tr[x] = tr[lc] + tr[rc];
44     }
45
46     int n;
47     vector<node> tr;
48
49     void build(int x, int l, int r) {
50         if (l == r) {
51             return;
52         }
53         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
54         build(lc, l, mid);
55         build(rc, mid + 1, r);
56         push_up(x);

```

```

57     }
58
59     template<class T>
60     void build(int x, int l, int r, const vector<T>& arr){
61         if (l == r) {
62             tr[x].apply(l, r, arr[l]);
63             return;
64         }
65         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
66         build(lc, l, mid, arr);
67         build(rc, mid + 1, r, arr);
68         push_up(x);
69     }
70
71     template<class T>
72     void build(int x, int l, int r, T* arr){
73         if (l == r) {
74             tr[x].apply(l, r, arr[l]);
75             return;
76         }
77         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
78         build(lc, l, mid);
79         build(rc, mid + 1, r);
80         push_up(x);
81     }
82
83     node get(int x, int l, int r, int L, int R) {
84         if (L <= l && r <= R) {
85             return tr[x];
86         }
87         push_down(x, l, r);
88         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
89         node res;
90         if (R <= mid) res = get(lc, l, mid, L, R);
91         else if (L > mid) res = get(rc, mid + 1, r, L, R);
92         else res = get(lc, l, mid, L, mid) + get(rc, mid + 1, r, mid + 1, R);
93         push_up(x);
94         return res;
95     }
96
97     template<class... T>
98     void upd(int x, int l, int r, int L, int R, const T&... v) {
99         if (L <= l && r <= R) {
100             tr[x].apply(l, r, v...);
101             return;
102         }
103         push_down(x, l, r);
104         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
105         node res;
106         if (L <= mid) upd(lc, l, mid, L, R, v...);
107         if (R > mid) upd(rc, mid + 1, r, L, R, v...);
108         push_up(x);
109     }
110
111     int __get_first(int x, int l, int r, const function<bool(const node&)> &f) {
112         if (l == r) {
113             return l;
114         }
115         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
116         push_down(x, l, r);
117         int res;
118         if (f(tr[lc])) res = __get_first(lc, l, mid, f);
119         else res = __get_first(rc, mid + 1, r, f);
120         push_up(x);
121         return res;

```

```

122     }
123
124     int get_first(int x, int l, int r, int L, int R, const function<bool(const node&)> &f) {
125         if (L <= l && r <= R) {
126             if (!f(tr[x])) {
127                 return -1;
128             }
129             return __get_first(x, l, r, f);
130         }
131         push_down(x, l, r);
132         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
133         int res;
134         if (L <= mid) res = get_first(lc, l, mid, L, R, f);
135         if (res == -1 && R > mid) res = get_first(rc, mid + 1, r, L, R, f);
136         push_up(x);
137         return res;
138     }
139
140     int __get_last(int x, int l, int r, const function<bool(const node&)> &f) {
141         if (l == r) {
142             return l;
143         }
144         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
145         push_down(x, l, r);
146         int res;
147         if (f(tr[lc])) res = __get_first(rc, mid + 1, r, f);
148         else res = __get_first(lc, l, mid, f);
149         push_up(x);
150         return res;
151     }
152
153     int get_last(int x, int l, int r, int L, int R, const function<bool(const node&)> &f) {
154         if (L <= l && r <= R) {
155             if (!f(tr[x])) {
156                 return -1;
157             }
158             return __get_first(x, l, r, f);
159         }
160         push_down(x, l, r);
161         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
162         int res;
163         if (R > mid) res = get_last(rc, mid + 1, r, L, R, f);
164         if (res == -1 && L <= mid) res = get_last(lc, l, mid, L, R, f);
165         push_up(x);
166         return res;
167     }
168
169     int find_first(int l, int r, const function<bool(const node&)> &f) {
170         int L = l, R = r, mid, res = -1;
171         while(L <= R) {
172             mid = (L + R) >> 1;
173             if (f(get(l, mid))) R = mid - 1, res = mid;
174             else L = mid + 1;
175         }
176         return res;
177     }
178
179     int find_last(int l, int r, const function<bool(const node&)> &f) {
180         int L = l, R = r, mid, res = -1;
181         while(L <= R) {
182             mid = (L + R) >> 1;
183             if (f(get(l, mid))) L = mid + 1, res = mid;
184             else R = mid - 1;
185         }
186         return res;

```



```

187     }
188
189     segtree(int _n) : n(_n) {
190         assert(n > 0);
191         tr.resize((n << 2) + 5);
192         build(1, 1, n);
193     }
194
195     template<class T>
196     segtree(const vector<T>& arr) {
197         n = arr.size() - 1;
198         assert(n > 0);
199         tr.resize((n << 2) + 5);
200         build(1, 1, n, arr);
201     }
202
203     template<class T>
204     segtree(int _n, T* arr) {
205         n = _n;
206         assert(n > 0);
207         tr.resize((n << 2) + 5);
208         build(1, 1, n, arr);
209     }
210
211     node get(int l, int r) {
212         assert(l >= 1 && l <= r && r <= n);
213         return get(1, 1, n, l, r);
214     }
215
216     node get(int p) {
217         assert(1 <= p && p <= n);
218         return get(1, 1, n, p, p);
219     }
220
221     template <class... T>
222     void upd(int l, int r, const T&... v) {
223         assert(l >= 1 && l <= r && r <= n);
224         upd(1, 1, n, l, r, v...);
225     }
226
227     template <class... T>
228     void upd1(int p, const T&... v) {
229         assert(p >= 1 && p <= n);
230         upd(1, 1, n, p, p, v...);
231     }
232
233     int get_first(int l, int r, const function<bool(const node&)> &f) {
234         assert(l >= 1 && l <= r && r <= n);
235         return get_first(1, 1, n, l, r, f);
236     }
237
238
239     int get_last(int l, int r, const function<bool(const node&)> &f) {
240         assert(l >= 1 && l <= r && r <= n);
241         return get_last(1, 1, n, l, r, f);
242     }
243
244     void print(int x, int l, int r) {
245         if (l == r) {
246             cerr << tr[x].sum << " ";
247             return;
248         }
249         push_down(x, l, r);
250         int lc = x << 1, rc = lc | 1, mid = (l + r) >> 1;
251         print(lc, l, mid);

```

```

252     print(rc, mid + 1, r);
253 }
254
255 void print() {
256     #ifdef BACKLIGHT
257     cerr << "SGTREE: " << endl;
258     print(1, 1, n);
259     cerr << "\n-----" << endl;
260     #endif
261 }
262 };

```

1.14 SGTree

```

1  template<typename T>
2  struct SGTree {
3      static constexpr double alpha = 0.75; // alpha \in (0.5, 1)
4      int root, tot, buf_size;
5      T v[N];
6      int s[N], sz[N], sd[N], cnt[N], l[N], r[N], buf[N];
7
8
9      SGTree()
10     {
11         root = tot = 0;
12     }
13
14     int new_node(T _v)
15     {
16         ++tot;
17         v[tot] = _v;
18         s[tot] = sz[tot] = sd[tot] = cnt[tot] = 1;
19         l[tot] = r[tot] = 0;
20         return tot;
21     }
22
23     void push_up(int x)
24     {
25         if (!x) return;
26         int lc = l[x], rc = r[x];
27         s[x] = s[lc] + 1 + s[rc];
28         sz[x] = sz[lc] + cnt[x] + sz[rc];
29         sd[x] = sd[lc] + (cnt[x] != 0) + sd[rc];
30     }
31
32     bool balance(int x)
33     {
34         int lc = l[x], rc = r[x];
35         if (alpha * s[x] <= max(s[lc], s[rc])) return false;
36         if (alpha * s[x] >= sd[x]) return false;
37         return true;
38     }
39
40     void flatten(int x)
41     {
42         if (!x) return;
43         flatten(l[x]);
44         if (cnt[x]) buf[++buf_size] = x;
45         flatten(r[x]);
46     }
47
48     void build(int& x, int L, int R)
49     {
50         if (L > R) {

```

```

51         x = 0;
52         return;
53     }
54     int mid = (L + R) >> 1;
55     x = buf[mid];
56     build(l[x], L, mid - 1);
57     build(r[x], mid + 1, R);
58     push_up(x);
59 }
60
61 void rebuild(int& x)
62 {
63     buf_size = 0;
64     flatten(x);
65     build(x, 1, buf_size);
66 }
67
68 void ins(int& rt, T val)
69 {
70     if (!rt) {
71         rt = new_node(val);
72         return;
73     }
74     if (val == v[rt]) {
75         ++cnt[rt];
76     } else if (val < v[rt]) {
77         ins(l[rt], val);
78     } else {
79         ins(r[rt], val);
80     }
81     push_up(rt);
82     if (!balance(rt)) rebuild(rt);
83 }
84
85 void del(int &rt, T val)
86 {
87     if (!rt) return;
88
89     if (val == v[rt]) {
90         if (cnt[rt] -- cnt[rt];
91     } else if (val < v[rt]) {
92         del(l[rt], val);
93     } else {
94         del(r[rt], val);
95     }
96     push_up(rt);
97     if (!balance(rt)) rebuild(rt);
98 }
99
100 int getPrevRank(int rt, T val)
101 {
102     if (!rt) return 0;
103     if (v[rt] == val && cnt[rt]) return sz[l[rt]];
104     if (v[rt] < val) return sz[l[rt]] + cnt[rt] + getPrevRank(r[rt], val);
105     return getPrevRank(l[rt], val);
106 }
107
108 int getSuccRank(int rt, T val)
109 {
110     if (!rt) return 1;
111     if (v[rt] == val && cnt[rt]) return sz[l[rt]] + cnt[rt] + 1;
112     if (v[rt] < val) return sz[l[rt]] + cnt[rt] + getSuccRank(r[rt], val);
113     return getSuccRank(l[rt], val);
114 }
115

```

```

116
117 T getKth(int rt, int k)
118 {
119     if (!rt) return 0;
120     if (k <= sz[l[rt]]) return getKth(l[rt], k);
121     if (k - sz[l[rt]] <= cnt[rt]) return v[rt];
122     return getKth(r[rt], k - sz[l[rt]] - cnt[rt]);
123 }
124
125 void ins(T val)
126 {
127     ins(root, val);
128 }
129
130 void del(T val)
131 {
132     del(root, val);
133 }
134
135 int getRank(T val)
136 {
137     return getPrevRank(root, val) + 1;
138 }
139
140 T getKth(int k)
141 {
142     return getKth(root, k);
143 }
144
145 T getPrev(T val)
146 {
147     return getKth(getPrevRank(root, val));
148 }
149
150 T getSucc(T val)
151 {
152     return getKth(getSuccRank(root, val));
153 }
154
155 void debug(int x)
156 {
157     if (!x) return;
158     debug(l[x]);
159     cerr << v[x] << " ";
160     debug(r[x]);
161 }
162
163 void debug()
164 {
165     cerr << "SGTree:" << endl;
166     debug(root);
167     cerr << endl;
168 }
169 };

```

1.15 Splay

```

1 namespace Backlight {
2
3 namespace Splay {
4     using T = int;
5     #define ls ch[x][0]
6     #define rs ch[x][1]
7     const int S = N;

```

```

8
9     int tot, rt, sz[S], cnt[S], ch[S][2], fa[S];
10
11     T v[S];
12
13     inline void init() { tot = rt = 0; }
14
15     inline void clear(int x) { ch[x][0] = ch[x][1] = fa[x] = sz[x] = cnt[x] = v[x] = 0; }
16
17     inline int get(int x) { return ch[fa[x]][1] == x; }
18
19     inline int newnode(T val) {
20         ++tot;
21         sz[tot] = cnt[tot] = 1;
22         ch[tot][0] = ch[tot][1] = fa[tot] = 0;
23         v[tot] = val;
24         return tot;
25     }
26
27     inline void push_up(int x) {
28         if (!x) return;
29         sz[x] = sz[ls] + cnt[x] + sz[rs];
30     }
31
32     void rotate(int x) {
33         int f = fa[x], g = fa[f], i = get(x);
34         ch[f][i] = ch[x][i^1]; fa[ch[f][i]] = f;
35         ch[x][i^1] = f; fa[f] = x;
36         fa[x] = g;
37         if (g) ch[g][ch[g][1] == f] = x;
38         push_up(f); push_up(x);
39     }
40
41     void splay(int x, int ed) {
42         for (int f; (f = fa[x]) != ed; rotate(x))
43             if (fa[f] != ed) rotate((get(x) == get(f) ? f : x));
44         if (ed == 0) rt = x;
45     }
46
47
48     void insert(T val) {
49         if (rt == 0) { rt = newnode(val); return; }
50         int p = rt, f = 0;
51         while(true) {
52             if (val == v[p]) {
53                 ++cnt[p];
54                 push_up(p); push_up(f);
55                 break;
56             }
57             f = p;
58             p = ch[p][v[p] < val];
59             if (p == 0) {
60                 p = newnode(val);
61                 fa[p] = f; ch[f][v[f] < val] = p;
62                 push_up(f);
63                 break;
64             }
65         }
66         splay(p, 0);
67     }
68
69     int getrank(T val) {
70         int p = rt, res = 0;
71         while(p) {
72             if (v[p] > val) p = ch[p][0];

```

```

73         else {
74             res += sz[ch[p][0]];
75             if (v[p] == val) break;
76             res += cnt[p];
77             p = ch[p][1];
78         }
79     }
80     assert(p != 0);
81     splay(p, 0);
82     return res + 1;
83 }
84
85 T getkth(int k) {
86     int p = rt, res = 0;
87     while(p) {
88         if (k <= sz[ch[p][0]]) p = ch[p][0];
89         else {
90             if (k <= sz[ch[p][0]] + cnt[p]) { res = v[p]; break; }
91             else k -= sz[ch[p][0]] + cnt[p], p = ch[p][1];
92         }
93     }
94     assert(p != 0);
95     splay(p, 0);
96     return res;
97 }
98
99 void remove(T val) {
100     getrank(val); // splay val to root
101     if (cnt[rt] > 1) { --cnt[rt]; push_up(rt); return; }
102     if (!ch[rt][0] && !ch[rt][1]) { clear(rt); rt = 0; return; }
103     if (!ch[rt][0] || !ch[rt][1]) {
104         int nrt = ch[rt][0] ? ch[rt][0] : ch[rt][1];
105         clear(rt); rt = nrt; fa[rt] = 0;
106         return;
107     }
108     int ort = rt;
109     int p = ch[rt][0]; while(ch[p][1]) p = ch[p][1];
110     splay(p, 0);
111     ch[rt][1] = ch[ort][1];
112     fa[ch[ort][1]] = rt;
113     clear(ort);
114     push_up(rt);
115 }
116
117 T getpre(T val) {
118     int p = rt, res = -INF;
119     while(p) {
120         if (v[p] < val && v[p] > res) res = v[p];
121         if (val > v[p]) p = ch[p][1];
122         else p = ch[p][0];
123     }
124     // splay(p, 0);
125     return res;
126 }
127
128 T getsuc(T val) {
129     int p = rt, res = INF;
130     while(p) {
131         if (v[p] > val && v[p] < res) res = v[p];
132         if (val < v[p]) p = ch[p][0];
133         else p = ch[p][1];
134     }
135     // splay(p, 0);
136     return res;
137 }

```

```

138
139 void DEBUG(int x) {
140     if (!x) return;
141     DEBUG(ls);
142     cerr << v[x] << " ";
143     DEBUG(rs);
144 }
145
146 void DEBUG() {
147     cerr << "Splay: ";
148     DEBUG(rt);
149     cerr << endl;
150 }
151 } // namespace Splay
152
153 } // namespace Backlight

```

1.16 Treap-pointer

```

1 // mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
2 // inline unsigned rng() {
3 //     static unsigned x = 7;
4 //     return x = x * 0xdefaced + 1;
5 // }
6
7 template <typename T>
8 struct Treap {
9     struct node {
10         node *l, *r;
11         unsigned rnd;
12         T v;
13         int sz;
14         node(T _v)
15             : l(NULL)
16             , r(NULL)
17             , rnd(rng())
18             , sz(1)
19             , v(_v)
20         {
21         }
22     };
23
24     inline int get_size(node*& p)
25     {
26         return p ? p->sz : 0;
27     }
28
29     inline void push_up(node*& p)
30     {
31         if (!p)
32             return;
33         p->sz = get_size(p->l) + get_size(p->r) + 1;
34     }
35
36     node* root = NULL;
37
38     node* merge(node* a, node* b)
39     {
40         if (!a)
41             return b;
42         if (!b)
43             return a;
44         if (a->rnd < b->rnd) {
45             a->r = merge(a->r, b);

```

```
46         push_up(a);
47         return a;
48     } else {
49         b->l = merge(a, b->l);
50         push_up(b);
51         return b;
52     }
53 }
54
55 void split_val(node* p, const T& k, node*& a, node*& b)
56 {
57     if (!p)
58         a = b = NULL;
59     else {
60         if (p->v <= k) {
61             a = p;
62             split_val(p->r, k, a->r, b);
63             push_up(a);
64         } else {
65             b = p;
66             split_val(p->l, k, a, b->l);
67             push_up(b);
68         }
69     }
70 }
71
72 void split_size(node* p, int k, node*& a, node*& b)
73 {
74     if (!p)
75         a = b = NULL;
76     else {
77         if (get_size(p->l) < k) {
78             a = p;
79             split_size(p->r, k - get_size(p->l) - 1, a->r, b);
80             push_up(a);
81         } else {
82             b = p;
83             split_size(p->l, k, a, b->l);
84             push_up(b);
85         }
86     }
87 }
88
89 void ins(T val)
90 {
91     node *a, *b;
92     split_val(root, val, a, b);
93     a = merge(a, new node(val));
94     root = merge(a, b);
95 }
96
97 void del(T val)
98 {
99     node *a, *b, *c, *d;
100     split_val(root, val, a, b);
101     split_val(a, val - 1, c, d);
102     node* e = d;
103     d = merge(d->l, d->r);
104     delete e;
105     a = merge(c, d);
106     root = merge(a, b);
107 }
108
109 T getRank(T val)
110 {
```



```

111     node *a, *b;
112     split_val(root, val - 1, a, b);
113     T res = get_size(a) + 1;
114     root = merge(a, b);
115     return res;
116 }
117
118 T getKth(int k)
119 {
120     node* x = root;
121     T res = numeric_limits<T>::min();
122     while (x) {
123         if (k <= get_size(x->l))
124             x = x->l;
125         else {
126             if (get_size(x->l) + 1 == k) {
127                 res = x->v;
128                 break;
129             } else {
130                 k -= get_size(x->l) + 1;
131                 x = x->r;
132             }
133         }
134     }
135     return res;
136 }
137
138 T getPrev(T val)
139 {
140     node *a, *b;
141     split_val(root, val - 1, a, b);
142     node* p = a;
143     while (p->r)
144         p = p->r;
145     root = merge(a, b);
146     return p->v;
147 }
148
149 T getSucc(T val)
150 {
151     node *a, *b;
152     split_val(root, val, a, b);
153     node* p = b;
154     while (p->l)
155         p = p->l;
156     root = merge(a, b);
157     return p->v;
158 }
159 };

```

1.17 Treap

```

1 namespace Treap {
2     using T = long long;
3     const int S = N;
4     mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
5
6     int tot, rt, sz[S], L[S], R[S], rnd[S];
7
8     T v[S];
9
10    inline void init() {
11        tot = rt = 0;
12    }

```

```

13
14 inline int newnode(T val) {
15     ++tot;
16     sz[tot] = 1;
17     L[tot] = R[tot] = 0;
18     rnd[tot] = rng();
19     v[tot] = val;
20     return tot;
21 }
22
23 inline void push_up(int x) {
24     sz[x] = sz[L[x]] + 1 + sz[R[x]];
25 }
26
27 void split(int u, T k, int &x, int &y) {
28     if (!u) x = y = 0;
29     else {
30         if (v[u] <= k) {
31             x = u;
32             split(R[u], k, R[u], y);
33         } else {
34             y = u;
35             split(L[u], k, x, L[u]);
36         }
37         push_up(u);
38     }
39 }
40
41 int merge(int x, int y) {
42     if (!x || !y) return x | y;
43     if (rnd[x] < rnd[y]) {
44         R[x] = merge(R[x], y);
45         push_up(x);
46         return x;
47     } else {
48         L[y] = merge(x, L[y]);
49         push_up(y);
50         return y;
51     }
52 }
53
54 void insert(T val) {
55     int x, y;
56     split(rt, val, x, y);
57     x = merge(x, newnode(val));
58     rt = merge(x, y);
59 }
60
61 void remove(T val) {
62     int x1, y1, x2, y2;
63     split(rt, val, x1, y1);
64     split(x1, val - 1, x2, y2);
65     y2 = merge(L[y2], R[y2]);
66     x1 = merge(x2, y2);
67     rt = merge(x1, y1);
68 }
69
70 int getrank(T val) {
71     int x, y;
72     split(rt, val - 1, x, y);
73     int res = sz[x] + 1;
74     rt = merge(x, y);
75     return res;
76 }
77

```

```

78     T getkth(int k) {
79         int u = rt;
80         while(true) {
81             if (k <= sz[L[u]]) u = L[u];
82             else {
83                 if (sz[L[u]] + 1 == k) break;
84                 else k -= sz[L[u]] + 1, u = R[u];
85             }
86         }
87         return v[u];
88     }
89
90     T getpre(T val) {
91         int x, y;
92         split(rt, val - 1, x, y);
93         int p = x;
94         while(R[p]) p = R[p];
95         rt = merge(x, y);
96         return v[p];
97     }
98
99     T getsuc(T val) {
100         int x, y;
101         split(rt, val, x, y);
102         int p = y;
103         while(L[p]) p = L[p];
104         rt = merge(x, y);
105         return v[p];
106     }
107
108     void DEBUG(int u) {
109         if (!u) return;
110         DEBUG(L[u]);
111         cerr << v[u] << " ";
112         DEBUG(R[u]);
113     }
114
115     void DEBUG() {
116         cerr << "Treap: ";
117         DEBUG(rt);
118         cerr << endl;
119     }
120 }

```

2 graph

2.1 BCC-Edge

```

1  namespace Backlight {
2
3  struct Graph {
4      #define fore(i, u) for (int i = h[u]; i; i = e[i].nxt)
5      struct Edge {
6          int v, nxt;
7          Edge(){}
8          Edge(int _v, int _nxt): v(_v), nxt(_nxt) {}
9      };
10
11      int V, E, tot;
12      vector<int> h;
13      vector<Edge> e;
14
15      Graph() : V(0) {}

```

```

16 Graph(int _V, int _E) : V(_V), E(2 * _E), tot(0), h(_V + 1), e(2 * _E + 1) { }
17
18 inline void addarc(int u, int v) {
19     assert(1 <= u && u <= V);
20     assert(1 <= v && v <= V);
21
22     e[++tot] = Edge(v, h[u]); h[u] = tot;
23 }
24
25 inline void addedge(int u, int v) {
26     addarc(u, v);
27     addarc(v, u);
28 }
29
30 /*****
31 int bcc_clock, bcc_cnt;
32 vector<int> dfn, low, belong, bcc_size;
33 vector<vector<int>>> bcc;
34 vector<bool> bridge;
35
36 void tarjan(int u, int fa) {
37     dfn[u] = low[u] = ++bcc_clock;
38     fore(i, u) {
39         int v = e[i].v;
40         if (v == fa) continue;
41
42         if (!dfn[v]) {
43             tarjan(v, u);
44             low[u] = min(low[u], low[v]);
45             if (dfn[u] < low[v]) {
46                 bridge[i] = true;
47                 if (i & 1) bridge[i + 1] = true;
48                 else bridge[i - 1] = true;
49             }
50             } else if (dfn[v] < dfn[u]) {
51                 low[u] = min(low[u], dfn[v]);
52             }
53     }
54 }
55
56 void blood_fill(int u) {
57     belong[u] = bcc_cnt; bcc[bcc_cnt].push_back(u);
58     fore(i, u) {
59         if (bridge[i]) continue;
60         int v = e[i].v;
61         if (!belong[v]) blood_fill(v);
62     }
63 }
64
65 void build_bcc_point() {
66     bcc_clock = bcc_cnt = 0;
67     dfn = vector<int>(V + 1);
68     low = vector<int>(V + 1);
69     belong = vector<int>(V + 1);
70     bridge = vector<bool>(E + 1);
71     bcc = vector<vector<int>>(1);
72
73     for (int i = 1; i <= V; ++i) {
74         if (!dfn[i]) {
75             tarjan(i, i);
76         }
77     }
78
79     for (int i = 1; i <= V; ++i) {
80         if (!belong[i]) {

```

```

81         ++bcc_cnt;
82         bcc.push_back(vector<int>());
83         blood_fill(i);
84     }
85 }
86
87 bcc_size = vector<int> (bcc_cnt + 1);
88 for (int i = 1; i <= bcc_cnt; ++i) bcc_size[i] = bcc[i].size();
89 }
90 };
91
92 }

```

2.2 BCC-Point

```

1 namespace Backlight {
2
3 struct Graph {
4     struct Edge {
5         int u, v;
6         Edge(){}
7         Edge(int _u, int _v): u(_u), v(_v) {}
8     };
9
10    int V;
11    vector<vector<Edge>> G;
12
13    Graph() : V(0) {}
14    Graph(int _V) : V(_V), G(_V + 1) {}
15
16    inline void addarc(int u, int v) {
17        assert(1 <= u && u <= V);
18        assert(1 <= v && v <= V);
19        G[u].push_back(Edge(u, v));
20    }
21
22    inline void addedge(int u, int v) {
23        addarc(u, v);
24        addarc(v, u);
25    }
26
27    /*****
28    int bcc_clock;
29    vector<int> dfn, low;
30    vector<vector<int>> bcc;
31    vector<bool> cut;
32    stack<int> stk;
33
34    void tarjan(int u, int fa) {
35        dfn[u] = low[u] = ++bcc_clock; stk.push(u);
36
37        if (u == fa && G[u].empty()) {
38            vector<int> nb;
39            nb.push_back(u);
40            bcc.push_back(nb);
41            return;
42        }
43
44        int son = 0;
45        for (Edge& e: G[u]) {
46            int v = e.v;
47            if (v == fa) continue;
48
49            if (!dfn[v]) {

```

```

50         tarjan(v, u);
51         low[u] = min(low[u], low[v]);
52         if (dfn[u] <= low[v]) {
53             ++son;
54             if (u != fa || son > 1) cut[u] = true;
55             vector<int> nb;
56             int top;
57             do {
58                 top = stk.top(); stk.pop();
59                 nb.push_back(top);
60             } while (top != v);
61             nb.push_back(u);
62             bcc.push_back(nb);
63         }
64     } else low[u] = min(low[u], dfn[v]);
65 }
66 }
67
68 void build_bcc_point() {
69     bcc_clock = 0;
70     dfn = vector<int>(V + 1);
71     low = vector<int>(V + 1);
72     cut = vector<bool>(V + 1);
73     bcc = vector<vector<int>>(1);
74
75     for (int i = 1; i <= V; ++i) {
76         if (!dfn[i]) {
77             while (!stk.empty()) stk.pop();
78             tarjan(i, i);
79         }
80     }
81 }
82 };
83
84 }

```

2.3 BiGraphMatch

```

1 // Hopcroft Karp,  $O(\sqrt{V}E)$ 
2 struct bigraph {
3     int dfn;
4
5     vector<vector<int>> G;
6
7     int nl, nr;
8     vector<int> ml, mr;
9     vector<int> ll, lr;
10    vector<int> vis;
11
12    bigraph(int _nl, int _nr) {
13        nl = _nl; nr = _nr;
14        G = vector<vector<int>>(nl + 1);
15    }
16
17    void addarc(int u, int v) {
18        G[u].push_back(v);
19    }
20
21    void addedge(int u, int v) {
22        G[u].push_back(v);
23        G[v].push_back(u);
24    }
25
26    bool bfs() {

```

```

27     queue<int> q;
28     bool res = false;
29
30     for (int i = 1; i <= n1; ++i) {
31         if (m1[i]) l1[i] = 0;
32         else l1[i] = 1, q.push(i);
33     }
34
35     for (int i = 1; i <= nr; ++i) lr[i] = 0;
36
37     while(!q.empty()) {
38         int u = q.front(); q.pop();
39         for (int v: G[u]) {
40             if (lr[v] == 0) {
41                 lr[v] = l1[u] + 1;
42                 if (mr[v]) {
43                     l1[mr[v]] = lr[v] + 1;
44                     q.push(mr[v]);
45                 } else res = true;
46             }
47         }
48     }
49
50     return res;
51 };
52
53 bool dfs(int u) {
54     for (int v: G[u]) {
55         if (lr[v] == l1[u] + 1 && vis[v] != dfn) {
56             vis[v] = dfn;
57             if (mr[v] == 0 || dfs(mr[v])) {
58                 mr[v] = u; m1[u] = v;
59                 return true;
60             }
61         }
62     }
63     return false;
64 };
65
66 int HK() {
67     m1 = vector<int> (n1 + 1);
68     mr = vector<int> (nr + 1);
69     l1 = vector<int> (n1 + 1);
70     lr = vector<int> (nr + 1);
71     vis = vector<int> (nr + 1);
72
73     int res = 0;
74     while(bfs()) {
75         ++dfn;
76         for (int i = 1; i <= n1; ++i)
77             if (!m1[i]) res += dfs(i);
78     }
79     return res;
80 }
81 };
82
83 /**
84  * 最小覆盖数 = 最大匹配数
85  * 最大独立集 = 顶点数 - 二分图匹配数
86  * DAG 最小路径覆盖数 = 结点数 - 拆点后二分图最大匹配数
87  */

```

```
// Kuhn Munkres,  $O(V^3)$ 
template<typename T>
struct biwraph {
    T TMAX, TMIN;

    int n, nl, nr;
    vector<vector<T>> G;
    vector<T> highl, highr;
    vector<T> slack;
    vector<int> matchl, matchr; // match
    vector<int> pre; // pre node
    vector<bool> visl, visr; // vis
    vector<int> q;
    int ql, qr;

    biwraph(int _nl, int _nr) {
        TMAX = numeric_limits<T>::max();

        nl = _nl; nr = _nr; n = max(nl, nr);
        G = vector<vector<T>> (n + 1, vector<T> (n + 1));
        highl = vector<T> (n + 1);
        highr = vector<T> (n + 1);
        slack = vector<T> (n + 1);
        matchl = vector<int> (n + 1);
        matchr = vector<int> (n + 1);
        pre = vector<int> (n + 1);
        visl = vector<bool> (n + 1);
        visr = vector<bool> (n + 1);
        q = vector<int> (n + 1);
    }

    void addarc(int u, int v, T w) {
        G[u][v] = max(G[u][v], w);
    }

    bool check(int v) {
        visr[v] = true;
        if (matchr[v]) {
            q[qr++] = matchr[v];
            visl[matchr[v]] = true;
            return false;
        }

        while(v) {
            matchr[v] = pre[v];
            swap(v, matchl[pre[v]]);
        }

        return true;
    }

    void bfs(int now) {
        ql = qr = 0; q[qr++] = now; visl[now] = 1;
        while(true) {
            while(ql < qr) {
                int u = q[ql++];
                for (int v = 1; v <= n; ++v) {
                    if (!visr[v]) {
                        T delta = highl[u] + highr[v] - G[u][v];
                        if (slack[v] >= delta) {
                            pre[v] = u;
                            if (delta) slack[v] = delta;
                            else if (check(v)) return;
                        }
                    }
                }
            }
        }
    }
};
```



```

64         }
65     }
66 }
67
68
69 T a = TMAX;
70 for (int i = 1; i <= n; ++i) if (!visr[i]) a = min(a, slack[i]);
71 for (int i = 1; i <= n; ++i) {
72     if (visl[i]) highl[i] -= a;
73     if (visr[i]) highr[i] += a;
74     else slack[i] -= a;
75 }
76 for (int i = 1; i <= n; ++i)
77     if (!visr[i] && !slack[i] && check(i)) return;
78 }
79 }
80
81 void match() {
82     fill(highr.begin(), highr.end(), 0);
83     fill(matchl.begin(), matchl.end(), 0);
84     fill(matchr.begin(), matchr.end(), 0);
85     for (int i = 1; i <= n; ++i) highl[i] = *max_element(G[i].begin() + 1, G[i].end());
86
87     for (int i = 1; i <= n; ++i) {
88         fill(slack.begin(), slack.end(), TMAX);
89         fill(visl.begin(), visl.end(), false);
90         fill(visr.begin(), visr.end(), false);
91         bfs(i);
92     }
93 }
94
95 T getMaxMatch() {
96     T res = 0;
97     match();
98     for (int i = 1; i <= n; ++i) {
99         if (G[i][matchl[i]] > 0) res += G[i][matchl[i]];
100        else matchl[i] = 0;
101    }
102    return res;
103 }
104 };

```

2.5 BlockForest

```

1 // 「APIO2018」铁人两项 (https://loj.ac/p/2587)
2 // 给定一张简单无向图，问有多少对三元组  $\langle s, c, f \rangle$  ( $s, c, f$  互不相同) 使得存在一条简单路径从  $s$  出发，经过  $c$  到达  $f$ 。
3 #include <bits/stdc++.h>
4 using namespace std;
5 using ll = long long;
6 const int N = 2e5 + 5;
7
8 int n, m;
9 int w[N];
10 vector<int> G[N], F[N];
11
12 int cc, scc;
13 int dfc, dfn[N], low[N];
14 int top, stk[N];
15 void tarjan(int u) {
16     ++cc;
17     dfn[u] = low[u] = ++dfc;
18     stk[++top] = u;
19     for (int v: G[u]) {
20         if (!dfn[v]) {

```

```

21         tarjan(v);
22         low[u] = min(low[u], low[v]);
23         if (low[v] == dfn[u]) {
24             ++scc;
25             int np = n + scc;
26             w[np] = 0;
27             for (int x = 0; x != v; --top) {
28                 x = stk[top];
29                 F[np].push_back(x);
30                 F[x].push_back(np);
31                 ++w[np];
32             }
33             F[np].push_back(u);
34             F[u].push_back(np);
35             ++w[np];
36         }
37     } else low[u] = min(low[u], dfn[v]);
38 }
39 }
40
41 ll ans;
42 int sz[N];
43 void dfs(int u, int fa) {
44     sz[u] = (u <= n);
45     for (int v: F[u]) if (v != fa) {
46         dfs(v, u);
47         ans += 2ll * w[u] * sz[u] * sz[v];
48         sz[u] += sz[v];
49     }
50     ans += 2ll * w[u] * sz[u] * (cc - sz[u]);
51 }
52
53 void buildBlockForest() {
54     for (int i = 1; i <= n; ++i) if (!dfn[i]) {
55         cc = 0;
56         tarjan(i);
57         --top;
58         dfs(i, i);
59     }
60 }
61
62 void solve(int Case) {
63     scanf("%d %d", &n, &m);
64     fill(w + 1, w + 1 + n, -1);
65     int u, v;
66     for (int i = 1; i <= m; ++i) {
67         scanf("%d %d", &u, &v);
68         G[u].push_back(v);
69         G[v].push_back(u);
70     }
71     buildBlockForest();
72     printf("%lld\n", ans);
73 }
74
75 int main () {
76     int T = 1;
77     // scanf("%d", &T);
78     for (int i = 1; i <= T; ++i) solve(i);
79     return 0;
80 }

```

2.6 BlockTree

```

1 // 树分块: uv 之间路径上不同的颜色数 (强制在线)
2 #include <bits/stdc++.h>
3 using namespace std;
4
5 const int N = 4e4 + 5;
6
7 int n, m, a[ N ];
8 int nt, t[ N ];
9
10 int tot, head[ N ];
11 struct edge
12 {
13     int v, nxt;
14 } e[ N << 1 ];
15 void init( int n )
16 {
17     tot = 0;
18     for ( int i = 1; i <= n; ++i )
19         head[ i ] = 0;
20 }
21 void add( int u, int v )
22 {
23     ++tot;
24     e[ tot ] = ( edge ){ v, head[ u ] };
25     head[ u ] = tot;
26 }
27 #define fore( i, u ) for ( int i = head[ u ]; i; i = e[ i ].nxt )
28
29 int sz[ N ], son[ N ], f[ N ], h[ N ], top[ N ];
30
31 void dfs1( int u, int fa )
32 {
33     f[ u ] = fa;
34     h[ u ] = h[ fa ] + 1;
35     sz[ u ] = 1;
36     son[ u ] = 0;
37     fore( i, u )
38     {
39         int v = e[ i ].v;
40         if ( v == fa )
41             continue;
42         dfs1( v, u );
43         sz[ u ] += sz[ v ];
44         if ( sz[ v ] > sz[ son[ u ] ] )
45             son[ u ] = v;
46     }
47 }
48
49 void dfs2( int u, int fa, int k )
50 {
51     top[ u ] = k;
52     if ( son[ u ] )
53         dfs2( son[ u ], u, k );
54     fore( i, u )
55     {
56         int v = e[ i ].v;
57         if ( v == fa || v == son[ u ] )
58             continue;
59         dfs2( v, u, v );
60     }
61 }
62
63 int lca( int u, int v )

```

```

64 {
65     while ( top[ u ] != top[ v ] )
66     {
67         if ( h[ top[ u ] ] < h[ top[ v ] ] )
68             swap( u, v );
69         u = f[ top[ u ] ];
70     }
71     if ( h[ u ] > h[ v ] )
72         swap( u, v );
73     return u;
74 }
75
76 int dep[ N ], max_dep[ N ], pa[ N ];
77 int key_cnt, keyid[ N ];
78
79 const int COLORCNT = 4e4 + 2;
80 const int KEYCNT   = 101;
81 const int gap      = 400;
82
83 bitset< COLORCNT > c[ KEYCNT ][ KEYCNT ];
84
85 int stk[ N ], tp;
86
87 void dfs_key( int u, int fa )
88 {
89     dep[ u ] = dep[ fa ] + 1;
90     max_dep[ u ] = dep[ u ];
91     fore( i, u )
92     {
93         int v = e[ i ].v;
94         if ( v == fa )
95             continue;
96         dfs_key( v, u );
97         if ( max_dep[ v ] > max_dep[ u ] )
98             max_dep[ u ] = max_dep[ v ];
99     }
100     if ( max_dep[ u ] - dep[ u ] >= gap )
101     {
102         keyid[ u ] = ++key_cnt;
103         max_dep[ u ] = dep[ u ];
104     }
105 }
106
107 void dfs_bitset( int u )
108 {
109     if ( keyid[ u ] && u != stk[ tp ] )
110     {
111         for ( int x = u; x != stk[ tp ]; x = f[ x ] )
112             c[ keyid[ stk[ tp ] ] ][ keyid[ u ] ].set( a[ x ] );
113
114         for ( int i = 1; i < tp; ++i )
115         {
116             c[ keyid[ stk[ i ] ] ][ keyid[ u ] ] = c[ keyid[ stk[ i ] ] ][ keyid[ stk[ tp ] ] ];
117             c[ keyid[ stk[ i ] ] ][ keyid[ u ] ] |= c[ keyid[ stk[ tp ] ] ][ keyid[ u ] ];
118         }
119         pa[ u ] = stk[ tp ];
120         stk[ ++tp ] = u;
121     }
122     for ( int i = head[ u ]; i; i = e[ i ].nxt )
123     {
124         if ( e[ i ].v != f[ u ] )
125             dfs_bitset( e[ i ].v );
126     }
127     if ( keyid[ u ] )
128         --tp;

```

```

129 }
130
131 void build_block_tree()
132 {
133     key_cnt = 0;
134     dfs_key( 1, 1 );
135     if ( !keyid[ 1 ] )
136         keyid[ 1 ] = ++key_cnt;
137
138     tp      = 1;
139     stk[ 1 ] = 1;
140     dfs_bitset( 1 );
141 }
142
143 bitset< COLORCNT > res;
144
145 int query( int u, int v )
146 {
147     res.reset();
148     int uv = lca( u, v );
149
150     // step 1: jump to nearest key node
151     while ( u != uv && !keyid[ u ] )
152     {
153         res.set( a[ u ] );
154         u = f[ u ];
155     }
156     while ( v != uv && !keyid[ v ] )
157     {
158         res.set( a[ v ] );
159         v = f[ v ];
160     }
161
162     // step 2: jump to Lowest key node
163     int pu = u;
164     while ( dep[ pa[ pu ] ] >= dep[ uv ] )
165         pu = pa[ pu ];
166     if ( pu != u )
167     {
168         res |= c[ keyid[ pu ] ][ keyid[ u ] ];
169         u = pu;
170     }
171
172     int pv = v;
173     while ( dep[ pa[ pv ] ] >= dep[ uv ] )
174         pv = pa[ pv ];
175     if ( pv != v )
176     {
177         res |= c[ keyid[ pv ] ][ keyid[ v ] ];
178         v = pv;
179     }
180
181     // step 3: jump to lca
182     while ( u != uv )
183     {
184         res.set( a[ u ] );
185         u = f[ u ];
186     }
187     while ( v != uv )
188     {
189         res.set( a[ v ] );
190         v = f[ v ];
191     }
192
193     // step 4: set lca

```

```

194     res.set( a[ uv ] );
195
196     return res.count();
197 }
198
199 void solve( int Case )
200 {
201     scanf( "%d %d", &n, &m );
202     for ( int i = 1; i <= n; ++i )
203     {
204         scanf( "%d", &a[ i ] );
205         t[ i ] = a[ i ];
206     }
207
208     sort( t + 1, t + 1 + n );
209     nt = unique( t + 1, t + 1 + n ) - ( t + 1 );
210
211     for ( int i = 1; i <= n; ++i )
212         a[ i ] = lower_bound( t + 1, t + 1 + nt, a[ i ] ) - t;
213
214     init( n );
215     int u, v;
216     for ( int i = 1; i <= n - 1; ++i )
217     {
218         scanf( "%d %d", &u, &v );
219         add( u, v );
220         add( v, u );
221     }
222
223     dfs1( 1, 1 );
224     dfs2( 1, 1, 1 );
225
226     build_block_tree();
227
228     int lastans = 0;
229     for ( int i = 1; i <= m; ++i )
230     {
231         scanf( "%d %d", &u, &v );
232         u ^= lastans;
233         lastans = query( u, v );
234         printf( "%d\n", lastans );
235     }
236 }
237
238 int main()
239 {
240     int T = 1;
241     // scanf( "%d", &T );
242     for ( int _ = 1; _ <= T; _++ )
243         solve( _ );
244     return 0;
245 }

```

2.7 Dijkstra

```

1 namespace Backlight {
2
3 template<typename T>
4 struct Wraph {
5     struct Edge {
6         int u, v;
7         T w;
8         Edge(){}
9         Edge(int _u, int _v, T _w): u(_u), v(_v), w(_w) {}

```

```

10     };
11
12     int V;
13     vector<vector<Edge>> G;
14
15     Wrapth() : V(0) {}
16     Wrapth(int _V) : V(_V), G(_V + 1) {}
17
18     inline void addarc(int u, int v, T w) {
19         assert(1 <= u && u <= V);
20         assert(1 <= v && v <= V);
21         G[u].push_back(Edge(u, v, w));
22     }
23
24     inline void addedge(int u, int v, T w) {
25         addarc(u, v, w);
26         addarc(v, u, w);
27     }
28
29     /*****
30     vector<T> dijkstra(int S, T T_MAX) {
31         typedef pair<T, int> Node;
32         priority_queue<Node, vector<Node>, greater<Node>> q;
33         vector<T> dis(V + 1);
34         for (int i = 1; i <= V; i++) dis[i] = T_MAX;
35         dis[S] = 0; q.push(Node(0, S));
36         while (!q.empty()){
37             Node p = q.top(); q.pop();
38             T cost = p.first; int u = p.second;
39             if (dis[u] != cost) continue;
40
41             for (Edge e: G[u]){
42                 int v = e.v;
43                 T w = e.w;
44                 if (dis[v] > dis[u] + w) {
45                     dis[v] = dis[u] + w;
46                     q.push(Node(dis[v], v));
47                 }
48             }
49         }
50         return dis;
51     }
52 };
53
54 }

```

2.8 dsu-on-tree

```

1 // CF600E
2 // 对于每个节点，输出其子树中出现次数最多的颜色之和。
3 vector<int> G[N];
4 inline void addedge(int u, int v) {
5     G[u].push_back(v);
6     G[v].push_back(u);
7 }
8
9 int n, color[N];
10
11 int sz[N], son[N], cnt[N], ma;
12 ll cur, ans[N];
13 void dfs1(int u, int fa) {
14     sz[u] = 1; son[u] = -1;
15     for (int v: G[u]) {
16         if (v == fa) continue;

```

```

17     dfs1(v, u);
18     sz[u] += sz[v];
19     if (sz[v] > sz[son[u]]) son[u] = v;
20 }
21 }
22
23 void add(int u, int fa, int Son, int d) {
24     // update data here
25     cnt[color[u]] += d;
26     if (cnt[color[u]] > ma) ma = cnt[color[u]], cur = 0;
27     if (cnt[color[u]] == ma) cur += color[u];
28
29     for (int v: G[u]) {
30         if (v == fa || v == Son) continue;
31         add(v, u, Son, d);
32     }
33 }
34
35 void dfs2(int u, int fa, bool keep) {
36     for (int v: G[u]) {
37         if (v == fa || v == son[u]) continue;
38         dfs2(v, u, false);
39     }
40     if (son[u] != -1) dfs2(son[u], u, true);
41
42     add(u, fa, son[u], 1);
43
44     // answer queries here
45     ans[u] = cur;
46
47     if (!keep) {
48         add(u, fa, -1, -1);
49         ma = 0; cur = 0;
50     }
51 }
52
53 void solve() {
54     read(n);
55     FOR(i, 1, n) read(color[i]);
56
57     int u, v;
58     FOR(i, 2, n) {
59         read(u, v);
60         addedge(u, v);
61     }
62
63     dfs1(1, 0);
64     dfs2(1, 0, 0);
65
66     FOR(i, 1, n - 1) printf("%lld ", ans[i]);
67     println(ans[n]);
68 }

```

2.9 FullyDCP

```

1 // Got this code from LOJ
2 #include <bits/stdc++.h>
3 using namespace std;
4
5 struct Xor128 {
6     unsigned x, y, z, w;
7     Xor128() : x(123456789), y(362436069), z(521288629), w(88675123) {}
8     unsigned next() {
9         unsigned t = x ^ (x << 11);

```



```

10     x = y;
11     y = z;
12     z = w;
13     return w = w ^ (w >> 19) ^ (t ^ (t >> 8));
14 }
15 //手回き
16 inline unsigned next(unsigned n) { return next() % n; }
17 };
18
19 // bottom up な Treap
20 //脱再!
21 // randomized binary search するには choiceRandomly を
22 // bool choiceRandomly(Ref l, Ref r) { return rng.next(l->size + r->size) < l->size; }
23 //に書き込めるだけでよい。
24 template <typename Node>
25 struct BottomupTreap {
26     Xor128 rng;
27     typedef Node *Ref;
28     static int size(Ref t) { return !t ? 0 : t->size; }
29
30     unsigned nextRand() { return rng.next(); }
31
32 private:
33     bool choiceRandomly(Ref l, Ref r) { return l->priority < r->priority; }
34
35 public:
36     Ref join(Ref l, Ref r) {
37         if (!l)
38             return r;
39         if (!r)
40             return l;
41
42         Ref t = NULL;
43         unsigned long long dirs = 0;
44         int h;
45         for (h = 0;; ++h) {
46             if (h >= sizeof(dirs) * 8 - 2) {
47                 // dirs のオーバーフローを防ぐために再帰する。
48                 //あくまでセーフティガードなのでバランスは多少崩れるかもしれない
49                 t = join(l->right, r->left);
50                 dirs = dirs << 2 | 1;
51                 h++;
52                 break;
53             }
54             dirs <<= 1;
55             if (choiceRandomly(l, r)) {
56                 Ref c = l->right;
57                 if (!c) {
58                     t = r;
59                     r = r->parent;
60                     break;
61                 }
62                 l = c;
63             } else {
64                 dirs |= 1;
65                 Ref c = r->left;
66                 if (!c) {
67                     t = l;
68                     l = l->parent;
69                     break;
70                 }
71                 r = c;
72             }
73         }
74         for (; h >= 0; --h) {

```

```

75         if (!(dirs & 1)) {
76             Ref p = l->parent;
77             t = l->linkr(t);
78             l = p;
79         } else {
80             Ref p = r->parent;
81             t = r->linkl(t);
82             r = p;
83         }
84         dirs >>= 1;
85     }
86     return t;
87 }
88
89 typedef std::pair<Ref, Ref> RefPair;
90
91 // L < t < r の (L,r) に分割する
92 RefPair split2(Ref t) {
93     Ref p, l = t->left, r = t;
94     Node::cut(l);
95     t->linkl(NULL);
96     while (p = t->parent) {
97         t->parent = NULL;
98         if (p->left == t)
99             r = p->linkl(r);
100         else
101             l = p->linkr(l);
102         t = p;
103     }
104     return RefPair(l, r);
105 }
106 // L < t < r の (L,t,r) に分割する。(L,r) を返す
107 RefPair split3(Ref t) {
108     Ref p, l = t->left, r = t->right;
109     Node::cut(l), Node::cut(r);
110     t->linklr(NULL, NULL);
111     while (p = t->parent) {
112         t->parent = NULL;
113         if (p->left == t)
114             r = p->linkl(r);
115         else
116             l = p->linkr(l);
117         t = p;
118     }
119     return RefPair(l, r);
120 }
121 Ref cons(Ref h, Ref t) {
122     assert(size(h) == 1);
123     if (!t)
124         return h;
125     Ref u = NULL;
126     while (true) {
127         if (choiceRandomly(h, t)) {
128             Ref p = t->parent;
129             u = h->linkr(t);
130             t = p;
131             break;
132         }
133         Ref l = t->left;
134         if (!l) {
135             u = h;
136             break;
137         }
138         t = l;
139     }

```

```

140     while (t) {
141         u = t->linkl(u);
142         t = t->parent;
143     }
144     return u;
145 }
146 };
147
148 // free tree のために、 $\mathbb{F}$ を基本として $\mathbb{F}$ う
149 class EulerTourTreeWithMarks {
150     struct Node {
151         typedef BottomupTreap<Node> BST;
152
153         Node *left, *right, *parent;
154         int size;
155         unsigned priority;
156         char marks, markUnions; // 0 ビット目が edgeMark, 1 ビット目が vertexMark
157
158         Node() : left(NULL), right(NULL), parent(NULL), size(1), priority(0), marks(0), markUnions(0) {}
159
160         inline Node *update() {
161             int size_t = 1, markUnions_t = marks;
162             if (left) {
163                 size_t += left->size;
164                 markUnions_t |= left->markUnions;
165             }
166             if (right) {
167                 size_t += right->size;
168                 markUnions_t |= right->markUnions;
169             }
170             size = size_t, markUnions = markUnions_t;
171             return this;
172         }
173
174         inline Node *linkl(Node *c) {
175             if (left = c)
176                 c->parent = this;
177             return update();
178         }
179         inline Node *linkr(Node *c) {
180             if (right = c)
181                 c->parent = this;
182             return update();
183         }
184         inline Node *linklr(Node *l, Node *r) {
185             if (left = l)
186                 l->parent = this;
187             if (right = r)
188                 r->parent = this;
189             return update();
190         }
191         static Node *cut(Node *t) {
192             if (t)
193                 t->parent = NULL;
194             return t;
195         }
196
197         static const Node *findRoot(const Node *t) {
198             while (t->parent) t = t->parent;
199             return t;
200         }
201         static std::pair<Node *, int> getPosition(Node *t) {
202             int k = BST::size(t->left);
203             Node *p;
204             while (p = t->parent) {

```

```

205         if (p->right == t)
206             k += BST::size(p->left) + 1;
207         t = p;
208     }
209     return std::make_pair(t, k);
210 }
211 static const Node *findHead(const Node *t) {
212     while (t->left) t = t->left;
213     return t;
214 }
215 static void updatePath(Node *t) {
216     while (t) {
217         t->update();
218         t = t->parent;
219     }
220 }
221 };
222
223 typedef Node::BST BST;
224 BST bst;
225
226 std::vector<Node> nodes;
227 //各頂点に④してその頂点から出ている arc を 1 つだけ代表として持つ (無い場合は-1)
228 //逆に arc に④して④④する頂点はたかだか 1 つである
229 std::vector<int> firstArc;
230 //④・頂点に④する属性
231 std::vector<bool> edgeMark, vertexMark;
232
233 inline int getArcIndex(const Node *a) const { return a - &nodes[0]; }
234
235 inline int arc1(int ei) const { return ei; }
236 inline int arc2(int ei) const { return ei + (numVertices() - 1); }
237
238 public:
239     inline int numVertices() const { return firstArc.size(); }
240     inline int numEdges() const { return numVertices() - 1; }
241
242     inline bool getEdgeMark(int a) const { return a < numEdges() ? edgeMark[a] : false; }
243     inline bool getVertexMark(int v) const { return vertexMark[v]; }
244
245 private:
246     void updateMarks(int a, int v) {
247         Node *t = &nodes[a];
248         t->marks = getEdgeMark(a) << 0 | getVertexMark(v) << 1;
249         Node::updatePath(t);
250     }
251
252     // firstArc の④更に④じて更新する
253     void firstArcChanged(int v, int a, int b) {
254         if (a != -1)
255             updateMarks(a, v);
256         if (b != -1)
257             updateMarks(b, v);
258     }
259
260 public:
261     class TreeRef {
262     friend class EulerTourTreeWithMarks;
263     const Node *ref;
264
265     public:
266         TreeRef() {}
267         TreeRef(const Node *ref_) : ref(ref_) {}
268         bool operator==(const TreeRef &that) const { return ref == that.ref; }
269         bool operator!=(const TreeRef &that) const { return ref != that.ref; }

```

```

270     bool isIsolatedVertex() const { return ref == NULL; }
271 };
272
273 void init(int N) {
274     int M = N - 1;
275     firstArc.assign(N, -1);
276     nodes.assign(M * 2, Node());
277     for (int i = 0; i < M * 2; i++) nodes[i].priority = bst.nextRand();
278     edgeMark.assign(M, false);
279     vertexMark.assign(N, false);
280 }
281
282 TreeRef getTreeRef(int v) const {
283     int a = firstArc[v];
284     return TreeRef(a == -1 ? NULL : Node::findRoot(&nodes[a]));
285 }
286
287 bool isConnected(int v, int w) const {
288     if (v == w)
289         return true;
290     int a = firstArc[v], b = firstArc[w];
291     if (a == -1 || b == -1)
292         return false;
293     return Node::findRoot(&nodes[a]) == Node::findRoot(&nodes[b]);
294 }
295
296 static int getSize(TreeRef t) {
297     if (t.isIsolatedVertex())
298         return 1;
299     else
300         return t.ref->size / 2 + 1;
301 }
302
303 void link(int ti, int v, int w) {
304     int a1 = arc1(ti), a2 = arc2(ti);
305     // v→w が a1 に FF するようにする
306     if (v > w)
307         std::swap(a1, a2);
308
309     int va = firstArc[v], wa = firstArc[w];
310
311     Node *l, *m, *r;
312     if (va != -1) {
313         // event. 順番を入れ替えるだけ
314         std::pair<Node *, Node *> p = bst.split2(&nodes[va]);
315         m = bst.join(p.second, p.first);
316     } else {
317         // v が孤立点の場合
318         m = NULL;
319         firstArc[v] = a1;
320         firstArcChanged(v, -1, a1);
321     }
322     if (wa != -1) {
323         std::pair<Node *, Node *> p = bst.split2(&nodes[wa]);
324         l = p.first, r = p.second;
325     } else {
326         // w が孤立点の場合
327         l = r = NULL;
328         firstArc[w] = a2;
329         firstArcChanged(w, -1, a2);
330     }
331     // w→v の E を m の先頭 = l の末尾に insert
332     m = bst.cons(&nodes[a2], m);
333     // v→w の E を m の末尾 = r の先頭に insert
334     r = bst.cons(&nodes[a1], r);

```

```

335     bst.join(bst.join(l, m), r);
336 }
337
338
339 void cut(int ti, int v, int w) {
340     // v→w が a1 に繋がるようにする
341     if (v > w)
342         std::swap(v, w);
343
344     int a1 = arc1(ti), a2 = arc2(ti);
345     std::pair<Node *, Node *> p = bst.split3(&nodes[a1]);
346     int prsize = BST::size(p.second);
347     std::pair<Node *, Node *> q = bst.split3(&nodes[a2]);
348     Node *l, *m, *r;
349     // a1, a2 の順番を判定する。a1 < a2 なら p.second が繋がっているはず
350     if (p.second == &nodes[a2] || BST::size(p.second) != prsize) {
351         l = p.first, m = q.first, r = q.second;
352     } else {
353         // a2 < a1 の順番である。v→w の繋がり方が a1 であって親 → 子であることにする
354         std::swap(v, w);
355         std::swap(a1, a2);
356         l = q.first, m = q.second, r = p.second;
357     }
358
359     // firstArc を必要に応じて書き換える
360     if (firstArc[v] == a1) {
361         int b;
362         if (r != NULL) {
363             // v が根じゃないなら右側の最初の繋がり方
364             b = getArcIndex(Node::findHead(r));
365         } else {
366             // v が根なら最初の繋がり方。孤立点になるなら -1
367             b = !l ? -1 : getArcIndex(Node::findHead(l));
368         }
369         firstArc[v] = b;
370         firstArcChanged(v, a1, b);
371     }
372     if (firstArc[w] == a2) {
373         // w が根になるので最初の繋がり方。孤立点になるなら -1
374         int b = !m ? -1 : getArcIndex(Node::findHead(m));
375         firstArc[w] = b;
376         firstArcChanged(w, a2, b);
377     }
378
379     bst.join(l, r);
380 }
381
382 void changeEdgeMark(int ti, bool b) {
383     assert(ti < numEdges());
384     edgeMark[ti] = b;
385     Node *t = &nodes[ti];
386     t->marks = (b << 0) | (t->marks & (1 << 1));
387     Node::updatePath(t);
388 }
389
390 void changeVertexMark(int v, bool b) {
391     vertexMark[v] = b;
392     int a = firstArc[v];
393     if (a != -1) {
394         Node *t = &nodes[a];
395         t->marks = (t->marks & (1 << 0)) | (b << 1);
396         Node::updatePath(t);
397     }
398 }
399
400 template <typename Callback>

```

```

400     bool enumMarkedEdges(TreeRef tree, Callback callback) const {
401         return enumMarks<0, Callback>(tree, callback);
402     }
403     //孤立点の場合は呼び側でその頂点だけ管理する必要がある
404     template <typename Callback>
405     bool enumMarkedVertices(TreeRef tree, Callback callback) const {
406         return enumMarks<1, Callback>(tree, callback);
407     }
408
409 private:
410     // callback : TreeEdgeIndex*2 -> Bool
411     // 引数は頂点をそこからの incident arc で示し、"(正方向 ? 0 : N-1) +
412     // treeEdgeIndex" を表す。方向は v,w の大小で管理すればよい
413     // callback は管理するかどうかを bool で返す。最後まで列挙し終えたかどうかを返す。
414     template <int Mark, typename Callback>
415     bool enumMarks(TreeRef tree, Callback callback) const {
416         if (tree.isIsolatedVertex())
417             return true;
418         const Node *t = tree.ref;
419         if (t->markUnions >> Mark & 1)
420             return enumMarksRec<Mark, Callback>(t, callback);
421         else
422             return true;
423     }
424
425     //平衡木なので深さは深くないので再帰して問題ない
426     template <int Mark, typename Callback>
427     bool enumMarksRec(const Node *t, Callback callback) const {
428         const Node *l = t->left, *r = t->right;
429         if (l && (l->markUnions >> Mark & 1))
430             if (!enumMarksRec<Mark, Callback>(l, callback))
431                 return false;
432         if (t->marks >> Mark & 1)
433             if (!callback(getArcIndex(t)))
434                 return false;
435         if (r && (r->markUnions >> Mark & 1))
436             if (!enumMarksRec<Mark, Callback>(r, callback))
437                 return false;
438         return true;
439     }
440
441 public:
442     //デバッグ用
443     void debugEnumEdges(std::vector<int> &out_v) const {
444         int M = numEdges();
445         for (int ti = 0; ti < M; ti++) {
446             const Node *t = &nodes[ti];
447             if (t->left || t->right || t->parent)
448                 out_v.push_back(ti);
449         }
450     }
451 };
452
453 // treeEdge にはそれぞれ 0~N-1 のインデックスが与えられる。これは全てのレベルで共通。
454 //ところで"Level up" って和英語なんだ。promote でいいかな。
455 // Sampling heuristic ランダム探索で超速く (4 倍とか) なったんだけど! いいね!
456 //
457 // References
458 // · Holm, Jacob, Kristian De Lichtenberg, and Mikkel Thorup. "Poly-Logarithmic deterministic fully-dynamic
459 // algorithms for connectivity, minimum spanning tree, 2-edge, and biconnectivity." Journal of the ACM
460 // (JACM) 48.4 (2001): 723-760. · Iyer, Raj, et al. "An experimental study of polylogarithmic, fully dynamic,
461 // connectivity algorithms." Journal of Experimental Algorithmics (JEA) 6 (2001): 4.
462
463 class HolmDeLichtenbergThorup {
464     typedef HolmDeLichtenbergThorup This;

```

```

465 typedef EulerTourTreeWithMarks Forest;
466 typedef Forest::TreeRef TreeRef;
467
468 int numVertices_m;
469 int numSamplings;
470
471 // DynamicTree はコピーできないけどまあその状態で使わなきゃいいじゃんということで...
472 std::vector<Forest> forests;
473
474 std::vector<char> edgeLevel;
475 std::vector<int> treeEdgeIndex;           // : EdgeIndex -> TreeEdgeIndex
476 std::vector<int> treeEdgeMap;           // : TreeEdgeIndex -> EdgeIndex
477 std::vector<int> treeEdgeIndexFreeList; // : [TreeEdgeIndex]
478
479 // arc も方向は EulerTourTree と同じように v,w の大小に合わせる
480 std::vector<int> arcHead;
481
482 std::vector<std::vector<int>> firstIncidentArc;
483 std::vector<int> nextIncidentArc, prevIncidentArc;
484
485 //一時的に使う。使い回して使う
486 std::vector<bool> edgeVisited;
487 std::vector<int> visitedEdges; // : [EdgeIndex | TreeEdgeIndex]
488
489 int arc1(int ei) const { return ei; }
490 int arc2(int ei) const { return numMaxEdges() + ei; }
491 int arcEdge(int i) const { return i >= numMaxEdges() ? i - numMaxEdges() : i; }
492
493 bool replace(int lv, int v, int w) {
494     Forest &forest = forests[lv];
495
496     TreeRef vRoot = forest.getTreeRef(v), wRoot = forest.getTreeRef(w);
497     assert(vRoot.isIsolatedVertex() || wRoot.isIsolatedVertex() || vRoot != wRoot);
498
499     int vSize = forest.getSize(vRoot), wSize = forest.getSize(wRoot);
500
501     int u;
502     TreeRef uRoot;
503     int uSize;
504     if (vSize <= wSize)
505         u = v, uRoot = vRoot, uSize = vSize;
506     else
507         u = w, uRoot = wRoot, uSize = wSize;
508
509     // replacement edge を探す
510     int replacementEdge = -1;
511     enumIncidentArcs(forest, uRoot, u, lv, FindReplacementEdge(uRoot, &replacementEdge));
512
513     // "Sampling heuristic"
514     //早い時点で見つかったなら T_u, 他の incident arcs をレベルアップさせなくても計算量的に問題ない
515     if (replacementEdge != -1 && (int)visitedEdges.size() + 1 <= numSamplings) {
516         // replacementEdge を削除する
517         deleteNontreeEdge(replacementEdge);
518         addTreeEdge(replacementEdge);
519         for (int i = 0; i < (int)visitedEdges.size(); i++) edgeVisited[visitedEdges[i]] = false;
520         visitedEdges.clear();
521         return true;
522     }
523
524     //見つけた incident arcs を一箇所にレベルアップさせる。edgeVisited の後処理もする
525     for (int i = 0; i < (int)visitedEdges.size(); i++) {
526         int ei = visitedEdges[i];
527         edgeVisited[ei] = false;
528
529         deleteNontreeEdge(ei);

```



```

530         ++edgeLevel[ei];
531
532         insertNontreeEdge(ei);
533     }
534     visitedEdges.clear();
535
536     //このレベルの  $T_u$  の  $E$  を列  $E$  する
537     forest.enumMarkedEdges(uRoot, EnumLevelTreeEdges(this));
538     //列  $E$  した  $T_u$  の  $E$  を一  $E$  にレベルアップさせる
539     for (int i = 0; i < (int)visitedEdges.size(); i++) {
540         int ti = visitedEdges[i];
541
542         int ei = treeEdgeMap[ti];
543         int v = arcHead[arc2(ei)], w = arcHead[arc1(ei)];
544         int lv = edgeLevel[ei];
545
546         edgeLevel[ei] = lv + 1;
547
548         forests[lv].changeEdgeMark(ti, false);
549         forests[lv + 1].changeEdgeMark(ti, true);
550
551         forests[lv + 1].link(ti, v, w);
552     }
553     visitedEdges.clear();
554
555     if (replacementEdge != -1) {
556         //  $T_u$  の  $E$  列  $E$  の前に構造が  $E$  変わると困るので replacementEdge はこのタイミングで  $E$  理する
557         deleteNontreeEdge(replacementEdge);
558         addTreeEdge(replacementEdge);
559         return true;
560     } else if (lv > 0) {
561         return replace(lv - 1, v, w);
562     } else {
563         return false;
564     }
565 }
566
567 struct EnumLevelTreeEdges {
568     This *thisp;
569     EnumLevelTreeEdges(This *thisp_) : thisp(thisp_) {}
570
571     inline bool operator()(int a) {
572         thisp->enumLevelTreeEdges(a);
573         return true;
574     }
575 };
576
577 void enumLevelTreeEdges(int ti) { visitedEdges.push_back(ti); }
578
579 //孤立点の時特  $E$  な  $E$  理をするなどしなければいけないのでヘルパ  $E$ 
580 template <typename Callback>
581 bool enumIncidentArcs(Forest &forest, TreeRef t, int u, int lv, Callback callback) {
582     if (t.isIsolatedVertex())
583         return enumIncidentArcsWithVertex<Callback>(lv, u, callback);
584     else
585         return forest.enumMarkedVertices(t, EnumIncidentArcs<Callback>(this, lv, callback));
586 }
587
588 template <typename Callback>
589 struct EnumIncidentArcs {
590     This *thisp;
591     int lv;
592     Callback callback;
593
594     EnumIncidentArcs(This *thisp_, int lv_, Callback callback_)

```

```

595         : thisp(thisp_), lv(lv_), callback(callback_) {}
596
597     inline bool operator()(int tii) const {
598         return thisp->enumIncidentArcsWithTreeArc(tii, lv, callback);
599     }
600 };
601
602 template <typename Callback>
603 bool enumIncidentArcsWithTreeArc(int tii, int lv, Callback callback) {
604     bool dir = tii >= numVertices() - 1;
605     int ti = dir ? tii - (numVertices() - 1) : tii;
606     int ei = treeEdgeMap[ti];
607     int v = arcHead[arc2(ei)], w = arcHead[arc1(ei)];
608     //方向を求め、その arc の tail の頂点を取得する
609     int u = !(dir != (v > w)) ? v : w;
610
611     return enumIncidentArcsWithVertex(lv, u, callback);
612 }
613
614 // 1 つの頂点を図理する
615 template <typename Callback>
616 bool enumIncidentArcsWithVertex(int lv, int u, Callback callback) {
617     int it = firstIncidentArc[lv][u];
618     while (it != -1) {
619         if (!callback(this, it))
620             return false;
621         it = nextIncidentArc[it];
622     }
623     return true;
624 }
625
626 struct FindReplacementEdge {
627     TreeRef uRoot;
628     int *replacementEdge;
629     FindReplacementEdge(TreeRef uRoot_, int *replacementEdge_)
630         : uRoot(uRoot_), replacementEdge(replacementEdge_) {}
631
632     inline bool operator()(This *thisp, int a) const {
633         return thisp->findReplacementEdge(a, uRoot, replacementEdge);
634     }
635 };
636
637 // 1 つの arc を図理する
638 bool findReplacementEdge(int a, TreeRef uRoot, int *replacementEdge) {
639     int ei = arcEdge(a);
640     if (edgeVisited[ei])
641         return true;
642
643     int lv = edgeLevel[ei];
644     TreeRef hRoot = forests[lv].getTreeRef(arcHead[a]);
645
646     if (hRoot.isIsolatedVertex() || hRoot != uRoot) {
647         //図の木に渡されているなら replacement edge である。
648         *replacementEdge = ei;
649         return false;
650     }
651     // replacement edge は visitedEdges に入れたくないのでこの位置でマ図クする
652     edgeVisited[ei] = true;
653     visitedEdges.push_back(ei);
654     return true;
655 }
656
657 void addTreeEdge(int ei) {
658     int v = arcHead[arc2(ei)], w = arcHead[arc1(ei)];
659     int lv = edgeLevel[ei];

```

```

660
661     int ti = treeEdgeIndexFreelist.back();
662     treeEdgeIndexFreelist.pop_back();
663     treeEdgeIndex[ei] = ti;
664     treeEdgeMap[ti] = ei;
665
666     forests[lv].changeEdgeMark(ti, true);
667
668     for (int i = 0; i <= lv; i++) forests[i].link(ti, v, w);
669 }
670
671 void insertIncidentArc(int a, int v) {
672     int ei = arcEdge(a);
673     int lv = edgeLevel[ei];
674     assert(treeEdgeIndex[ei] == -1);
675
676     int next = firstIncidentArc[lv][v];
677     firstIncidentArc[lv][v] = a;
678     nextIncidentArc[a] = next;
679     prevIncidentArc[a] = -1;
680     if (next != -1)
681         prevIncidentArc[next] = a;
682
683     if (next == -1)
684         forests[lv].changeVertexMark(v, true);
685 }
686
687 void deleteIncidentArc(int a, int v) {
688     int ei = arcEdge(a);
689     int lv = edgeLevel[ei];
690     assert(treeEdgeIndex[ei] == -1);
691
692     int next = nextIncidentArc[a], prev = prevIncidentArc[a];
693     nextIncidentArc[a] = prevIncidentArc[a] = -2;
694
695     if (next != -1)
696         prevIncidentArc[next] = prev;
697     if (prev != -1)
698         nextIncidentArc[prev] = next;
699     else
700         firstIncidentArc[lv][v] = next;
701
702     if (next == -1 && prev == -1)
703         forests[lv].changeVertexMark(v, false);
704 }
705
706 void insertNontreeEdge(int ei) {
707     int a1 = arc1(ei), a2 = arc2(ei);
708     insertIncidentArc(a1, arcHead[a2]);
709     insertIncidentArc(a2, arcHead[a1]);
710 }
711
712 void deleteNontreeEdge(int ei) {
713     int a1 = arc1(ei), a2 = arc2(ei);
714     deleteIncidentArc(a1, arcHead[a2]);
715     deleteIncidentArc(a2, arcHead[a1]);
716 }
717
718 public:
719     HolmDeLichtenbergThorup() : numVertices_m(0), numSamplings(0) {}
720
721     int numVertices() const { return numVertices_m; }
722     int numMaxEdges() const { return edgeLevel.size(); }
723
724     void init(int N, int M) {

```

```

725     numVertices_m = N;
726
727     int levels = 1;
728     while (1 << levels <= N / 2) levels++;
729
730     //サンプリング数を設定する。適切な $\square$ はよくわからない
731     numSamplings = (int)(levels * 1);
732
733     forests.resize(levels);
734     for (int lv = 0; lv < levels; lv++) forests[lv].init(N);
735
736     edgeLevel.assign(M, -1);
737
738     treeEdgeIndex.assign(M, -1);
739     treeEdgeMap.assign(N - 1, -1);
740
741     treeEdgeIndexFreeList.resize(N - 1);
742     for (int ti = 0; ti < N - 1; ti++) treeEdgeIndexFreeList[ti] = ti;
743
744     arcHead.assign(M * 2, -1);
745
746     firstIncidentArc.resize(levels);
747     for (int lv = 0; lv < levels; lv++) firstIncidentArc[lv].assign(N, -1);
748     nextIncidentArc.assign(M * 2, -2);
749     prevIncidentArc.assign(M * 2, -2);
750
751     edgeVisited.assign(M, false);
752 }
753
754 bool insertEdge(int ei, int v, int w) {
755     if (!(0 <= ei && ei < numMaxEdges() && 0 <= v && v < numVertices() && 0 <= w && w < numVertices())) {
756         system("pause");
757     }
758     assert(0 <= ei && ei < numMaxEdges() && 0 <= v && v < numVertices() && 0 <= w && w < numVertices());
759     assert(edgeLevel[ei] == -1);
760
761     int a1 = arc1(ei), a2 = arc2(ei);
762     arcHead[a1] = w, arcHead[a2] = v;
763
764     bool treeEdge = !forests[0].isConnected(v, w);
765
766     edgeLevel[ei] = 0;
767     if (treeEdge) {
768         addTreeEdge(ei);
769     } else {
770         treeEdgeIndex[ei] = -1;
771         //ル $\square$ プは見たくないのでリストにも入れない
772         if (v != w)
773             insertNontreeEdge(ei);
774     }
775
776     return treeEdge;
777 }
778
779 bool deleteEdge(int ei) {
780     assert(0 <= ei && ei < numMaxEdges() && edgeLevel[ei] != -1);
781
782     int a1 = arc1(ei), a2 = arc2(ei);
783     int v = arcHead[a2], w = arcHead[a1];
784
785     int lv = edgeLevel[ei];
786     int ti = treeEdgeIndex[ei];
787
788     bool splitted = false;
789     if (ti != -1) {

```

```

790         treeEdgeMap[ti] = -1;
791         treeEdgeIndex[ei] = -1;
792         treeEdgeIndexFreeList.push_back(ti);
793
794         for (int i = 0; i <= lv; i++) forests[i].cut(ti, v, w);
795
796         forests[lv].changeEdgeMark(ti, false);
797
798         splitted = !replace(lv, v, w);
799     } else {
800         //ルEはリストに入っていない
801         if (v != w)
802             deleteNontreeEdge(ei);
803     }
804
805     arcHead[a1] = arcHead[a2] = -1;
806     edgeLevel[ei] = -1;
807
808     return splitted;
809 }
810
811 bool isConnected(int v, int w) const { return forests[0].isConnected(v, w); }
812 };
813 typedef HolmDeLichtenbergThorup FullyDynamicConnectivity;
814 map<int, map<int, int>> mp;
815
816 int main() {
817     int n, m;
818     scanf("%d%d", &n, &m);
819     mp.clear();
820     FullyDynamicConnectivity fdc;
821     fdc.init(n + 1, m + 1);
822     int posE = 0;
823     int lstans = 0;
824     for (int i = 1, op, u, v, _u, _v; i <= m; ++i) {
825         scanf("%d%d%d", &op, &u, &v);
826         u ^= lstans;
827         v ^= lstans;
828         _u = u, _v = v;
829         if (u < v)
830             swap(u, v);
831         if (op == 0) {
832             mp[u][v] = ++posE;
833             fdc.insertEdge(posE, u, v);
834         } else if (op == 1) {
835             fdc.deleteEdge(mp[u][v]);
836             mp[u].erase(v);
837         } else {
838             int ok = fdc.isConnected(u, v);
839             if (ok)
840                 lstans = _u;
841             else
842                 lstans = _v;
843             printf("%c\n", "NY"[ok]);
844         }
845     }
846     return 0;
847 }

```

2.10 Graph

```

1 namespace Backlight {
2
3 struct Graph {

```

```

4   struct Edge {
5       int u, v;
6       Edge(){}
7       Edge(int _u, int _v): u(_u), v(_v) {}
8   };
9
10  int V;
11  vector<vector<Edge>> G;
12
13  Graph() : V(0) {}
14  Graph(int _V) : V(_V), G(_V + 1) {}
15
16  inline void addarc(int u, int v) {
17      assert(1 <= u && u <= V);
18      assert(1 <= v && v <= V);
19      G[u].push_back(Edge(u, v));
20  }
21
22  inline void addedge(int u, int v) {
23      addarc(u, v);
24      addarc(v, u);
25  }
26 };
27
28 }

```

2.11 GraphMatch

```

1  #include <bits/stdc++.h>
2  using namespace std;
3
4  // graph
5  template <typename T>
6  class graph {
7  public:
8      struct edge {
9          int from;
10         int to;
11         T cost;
12     };
13     vector<edge> edges;
14     vector<vector<int>> g;
15     int n;
16     graph(int _n)
17         : n(_n)
18     {
19         g.resize(n);
20     }
21     virtual int add(int from, int to, T cost) = 0;
22 };
23
24 // undirectedgraph
25 template <typename T>
26 class undirectedgraph : public graph<T> {
27 public:
28     using graph<T>::edges;
29     using graph<T>::g;
30     using graph<T>::n;
31
32     undirectedgraph(int _n)
33         : graph<T>(_n)
34     {
35     }
36     int add(int from, int to, T cost = 1)

```

```

37     {
38         assert(0 <= from && from < n && 0 <= to && to < n);
39         int id = (int)edges.size();
40         g[from].push_back(id);
41         g[to].push_back(id);
42         edges.push_back({ from, to, cost });
43         return id;
44     }
45 };
46
47 // blossom / find_max_unweighted_matching
48 template <typename T>
49 vector<int> find_max_unweighted_matching(const undirectedgraph<T>& g)
50 {
51     std::mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
52     vector<int> match(g.n, -1); // 匹配
53     vector<int> aux(g.n, -1); // 时间戳记
54     vector<int> label(g.n); // "o" or "i"
55     vector<int> orig(g.n); // 花根
56     vector<int> parent(g.n, -1); // 父节点
57     queue<int> q;
58     int aux_time = -1;
59
60     auto lca = [&](int v, int u) {
61         aux_time++;
62         while (true) {
63             if (v != -1) {
64                 if (aux[v] == aux_time) { // 找到拜访过的点 也就是 LCA
65                     return v;
66                 }
67                 aux[v] = aux_time;
68                 if (match[v] == -1) {
69                     v = -1;
70                 } else {
71                     v = orig[parent[match[v]]]; // 以匹配点的父节点继续寻找
72                 }
73             }
74             swap(v, u);
75         }
76     }; // lca
77
78     auto blossom = [&](int v, int u, int a) {
79         while (orig[v] != a) {
80             parent[v] = u;
81             u = match[v];
82             if (label[u] == 1) { // 初始点设为 "o" 找增广路
83                 label[u] = 0;
84                 q.push(u);
85             }
86             orig[v] = orig[u] = a; // 缩花
87             v = parent[u];
88         }
89     }; // blossom
90
91     auto augment = [&](int v) {
92         while (v != -1) {
93             int pv = parent[v];
94             int next_v = match[pv];
95             match[v] = pv;
96             match[pv] = v;
97             v = next_v;
98         }
99     }; // augment
100
101     auto bfs = [&](int root) {

```

```

102     fill(label.begin(), label.end(), -1);
103     iota(orig.begin(), orig.end(), 0);
104     while (!q.empty()) {
105         q.pop();
106     }
107     q.push(root);
108     // 初始点设为 "o", 这里以 "0" 代替 "o", "1" 代替 "i"
109     label[root] = 0;
110     while (!q.empty()) {
111         int v = q.front();
112         q.pop();
113         for (int id : g.g[v]) {
114             auto& e = g.edges[id];
115             int u = e.from ^ e.to ^ v;
116             if (label[u] == -1) { // 找到未拜访点
117                 label[u] = 1; // 标记 "i"
118                 parent[u] = v;
119                 if (match[u] == -1) { // 找到未匹配点
120                     augment(u); // 寻找增广路径
121                     return true;
122                 }
123                 // 找到已匹配点 将与她匹配的点丢入 queue 延伸交错树
124                 label[match[u]] = 0;
125                 q.push(match[u]);
126                 continue;
127             } else if (label[u] == 0 && orig[v] != orig[u]) { // 找到已拜访点 且标记同为 "o" 代表找到 "花"
128                 int a = lca(orig[v], orig[u]);
129                 // 找 LCA 然后缩花
130                 blossom(u, v, a);
131                 blossom(v, u, a);
132             }
133         }
134     }
135     return false;
136 }; // bfs
137
138 auto greedy = [&]() {
139     vector<int> order(g.n);
140     // 随机打乱 order
141     iota(order.begin(), order.end(), 0);
142     shuffle(order.begin(), order.end(), rng);
143
144     // 将可以匹配的点匹配
145     for (int i : order) {
146         if (match[i] == -1) {
147             for (auto id : g.g[i]) {
148                 auto& e = g.edges[id];
149                 int to = e.from ^ e.to ^ i;
150                 if (match[to] == -1) {
151                     match[i] = to;
152                     match[to] = i;
153                     break;
154                 }
155             }
156         }
157     }
158 }; // greedy
159
160 // 一开始先随机匹配
161 greedy();
162 // 对未匹配点找增广路
163 for (int i = 0; i < g.n; i++) {
164     if (match[i] == -1) {
165         bfs(i);
166     }

```



```

167     }
168     return match;
169 }
170 int main()
171 {
172     ios::sync_with_stdio(0), cin.tie(0);
173     int n, m;
174     cin >> n >> m;
175     undirectedgraph<int> g(n);
176     int u, v;
177     for (int i = 0; i < m; i++) {
178         cin >> u >> v;
179         u--;
180         v--;
181         g.add(u, v, 1);
182     }
183     auto blossom_match = find_max_unweighted_matching(g);
184     vector<int> ans;
185     int tot = 0;
186     for (int i = 0; i < blossom_match.size(); i++) {
187         ans.push_back(blossom_match[i]);
188         if (blossom_match[i] != -1) {
189             tot++;
190         }
191     }
192     cout << (tot >> 1) << "\n";
193     for (auto x : ans) {
194         cout << x + 1 << " ";
195     }
196 }

```

2.12 HLD-Edge

```

1  #include <bits/stdc++.h>
2  using namespace std;
3
4  const int N = 2e5 + 5;
5
6  int n, q;
7
8  struct edge
9  {
10     int v, w, nxt;
11 } e[ N << 1 ];
12 int tot, head[ N ];
13 void init_graph( int n )
14 {
15     tot = 0;
16     fill( head + 1, head + 1 + n, 0 );
17 }
18 void add( int u, int v, int w )
19 {
20     ++tot;
21     e[ tot ] = ( edge ){ v, w, head[ u ] };
22     head[ u ] = tot;
23 }
24
25 int sz[ N ], son[ N ], h[ N ], f[ N ], w[ N ];
26 void dfs1( int u, int fa )
27 {
28     h[ u ] = h[ fa ] + 1;
29     f[ u ] = fa;
30     sz[ u ] = 1;
31     son[ u ] = 0;

```

```

32     for ( int i = head[ u ]; i; i = e[ i ].nxt )
33     {
34         int v = e[ i ].v;
35         if ( v == fa )
36             continue;
37         w[ v ] = e[ i ].w;
38         dfs1( v, u );
39         sz[ u ] += sz[ v ];
40         if ( sz[ v ] > sz[ son[ u ] ] )
41             son[ u ] = v;
42     }
43 }
44 int dfs_clock, dfn[ N ], rk[ N ], top[ N ];
45 void dfs2( int u, int fa, int tp )
46 {
47     ++dfs_clock;
48     dfn[ dfs_clock ] = w[ u ];
49     rk[ u ] = dfs_clock;
50     top[ u ] = tp;
51     if ( son[ u ] )
52         dfs2( son[ u ], u, tp );
53     for ( int i = head[ u ]; i; i = e[ i ].nxt )
54     {
55         int v = e[ i ].v;
56         if ( v == fa || v == son[ u ] )
57             continue;
58         dfs2( v, u, v );
59     }
60 }
61
62 #define mid ( ( l + r ) >> 1 )
63 #define lc ( x << 1 )
64 #define rc ( x << 1 | 1 )
65 #define lson lc, l, mid
66 #define rson rc, mid + 1, r
67 int sum[ N << 2 ], ma[ N << 2 ], mi[ N << 2 ], tag_inv[ N << 2 ];
68 void push_up( int x )
69 {
70     sum[ x ] = sum[ lc ] + sum[ rc ];
71     ma[ x ] = max( ma[ lc ], ma[ rc ] );
72     mi[ x ] = min( mi[ lc ], mi[ rc ] );
73 }
74 void push_down( int x )
75 {
76     if ( tag_inv[ x ] != 1 )
77     {
78         sum[ lc ] = -sum[ lc ];
79         swap( ma[ lc ], mi[ lc ] );
80         ma[ lc ] = -ma[ lc ];
81         mi[ lc ] = -mi[ lc ];
82         tag_inv[ lc ] = -tag_inv[ lc ];
83
84         sum[ rc ] = -sum[ rc ];
85         swap( ma[ rc ], mi[ rc ] );
86         ma[ rc ] = -ma[ rc ];
87         mi[ rc ] = -mi[ rc ];
88         tag_inv[ rc ] = -tag_inv[ rc ];
89
90         tag_inv[ x ] = 1;
91     }
92 }
93 void build( int x, int l, int r )
94 {
95     tag_inv[ x ] = 1;
96     if ( l == r )

```

```
97     {
98         sum[ x ] = ma[ x ] = mi[ x ] = dfn[ l ];
99         return;
100     }
101     build( lson );
102     build( rson );
103     push_up( x );
104 }
105
106 void update( int x, int l, int r, int p, int w )
107 {
108     if ( l == r )
109     {
110         sum[ x ] = ma[ x ] = mi[ x ] = w;
111         return;
112     }
113     push_down( x );
114     if ( p <= mid )
115         update( lson, p, w );
116     else
117         update( rson, p, w );
118     push_up( x );
119 }
120
121 void inverse( int x, int l, int r, int L, int R )
122 {
123     if ( l == L && r == R )
124     {
125         sum[ x ] = -sum[ x ];
126         swap( ma[ x ], mi[ x ] );
127         ma[ x ] = -ma[ x ];
128         mi[ x ] = -mi[ x ];
129         tag_inv[ x ] = -tag_inv[ x ];
130         return;
131     }
132     push_down( x );
133     if ( R <= mid )
134         inverse( lson, L, R );
135     else if ( L > mid )
136         inverse( rson, L, R );
137     else
138     {
139         inverse( lson, L, mid );
140         inverse( rson, mid + 1, R );
141     }
142     push_up( x );
143 }
144
145 int getsum( int x, int l, int r, int L, int R )
146 {
147     if ( l == L && r == R )
148         return sum[ x ];
149     push_down( x );
150     if ( R <= mid )
151         return getsum( lson, L, R );
152     else if ( L > mid )
153         return getsum( rson, L, R );
154     return getsum( lson, L, mid ) + getsum( rson, mid + 1, R );
155 }
156
157 int getmax( int x, int l, int r, int L, int R )
158 {
159     if ( l == L && r == R )
160         return ma[ x ];
161     push_down( x );
```

```

162     if ( R <= mid )
163         return getmax( lson, L, R );
164     else if ( L > mid )
165         return getmax( rson, L, R );
166     return max( getmax( lson, L, mid ), getmax( rson, mid + 1, R ) );
167 }
168
169 int getmin( int x, int l, int r, int L, int R )
170 {
171     if ( l == L && r == R )
172         return mi[ x ];
173     push_down( x );
174     if ( R <= mid )
175         return getmin( lson, L, R );
176     else if ( L > mid )
177         return getmin( rson, L, R );
178     return min( getmin( lson, L, mid ), getmin( rson, mid + 1, R ) );
179 }
180
181 void INVERSE( int u, int v )
182 {
183     while ( top[ u ] != top[ v ] )
184     {
185         if ( h[ top[ u ] ] < h[ top[ v ] ] )
186             swap( u, v );
187         inverse( 1, 1, n, rk[ top[ u ] ], rk[ u ] );
188         u = f[ top[ u ] ];
189     }
190     if ( h[ u ] != h[ v ] )
191     {
192         if ( h[ u ] > h[ v ] )
193             swap( u, v );
194         inverse( 1, 1, n, rk[ son[ u ] ], rk[ v ] );
195     }
196 }
197
198 int QSUM( int u, int v )
199 {
200     int res = 0;
201     while ( top[ u ] != top[ v ] )
202     {
203         if ( h[ top[ u ] ] < h[ top[ v ] ] )
204             swap( u, v );
205         res += getsum( 1, 1, n, rk[ top[ u ] ], rk[ u ] );
206         u = f[ top[ u ] ];
207     }
208     if ( h[ u ] != h[ v ] )
209     {
210         if ( h[ u ] > h[ v ] )
211             swap( u, v );
212         res += getsum( 1, 1, n, rk[ son[ u ] ], rk[ v ] );
213     }
214     return res;
215 }
216
217 int QMAX( int u, int v )
218 {
219     int res = INT_MIN;
220     while ( top[ u ] != top[ v ] )
221     {
222         if ( h[ top[ u ] ] < h[ top[ v ] ] )
223             swap( u, v );
224         res = max( res, getmax( 1, 1, n, rk[ top[ u ] ], rk[ u ] ) );
225         u = f[ top[ u ] ];
226     }

```

```

227     if ( h[ u ] != h[ v ] )
228     {
229         if ( h[ u ] > h[ v ] )
230             swap( u, v );
231         res = max( res, getMax( 1, 1, n, rk[ son[ u ] ], rk[ v ] ) );
232     }
233     return res;
234 }
235
236 int QMIN( int u, int v )
237 {
238     int res = INT_MAX;
239     while ( top[ u ] != top[ v ] )
240     {
241         if ( h[ top[ u ] ] < h[ top[ v ] ] )
242             swap( u, v );
243         res = min( res, getmin( 1, 1, n, rk[ top[ u ] ], rk[ u ] ) );
244         u = f[ top[ u ] ];
245     }
246     if ( h[ u ] != h[ v ] )
247     {
248         if ( h[ u ] > h[ v ] )
249             swap( u, v );
250         res = min( res, getmin( 1, 1, n, rk[ son[ u ] ], rk[ v ] ) );
251     }
252     return res;
253 }
254
255 int tu[ N ], tv[ N ];
256 void solve( int Case )
257 {
258     /* write code here */
259     /* gl & hf */
260     scanf( "%d", &n );
261     int u, v, w;
262     for ( int i = 1; i <= n - 1; ++i )
263     {
264         scanf( "%d %d %d", &u, &v, &w );
265         ++u, ++v;
266         add( u, v, w );
267         add( v, u, w );
268
269         tu[ i ] = u;
270         tv[ i ] = v;
271     }
272
273     dfs1( 1, 1 );
274     dfs2( 1, 1, 1 );
275
276     build( 1, 1, n );
277
278     scanf( "%d", &q );
279     char op[ 5 ];
280     int x, y;
281     for ( int i = 1; i <= q; ++i )
282     {
283         scanf( "%s %d %d", op, &x, &y );
284         ++x, ++y;
285         if ( op[ 0 ] == 'C' )
286         {
287             --x, --y;
288             int id = h[ tu[ x ] ] > h[ tv[ x ] ] ? tu[ x ] : tv[ x ];
289             update( 1, 1, n, rk[ id ], y );
290         }
291         else if ( op[ 0 ] == 'N' )

```

```

292     {
293         INVERSE( x, y );
294     }
295     else if ( op[ 0 ] == 'S' )
296     {
297         printf( "%d\n", QSUM( x, y ) );
298     }
299     else if ( op[ 1 ] == 'A' )
300     {
301         printf( "%d\n", QMAX( x, y ) );
302     }
303     else if ( op[ 1 ] == 'I' )
304     {
305         printf( "%d\n", QMIN( x, y ) );
306     }
307 }
308 }
309
310 int main()
311 {
312     int T = 1;
313     for ( int _ = 1; _ <= T; _++ )
314         solve( _ );
315     return 0;
316 }

```

2.13 Kosaraju

```

1  const int N = 1e5 + 5;
2  vector<int> G[N], R[N];
3  void init(int n) {
4      for (int i = 1; i <= n; ++i) G[i].clear(), R[i].clear();
5  }
6  inline void addarc(int u, int v) {
7      G[u].push_back(v);
8      R[v].push_back(u);
9  }
10
11 int n, m;
12 int dfs_clock, scc_cnt;
13 int dfn[N], belong[N];
14 bool vis[N];
15 void dfs1(int u) {
16     vis[u] = true;
17     for (const int& v: G[u]) {
18         if (!vis[v]) dfs1(v);
19     }
20     dfn[++dfs_clock] = u;
21 }
22 void dfs2(int u) {
23     belong[u] = scc_cnt;
24     for (const int& v: R[u]) {
25         if (!belong[v]) dfs2(v);
26     }
27 }
28 void kosaraju() {
29     dfs_clock = scc_cnt = 0;
30     fill(dfn + 1, dfn + 1 + n, 0);
31     fill(belong + 1, belong + 1 + n, 0);
32     fill(vis + 1, vis + 1 + n, false);
33     for (int i = 1; i <= n; ++i) {
34         if (!vis[i]) dfs1(i);
35     }
36 }

```

```

37     for (int i = n; i >= 1; --i) {
38         if (!belong[dfn[i]]) {
39             ++scc_cnt;
40             dfs2(dfn[i]);
41         }
42     }
43 }

```

2.14 Kruskal

```

1 namespace Backlight {
2
3 template<typename T>
4 struct Wraph {
5     struct Edge {
6         int u, v;
7         T w;
8         Edge(){}
9         Edge(int _u, int _v, T _w): u(_u), v(_v), w(_w) {}
10        bool operator < (const Edge& e) {
11            return w < e.w;
12        }
13    };
14
15    int V;
16    vector<vector<Edge>> G;
17    vector<Edge> E;
18
19    Wraph() : V(0) {}
20    Wraph(int _V) : V(_V), G(_V + 1) {}
21
22    inline void addarc(int u, int v, T w) {
23        assert(1 <= u && u <= V);
24        assert(1 <= v && v <= V);
25        G[u].push_back(Edge(u, v, w));
26        E.push_back(Edge(u, v, w));
27    }
28
29    inline void addedge(int u, int v, T w) {
30        addarc(u, v, w);
31        addarc(v, u, w);
32    }
33
34    /*****
35    T kruskal() {
36        vector<int> fa(V + 1);
37        for (int i = 1; i <= V; ++i) fa[i] = i;
38
39        auto find = [&fa] (auto self, int x) {
40            if (x == fa[x]) return x;
41            fa[x] = self(self, fa[x]);
42            return fa[x];
43        };
44
45        auto merge = [&fa, find] (int x, int y) {
46            x = find(find, x); y = find(find, y);
47            if (x == y) return false;
48            fa[x] = y;
49            return true;
50        };
51
52        T cost = 0;
53        int cnt = 0;
54        sort(E.begin(), E.end());

```

```

55     for (int i = 0; i < (int)E.size(); ++i) {
56         Edge e = E[i];
57         if (merge(e.u, e.v)) {
58             cost = e.w;
59             ++cnt;
60             if (cnt == V - 1) break;
61         }
62     }
63     return cost;
64 }
65 };
66
67 }

```

2.15 LCA-HLD

```

1  int tot, head[N];
2  struct Edge {
3      int v, nxt;
4  }e[M];
5
6  void addedge(int u, int v) {
7      ++tot; e[tot] = (Edge){v, head[u]}; head[u] = tot;
8      ++tot; e[tot] = (Edge){u, head[v]}; head[v] = tot;
9  }
10
11 int h[N], f[N], sz[N], son[N], top[N];
12 void dfs1(int u, int fa) {
13     h[u] = h[fa] + 1; f[u] = fa;
14     sz[u] = 1; son[u] = 0;
15     for (int i = head[u]; i; i = e[i].nxt) {
16         int v = e[i].v;
17         if (v == fa) continue;
18         dfs1(v, u);
19         sz[u] += sz[v];
20         if (sz[v] > sz[son[u]]) son[u] = v;
21     }
22 }
23
24 void dfs2(int u, int fa, int tp) {
25     top[u] = tp;
26     if (son[u]) dfs2(son[u], u, tp);
27     for (int i = head[u]; i; i = e[i].nxt) {
28         int v = e[i].v;
29         if (v == fa || v == son[u]) continue;
30         dfs2(v, u, v);
31     }
32 }
33
34 int LCA(int u, int v) {
35     while (top[u] != top[v]) {
36         if (h[top[u]] < h[top[v]]) swap(u, v);
37         u = f[top[u]];
38     }
39     if (h[u] > h[v]) swap(u, v);
40     return u;
41 }

```

2.16 LCA

```

1  namespace Backlight {
2

```



```

3  template<typename T>
4  struct Wraph {
5      struct Edge {
6          int u, v;
7          T w;
8          Edge() {}
9          Edge(int _u, int _v, T _w): u(_u), v(_v), w(_w) {}
10 };
11
12 int V;
13 vector<vector<Edge>> G;
14
15 Wraph() : V(0) {}
16 Wraph(int _V) : V(_V), G(_V + 1) {}
17
18 inline void addarc(int u, int v, T w = 1) {
19     assert(1 <= u && u <= V);
20     assert(1 <= v && v <= V);
21     G[u].push_back(Edge(u, v, w));
22 }
23
24 inline void addedge(int u, int v, T w = 1) {
25     addarc(u, v, w);
26     addarc(v, u, w);
27 }
28
29 /*****
30 vector<int> dep;
31 vector<T> dis;
32 vector<vector<int>> par;
33 int rt, LG;
34 void dfs(int u, int fa, int d1, int d2) {
35     dep[u] = d1; dis[u] = d2;
36     if (u == rt) {
37         for (int i = 0; i < LG; ++i) par[u][i] = rt;
38     } else {
39         par[u][0] = fa;
40         for (int i = 1; i < LG; ++i) {
41             par[u][i] = par[par[u][i - 1]][i - 1];
42         }
43     }
44
45     for (Edge& e: G[u]) {
46         int v = e.v; T w = e.w;
47         if (v == fa) continue;
48         dfs(v, u, d1 + 1, d2 + w);
49     }
50 }
51
52 inline void build_lca(int _rt) {
53     rt = _rt; LG = __lg(V + 1) + 1;
54     dep = vector<int>(V + 1);
55     dis = vector<T>(V + 1);
56     par = vector<vector<int>>(V + 1, vector<int>(LG));
57     dfs(rt, rt, 0, 0);
58 }
59
60 inline int jump(int u, int d) {
61     for (int j = LG - 1; j >= 0; --j) {
62         if ((1<<j) & d) u = par[u][j];
63     }
64     return u;
65 }
66
67 int lca(int u, int v) {

```

```

68     if (dep[u] < dep[v]) swap(u, v);
69     u = jump(u, dep[u] - dep[v]);
70     if (u == v) return u;
71     for(int i = LG - 1; i >= 0; --i){
72         if(par[u][i] != par[v][i]){
73             u = par[u][i];
74             v = par[v][i];
75         }
76     }
77     return par[u][0];
78 }
79 };
80
81 };

```

2.17 maxflow

```

1 namespace Backlight {
2
3     template<typename Cap>
4     struct mf_graph {
5         static const Cap INF = numeric_limits<Cap>::max();
6
7         struct Edge {
8             int v, nxt;
9             Cap c, f;
10            Edge(){}
11            Edge(int _v, int _nxt, Cap _c): v(_v), nxt(_nxt), c(_c), f(0) {}
12        };
13
14        int V, E;
15        vector<int> h;
16        vector<Edge> e;
17
18        mf_graph() : V(0) {}
19        mf_graph(int _V) : V(_V), h(_V + 1, -1) {}
20
21        inline void addarc(int u, int v, Cap c) {
22            assert(1 <= u && u <= V);
23            assert(1 <= v && v <= V);
24            assert(0 <= c);
25
26            e.push_back(Edge(v, h[u], c)); h[u] = e.size() - 1;
27        }
28
29        inline void addedge(int u, int v, Cap c) {
30            addarc(u, v, c);
31            addarc(v, u, 0);
32        }
33
34        Cap maxflow(int s, int t) {
35            assert(1 <= s && s <= V);
36            assert(1 <= t && t <= V);
37            assert(s != t);
38
39            vector<int> f(V + 1), d(V + 1), st(V + 1);
40
41            auto bfs = [&]() {
42                fill(d.begin(), d.end(), -1);
43                queue<int> q;
44                q.push(s); d[s] = 0;
45                while(!q.empty()){
46                    int u = q.front(); q.pop();
47                    for(int i = h[u]; i != -1; i = e[i].nxt) {

```

```

48         int v = e[i].v;
49         if(e[i].c > e[i].f && d[v] == -1) {
50             d[v] = d[u] + 1;
51             if (v == t) break;
52             q.push(v);
53         }
54     }
55 }
56 return (d[t] != -1);
57 };
58
59 auto dfs = [&] (auto self, int u, Cap up) {
60     if(u == t || up == 0) return up;
61     Cap res = 0;
62     for(int& i = f[u]; i != -1; i = e[i].nxt) {
63         int v = e[i].v;
64         if(d[u] + 1 == d[v]) {
65             Cap nf = self(self, v, min(up, e[i].c - e[i].f));
66             if (nf <= 0) continue;
67             up -= nf;
68             res += nf;
69             e[i].f += nf;
70             e[i ^ 1].f -= nf;
71             if(up == 0) break;
72         }
73     }
74     if(res == 0) d[u] = -1;
75     return res;
76 };
77
78 Cap res = 0;
79 while(bfs()) {
80     f = h;
81     res += dfs(dfs, s, INF);
82 }
83 return res;
84 }
85 };
86
87 } // namespace Backlight

```

2.18 mincostflow

```

1 namespace Backlight {
2
3     template<typename Cap, typename Cost>
4     struct mcmf_graph {
5         static const Cap INF = numeric_limits<Cap>::max();
6
7         struct Edge {
8             int v, nxt;
9             Cap cap, flow;
10            Cost cost;
11            Edge() {}
12            Edge(int _v, int _nxt, Cap _cap, Cost _cost)
13                : v(_v), nxt(_nxt), cap(_cap), flow(0), cost(_cost) {}
14        };
15
16        int V, E;
17        vector<int> h;
18        vector<Edge> e;
19
20        mcmf_graph() : V(0) {}
21        mcmf_graph(int _V) : V(_V), h(_V + 1, -1) {}

```

```

22
23 inline void addarc(int u, int v, Cap cap, Cost cost) {
24     assert(1 <= u && u <= V);
25     assert(1 <= v && v <= V);
26     e.push_back(Edge(v, h[u], cap, cost)); h[u] = e.size() - 1;
27 }
28
29 inline void addedge(int u, int v, Cap cap, Cost cost) {
30     addarc(u, v, cap, cost);
31     addarc(v, u, 0, -cost);
32 }
33
34 pair<Cap, Cost> mcmf(int s, int t) {
35     assert(1 <= s && s <= V);
36     assert(1 <= t && t <= V);
37     assert(s != t);
38
39     Cap flow = 0;
40     Cost cost = 0;
41
42     vector<int> pe(V + 1);
43     vector<bool> inq(V + 1);
44     vector<Cost> dis(V + 1);
45     vector<Cap> incf(V + 1);
46
47     auto spfa = [&]() {
48         fill(dis.begin(), dis.end(), INF);
49         queue<int> q;
50         q.push(s); dis[s] = 0; incf[s] = INF; incf[t] = 0;
51         while(!q.empty()) {
52             int u = q.front(); q.pop();
53             inq[u] = false;
54             for (int i = h[u]; i != -1; i = e[i].nxt) {
55                 int v = e[i].v, _cap = e[i].cap, _cost = e[i].cost;
56                 if (_cap == 0 || dis[v] <= dis[u] + _cost) continue;
57                 dis[v] = dis[u] + _cost;
58                 incf[v] = min(_cap, incf[u]);
59                 pe[v] = i;
60                 if (!inq[v]) q.push(v), inq[v] = true;
61             }
62         }
63         return incf[t];
64     };
65
66     auto update = [&]() {
67         flow += incf[t];
68         for (int i = t; i != s; i = e[pe[i] ^ 1].v) {
69             e[pe[i]].cap -= incf[t];
70             e[pe[i] ^ 1].cap += incf[t];
71             cost += incf[t] * e[pe[i]].cost;
72         }
73     };
74
75     while(spfa()) update();
76
77     return make_pair(flow, cost);
78 }
79
80 };
81
82 } // namespace Backlight

```

2.19 SCC

```

1 namespace Backlight {
2
3 struct Graph {
4     struct Edge {
5         int u, v;
6         Edge(){}
7         Edge(int _u, int _v): u(_u), v(_v) {}
8     };
9
10    int V;
11    vector<vector<Edge>> G;
12
13    Graph() : V(0) {}
14    Graph(int _V) : V(_V), G(_V + 1) {}
15
16    inline void addarc(int u, int v) {
17        assert(1 <= u && u <= V);
18        assert(1 <= v && v <= V);
19        G[u].push_back(Edge(u, v));
20    }
21
22    inline void addedge(int u, int v) {
23        addarc(u, v);
24        addarc(v, u);
25    }
26
27    /*****
28    int scc_clock, scc_cnt;
29    vector<int> dfn, low, belong, scc_size;
30    vector<bool> ins;
31    stack<int> stk;
32
33    void tarjan(int u, int fa) {
34        dfn[u] = low[u] = ++scc_clock;
35        ins[u] = true;
36        stk.push(u);
37
38        // bool flag = false;
39        for (Edge& e: G[u]) {
40            int v = e.v;
41            // if (v == fa && !flag) {
42            //     flag = true;
43            //     continue;
44            // }
45
46            if (!dfn[v]) {
47                tarjan(v, u);
48                low[u] = min(low[u], low[v]);
49            } else if (ins[v]) low[u] = min(low[u], dfn[v]);
50        }
51
52        if (dfn[u] == low[u]) {
53            ++scc_cnt; scc_size.push_back(0);
54            int top;
55            do {
56                top = stk.top(); stk.pop();
57                ins[top] = false;
58                belong[top] = scc_cnt;
59                ++scc_size[scc_cnt];
60            } while(u != top);
61        }
62    }
63

```

```

64 void build_scc() {
65     scc_clock = scc_cnt = 0;
66     dfn = vector<int>(V + 1);
67     low = vector<int>(V + 1);
68     belong = vector<int>(V + 1);
69     ins = vector<bool>(V + 1);
70     scc_size = vector<int>(1);
71
72     for (int i = 1; i <= V; ++i) {
73         if (!dfn[i]) tarjan(i, i);
74     }
75 }
76 };
77
78 }

```

2.20 SPFA

```

1 namespace Backlight {
2
3 template<typename T>
4 struct Wraph {
5     struct Edge {
6         int u, v;
7         T w;
8         Edge(){}
9         Edge(int _u, int _v, T _w): u(_u), v(_v), w(_w) {}
10    };
11
12    int V;
13    vector<vector<Edge>> G;
14
15    Wraph() : V(0) {}
16    Wraph(int _V) : V(_V), G(_V + 1) {}
17
18    inline void addarc(int u, int v, T w) {
19        assert(1 <= u && u <= V);
20        assert(1 <= v && v <= V);
21        G[u].push_back(Edge(u, v, w));
22    }
23
24    inline void addedge(int u, int v, T w) {
25        addarc(u, v, w);
26        addarc(v, u, w);
27    }
28
29    /*****
30    vector<T> spfa(int S, T T_MAX) {
31        queue<int> q;
32        vector<T> dis(V + 1, T_MAX);
33        vector<bool> inq(V + 1, 0);
34        q.push(S); dis[S] = 0;
35        while(!q.empty()) {
36            int u = q.front(); q.pop();
37            inq[u] = 0;
38            for(Edge e: G[u]) {
39                if(dis[e.v] > dis[u] + e.w) {
40                    dis[e.v] = dis[u] + e.w;
41                    if(!inq[e.v]) {
42                        inq[e.v] = 1;
43                        q.push(e.v);
44                    }
45                }
46            }
47        }
48    }
49    */

```

```

47     }
48     return dis;
49 }
50 };
51
52 }

```

2.21 tree-divide

```

1 struct Edge {
2     int v, w;
3     Edge(){}
4     Edge(int _v, int _w): v(_v), w(_w) {}
5 };
6
7 vector<Edge> G[N];
8 inline void addedge(int u, int v, int w) {
9     G[u].push_back(Edge(v, w));
10    G[v].push_back(Edge(u, w));
11 }
12
13 bool vis[N];
14 int sz[N], max_sz[N];
15 void dfs_size(int u, int fa) {
16     sz[u] = 1; max_sz[u] = 0;
17     for (const Edge& e: G[u]) {
18         int v = e.v;
19         if (v == fa || vis[v]) continue;
20         dfs_size(v, u);
21         sz[u] += sz[v];
22         max_sz[u] = max(max_sz[u], sz[v]);
23     }
24 }
25
26 int Max, rt;
27 void dfs_root(int r, int u, int fa) {
28     max_sz[u] = max(max_sz[u], sz[r] - sz[u]);
29     if (Max > max_sz[u]) Max = max_sz[u], rt = u;
30     for (const Edge& e: G[u]) {
31         int v = e.v;
32         if (v == fa || vis[v]) continue;
33         dfs_root(r, v, u);
34     }
35 }
36
37 int dcnt, dis[N];
38 void dfs_dis(int u, int fa, int d) {
39     dis[++dcnt] = d;
40     for (const Edge& e: G[u]) {
41         int v = e.v, w = e.w;
42         if (v == fa || vis[v]) continue;
43         dfs_dis(v, u, d + w);
44     }
45 }
46
47 int ans[K];
48 void calc(int u, int w, int delta) {
49     dcnt = 0; dfs_dis(u, -1, w);
50     for (int i = 1; i <= dcnt; ++i) {
51         for (int j = i + 1; j <= dcnt; ++j) {
52             ans[dis[i] + dis[j]] += delta;
53         }
54     }
55 }

```

```

56
57 int n, m;
58 void DFS(int u) {
59     Max = n; dfs_size(u, -1); dfs_root(u, u, -1);
60     vis[rt] = 1;
61     calc(rt, 0, 1);
62     for (const Edge& e: G[rt]) {
63         int v = e.v, w = e.w;
64         if (vis[v]) continue;
65         calc(v, w, -1);
66         DFS(v);
67     }
68 }
69
70 void solve() {
71     read(n, m);
72
73     int u, v, w;
74     FOR(i, 2, n) {
75         read(u, v, w);
76         addedge(u, v, w);
77     }
78
79     DFS(1);
80
81     int k;
82     FOR(i, 1, m) {
83         read(k);
84         puts(ans[k] ? "AYE" : "NAY");
85     }
86 }

```

2.22 Wrap

```

1 namespace Backlight {
2
3 template<typename T>
4 struct Wrap {
5     struct Edge {
6         int u, v;
7         T w;
8         Edge(){}
9         Edge(int _u, int _v, T _w): u(_u), v(_v), w(_w) {}
10    };
11
12    int V;
13    vector<vector<Edge>> G;
14
15    Wrap() : V(0) {}
16    Wrap(int _V) : V(_V), G(_V + 1) {}
17
18    inline void addarc(int u, int v, T w = 1) {
19        assert(1 <= u && u <= V);
20        assert(1 <= v && v <= V);
21        G[u].push_back(Edge(u, v, w));
22    }
23
24    inline void addedge(int u, int v, T w = 1) {
25        addarc(u, v, w);
26        addarc(v, u, w);
27    }
28 };
29
30 }

```


2.23 WrapMatch

```

1 // Got this code from UOJ
2 #include <bits/stdc++.h>
3 using namespace std;
4
5 template <typename CostType, typename TotalCostType = int64_t>
6 class MaximumWeightedMatching {
7     /*
8      * Maximum Weighted Matching in General Graphs.
9      * -  $O(nm \log(n))$  time
10     * -  $O(n + m)$  space
11
12     * Note: each vertex is 1-indexed.
13     */
14 public:
15     using cost_t = CostType;
16     using tcost_t = TotalCostType;
17
18 private:
19     enum Label { kSeparated = -2,
20                 kInner = -1,
21                 kFree = 0,
22                 kOuter = 1 };
23     static constexpr cost_t Inf = cost_t(1) << (sizeof(cost_t) * 8 - 2);
24
25 private:
26     template <typename T>
27     class BinaryHeap {
28     public:
29         struct Node {
30             bool operator<(const Node& rhs) const { return value < rhs.value; }
31             T value;
32             int id;
33         };
34         BinaryHeap() { }
35         BinaryHeap(int N)
36             : size_(0)
37             , node(N + 1)
38             , index(N, 0)
39         {
40         }
41         int size() const { return size_; }
42         bool empty() const { return size_ == 0; }
43         void clear()
44         {
45             while (size_ > 0)
46                 index[node[size_--].id] = 0;
47         }
48         T min() const { return node[1].value; }
49         int argmin() const { return node[1].id; } // argmin ?
50         T get_val(int id) const { return node[index[id]].value; }
51         void pop()
52         {
53             if (size_ > 0)
54                 pop(1);
55         }
56         void erase(int id)
57         {
58             if (index[id])
59                 pop(index[id]);
60         }

```

```

61     bool has(int id) const { return index[id] != 0; }
62     void update(int id, T v)
63     {
64         if (!has(id))
65             return push(id, v);
66         bool up = (v < node[index[id]].value);
67         node[index[id]].value = v;
68         if (up)
69             up_heap(index[id]);
70         else
71             down_heap(index[id]);
72     }
73     void decrease_key(int id, T v)
74     {
75         if (!has(id))
76             return push(id, v);
77         if (v < node[index[id]].value)
78             node[index[id]].value = v, up_heap(index[id]);
79     }
80     void push(int id, T v)
81     {
82         // assert(!has(id));
83         index[id] = ++size_;
84         node[size_] = { v, id };
85         up_heap(size_);
86     }
87
88 private:
89     void pop(int pos)
90     {
91         index[node[pos].id] = 0;
92         if (pos == size_) {
93             --size_;
94             return;
95         }
96         bool up = (node[size_].value < node[pos].value);
97         node[pos] = node[size_--];
98         index[node[pos].id] = pos;
99         if (up)
100             up_heap(pos);
101         else
102             down_heap(pos);
103     }
104     void swap_node(int a, int b)
105     {
106         swap(node[a], node[b]);
107         index[node[a].id] = a;
108         index[node[b].id] = b;
109     }
110     void down_heap(int pos)
111     {
112         for (int k = pos, nk = k; 2 * k <= size_; k = nk) {
113             if (node[2 * k] < node[nk])
114                 nk = 2 * k;
115             if (2 * k + 1 <= size_ && node[2 * k + 1] < node[nk])
116                 nk = 2 * k + 1;
117             if (nk == k)
118                 break;
119             swap_node(k, nk);
120         }
121     }
122     void up_heap(int pos)
123     {
124         for (int k = pos; k > 1 && node[k] < node[k >> 1]; k >>= 1)
125             swap_node(k, k >> 1);

```

```

126     }
127     int size_;
128     vector<Node> node;
129     vector<int> index;
130 };
131
132 template <typename Key>
133 class PairingHeaps {
134 private:
135     struct Node {
136         Node()
137             : prev(-1)
138         {
139             // "prev < 0" means the node is unused.
140         }
141         Node(Key v)
142             : key(v)
143             , child(0)
144             , next(0)
145             , prev(0)
146         {
147         }
148         Key key;
149         int child, next, prev;
150     };
151 public:
152     PairingHeaps(int H, int N)
153         : heap(H)
154         , node(N)
155     {
156         // It consists of `H` Pairing heaps.
157         // Each heap-node ID can appear at most 1 time(s) among heaps
158         // and should be in [1, N).
159     }
160
161     void clear(int h)
162     {
163         if (heap[h])
164             clear_rec(heap[h]), heap[h] = 0;
165     }
166     void clear_all()
167     {
168         for (size_t i = 0; i < heap.size(); ++i)
169             heap[i] = 0;
170         for (size_t i = 0; i < node.size(); ++i)
171             node[i] = Node();
172     }
173     bool empty(int h) const { return !heap[h]; }
174     bool used(int v) const { return node[v].prev >= 0; }
175     Key min(int h) const { return node[heap[h]].key; }
176     int argmin(int h) const { return heap[h]; }
177
178     void pop(int h)
179     {
180         // assert(!empty(h));
181         erase(h, heap[h]);
182     }
183     void push(int h, int v, Key key)
184     {
185         // assert(!used(v));
186         node[v] = Node(key);
187         heap[h] = merge(heap[h], v);
188     }
189     void erase(int h, int v)
190     {

```

```

191     if (!used(v))
192         return;
193     int w = two_pass_pairing(node[v].child);
194     if (!node[v].prev)
195         heap[h] = w;
196     else {
197         cut(v);
198         heap[h] = merge(heap[h], w);
199     }
200     node[v].prev = -1;
201 }
202 void decrease_key(int h, int v, Key key)
203 {
204     if (!used(v))
205         return push(h, v, key);
206     if (!node[v].prev)
207         node[v].key = key;
208     else {
209         cut(v);
210         node[v].key = key;
211         heap[h] = merge(heap[h], v);
212     }
213 }
214
215 private:
216 void clear_rec(int v)
217 {
218     for (; v; v = node[v].next) {
219         if (node[v].child)
220             clear_rec(node[v].child);
221         node[v].prev = -1;
222     }
223 }
224
225 inline void cut(int v)
226 {
227     auto& n = node[v];
228     int pv = n.prev, nv = n.next;
229     auto& pn = node[pv];
230     if (pn.child == v)
231         pn.child = nv;
232     else
233         pn.next = nv;
234     node[nv].prev = pv;
235     n.next = n.prev = 0;
236 }
237
238 int merge(int l, int r)
239 {
240     if (!l)
241         return r;
242     if (!r)
243         return l;
244     if (node[l].key > node[r].key)
245         swap(l, r);
246     int lc = node[r].next = node[l].child;
247     node[l].child = node[lc].prev = r;
248     return node[r].prev = l;
249 }
250
251 int two_pass_pairing(int root)
252 {
253     if (!root)
254         return 0;
255     int a = root;

```

```

256     root = 0;
257     while (a) {
258         int b = node[a].next, na = 0;
259         node[a].prev = node[a].next = 0;
260         if (b)
261             na = node[b].next, node[b].prev = node[b].next = 0;
262         a = merge(a, b);
263         node[a].next = root;
264         root = a;
265         a = na;
266     }
267     int s = node[root].next;
268     node[root].next = 0;
269     while (s) {
270         int t = node[s].next;
271         node[s].next = 0;
272         root = merge(root, s);
273         s = t;
274     }
275     return root;
276 }
277
278 private:
279     vector<int> heap;
280     vector<Node> node;
281 };
282
283 template <typename T>
284 struct PriorityQueue : public priority_queue<T, vector<T>, greater<T>> {
285     PriorityQueue() { }
286     PriorityQueue(int N) { this->c.reserve(N); }
287     T min() { return this->top(); }
288     void clear() { this->c.clear(); }
289 };
290
291 template <typename T>
292 struct Queue {
293     Queue() { }
294     Queue(int N)
295         : qh(0)
296         , qt(0)
297         , data(N)
298     {
299     }
300     T operator[](int i) const { return data[i]; }
301     void enqueue(int u) { data[qt++] = u; }
302     int dequeue() { return data[qh++]; }
303     bool empty() const { return qh == qt; }
304     void clear() { qh = qt = 0; }
305     int size() const { return qt; }
306     int qh, qt;
307     vector<T> data;
308 };
309
310 public:
311     struct InputEdge {
312         int from, to;
313         cost_t cost;
314     };
315
316 private:
317     template <typename T>
318     using ModifiableHeap = BinaryHeap<T>;
319     template <typename T>
320     using ModifiableHeaps = PairingHeaps<T>;

```

```

321 template <typename T>
322 using FastHeap = PriorityQueue<T>;
323
324 struct Edge {
325     int to;
326     cost_t cost;
327 };
328 struct Link {
329     int from, to;
330 };
331 struct Node {
332     struct NodeLink {
333         int b, v;
334     };
335     Node() { }
336     Node(int u)
337         : parent(0)
338         , size(1)
339     {
340         link[0] = link[1] = { u, u };
341     }
342     int next_v() const { return link[0].v; }
343     int next_b() const { return link[0].b; }
344     int prev_v() const { return link[1].v; }
345     int prev_b() const { return link[1].b; }
346     int parent, size;
347     NodeLink link[2];
348 };
349 struct Event {
350     Event() { }
351     Event(cost_t time, int id)
352         : time(time)
353         , id(id)
354     {
355     }
356     bool operator<(const Event& rhs) const { return time < rhs.time; }
357     bool operator>(const Event& rhs) const { return time > rhs.time; }
358     cost_t time;
359     int id;
360 };
361 struct EdgeEvent {
362     EdgeEvent() { }
363     EdgeEvent(cost_t time, int from, int to)
364         : time(time)
365         , from(from)
366         , to(to)
367     {
368     }
369     bool operator>(const EdgeEvent& rhs) const { return time > rhs.time; }
370     bool operator<(const EdgeEvent& rhs) const { return time < rhs.time; }
371     cost_t time;
372     int from, to;
373 };
374
375 public:
376     MaximumWeightedMatching(int N, const vector<InputEdge>& in)
377         : N(N)
378         , B((N - 1) / 2)
379         , S(N + B + 1)
380         , ofs(N + 2)
381         , edges(in.size() * 2)
382         , heap2(S)
383         , heap2s(S, S)
384         , heap3(edges.size())
385         , heap4(S)

```

```

386     {
387
388         for (auto& e : in)
389             ofs[e.from + 1]++, ofs[e.to + 1]++;
390         for (int i = 1; i <= N + 1; ++i)
391             ofs[i] += ofs[i - 1];
392         for (auto& e : in) {
393             edges[ofs[e.from]++] = { e.to, e.cost * 2 };
394             edges[ofs[e.to]++] = { e.from, e.cost * 2 };
395         }
396         for (int i = N + 1; i > 0; --i)
397             ofs[i] = ofs[i - 1];
398         ofs[0] = 0;
399     }
400
401     pair<tcost_t, vector<int>> maximum_weighted_matching(bool init_matching = false)
402     {
403         initialize();
404         set_potential();
405         if (init_matching)
406             find_maximal_matching();
407         for (int u = 1; u <= N; ++u)
408             if (!mate[u])
409                 do_edmonds_search(u);
410         tcost_t ret = compute_optimal_value();
411         return make_pair(ret, mate);
412     }
413
414 private:
415     tcost_t compute_optimal_value() const
416     {
417         tcost_t ret = 0;
418         for (int u = 1; u <= N; ++u)
419             if (mate[u] > u) {
420                 cost_t max_c = 0;
421                 for (int eid = ofs[u]; eid < ofs[u + 1]; ++eid) {
422                     if (edges[eid].to == mate[u])
423                         max_c = max(max_c, edges[eid].cost);
424                 }
425                 ret += max_c;
426             }
427         return ret >> 1;
428     }
429
430     inline tcost_t reduced_cost(int u, int v, const Edge& e) const
431     {
432         return tcost_t(potential[u]) + potential[v] - e.cost;
433     }
434
435     void rematch(int v, int w)
436     {
437         int t = mate[v];
438         mate[v] = w;
439         if (mate[t] != v)
440             return;
441         if (link[v].to == surface[link[v].to]) {
442             mate[t] = link[v].from;
443             rematch(mate[t], t);
444         } else {
445             int x = link[v].from, y = link[v].to;
446             rematch(x, y);
447             rematch(y, x);
448         }
449     }
450

```

```

451 void fix_mate_and_base(int b)
452 {
453     if (b <= N)
454         return;
455     int bv = base[b], mv = node[bv].link[0].v, bmv = node[bv].link[0].b;
456     int d = (node[bmv].link[1].v == mate[mv]) ? 0 : 1;
457     while (1) {
458         int mv = node[bv].link[d].v, bmv = node[bv].link[d].b;
459         if (node[bmv].link[1 ^ d].v != mate[mv])
460             break;
461         fix_mate_and_base(bv);
462         fix_mate_and_base(bmv);
463         bv = node[bmv].link[d].b;
464     }
465     fix_mate_and_base(base[b] = bv);
466     mate[b] = mate[bv];
467 }
468
469 void reset_time()
470 {
471     time_current_ = 0;
472     event1 = { Inf, 0 };
473 }
474
475 void reset_blossom(int b)
476 {
477     label[b] = kFree;
478     link[b].from = 0;
479     slack[b] = Inf;
480     lazy[b] = 0;
481 }
482
483 void reset_all()
484 {
485     label[0] = kFree;
486     link[0].from = 0;
487     for (int v = 1; v <= N; ++v) { // should be optimized for sparse graphs.
488         if (label[v] == kOuter)
489             potential[v] -= time_current_;
490         else {
491             int bv = surface[v];
492             potential[v] += lazy[bv];
493             if (label[bv] == kInner)
494                 potential[v] += time_current_ - time_created[bv];
495         }
496         reset_blossom(v);
497     }
498     for (int b = N + 1, r = B - unused_bid_idx; r > 0 && b < S; ++b)
499         if (base[b] != b) {
500             if (surface[b] == b) {
501                 fix_mate_and_base(b);
502                 if (label[b] == kOuter)
503                     potential[b] += (time_current_ - time_created[b]) << 1;
504                 else if (label[b] == kInner)
505                     fix_blossom_potential<kInner>(b);
506                 else
507                     fix_blossom_potential<kFree>(b);
508             }
509             heap2s.clear(b);
510             reset_blossom(b);
511             --r;
512         }
513
514     que.clear();
515     reset_time();

```



```

516     heap2.clear();
517     heap3.clear();
518     heap4.clear();
519 }
520
521 void do_edmonds_search(int root)
522 {
523     if (potential[root] == 0)
524         return;
525     link_blossom(surface[root], { 0, 0 });
526     push_outer_and_fix_potentials(surface[root], 0);
527     for (bool augmented = false; !augmented;) {
528         augmented = augment(root);
529         if (augmented)
530             break;
531         augmented = adjust_dual_variables(root);
532     }
533     reset_all();
534 }
535
536 template <Label Lab>
537 inline cost_t fix_blossom_potential(int b)
538 {
539     // Return the amount.
540     // (If v is an atom, the potential[v] will not be changed.)
541     cost_t d = lazy[b];
542     lazy[b] = 0;
543     if (Lab == kInner) {
544         cost_t dt = time_current_ - time_created[b];
545         if (b > N)
546             potential[b] -= dt << 1;
547         d += dt;
548     }
549     return d;
550 }
551
552 template <Label Lab>
553 inline void update_heap2(int x, int y, int by, cost_t t)
554 {
555     if (t >= slack[y])
556         return;
557     slack[y] = t;
558     best_from[y] = x;
559     if (y == by) {
560         if (Lab != kInner)
561             heap2.decrease_key(y, EdgeEvent(t + lazy[y], x, y));
562     } else {
563         int gy = group[y];
564         if (gy != y) {
565             if (t >= slack[gy])
566                 return;
567             slack[gy] = t;
568         }
569         heap2s.decrease_key(by, gy, EdgeEvent(t, x, y));
570         if (Lab == kInner)
571             return;
572         EdgeEvent m = heap2s.min(by);
573         heap2.decrease_key(by, EdgeEvent(m.time + lazy[by], m.from, m.to));
574     }
575 }
576
577 void activate_heap2_node(int b)
578 {
579     if (b <= N) {
580         if (slack[b] < Inf)

```

```

581         heap2.push(b, EdgeEvent(slack[b] + lazy[b], best_from[b], b));
582     } else {
583         if (heap2s.empty(b))
584             return;
585         EdgeEvent m = heap2s.min(b);
586         heap2.push(b, EdgeEvent(m.time + lazy[b], m.from, m.to));
587     }
588 }
589
590 void swap_blossom(int a, int b)
591 {
592     // Assume that `b` is a maximal blossom.
593     swap(base[a], base[b]);
594     if (base[a] == a)
595         base[a] = b;
596     swap(heavy[a], heavy[b]);
597     if (heavy[a] == a)
598         heavy[a] = b;
599     swap(link[a], link[b]);
600     swap(mate[a], mate[b]);
601     swap(potential[a], potential[b]);
602     swap(lazy[a], lazy[b]);
603     swap(time_created[a], time_created[b]);
604     for (int d = 0; d < 2; ++d)
605         node[node[a].link[d].b].link[1 ^ d].b = b;
606     swap(node[a], node[b]);
607 }
608
609 void set_surface_and_group(int b, int sf, int g)
610 {
611     surface[b] = sf, group[b] = g;
612     if (b <= N)
613         return;
614     for (int bb = base[b]; surface[bb] != sf; bb = node[bb].next_b()) {
615         set_surface_and_group(bb, sf, g);
616     }
617 }
618
619 void merge_smaller_blossoms(int bid)
620 {
621     int lb = bid, largest_size = 1;
622     for (int beta = base[bid], b = beta;;) {
623         if (node[b].size > largest_size)
624             largest_size = node[b].size, lb = b;
625         if ((b = node[b].next_b()) == beta)
626             break;
627     }
628     for (int beta = base[bid], b = beta;;) {
629         if (b != lb)
630             set_surface_and_group(b, lb, b);
631         if ((b = node[b].next_b()) == beta)
632             break;
633     }
634     group[lb] = lb;
635     if (largest_size > 1) {
636         surface[bid] = heavy[bid] = lb;
637         swap_blossom(lb, bid);
638     } else
639         heavy[bid] = 0;
640 }
641
642 void contract(int x, int y, int eid)
643 {
644     int bx = surface[x], by = surface[y];
645     assert(bx != by);

```

```

646     const int h = -(eid + 1);
647     link[surface[mate[bx]]].from = link[surface[mate[by]]].from = h;
648
649     int lca = -1;
650     while (1) {
651         if (mate[by] != 0)
652             swap(bx, by);
653         bx = lca = surface[link[bx].from];
654         if (link[surface[mate[bx]]].from == h)
655             break;
656         link[surface[mate[bx]]].from = h;
657     }
658
659     const int bid = unused_bid[--unused_bid_idx_];
660     assert(unused_bid_idx_ >= 0);
661     int tree_size = 0;
662     for (int d = 0; d < 2; ++d) {
663         for (int bv = surface[x]; bv != lca;) {
664             int mv = mate[bv], bmv = surface[mv], v = mate[mv];
665             int f = link[v].from, t = link[v].to;
666             tree_size += node[bv].size + node[bmv].size;
667             link[mv] = { x, y };
668
669             if (bv > N)
670                 potential[bv] += (time_current_ - time_created[bv]) << 1;
671             if (bmv > N)
672                 heap4.erase(bmv);
673             push_outer_and_fix_potentials(bmv, fix_blossom_potential<kInner>(bmv));
674
675             node[bv].link[d] = { bmv, mv };
676             node[bmv].link[1 ^ d] = { bv, v };
677             node[bmv].link[d] = { bv = surface[f], f };
678             node[bv].link[1 ^ d] = { bmv, t };
679         }
680         node[surface[x]].link[1 ^ d] = { surface[y], y };
681         swap(x, y);
682     }
683     if (lca > N)
684         potential[lca] += (time_current_ - time_created[lca]) << 1;
685     node[bid].size = tree_size + node[lca].size;
686     base[bid] = lca;
687     link[bid] = link[lca];
688     mate[bid] = mate[lca];
689     label[bid] = kOuter;
690     surface[bid] = bid;
691     time_created[bid] = time_current_;
692     potential[bid] = 0;
693     lazy[bid] = 0;
694
695     merge_smaller_blossoms(bid); // O(n log n) time / Edmonds search
696 }
697
698 void link_blossom(int v, Link l)
699 {
700     link[v] = { l.from, l.to };
701     if (v <= N)
702         return;
703     int b = base[v];
704     link_blossom(b, l);
705     int pb = node[b].prev_b();
706     l = { node[pb].next_v(), node[b].prev_v() };
707     for (int bv = b;;) {
708         int bw = node[bv].next_b();
709         if (bw == b)
710             break;

```

```

711         link_blossom(bw, l);
712         Link n1 = { node[bw].prev_v(), node[bv].next_v() };
713         bv = node[bw].next_b();
714         link_blossom(bv, n1);
715     }
716 }
717
718 void push_outer_and_fix_potentials(int v, cost_t d)
719 {
720     label[v] = kOuter;
721     if (v > N) {
722         for (int b = base[v]; label[b] != kOuter; b = node[b].next_b()) {
723             push_outer_and_fix_potentials(b, d);
724         }
725     } else {
726         potential[v] += time_current_ + d;
727         if (potential[v] < event1.time)
728             event1 = { potential[v], v };
729         que.enqueue(v);
730     }
731 }
732
733 bool grow(int root, int x, int y)
734 {
735     int by = surface[y];
736     bool visited = (label[by] != kFree);
737     if (!visited)
738         link_blossom(by, { 0, 0 });
739     label[by] = kInner;
740     time_created[by] = time_current_;
741     heap2.erase(by);
742     if (y != by)
743         heap4.update(by, time_current_ + (potential[by] >> 1));
744     int z = mate[by];
745     if (z == 0 && by != surface[root]) {
746         rematch(x, y);
747         rematch(y, x);
748         return true;
749     }
750     int bz = surface[z];
751     if (!visited)
752         link_blossom(bz, { x, y });
753     else
754         link[bz] = link[z] = { x, y };
755     push_outer_and_fix_potentials(bz, fix_blossom_potential<kFree>(bz));
756     time_created[bz] = time_current_;
757     heap2.erase(bz);
758     return false;
759 }
760
761 void free_blossom(int bid)
762 {
763     unused_bid[unused_bid_idx++] = bid;
764     base[bid] = bid;
765 }
766
767 int recalculate_minimum_slack(int b, int g)
768 {
769     // Return the destination of the best edge of blossom `g`.
770     if (b <= N) {
771         if (slack[b] >= slack[g])
772             return 0;
773         slack[g] = slack[b];
774         best_from[g] = best_from[b];
775         return b;

```

```

776     }
777     int v = 0;
778     for (int beta = base[b], bb = beta;;) {
779         int w = recalculate_minimum_slack(bb, g);
780         if (w != 0)
781             v = w;
782         if ((bb = node[bb].next_b()) == beta)
783             break;
784     }
785     return v;
786 }
787
788 void construct_smaller_components(int b, int sf, int g)
789 {
790     surface[b] = sf, group[b] = g; // `group[b] = g` is unneeded.
791     if (b <= N)
792         return;
793     for (int bb = base[b]; surface[bb] != sf; bb = node[bb].next_b()) {
794         if (bb == heavy[b]) {
795             construct_smaller_components(bb, sf, g);
796         } else {
797             set_surface_and_group(bb, sf, bb);
798             int to = 0;
799             if (bb > N)
800                 slack[bb] = Inf, to = recalculate_minimum_slack(bb, bb);
801             else if (slack[bb] < Inf)
802                 to = bb;
803             if (to > 0)
804                 heap2s.push(sf, bb, EdgeEvent(slack[bb], best_from[bb], to));
805         }
806     }
807 }
808
809 void move_to_largest_blossom(int bid)
810 {
811     const int h = heavy[bid];
812     cost_t d = (time_current_ - time_created[bid]) + lazy[bid];
813     lazy[bid] = 0;
814     for (int beta = base[bid], b = beta;;) {
815         time_created[b] = time_current_;
816         lazy[b] = d;
817         if (b != h)
818             construct_smaller_components(b, b, b), heap2s.erase(bid, b);
819         if ((b = node[b].next_b()) == beta)
820             break;
821     }
822     if (h > 0)
823         swap_blossom(h, bid), bid = h;
824     free_blossom(bid);
825 }
826
827 void expand(int bid)
828 {
829     int mv = mate[base[bid]];
830     move_to_largest_blossom(bid); // O(n log n) time / Edmonds search
831     Link old_link = link[mv];
832     int old_base = surface[mate[mv]], root = surface[old_link.to];
833     int d = (mate[root] == node[root].link[0].v) ? 1 : 0;
834     for (int b = node[old_base].link[d ^ 1].b; b != root;) {
835         label[b] = kSeparated;
836         activate_heap2_node(b);
837         b = node[b].link[d ^ 1].b;
838         label[b] = kSeparated;
839         activate_heap2_node(b);
840         b = node[b].link[d ^ 1].b;

```

```

841     }
842     for (int b = old_base;; b = node[b].link[d].b) {
843         label[b] = kInner;
844         int nb = node[b].link[d].b;
845         if (b == root)
846             link[mate[b]] = old_link;
847         else
848             link[mate[b]] = { node[b].link[d].v, node[nb].link[d ^ 1].v };
849         link[surface[mate[b]]] = link[mate[b]]; // fix tree links
850         if (b > N) {
851             if (potential[b] == 0)
852                 expand(b);
853             else
854                 heap4.push(b, time_current_ + (potential[b] >> 1));
855         }
856         if (b == root)
857             break;
858         push_outer_and_fix_potentials(nb, fix_blossom_potential<kInner>(b = nb));
859     }
860 }
861
862 bool augment(int root)
863 {
864     // Return true if an augmenting path is found.
865     while (!que.empty()) {
866         int x = que.dequeue(), bx = surface[x];
867         if (potential[x] == time_current_) {
868             if (x != root)
869                 rematch(x, 0);
870             return true;
871         }
872         for (int eid = ofs[x]; eid < ofs[x + 1]; ++eid) {
873             auto& e = edges[eid];
874             int y = e.to, by = surface[y];
875             if (bx == by)
876                 continue;
877             Label l = label[by];
878             if (l == kOuter) {
879                 cost_t t = reduced_cost(x, y, e) >> 1; // < 2 * Inf
880                 if (t == time_current_) {
881                     contract(x, y, eid);
882                     bx = surface[x];
883                 } else if (t < event1.time) {
884                     heap3.emplace(t, x, eid);
885                 }
886             } else {
887                 tcost_t t = reduced_cost(x, y, e); // < 3 * Inf
888                 if (t >= Inf)
889                     continue;
890                 if (l != kInner) {
891                     if (cost_t(t) + lazy[by] == time_current_) {
892                         if (grow(root, x, y))
893                             return true;
894                     } else
895                         update_heap2<kFree>(x, y, by, t);
896                 } else {
897                     if (mate[x] != y)
898                         update_heap2<kInner>(x, y, by, t);
899                 }
900             }
901         }
902     }
903     return false;
904 }
905

```

```

906 bool adjust_dual_variables(int root)
907 {
908     // delta1 : rematch
909     cost_t time1 = event1.time;
910
911     // delta2 : grow
912     cost_t time2 = Inf;
913     if (!heap2.empty())
914         time2 = heap2.min().time;
915
916     // delta3 : contract :  $O(m \log n)$  time / Edmonds search [ bottleneck (?) ]
917     cost_t time3 = Inf;
918     while (!heap3.empty()) {
919         EdgeEvent e = heap3.min();
920         int x = e.from, y = edges[e.to].to; // e.to is some edge id.
921         if (surface[x] != surface[y]) {
922             time3 = e.time;
923             break;
924         } else
925             heap3.pop();
926     }
927
928     // delta4 : expand
929     cost_t time4 = Inf;
930     if (!heap4.empty())
931         time4 = heap4.min().time;
932
933     // -- events --
934     cost_t time_next = min(min(time1, time2), min(time3, time4));
935     assert(time_current_ <= time_next && time_next < Inf);
936     time_current_ = time_next;
937
938     if (time_current_ == event1.time) {
939         int x = event1.id;
940         if (x != root)
941             rematch(x, 0);
942         return true;
943     }
944     while (!heap2.empty() && heap2.min().time == time_current_) {
945         int x = heap2.min().from, y = heap2.min().to;
946         if (grow(root, x, y))
947             return true; // `grow` function will call `heap2.erase(by)`.
948     }
949     while (!heap3.empty() && heap3.min().time == time_current_) {
950         int x = heap3.min().from, eid = heap3.min().to;
951         int y = edges[eid].to;
952         heap3.pop();
953         if (surface[x] == surface[y])
954             continue;
955         contract(x, y, eid);
956     }
957     while (!heap4.empty() && heap4.min().time == time_current_) {
958         int b = heap4.argmin();
959         heap4.pop();
960         expand(b);
961     }
962     return false;
963 }
964
965 private:
966 void initialize()
967 {
968     que = Queue<int>(N);
969     mate.assign(S, 0);
970     link.assign(S, { 0, 0 });

```

```

971     label.assign(S, kFree);
972     base.resize(S);
973     for (int u = 1; u < S; ++u)
974         base[u] = u;
975     surface.resize(S);
976     for (int u = 1; u < S; ++u)
977         surface[u] = u;
978
979     potential.resize(S);
980     node.resize(S);
981     for (int b = 1; b < S; ++b)
982         node[b] = Node(b);
983
984     unused_bid.resize(B);
985     for (int i = 0; i < B; ++i)
986         unused_bid[i] = N + B - i;
987     unused_bid_idx_ = B;
988
989     // for  $O(nm \log n)$  implementation
990     reset_time();
991     time_created.resize(S);
992     slack.resize(S);
993     for (int i = 0; i < S; ++i)
994         slack[i] = Inf;
995     best_from.assign(S, 0);
996     heavy.assign(S, 0);
997     lazy.assign(S, 0);
998     group.resize(S);
999     for (int i = 0; i < S; ++i)
1000         group[i] = i;
1001 }
1002
1003 void set_potential()
1004 {
1005     for (int u = 1; u <= N; ++u) {
1006         cost_t max_c = 0;
1007         for (int eid = ofs[u]; eid < ofs[u + 1]; ++eid) {
1008             max_c = max(max_c, edges[eid].cost);
1009         }
1010         potential[u] = max_c >> 1;
1011     }
1012 }
1013
1014 void find_maximal_matching()
1015 {
1016     // Find a maximal matching naively.
1017     for (int u = 1; u <= N; ++u)
1018         if (!mate[u]) {
1019             for (int eid = ofs[u]; eid < ofs[u + 1]; ++eid) {
1020                 auto& e = edges[eid];
1021                 int v = e.to;
1022                 if (mate[v] > 0 || reduced_cost(u, v, e) > 0)
1023                     continue;
1024                 mate[u] = v;
1025                 mate[v] = u;
1026                 break;
1027             }
1028         }
1029 }
1030
1031 private:
1032     int N, B, S; //  $N = |V|$ ,  $B = (|V| - 1) / 2$ ,  $S = N + B + 1$ 
1033     vector<int> ofs;
1034     vector<Edge> edges;
1035

```



```

1036 Queue<int> que;
1037 vector<int> mate, surface, base;
1038 vector<Link> link;
1039 vector<Label> label;
1040 vector<cost_t> potential;
1041
1042 vector<int> unused_bid;
1043 int unused_bid_idx_;
1044 vector<Node> node;
1045
1046 // for O(nm log n) implementation
1047 vector<int> heavy, group;
1048 vector<cost_t> time_created, lazy, slack;
1049 vector<int> best_from;
1050
1051 cost_t time_current_;
1052 Event event1;
1053 ModifiableHeap<EdgeEvent> heap2;
1054 ModifiableHeaps<EdgeEvent> heap2s;
1055 FastHeap<EdgeEvent> heap3;
1056 ModifiableHeap<cost_t> heap4;
1057 };
1058
1059 using MWM = MaximumWeightedMatching<int>;
1060 using Edge = MWM::InputEdge;
1061
1062 int main()
1063 {
1064     ios::sync_with_stdio(false); cin.tie(0); cout.tie(0);
1065     int N, M;
1066     cin >> N >> M;
1067     vector<Edge> edges(2 * M);
1068     vector<int> ou(N + 2), ov(N + 2);
1069
1070     int u, v, c;
1071     for (int i = 0; i < M; ++i) {
1072         cin >> u >> v >> c;
1073         edges[i] = { u, v, c };
1074         ou[u + 1] += 1;
1075         ov[v + 1] += 1;
1076     }
1077     for (int i = 1; i <= N + 1; ++i)
1078         ov[i] += ov[i - 1];
1079     for (int i = 0; i < M; ++i)
1080         edges[M + (ov[edges[i].to]++)] = edges[i];
1081     for (int i = 1; i <= N + 1; ++i)
1082         ou[i] += ou[i - 1];
1083     for (int i = 0; i < M; ++i)
1084         edges[ou[edges[i + M].from]++] = edges[i + M];
1085     edges.resize(M);
1086
1087     auto ans = MWM(N, edges).maximum_weighted_matching();
1088     cout << ans.first << endl;
1089     for (int i = 1; i <= N; ++i) {
1090         cout << ans.second[i] << (i == N ? '\n' : ' ');
1091     }
1092     return 0;
1093 }

```

3 math

3.1 2DGeometry

```

1 namespace Geometry
2 {
3     // 定义以及防止精度出错
4     const double eps = 1e-8;
5     const double inf = 1e9;
6     const double pi = acos(-1.0);
7
8     inline int sgn(double x) {
9         if(fabs(x) < eps) return 0;
10        if(x < 0) return -1;
11        return 1;
12    }
13
14    // 单位换算
15    inline double degree2radian(const double& alpha) {
16        return alpha / 180 * pi;
17    }
18
19    inline double radian2degree(const double& alpha) {
20        return alpha / pi * 180;
21    }
22
23    // 点 (向量)
24    // 也是远点到该点的向量
25    struct point
26    {
27        double x, y;
28        point(double _x = 0, double _y = 0) : x(_x), y(_y) {}
29
30        point operator - (const point& b) const {
31            return point(x - b.x, y - b.y);
32        }
33
34        point operator + (const point& b) const {
35            return point(x + b.x, y + b.y);
36        }
37
38        bool operator < (const point& b) const {
39            return sgn(x - b.x) == 0 ? sgn(y - b.y) < 0 : sgn(x - b.x) < 0;
40        }
41
42        bool operator == (const point& b) const {
43            return sgn(x - b.x) == 0 && sgn(y - b.y) == 0;
44        }
45
46        point operator * (const double& b) {
47            return point(x * b, y * b);
48        }
49
50        point operator / (const double& b) {
51            return point(x / b, y / b);
52        }
53
54        // 绕原点逆时针旋转, 给出正弦和余弦值
55        // 若绕另一点 p, 则先转换成以 p 为原点, 完成旋转, 再转换回来
56        void transxy(const double& sinb, const double& cosb) {
57            double tx = x, ty = y;
58            x = tx * cosb - ty * sinb;
59            y = tx * sinb + ty * cosb;
60        }
61    }

```

```
62 // 绕原点逆时针旋转，给出旋转弧度
63 void transxy(const double& b) {
64     double tx = x, ty = y;
65     x=tx * cos(b) - ty * sin(b);
66     y=tx * sin(b) + ty * cos(b);
67 }
68
69 // 逆时针旋转 90 度
70 point trans90() {
71     return point(-y, x);
72 }
73
74 // 顺时针旋转 90 度
75 point trans270() {
76     return point(y, -x);
77 }
78
79 // 与原点的距离
80 // a,b 之间的距离: (b- a).length()
81 double length() {
82     return sqrt(x * x + y * y);
83 }
84
85 // 与原点的距离的平方
86 double length2() {
87     return x * x + y * y;
88 }
89
90 // 与点 a 之间的距离
91 double disTo(const point& a) {
92     return (a - *this).length();
93 }
94
95 // 与 x 轴正方向的夹角，单位为弧度
96 double alpha() {
97     return atan2(y, x);
98 }
99
100 // 单位向量
101 point unit() {
102     return point(x, y) / length();
103 }
104 };
105
106 // 向量 Oa 和向量 Ob 的叉积
107 inline double det(const point& a,const point& b) {
108     return a.x * b.y - a.y * b.x;
109 }
110
111 // 向量 ab 和向量 ac 的叉积
112 inline double det(const point& a,const point& b,const point& c) {
113     return det(b - a, c - a);
114 }
115
116 // 向量 Oa 和向量 Ob 的点积
117 inline double dot(const point&a,const point& b) {
118     return a.x * b.x + a.y * b.y;
119 }
120
121 // 向量 ab 和向量 ac 的点积
122 inline double dot(const point&a, const point& b,const point& c) {
123     return dot(b - a, c - a);
124 }
125
126 // 两点间距离
```

```

127 inline double distance(const point& a, const point& b) {
128     return (a - b).length();
129 }
130
131 // 两点间距离的平方
132 inline double distance2(const point& a, const point& b) {
133     return (b.x - a.x) * (b.x - a.x) + (b.y - a.y) * (b.y - a.y);
134 }
135
136 // LightOJ1203
137 // 最终答案会在凸包上, 然后算 ab 与 ac 的夹角, 单位为弧度
138 // ab 与 ac 的夹角
139 double radian(point a, point b, point c) {
140     return fabs(atan2(fabs(det(a, b, c)), dot(a, b, c)));
141 }
142
143 double angle(point a, point b, point c) {
144     double r = radian(a, b, c);
145     return radian2degree(r);
146 }
147
148 // 从点 a, 由 b 遮挡, 能否看见 c
149 bool canSee(point a, point b, point c) {
150     return sgn(det(a, b, c)) <= 0;
151 }
152
153 // 直线或者线段
154 struct line
155 {
156     point s, e;           // 直线端点
157     double a, b, c;       //  $ax+by+c=0$ 
158     double k;             // 斜率,  $[-\pi, \pi]$ 
159
160     line(point _s = point(), point _e = point()) : s(_s), e(_e) {
161         k = atan2(e.y - s.y, e.x - s.x);
162         a = e.y - s.y;
163         b = s.x - e.x;
164         c = e.x * s.y - e.y * s.x;
165     }
166
167     //  $ax + by + c = 0$ ;
168     line(const double& _a, const double& _b, const double& _c) : a(_a), b(_b), c(_c) {
169         if (sgn(a) == 0) {
170             s = point(0, -c / b);
171             e = point(1, -c / b);
172         } else if (sgn(b) == 0) {
173             s = point(-c / a, 0);
174             e = point(-c / a, 1);
175         } else {
176             s = point(0, -c / b);
177             e = point(1, (-c - a) / b);
178         }
179     }
180
181     // 点和倾斜角确定直线
182     line(const point& a, const double b) : s(a) {
183         if (sgn(b - pi / 2) == 0) e = s + point(0, 1);
184         else e = s + point(1, tan(b));
185     }
186
187     bool operator == (const line& l) {
188         return (s == l.s) && (e == l.e);
189     }
190
191     void adjust() {

```

```

192         if(e < s) swap(s, e);
193     }
194
195     double length() {
196         return s.disTo(e);
197     }
198
199     // 判断点和直线的关系
200     // 1 在直线左侧
201     // 2 在直线右侧
202     // 3 在直线上
203     int relationToPoint(point p) {
204         int c = sgn(det(s, p, e));
205         if(c < 0) return 1;
206         else if(c > 0) return 2;
207         else return 3;
208     }
209
210     // 判断点 p 是否在线段上
211     bool isPointOnLine(const point& p) {
212         return sgn(det(p - s, e - s)) == 0 && sgn(det(p - s, p - e)) <= 0;
213     }
214
215     // 判断两直线是否平行
216     bool parallelTo(line l) {
217         return sgn(det(e - s, l.e - l.s)) == 0;
218     }
219
220     // 线段相交判断
221     // 0 不相交
222     // 1 交点是端点
223     // 2 交点不是端点
224     int isSegCrossSeg(line l) {
225         int d1 = sgn(det(s, e, l.s));
226         int d2 = sgn(det(s, e, l.e));
227         int d3 = sgn(det(l.s, l.e, s));
228         int d4 = sgn(det(l.s, l.e, e));
229         if((d1^d2) == -2 && (d3^d4) == -2) return 2;
230         return (d1 == 0 && sgn(dot(l.s - s, l.s - e)) <= 0)
231             || (d2 == 0 && sgn(dot(l.e - s, l.e - e)) <= 0)
232             || (d3 == 0 && sgn(dot(s - l.s, s - l.e)) <= 0)
233             || (d4 == 0 && sgn(dot(e - l.s, e - l.e)) <= 0);
234     }
235
236     // 直线相交判断
237     // 0 平行
238     // 1 重合
239     // 2 相交
240     bool isLineCrossLine(line l) {
241         if(parallelTo(l))
242             return l.relationToPoint(s) == 3;
243         return 2;
244     }
245
246     // 本直线与线段 v 相交判断
247     // 0 不相交
248     // 1 交点是端点
249     // 2 交点不是端点
250     int isLineCrossSeg(line seg) {
251         int d1 = sgn(det(s, e, seg.s));
252         int d2 = sgn(det(s, e, seg.e));
253         if((d1^d2) == -2) return 2;
254         return (d1 == 0 || d2 == 0);
255     }
256

```

```

257 // 求两直线交点
258 // 要求两直线不平行或重合
259 point getCrossPoint(line l) {
260     double a1 = det(l.s, l.e, s);
261     double a2 = -det(l.s, l.e, e);
262     return (s * a2 + e * a1) / (a1 + a2);
263 }
264
265 // 点到直线的距离
266 double disPointToLine(const point& p) {
267     double d = det(s, p, e) / length();
268     return fabs(d);
269 }
270
271 // 点到线段的距离
272 double disPointToSeg(const point& p) {
273     if (sgn(dot(s, p, e)) < 0 || sgn(dot(e, p, s)) < 0)
274         return min(distance(p, s), distance(p, e));
275     return fabs(disPointToLine(p));
276 }
277
278 // 线段到线段的距离
279 double disSegToSeg(line& l) {
280     if (isSegCrossSeg(l) == 0) {
281         double d1 = min(disPointToSeg(l.s), disPointToSeg(l.e));
282         double d2 = min(l.disPointToSeg(s), l.disPointToSeg(e));
283         return min(d1, d2);
284     }
285     return 0;
286 }
287
288 // 点在直线上的投影
289 point projectionPointOnLine(const point& p) {
290     return s + (dot(e - s, dot(s, e, p))) / ((e - s).length2());
291 }
292
293 // 点关于直线的对称点
294 point symmetryPoint(const point& p) {
295     point q = projectionPointOnLine(p);
296     return point(2 * q.x - p.x, 2 * q.y - p.y);
297 }
298
299 // 垂直平分线
300 line getVerticalBisector() {
301     point m = (s + e) / 2;
302     double radian = (e - s).alpha() + pi / 2;
303     return line(m, radian);
304 }
305 };
306
307 point getLineCrossLine(line l1, line l2) {
308     return l1.getCrossPoint(l2);
309 }
310
311 // 向量表示法, 方向为由 s -> e
312 // struct line
313 // {
314 //     point s, v;
315 //     line(point a=point(), point b=point()) {
316 //         s=a;
317 //         v.x=b.x-a.x;
318 //         v.y=b.y-a.y;
319 //     }
320 // };
321

```

```
322 // 圆
323 struct circle
324 {
325     point p;           // 圆心
326     double r;          // 半径
327
328     circle() {}
329
330     circle(point _p, double _r) : p(_p), r(_r) {}
331     circle(double _x, double _y, double _r) : p(point(_x, _y)), r(_r) {}
332
333     // 圆上三点确定圆
334     circle(point x1, point x2, point x3) {
335         double a = x2.x - x1.x;
336         double b = x2.y - x1.y;
337         double c = x3.x - x2.x;
338         double d = x3.y - x2.y;
339         double e = x2.x * x2.x + x2.y * x2.y - x1.x * x1.x - x1.y * x1.y;
340         double f = x3.x * x3.x + x3.y * x3.y - x2.x * x2.x - x2.y * x2.y;
341
342         p = point((f * b - e * d) / (c * b - a * d) / 2, (a * f - e * c) / (a * d - b * c) / 2);
343         r = distance(p, x1);
344     }
345
346     double area() {
347         return pi * r * r;
348     }
349
350     double perimeter() {
351         return 2 * pi * r;
352     }
353
354     // 点和圆的关系
355     // 0 圆外
356     // 1 圆上
357     // 2 圆内
358     int relationToPoint(point a) {
359         double d2 = distance2(p, a);
360         if(sgn(d2 - r * r) < 0) return 2;
361         else if(sgn(d2 - r * r) == 0) return 1;
362         return 0;
363     }
364
365     // 圆和直线的关系
366     // 0 圆外
367     // 1 圆上
368     // 2 圆内
369     int relationToLine(line l) {
370         double d = l.disPointToLine(p);
371         if (sgn(d - r) < 0) return 2;
372         else if(sgn(d - r) == 0) return 1;
373         return 0;
374     }
375
376     // 圆和线段的关系
377     // 0 圆外
378     // 1 圆上
379     // 2 圆内
380     int relationToSeg(line l) {
381         double d = l.disPointToSeg(p);
382         if (sgn(d - r) < 0) return 2;
383         else if (sgn(d - r) == 0) return 1;
384         return 0;
385     }
386 }
```

```

387 // 圆和圆的关系
388 // 5 相离
389 // 4 外切
390 // 3 相交
391 // 2 内切
392 // 1 内含
393 int relationToCircle(circle c) {
394     double d = distance(p, c.p);
395     if(sgn(d - r - c.r) > 0) return 5;
396     if(sgn(d - r - c.r) == 0) return 4;
397     double l = fabs(r - c.r);
398     if(sgn(d - r - c.r) < 0 && sgn(d - l) > 0) return 3;
399     if(sgn(d - l) == 0) return 2;
400     if(sgn(d - l) < 0) return 1;
401     return -1;
402 }
403 };
404
405 // 多边形
406 struct polygon
407 {
408     int n; // 顶点个数
409     vector<point> p; // 顶点
410     vector<line> l; // 边
411
412     polygon() : n(0) {}
413     polygon(int _n) : n(_n), p(n) {}
414
415     point& operator [] (int idx) { return p[idx]; }
416
417     void resize(int _n) {
418         n = _n;
419         p.resize(n);
420     }
421
422     // 多边形周长
423     double perimeter() {
424         double sum = 0;
425         for(int i = 0; i < n; i++) sum += (p[(i + 1) % n] - p[i]).length();
426         return sum;
427     }
428
429     // 多边形面积
430     double area() {
431         double sum = 0;
432         for(int i = 0; i < n; i++) sum += det(p[i], p[(i + 1) % n]);
433         return fabs(sum) / 2;
434     }
435
436     void getline() {
437         l.resize(n);
438         for(int i = 0; i < n; i++) l[i] = line(p[i], p[(i + 1) % n]);
439     }
440
441     // 极角排序
442     struct cmp {
443         point p;
444         cmp(const point& _p) : p(_p) {}
445         bool operator () (const point& a, const point& b) const {
446             int d = sgn(det(p, a, b));
447             if(d == 0) return sgn(distance(a, p) - distance(b, p)) < 0;
448             return d > 0;
449         }
450     };
451

```



```

452 // 标准化, 即极角排序 (逆时针)
453 void norm() {
454     point mi = p[0];
455     for(int i = 1; i < n; i++) mi = min(mi, p[i]);
456     sort(p.begin(), p.end(), cmp(mi));
457 }
458
459 // 凸包 (非严格)
460 // 若要求严格, 则需要再将共线的点除了端点全删去
461 polygon getConvex() {
462     norm();
463     if (n == 0) return polygon(0);
464     else if (n == 1) {
465         polygon convex(1);
466         convex[0] = p[0];
467         return convex;
468     } else if (n == 2) {
469         if (p[0] == p[1]) {
470             polygon convex(1);
471             convex[0] = p[0];
472             return convex;
473         }
474         polygon convex(2);
475         convex[0] = p[0];
476         convex[1] = p[1];
477         return convex;
478     }
479
480     polygon convex(n);
481     convex.p[0] = p[0];
482     convex.p[1] = p[1];
483     int top = 2;
484     for(int i = 2; i < n; i++) {
485         while(top > 1 && sgn(det(convex.p[top - 2], convex.p[top - 1], p[i])) <= 0) --top;
486         convex.p[top++] = p[i];
487     }
488     convex.resize(top);
489     if(convex.n == 2 && convex.p[0] == convex.p[1]) convex.resize(1);
490
491     return convex;
492 }
493
494 bool isConvex() {
495     bool s[3] = {0, 0, 0};
496     for(int i = 0, j, k; i < n; i++) {
497         j = (i + 1) % n;
498         k = (j + 1) % n;
499         s[sgn(det(p[i], p[j], p[k])) + 1] = true;
500         if(s[0] && s[2]) return false;
501     }
502     return true;
503 }
504
505 // 多边形方向
506 // 1 逆时针
507 // 2 顺时针
508 int direction() {
509     double sum = 0;
510     for(int i = 0; i < n; i++) sum += det(p[i], p[(i + 1) % n]);
511     if(sgn(sum) > 0) return 1;
512     return 0;
513 }
514
515 // 凸包上最远点对
516 // 平面最远点对就是点集的凸包上的最远点对

```

```

517 pair<point, point> getMaxPair() {
518     assert(n >= 2);
519     if (n == 2) return make_pair(p[0], p[1]);
520     point p1 = p[0], p2 = p[1];
521     double dis = distance(p1, p2);
522
523     // 旋转卡 (qia) 壳 (qiao)
524     int k = 1;
525     for (int i = 0; i < n; ++i) {
526         int j = (i + 1) % n;
527         while(sgn(det(p[i], p[j], p[k]) - det(p[i], p[j], p[(k + 1) % n])) <= 0) k = (k + 1) % n;
528
529         if (sgn(distance(p[i], p[k]) - dis) > 0) p1 = p[i], p2 = p[k], dis = distance(p1, p2);
530         if (sgn(distance(p[j], p[k]) - dis) > 0) p1 = p[j], p2 = p[k], dis = distance(p1, p2);
531     }
532     return make_pair(p1, p2);
533 }
534
535 double getMaxDis() {
536     pair<point, point> pr = getMaxPair();
537     return distance(pr.first, pr.second);
538 }
539
540 // 平面最近点对 (P1257, P1429)
541 // 分治法求解平面最近点对, 复杂度  $O(n \log n)$ 
542 void __getMinPair(int l, int r, point& p1, point& p2, double& dis) {
543     if (r - l <= 9) {
544         for (int i = l; i <= r; ++i) {
545             for (int j = i + 1; j <= r; ++j) {
546                 double d = distance(p[i], p[j]);
547                 if (d < dis) {
548                     dis = d;
549                     p1 = p[i];
550                     p2 = p[j];
551                 }
552             }
553         }
554         return;
555     }
556
557     int m = (l + r) >> 1;
558     __getMinPair(l, m, p1, p2, dis); __getMinPair(m, r, p1, p2, dis);
559     vector<point> tmp;
560     for (int i = l; i <= r; ++i) if (abs(p[i].x - p[m].x) <= dis) tmp.push_back(p[i]);
561     sort(tmp.begin(), tmp.end(), [] (const point& a, const point& b) {
562         return a.y < b.y;
563     });
564     for (int i = 1; i < (int)tmp.size(); ++i) {
565         for (int j = i - 1; j >= 0; --j) {
566             if (tmp[j].y < tmp[i].y - dis) break;
567             double d = distance(tmp[i], tmp[j]);
568             if (d < dis) {
569                 dis = d;
570                 p1 = tmp[i];
571                 p2 = tmp[j];
572             }
573         }
574     }
575 }
576
577 pair<point, point> getMinPair() {
578     assert(n >= 1);
579     if (n == 2) return make_pair(p[0], p[1]);
580
581     sort(p.begin(), p.end(), [] (const point& a, const point& b) {

```

```

582         return a.x < b.x;
583     });
584     point p1 = p[0], p2 = p[1];
585     double dis = distance(p1, p2);
586     __getMinPair(0, n - 1, p1, p2, dis);
587     return make_pair(p1, p2);
588 }
589
590 double getMinDis() {
591     assert(n >= 1);
592     if (n == 2) return distance(p[0], p[1]);
593
594     sort(p.begin(), p.end(), [] (const point& a, const point& b) {
595         return a.x < b.x;
596     });
597     point p1 = p[0], p2 = p[1];
598     double dis = distance(p1, p2);
599     __getMinPair(0, n - 1, p1, p2, dis);
600     return dis;
601 }
602
603 // 最小圆覆盖 (P2253, P1472)
604 // 随机增量法求解最小圆覆盖问题, 在随机顺序的点集上, 期望复杂度为  $O(n)$ 
605 circle getMinCircle() {
606     // 随机打乱顺序
607     srand(time(0));
608     for (int i = n - 1; i >= 1; --i) swap(p[i], p[rand() % i]);
609
610     circle c(p[0], 0);
611     for (int i = 0; i < n; ++i) {
612         if (c.relationToPoint(p[i]) == 2) continue;
613         c.p = (p[0] + p[i]) / 2;
614         c.r = distance(p[0], p[i]) / 2;
615
616         for (int j = 1; j < i; ++j) {
617             if (c.relationToPoint(p[j]) == 2) continue;
618             c.p = (p[i] + p[j]) / 2;
619             c.r = distance(p[i], p[j]) / 2;
620
621             for (int k = 1; k < j; ++k) {
622                 if (c.relationToPoint(p[k]) == 2) continue;
623                 c = circle(p[i], p[j], p[k]);
624             }
625         }
626     }
627     return c;
628 }
629
630
631 // 点与多边形的位置关系
632 // 0 外部
633 // 1 内部
634 // 2 边上
635 // 3 点上
636 int relationToPoint(point a) {
637     for (int i = 0; i < n; ++i) if (p[i] == a) return 3;
638
639     getline();
640     for (int i = 0; i < n; ++i) if (l[i].relationToPoint(a) == 3) return 2;
641
642     int cnt = 0;
643     for (int i = 0, j; i < n; ++i) {
644         j = (i + 1) % n;
645         int k = sgn(det(p[j], a, p[i]));
646         int u = sgn(p[i].y - a.y);

```

```

647         int v = sgn(p[j].y - a.y);
648         if (k > 0 && u < 0 && v >= 0) ++cnt;
649         if (k < 0 && v < 0 && u >= 0) --cnt;
650     }
651     return cnt != 0;
652 }
653
654 void DEBUG() {
655     cout << n << endl;
656     for (int i = 0; i < n; ++i) {
657         cout << p[i].x << " " << p[i].y << endl;
658     }
659 }
660 };
661
662 // 半平面 ( $ax + by + c \geq 0$ ), 其实也就是直线
663 // 对于直线 ( $s, e$ ),  $h.s$  为起点,  $h.e$  为方向向量 ( $e - s$ )
664 struct halfplane {
665     point s, v;
666     double k;
667     halfplane() {}
668     halfplane(point _s, point _v) : s(_s), v(_v) {
669         k = v.alpha();
670     }
671     bool operator < (const halfplane& h) const {
672         return k < h.k;
673     }
674 };
675
676 // 点和半平面的位置关系
677 // 0 不在右侧
678 // 1 在右侧
679 int relationPointToHalfplane(point p, halfplane h) {
680     return sgn(det(h.v, p - h.s)) < 0;
681 }
682
683 // 半平面交点
684 point HalfplaneCrossHalfplane(halfplane h1, halfplane h2) {
685     double a = det(h2.v, h1.s - h2.s) / det(h1.v, h2.v);
686     return h1.s + h1.v * a;
687 }
688
689 // 从点集构造出半平面集
690 // 多边形的半平面集即为多边形边集
691 void getHalfPlanes(polygon& p, vector<halfplane>& h) {
692     if (p.direction() != 1) reverse(p.p.begin(), p.p.end());
693     int n = p.n;
694     for (int i = 0, j; i < n; ++i) {
695         j = (i + 1) % n;
696         h.push_back(halfplane(p[i], p[j] - p[i]));
697     }
698 }
699
700 // 有时候题目给的不一定是闭合图形, 需要自行添加边界
701 // ( $x_1, y_1$ ) 为矩形边界左下角, ( $x_2, y_2$ ) 为矩形边界右上角
702 // Usage: addBorderHalfPlanes(0, 0, 1e4, 1e4, h);
703 // POJ2451
704 void addBorderHalfPlanes(double x1, double y1, double x2, double y2, vector<halfplane>& h) {
705     polygon p(4);
706     p[0] = point(x1, y1);
707     p[1] = point(x2, y1);
708     p[2] = point(x2, y2);
709     p[3] = point(x1, y2);
710     getHalfPlanes(p, h);
711 }

```

```

712 // 半平面交
713 // 排序随机增量法 (SI) 求解半平面交, 复杂度为  $O(n \log n)$ 
714 // 瓶颈为排序算法, 用基数排序则为  $O(n)$ 
715 // 最终的结果为一个凸包, 若少于 3 个点则说明无解
716
717
718 // 多边形的核: 位于多边形内且可以看到多边形内所有点的点集 (P5969, POJ1279)
719 // 多边形的半平面交即为多边形的核 (P4196)
720
721 bool getHalfPlaneIntersection(vector<halfplane>& h, polygon& hpi) {
722     int n = int(h.size()), l, r;
723     sort(h.begin(), h.end());
724
725     vector<point> p(n);
726     vector<halfplane> q(n);
727
728     l = r = 0;
729     q[l] = h[0];
730     for (int i = 1; i < n; ++i) {
731         while(l < r && relationPointToHalfplane(p[r - 1], h[i])) --r;
732         while(l < r && relationPointToHalfplane(p[l], h[i])) ++l;
733         q[++r] = h[i];
734         if (l < r && sgn(det(q[r].v, q[r - 1].v)) == 0) {
735             --r;
736             if (!relationPointToHalfplane(h[i].s, q[r])) q[r] = h[i];
737         }
738         if (l < r) p[r - 1] = HalfplaneCrossHalfplane(q[r - 1], q[r]);
739     }
740     while(l < r && relationPointToHalfplane(p[r - 1], q[l])) --r;
741     if (r - l + 1 <= 2) return false; // 交不存在
742     p[r] = HalfplaneCrossHalfplane(q[l], q[r]);
743
744     hpi.resize(r - l + 1);
745     for (int i = l, j = 0; i <= r; ++i) hpi[j++] = p[i];
746
747     return true;
748 }
749
750 // 多边形内部半径最大的圆半径 (POJ3525)
751 // 二分半径, 对多边形边集向内部进行平移, 若平移后的多边形存在核, 则可行
752 double getMaxInsideCircleRadius(polygon& p) {
753     if (p.direction() != 1) reverse(p.p.begin(), p.p.end());
754     int n = p.n;
755
756     // 方向向量, 垂直单位向量
757     vector<point> d(n), v(n);
758     for (int i = 0; i < n; ++i) {
759         d[i] = p[(i + 1) % n] - p[i];
760         v[i] = d[i].trans90().unit();
761     }
762
763     double l = 0, r = 1e4, m;
764     while(r - l >= eps) {
765         m = (l + r) / 2;
766
767         vector<halfplane> h(n);
768         polygon hpi;
769         for (int i = 0; i < n; ++i) h[i] = halfplane(p[i] + v[i] * m, d[i]);
770         bool can = getHalfPlaneIntersection(h, hpi);
771
772         if (can) l = m;
773         else r = m;
774     }
775     return l;
776 }

```

```

777 }
778 using namespace Geometry;

```

3.2 3DGeometry

```

1 namespace Geometry3 {
2     const double eps = 1e-8;
3
4     int sgn(double x) {
5         if (fabs(x) < eps) return 0;
6         if (x < 0) return -1;
7         return 1;
8     }
9
10    struct point3 {
11        double x, y, z;
12        point3(double _x = 0, double _y = 0, double _z = 0) : x(_x), y(_y), z(_z) {}
13
14        bool operator == (const point3& p) const {
15            return sgn(x - p.x) == 0 && sgn(y - p.y) == 0 && sgn(z - p.z) == 0;
16        }
17
18        bool operator < (const point3& p) const {
19            if (sgn(x - p.x) != 0) return sgn(x - p.x) < 0;
20            if (sgn(y - p.y) != 0) return sgn(y - p.y) < 0;
21            return sgn(z - p.z) < 0;
22        }
23
24        point3 operator - (const point3& p) const {
25            return point3(x - p.x, y - p.y, z - p.z);
26        }
27
28        point3 operator + (const point3& p) const {
29            return point3(x + p.x, y + p.y, z + p.z);
30        }
31
32        point3 operator * (const double& a) const {
33            return point3(x * a, y * a, z * a);
34        }
35
36        point3 operator / (const double& a) const {
37            return point3(x / a, y / a, z / a);
38        }
39
40        double operator * (const point3& p) const {
41            return x * p.x + y * p.y + z * p.z;
42        }
43
44        point3 operator ^ (const point3& p) const {
45            return point3(y * p.z - z * p.y, z * p.x - x * p.z, x * p.y - y * p.x);
46        }
47
48        double length() {
49            return sqrt(x * x + y * y + z * z);
50        }
51
52        double length2() {
53            return x * x + y * y + z * z;
54        }
55
56        double disTo(const point3& p) {
57            return (p - *this).length();
58        }
59    }

```

```
60     point3 trunc (double r) {
61         double l = length();
62         if (sgn(l) == 0) return *this;
63         r /= l;
64         return *this * r;
65     }
66 };
67
68 double distance(point3 a, point3 b) {
69     return (b - a).length();
70 }
71
72 double distance2(point3 a, point3 b) {
73     return (b - a).length2();
74 }
75
76 point3 det(point3 a, point3 b) {
77     return a ^ b;
78 }
79
80 point3 det(point3 a, point3 b, point3 c) {
81     return (b - a) ^ (c - a);
82 }
83
84 double dot(point3 a, point3 b) {
85     return a * b;
86 }
87
88 double dot(point3 a, point3 b, point3 c) {
89     return (b - a) * (c - a);
90 }
91
92 // ab 与 ac 之间的夹角
93 double radian(point3 a, point3 b, point3 c) {
94     return acos((b - a) * (c - a)) / (distance(a, b), distance(a, c));
95 }
96
97 // 三角形面积
98 double triArea(point3 a, point3 b, point3 c) {
99     return (det(a, b, c)).length() / 2;
100 }
101
102 double triArea2(point3 a, point3 b, point3 c) {
103     return (det(a, b, c)).length();
104 }
105
106 // 四面体有向面积
107 double QuadVolume(point3 a, point3 b, point3 c, point3 d) {
108     return (det(a, b, c) * (d - a)) / 6;
109 };
110
111 double QuadVolume6(point3 a, point3 b, point3 c, point3 d) {
112     return det(a, b, c) * (d - a);
113 };
114
115 struct line3 {
116     point3 s, e;
117
118     line3(point3 _s = point3(), point3 _e = point3()) : s(_s), e(_e) {}
119
120     bool operator == (const line3& l) const {
121         return (s == l.s) && (e == l.e);
122     }
123
124     // 点到直线的距离
```

```

125     double disPointToLine(point3 p) {
126         return det(s, e, p).length() / distance(s, e);
127     }
128
129     // 点到线段的距离
130     double disPointToSeg(point3 p) {
131         if (sgn(dot(s, p, e)) < 0 || sgn(dot(e, p, s)) < 0)
132             return min(distance(s, p), distance(e, p));
133         return disPointToLine(p);
134     }
135
136     // 点在直线上的投影
137     point3 projectionPointOnLine(point3 p) {
138         return s + (((e - s) * dot(s, e, p)) / (e - s).length2());
139     }
140
141     // 绕 p 旋转 alpha 度
142     point3 rotate(point3 p, double alpha) {
143         if (sgn(det(p, s, e).length()) == 0) return p;
144         point3 p1 = det(s, e, p);
145         point3 p2 = det(e - s, p1);
146         double len = det(p, s, e).length() / distance(s, e);
147         p1 = p1.trunc(len); p2 = p2.trunc(len);
148         point3 p3 = p + p2;
149         point3 p4 = p3 + p1;
150         return p3 + ((p - p3) * cos(alpha) + (p4 - p3) * sin(alpha));
151     }
152
153     // 点在线段上
154     bool isPointOnSeg(point3 p) {
155         return sgn(det(p, s, e).length()) == 0 && sgn(dot(p, s, e)) == 0;
156     }
157 };
158
159 struct plane {
160     point3 a, b, c; // 3 点确定平面
161     point3 o; // 平面的法向量
162
163     point3 pvec() {
164         return det(a, b, c);
165     }
166
167     plane(point3 _a, point3 _b, point3 _c) : a(_a), b(_b), c(_c) {}
168
169     plane(point3 _a, point3 _o) : a(_a), o(_o) {}
170
171     // ax + by + cz + d = 0;
172     plane(double _a, double _b, double _c, double _d) {
173         o = point3(_a, _b, _c);
174         if (sgn(_a) != 0)
175             a = point3((-_d - _c - _b) / _a, 1, 1);
176         else if (sgn(_b) != 0)
177             a = point3(1, (-_d - _c - _a) / _b, 1);
178         else if (sgn(_c) != 0)
179             a = point3(1, 1, (-_d - _b - _a) / _c);
180     }
181
182     // 点在平面上
183     bool isPointOnPlane(point3 p) {
184         return sgn((p - a) * o) == 0;
185     }
186
187     // 两平面夹角
188     double angle(plane f) {
189         return acos(o * f.o) / (o.length() * f.o.length());

```



```

190     }
191
192     // 平面和直线是否相交
193     int PlaneCrossLine(line3 l, point3& p) {
194         double x = o * (l.e - a);
195         double y = o * (l.s - a);
196         double d = x - y;
197         if (sgn(d) == 0) return 0;
198         p = ((l.s * x) - (l.e * y)) / d;
199         return 1;
200     }
201
202     // 点到平面的最近点
203     point3 PointToPlane(point3 p) {
204         line3 l = line3(p, p + o);
205         PlaneCrossLine(l, p);
206         return p;
207     }
208
209     // 平面和平面是否相交
210     int PlaneCrossPlane(plane f, line3& l) {
211         point3 o1 = o ^ f.o;
212         point3 o2 = o ^ o1;
213
214         double d = fabs(f.o * o2);
215         if (sgn(d) == 0) return 0;
216         point3 p = a + (o2 * (f.o * (f.a - a)) / d);
217         l = line3(p, p + o1);
218         return 1;
219     }
220 };
221
222 struct polygon3 {
223     struct face {
224         int a, b, c;
225         bool ok;
226     };
227
228     int n;
229     vector<point3> P;
230
231     int num;
232     vector<face> F;
233     vector<vector<int>> > G;
234
235     polygon3() : n(0) {}
236     polygon3(int _n) : n(_n), P(n), F(8 * n), G(n, vector<int>(n)) {}
237
238     double cmp(point3 p, face f) {
239         point3 p1 = P[f.b] - P[f.a];
240         point3 p2 = P[f.c] - P[f.a];
241         point3 p3 = p - P[f.a];
242         return (p1 ^ p2) * p3;
243     }
244
245     void deal(int p, int a, int b) {
246         int f = G[a][b];
247         if (F[f].ok) {
248             if (cmp(P[p], F[f]) > eps)
249                 dfs(p, f);
250             else {
251                 face add = {b, a, p, true};
252                 G[p][b] = G[a][p] = G[b][a] = num;
253                 F[num++] = add;
254             }

```

```

255     }
256 }
257
258 void dfs(int p, int now) {
259     F[now].ok = false;
260     deal(p, F[now].b, F[now].a);
261     deal(p, F[now].c, F[now].b);
262     deal(p, F[now].a, F[now].c);
263 }
264
265 bool same(int s, int t) {
266     point3 a = P[F[s].a];
267     point3 b = P[F[s].b];
268     point3 c = P[F[s].c];
269
270     bool flag = sgn(QuadVolume6(a, b, c, P[F[t].a])) == 0 &&
271                 sgn(QuadVolume6(a, b, c, P[F[t].b])) == 0 &&
272                 sgn(QuadVolume6(a, b, c, P[F[t].c])) == 0;
273
274     return flag;
275 }
276
277 void buildConvex3() {
278     // step 1: 确保前 4 点不共面
279     bool flag = true;
280     for (int i = 1; i < n; ++i) {
281         if (!(P[0] == P[i])) {
282             swap(P[1], P[i]);
283             flag = false;
284             break;
285         }
286     }
287     if (flag) return;
288
289     flag = true;
290     for (int i = 2; i < n; ++i) {
291         if (det(P[0], P[1], P[i]).length() > eps) {
292             swap(P[2], P[i]);
293             flag = false;
294             break;
295         }
296     }
297     if (flag) return;
298
299     flag = true;
300     for (int i = 3; i < n; ++i) {
301         if (fabs(det(P[0], P[1], P[2]) * (P[i] - P[0])) > eps) {
302             swap(P[3], P[i]);
303             flag = false;
304             break;
305         }
306     }
307     if (flag) return;
308
309     // step 2
310     num = 0;
311     for (int i = 0; i < 4; ++i) {
312         face add = {(i + 1) % 4, (i + 2) % 4, (i + 3) % 4, true};
313         if (cmp(P[i], add) > 0) swap(add.b, add.c);
314         G[add.a][add.b] = G[add.b][add.c] = G[add.c][add.a] = num;
315         F[num++] = add;
316     }
317
318     for (int i = 4; i < n; ++i) {
319         for (int j = 0; j < num; ++j) {

```

```

320         if (F[j].ok && cmp(P[i], F[j]) > eps) {
321             dfs(i, j);
322             break;
323         }
324     }
325 }
326
327 int tmp = num;
328 num = 0;
329 for (int i = 0; i < tmp; ++i) if (F[i].ok) {
330     F[num++] = F[i];
331 }
332 }
333
334 // 三维凸包表面积 (POJ3528)
335 double area() {
336     if (n == 3) return det(P[0], P[1], P[2]).length() / 2;
337
338     double res = 0;
339     for (int i = 0; i < num; ++i)
340         res += triArea(P[F[i].a], P[F[i].b], P[F[i].c]);
341     return res;
342 }
343
344 // 三维凸包体积
345 double volume() {
346     double res = 0;
347     point3 tmp(0, 0, 0);
348     for (int i = 0; i < num; ++i)
349         res += QuadVolume(tmp, P[F[i].a], P[F[i].b], P[F[i].c]);
350     return fabs(res);
351 }
352
353 // 表面三角形个数
354 double getTriangleCount() {
355     return num;
356 }
357
358 // 表面多边形个数 (HDU3662)
359 int getPolygonCount() {
360     int res = 0;
361     for (int i = 0; i < num; ++i) {
362         bool flag = true;
363         for (int j = 0; j < i; ++j) {
364             if (same(i, j)) {
365                 flag = 0;
366                 break;
367             }
368         }
369         res += flag;
370     }
371     return res;
372 }
373
374 // 重心 (HDU4273)
375 point3 getBaryCenter() {
376     point3 ans(0, 0, 0);
377     point3 o(0, 0, 0);
378
379     double all = 0;
380     for (int i = 0; i < num; ++i) {
381         double v = QuadVolume6(o, P[F[i].a], P[F[i].b], P[F[i].c]);
382         ans = ans + (((o + P[F[i].a] + P[F[i].b] + P[F[i].c]) / 4) * v);
383         all += v;
384     }

```

```

385         ans = ans / all;
386         return ans;
387     }
388
389     // 点到凸包第 i 个面上的距离
390     double PointToFace(point3 p, int i) {
391         double v1 = fabs(QuadVolume6(P[F[i].a], P[F[i].b], P[F[i].c], p));
392         double v2 = det(P[F[i].a], P[F[i].b], P[F[i].c]).length();
393         return v1 / v2;
394     }
395 };
396 }
397 using namespace Geometry3;

```

3.3 BigInt

```

1 // Source: https://github.com/Baobaobear/MiniBigInteger/blob/main/bigint\_tiny.h
2 // Author: https://github.com/Baobaobear
3 struct BigInt
4 {
5     int sign;
6     std::vector< int > v;
7
8     BigInt() : sign( 1 )
9     {
10     }
11     BigInt( const std::string &s )
12     {
13         *this = s;
14     }
15     BigInt( int v )
16     {
17         char buf[ 21 ];
18         sprintf( buf, "%d", v );
19         *this = buf;
20     }
21     void zip( int unzip )
22     {
23         if ( unzip == 0 )
24         {
25             for ( int i = 0; i < ( int ) v.size(); i++ )
26                 v[ i ] = get_pos( i * 4 ) + get_pos( i * 4 + 1 ) * 10 + get_pos( i * 4 + 2 ) * 100 +
27                     get_pos( i * 4 + 3 ) * 1000;
28         }
29         else
30             for ( int i = ( v.resize( v.size() * 4 ), ( int ) v.size() - 1 ), a; i >= 0; i-- )
31                 a = ( i % 4 >= 2 ) ? v[ i / 4 ] / 100 : v[ i / 4 ] % 100,
32                 v[ i ] = ( i & 1 ) ? a / 10 : a % 10;
33         setsign( 1, 1 );
34     }
35     int get_pos( unsigned pos ) const
36     {
37         return pos >= v.size() ? 0 : v[ pos ];
38     }
39     BigInt &setsign( int newsign, int rev )
40     {
41         for ( int i = ( int ) v.size() - 1; i > 0 && v[ i ] == 0; i-- )
42             v.erase( v.begin() + i );
43         sign = ( v.size() == 0 || ( v.size() == 1 && v[ 0 ] == 0 ) )
44             ? 1
45             : ( rev ? newsign * sign : newsign );
46         return *this;
47     }
48     std::string to_str() const

```

```

49     {
50         BigInt      b = *this;
51         std::string s;
52         for ( int i = ( b.zip( 1 ), 0 ); i < ( int ) b.v.size(); ++i )
53             s += char( *( b.v.rbegin() + i ) + '0' );
54         return ( sign < 0 ? "-" : "" ) + ( s.empty() ? std::string( "0" ) : s );
55     }
56     bool absless( const BigInt &b ) const
57     {
58         if ( v.size() != b.v.size() )
59             return v.size() < b.v.size();
60         for ( int i = ( int ) v.size() - 1; i >= 0; i-- )
61             if ( v[ i ] != b.v[ i ] )
62                 return v[ i ] < b.v[ i ];
63         return false;
64     }
65     BigInt operator-() const
66     {
67         BigInt c = *this;
68         c.sign = ( v.size() > 1 || v[ 0 ] ) ? -c.sign : 1;
69         return c;
70     }
71     BigInt &operator=( const std::string &s )
72     {
73         if ( s[ 0 ] == '-' )
74             *this = s.substr( 1 );
75         else
76         {
77             for ( int i = ( v.clear(), 0 ); i < ( int ) s.size(); ++i )
78                 v.push_back( *( s.rbegin() + i ) - '0' );
79             zip( 0 );
80         }
81         return setsign( s[ 0 ] == '-' ? -1 : 1, sign = 1 );
82     }
83     bool operator<( const BigInt &b ) const
84     {
85         return sign != b.sign ? sign < b.sign : ( sign == 1 ? absless( b ) : !absless( b ) );
86     }
87     bool operator==( const BigInt &b ) const
88     {
89         return v == b.v && sign == b.sign;
90     }
91     BigInt &operator+=( const BigInt &b )
92     {
93         if ( sign != b.sign )
94             return *this = ( *this ) - -b;
95         v.resize( std::max( v.size(), b.v.size() ) + 1 );
96         for ( int i = 0, carry = 0; i < ( int ) b.v.size() || carry; i++ )
97         {
98             carry += v[ i ] + b.get_pos( i );
99             v[ i ] = carry % 10000, carry /= 10000;
100         }
101         return setsign( sign, 0 );
102     }
103     BigInt operator+( const BigInt &b ) const
104     {
105         BigInt c = *this;
106         return c += b;
107     }
108     void add_mul( const BigInt &b, int mul )
109     {
110         v.resize( std::max( v.size(), b.v.size() ) + 2 );
111         for ( int i = 0, carry = 0; i < ( int ) b.v.size() || carry; i++ )
112         {
113             carry += v[ i ] + b.get_pos( i ) * mul;

```

```

114         v[ i ] = carry % 10000, carry /= 10000;
115     }
116 }
117 BigInt operator-( const BigInt &b ) const
118 {
119     if ( sign != b.sign )
120         return ( *this ) + -b;
121     if ( absless( b ) )
122         return -( b - *this );
123     BigInt c;
124     for ( int i = 0, borrow = 0; i < ( int ) v.size(); i++ )
125     {
126         borrow += v[ i ] - b.get_pos( i );
127         c.v.push_back( borrow );
128         c.v.back() -= 10000 * ( borrow >= 31 );
129     }
130     return c.setsign( sign, 0 );
131 }
132 BigInt operator*( const BigInt &b ) const
133 {
134     if ( b < *this )
135         return b * *this;
136     BigInt c, d = b;
137     for ( int i = 0; i < ( int ) v.size(); i++, d.v.insert( d.v.begin(), 0 ) )
138         c.add_mul( d, v[ i ] );
139     return c.setsign( sign * b.sign, 0 );
140 }
141 BigInt operator/( const BigInt &b ) const
142 {
143     BigInt c, d;
144     d.v.resize( v.size() );
145     double db = 1.0 / ( b.v.back() + ( b.get_pos( ( unsigned ) b.v.size() - 2 ) / 1e4 ) +
146                       ( b.get_pos( ( unsigned ) b.v.size() - 3 ) + 1 ) / 1e8 );
147     for ( int i = ( int ) v.size() - 1; i >= 0; i-- )
148     {
149         c.v.insert( c.v.begin(), v[ i ] );
150         int m = ( int ) ( ( c.get_pos( ( int ) b.v.size() ) * 10000 +
151                           c.get_pos( ( int ) b.v.size() - 1 ) ) *
152                         db );
153         c = c - b * m, d.v[ i ] += m;
154         while ( !( c < b ) )
155             c = c - b, d.v[ i ] += 1;
156     }
157     return d.setsign( sign * b.sign, 0 );
158 }
159 BigInt operator%( const BigInt &b ) const
160 {
161     return *this - *this / b * b;
162 }
163 bool operator>( const BigInt &b ) const
164 {
165     return b < *this;
166 }
167 bool operator<=( const BigInt &b ) const
168 {
169     return !( b < *this );
170 }
171 bool operator>=( const BigInt &b ) const
172 {
173     return !( *this < b );
174 }
175 bool operator!=( const BigInt &b ) const
176 {
177     return !( *this == b );
178 }

```

179 };

3.4 BSGS

```

1 namespace Backlight {
2
3 namespace BSGS {
4     typedef long long ll;
5
6     ll exgcd(ll a, ll b, ll& x, ll& y) {
7         if (b == 0) {
8             x = 1; y = 0;
9             return a;
10        }
11        ll d = exgcd(b, a % b, x, y);
12        ll z = x; x = y; y = z - y * (a / b);
13        return d;
14    }
15
16    ll qpow(ll a, ll n, ll p) {
17        ll ans = 1;
18        for (; n; n >>= 1) {
19            if (n & 1) ans = ans * a % p;
20            a = a * a % p;
21        }
22        return ans;
23    }
24
25    // solve  $a^x = b \pmod p$ ,  $p$  is a prime must hold
26    ll BSGS(ll a, ll b, ll p) {
27        unordered_map<ll, int> mp;
28        if (__gcd(a, p) != 1) return -1;
29        if (b % p == 1) return 0;
30        a %= p; b %= p;
31        ll k = sqrt(p), t = qpow(a, k, p), s = b;
32        for(int i = 0; i <= k; i++, s = s * a % p) mp[s] = i;
33        s = 1;
34        for(int i = 0; i <= k; i++, s = s * t % p) {
35            int ans = mp.count(s) ? mp[s] : -1;
36            if (ans != -1 && i * k - ans >= 0) return i * k - ans;
37        }
38        return -1;
39    }
40
41    // solve  $a^x = b \pmod p$ ,  $p$  don't need to be a prime
42    ll EXBSGS(ll a, ll b, ll p) {
43        ll k = 0, d, c = 1, x, y;
44        a %= p; b %= p;
45        if (a == b) return 1;
46        if (b == 1) return 0;
47        while ((d = __gcd(a, p)) != 1) {
48            if (b % d) return -1;
49            k++; b /= d; p /= d; c = c * (a / d) % p;
50            if (c == b) return k;
51        }
52        if (p == 1) return k;
53        exgcd(c, p, x, y); b = (b * x % p + p) % p; a %= p;
54        ll ans = BSGS(a, b, p);
55        return ans == -1 ? ans : ans + k;
56    }
57 }
58
59 }

```

3.5 Cipolla

```

1 namespace Backlight {
2
3 namespace Cipolla {
4     mt19937 rnd(chrono::steady_clock::now().time_since_epoch().count());
5     ll W, P;
6     struct complex {
7         ll r, i;
8         complex(ll _r, ll _i) : r(_r), i(_i) {}
9         inline complex operator * (const complex& c) const { return complex((r * c.r % P + i * c.i % P * W) % P, (r * c.i % P - i * c.r % P * W) % P); }
10 };
11
12 inline complex pow(complex a, int b) {
13     complex res(1, 0);
14     while(b) {
15         if (b & 1) res = res * a;
16         a = a * a;
17         b >>= 1;
18     }
19     return res;
20 }
21
22 inline ll pow(ll a, ll b, ll p) {
23     ll res = 1;
24     while(b) {
25         if (b & 1) res = res * a % p;
26         a = a * a % p;
27         b >>= 1;
28     }
29     return res;
30 }
31
32 // solve x for x^2 = a (mod p)
33 ll solve(ll a, ll p) {
34     P = p; a %= p;
35     if (a == 0) return 0;
36
37     ll t = pow(a, (p - 1) / 2, p);
38     if (t != 1) return -1;
39     while(true) {
40         t = rnd() % p;
41         ll c = (t * t % p + p - a) % p;
42         if (pow(c, (p - 1) / 2, p) == p - 1) break;
43     }
44
45     W = (t * t % p + p - a) % p;
46     ll x = pow(complex(t, 1), (p + 1) / 2).r;
47     return x;
48 }
49 } // namespace Cipolla
50 } // namespace Backlight

```

3.6 Combination

```

1 struct Combination {
2     int N;
3     vector<Mint> f, g;
4
5     Combination() : N(0) {}
6     Combination(int _n) : N(_n), f(N + 1), g(N + 1) {}

```



```

7         f[0] = 1;
8         for (int i = 1; i <= N; ++i) f[i] = f[i - 1] * i;
9         g[N] = f[N].inv();
10        for (int i = N - 1; i >= 0; --i) g[i] = g[i + 1] * (i + 1);
11    }
12
13    Mint get(int n, int m) {
14        if (n < 0 || m < 0 || n < m) return 0;
15        return f[n] * g[m] * g[n - m];
16    }
17 } C(N);

```

3.7 CRT

```

1 namespace Backlight {
2
3 // get x, y for ax + by = GCD(a, b)
4 ll exgcd(ll a, ll b, ll& x, ll& y) {
5     if (b == 0) {
6         x = 1; y = 0;
7         return a;
8     }
9     ll d = exgcd(b, a % b, x, y);
10    ll z = x; x = y; y = z - y * (a / b);
11    return d;
12 }
13
14
15
16 // CRT: solve x = a_i (mod m_i) for i in [0, n)
17
18 // GCD(m_i, m_j) = 1 hold
19 ll CRT(vector<ll>& a, vector<ll>& m) {
20     assert(a.size() == m.size());
21     assert(a.size() > 0);
22     int n = a.size();
23     ll M = 1, res = 0;
24     for (int i = 0; i < n; ++i) M *= m[i];
25     ll _M, x, y;
26     for (int i = 0; i < n; ++i) {
27         _M = M / m[i];
28         exgcd(_M, m[i], x, y);
29         res = (res + a[i] * _M % M * x % M) % M;
30     }
31     if (res < 0) res += M;
32     return res;
33 }
34
35 ll mul(ll a, ll b, ll mod) {
36     ll res = 0;
37     while(b) {
38         if (b & 1) res = (res + a) % mod;
39         b >>= 1;
40         a = (a + a) % mod;
41     }
42     return res;
43 }
44
45 // GCD(m_i, m_j) = 1 not hold
46 ll EXCRT(vector<ll>& a, vector<ll>& m) {
47     assert(a.size() == m.size());
48     assert(a.size() > 0);
49     int n = a.size();
50     ll res = a[0], M = m[0], B, g, x, y;

```

```

51     for (int i = 1; i < n; ++i) {
52         B = ((a[i] - res) % m[i] + m[i]) % m[i];
53         g = exgcd(M, m[i], x, y);
54         x = mul(x, B / g, m[i]);
55         res += M * x;
56         M *= m[i] / g;
57         res = (res + M) % M;
58     }
59     return res;
60 }
61
62
63 }

```

3.8 du

```

1  #include <bits/stdc++.h>
2  using namespace std;
3
4  using ll = int64_t;
5
6  const int LIM = 1e7;
7
8  int pcnt, prime[ LIM ], mu[ LIM ];
9  bool vis[ LIM ];
10 void seive( int n )
11 {
12     pcnt = 0;
13     mu[ 0 ] = 0;
14     mu[ 1 ] = 1;
15     for ( int i = 2; i <= n; ++i )
16     {
17         if ( !vis[ i ] )
18         {
19             prime[ ++pcnt ] = i;
20             mu[ i ] = -1;
21         }
22         for ( int j = 1; j <= pcnt; ++j )
23         {
24             ll nxt = 1ll * i * prime[ j ];
25             if ( nxt > n )
26                 break;
27             vis[ nxt ] = true;
28             if ( i % prime[ j ] == 0 )
29             {
30                 mu[ nxt ] = 0;
31                 break;
32             }
33             mu[ nxt ] = -mu[ i ];
34         }
35     }
36     for ( int i = 1; i <= n; ++i )
37         mu[ i ] += mu[ i - 1 ];
38 }
39
40 map< ll, ll > mp;
41
42 //  $S(n) = 1 - \sum_{i=2}^n S(\lfloor \frac{n}{i} \rfloor)$ 
43 // Time Complexity:  $O(n^{\frac{2}{3}})$ 
44 ll S_mu( ll n )
45 {
46     if ( n < LIM )
47         return mu[ n ];

```

```

48     if ( mp.count( n ) )
49         return mp[ n ];
50
51     ll ret = 0;
52     for ( ll i = 2, j; i <= n; i = j + 1 )
53     {
54         j = n / ( n / i );
55         ret += ( j - i + 1 ) * S_mu( n / i );
56     }
57     ret = 1 - ret;
58
59     mp[ n ] = ret;
60     return ret;
61 }
62
63 //  $S(n) = \frac{(n+1)n}{2} - \sum_{i=2}^n S(\lfloor \frac{n}{i} \rfloor)$ 
64 //  $S(n) = \sum_{d=1}^n \mu(d) \lfloor \frac{n}{d} \rfloor \lfloor \frac{n}{d} \rfloor$ 
65 ll S_phi( ll n )
66 {
67     ll ret = 0;
68     for ( ll i = 1, j; i <= n; i = j + 1 )
69     {
70         j = n / ( n / i );
71         ret += ( S_mu( j ) - S_mu( i - 1 ) ) * ( n / i ) * ( n / i );
72     }
73     ret = ( ret - 1 ) / 2 + 1;
74     return ret;
75 }
76
77 void solve( int Case )
78 {
79     ll n;
80     scanf( "%lld", &n );
81     printf( "%lld %lld\n", S_phi( n ), S_mu( n ) );
82 }
83
84 int main()
85 {
86     seive( LIM - 1 );
87     int T = 1;
88     scanf( "%d", &T );
89     for ( int _ = 1; _ <= T; _++ )
90         solve( _ );
91     return 0;
92 }

```

3.9 EulerSeive

```

1 namespace Backlight {
2
3 vector<int> euler_seive(int n) {
4     vector<int> primes;
5     vector<bool> is(n + 1, 1);
6
7     for (int i = 2; i <= n; ++i) {
8         if (is[i]) primes.push_back(i);
9         for (int j = 0; j < (int)primes.size(); ++j) {
10             ll nxt = 1ll * primes[j] * i;
11             if (nxt > n) break;
12             is[nxt] = false;
13             if (i % primes[j] == 0) break;
14         }
15     }
16     return primes;

```

```

17 }
18
19 }

```

3.10 eval

```

1  int pri(char c)
2  {
3      if (c == '^') return 3;
4      if (c == '*' || c == '/') return 2;
5      if (c == '+' || c == '-') return 1;
6      return 0;
7  }
8
9  void in2post(char *s, char *t)
10 {
11     int n = strlen(s), j = 0;
12     stack<char> ops;
13     for (int i = 0; i < n; ++i) {
14         t[j] = 0;
15         if (islower(s[i])) {
16             while(i < n && isdigit(s[i])) {
17                 t[j++] = s[i++];
18             }
19             t[j++] = ' ';
20             --i;
21         } else if (s[i] == '(') {
22             ops.push('(');
23         } else if (s[i] == ')') {
24             char op = 0;
25             while(!ops.empty()) {
26                 op = ops.top();
27                 ops.pop();
28                 if (op == '(') break;
29                 t[j++] = op;
30                 t[j++] = ' ';
31             }
32             assert(op == '(');
33         } else {
34             while(!ops.empty() && pri(s[i]) <= pri(ops.top())) {
35                 t[j++] = ops.top();
36                 t[j++] = ' ';
37                 ops.pop();
38             }
39             ops.push(s[i]);
40         }
41     }
42     while(!ops.empty()) {
43         assert(ops.top() != '(');
44         t[j++] = ops.top();
45         t[j++] = ' ';
46         ops.pop();
47     }
48     t[j] = 0;
49 }
50
51 int eval(char* s)
52 {
53     int n = strlen(s);
54     stack<int> nums;
55     for (int i = 0; i < n; ++i) {
56         if (isdigit(s[i])) {
57             int num = 0;
58             while(i < n && isdigit(s[i])) {

```

```

59         num = num * 10 + s[i++] - '0';
60     }
61     nums.push(num);
62     --i;
63     continue;
64 }
65
66 if (s[i] == ' ') continue;
67
68 assert(nums.size() >= 2);
69 int num2 = nums.top();
70 nums.pop();
71 int num1 = nums.top();
72 nums.pop();
73 switch(s[i]) {
74     case '+':
75         nums.push(num1 + num2);
76         break;
77     case '-':
78         nums.push(num1 - num2);
79         break;
80     case '*':
81         nums.push(num1 * num2);
82         break;
83     case '/':
84         nums.push(num1 / num2);
85         break;
86     default:
87         assert(false);
88         break;
89 }
90 }
91 assert(nums.size() == 1);
92 return nums.top();
93 }

```

3.11 EXGCD

```

1 namespace Backlight {
2
3 // get x_0, y_0 for ax + by = GCD(a, b)
4 // x = x_0 + bt
5 // y = y_0 - at
6 // for all interger t
7 #define EXGCD
8 ll exgcd(ll a, ll b, ll& x, ll& y) {
9     if (b == 0) {
10         x = 1; y = 0;
11         return a;
12     }
13     ll d = exgcd(b, a % b, x, y);
14     ll z = x; x = y; y = z - y * (a / b);
15     return d;
16 }
17
18 }

```

3.12 FFT

```

1 namespace FFT {
2     const long double PI = acos(-1.0);
3     using LL = int64_t;

```

```

4  struct Complex {
5      long double r, i;
6      Complex() : r(0), i(0) {}
7      Complex(long double _r, long double _i) : r(_r), i(_i) {}
8      Complex conj() { return Complex(r, -i); }
9      inline Complex operator-(const Complex &c) const { return Complex(r - c.r, i - c.i); }
10     inline Complex operator+(const Complex &c) const { return Complex(r + c.r, i + c.i); }
11     inline Complex operator*(const Complex &c) const { return Complex(r * c.r - i * c.i, r * c.i + i * c.r); }
12 };
13 ostream& operator << (ostream& os, Complex& c) { return os << "(" << c.r << ", " << c.i << ")"; }
14
15 int N;
16 vector<int> r;
17 void init(int n) {
18     N = 1; while(N <= n) N <<= 1;
19     r.resize(N);
20     for(int i = 1; i < N; ++i) r[i] = (r[i >> 1] >> 1) + ((i & 1) ? (N >> 1) : 0);
21 }
22
23 void FFT(vector<Complex>& a, int op) {
24     for (int i = 1; i < N; ++i) if (i < r[i]) swap(a[i], a[r[i]]);
25     for(int i = 2; i <= N; i <<= 1){
26         int l = i >> 1;
27         Complex w, x, wk(cos(PI / l), op * sin(PI / l));
28         for(int j = 0; j < N; j += i) {
29             w = Complex(1, 0);
30             for(int k = j; k < j + l; ++k) {
31                 x = a[k + 1] * w;
32                 a[k + 1] = a[k] - x;
33                 a[k] = a[k] + x;
34                 w = w * wk;
35             }
36         }
37     }
38     if(op == -1)
39         for(int i = 0; i < N; ++i) a[i].r /= N, a[i].i /= N;
40 }
41
42 inline void FFT(vector<Complex>& a) { FFT(a, 1); }
43 inline void IFT(vector<Complex>& a) { FFT(a, -1); }
44
45 vector<int> convolution(const vector<int>& f, const vector<int>& g) {
46     int n = f.size(), m = g.size(), k = n + m - 1;
47     init(k);
48     vector<Complex> a(N), b(N);
49     for (int i = 0; i < n; ++i) a[i] = Complex(f[i], 0);
50     for (int i = 0; i < m; ++i) b[i] = Complex(g[i], 0);
51
52     FFT(a); FFT(b);
53     for (int i = 0; i < N; ++i) a[i] = a[i] * b[i];
54     IFT(a);
55
56     vector<int> h(k);
57     for (int i = 0; i < k; ++i) h[i] = int(a[i].r + 0.5);
58     return h;
59 }
60
61 // 任意模数 FFT
62 vector<int> convolutionM(const vector<int>& f, const vector<int>& g, int p) {
63     int n = f.size(), m = g.size(), k = n + m - 1;
64     init(k);
65     vector<Complex> a(N), b(N), c(N), d(N);
66     for (int i = 0; i < n; ++i) a[i] = Complex(f[i] >> 15, f[i] & 32767);
67     for (int i = 0; i < m; ++i) c[i] = Complex(g[i] >> 15, g[i] & 32767);
68     FFT(a); FFT(c);

```

```

69     for (int i = 1; i < N; ++i) b[i] = a[N - i].conj();
70     for (int i = 1; i < N; ++i) d[i] = c[N - i].conj();
71     b[0] = a[0].conj(); d[0] = c[0].conj();
72     for (int i = 0; i < N; ++i) {
73         Complex aa, bb, cc, dd;
74         aa = (a[i] + b[i]) * Complex(0.5, 0);
75         bb = (a[i] - b[i]) * Complex(0, -0.5);
76         cc = (c[i] + d[i]) * Complex(0.5, 0);
77         dd = (c[i] - d[i]) * Complex(0, -0.5);
78         a[i] = aa * cc + Complex(0, 1) * (aa * dd + bb * cc);
79         b[i] = bb * dd;
80     }
81     IFT(a); IFT(b);
82     vector<int> h(k);
83     for (int i = 0; i < k; ++i) {
84         int aa, bb, cc;
85         aa = LL(a[i].r + 0.5) % p;
86         bb = LL(a[i].i + 0.5) % p;
87         cc = LL(b[i].r + 0.5) % p;
88         h[i] = ((1ll * aa * (1 << 30) % p + 1ll * bb * (1 << 15) % p + cc) % p + p) % p;
89     }
90     return h;
91 }
92 } // namespace FFT

```

3.13 FWT

```

1  #include <bits/stdc++.h>
2  using namespace std;
3
4  const int MOD = 998244353;
5
6  inline int add( int x, int y )
7  {
8      return x + y >= MOD ? x + y - MOD : x + y;
9  }
10 inline int mul( int x, int y )
11 {
12     return 1ll * x * y % MOD;
13 }
14 inline int sub( int x, int y )
15 {
16     return x - y < 0 ? x - y + MOD : x - y;
17 }
18 inline int qp( int x, int y )
19 {
20     int r = 1;
21     for ( ; y; y >>= 1 )
22     {
23         if ( y & 1 )
24             r = mul( r, x );
25         x = mul( x, x );
26     }
27     return r;
28 }
29 inline int inv( int x )
30 {
31     return qp( x, MOD - 2 );
32 }
33 inline int dvd( int x, int y )
34 {
35     return 1ll * x * qp( y, MOD - 2 ) % MOD;
36 }
37

```

```

38 namespace FWT
39 {
40     void OR( int* a, int n )
41     {
42         for ( int o = 2, k = 1; o <= n; o <<= 1, k <<= 1 )
43             for ( int i = 0; i < n; i += o )
44                 for ( int j = 0; j < k; ++j )
45                     a[ i + j + k ] = add( a[ i + j + k ], a[ i + j ] );
46     }
47
48     void IOR( int* a, int n )
49     {
50         for ( int o = 2, k = 1; o <= n; o <<= 1, k <<= 1 )
51             for ( int i = 0; i < n; i += o )
52                 for ( int j = 0; j < k; ++j )
53                     a[ i + j + k ] = sub( a[ i + j + k ], a[ i + j ] );
54     }
55
56     void AND( int* a, int n )
57     {
58         for ( int o = 2, k = 1; o <= n; o <<= 1, k <<= 1 )
59             for ( int i = 0; i < n; i += o )
60                 for ( int j = 0; j < k; ++j )
61                     a[ i + j ] = add( a[ i + j ], a[ i + j + k ] );
62     }
63
64     void IAND( int* a, int n )
65     {
66         for ( int o = 2, k = 1; o <= n; o <<= 1, k <<= 1 )
67             for ( int i = 0; i < n; i += o )
68                 for ( int j = 0; j < k; ++j )
69                     a[ i + j ] = sub( a[ i + j ], a[ i + j + k ] );
70     }
71
72     void XOR( int* a, int n )
73     {
74         int x, y;
75         for ( int o = 2, k = 1; o <= n; o <<= 1, k <<= 1 )
76             for ( int i = 0; i < n; i += o )
77                 for ( int j = 0; j < k; ++j )
78                 {
79                     x = a[ i + j ], y = a[ i + j + k ];
80                     a[ i + j ] = add( x, y );
81                     a[ i + j + k ] = sub( x, y );
82                 }
83     }
84
85     int inv2 = inv( 2 );
86     void IXOR( int* a, int n )
87     {
88         int x, y;
89         for ( int o = 2, k = 1; o <= n; o <<= 1, k <<= 1 )
90             for ( int i = 0; i < n; i += o )
91                 for ( int j = 0; j < k; ++j )
92                 {
93                     x = a[ i + j ], y = a[ i + j + k ];
94                     a[ i + j ] = mul( add( x, y ), inv2 );
95                     a[ i + j + k ] = mul( sub( x, y ), inv2 );
96                 }
97     }
98 } // namespace FWT
99
100 const int N = ( 1 << 17 ) + 5;
101
102 int n;

```



```

103 int A[ N ], B[ N ], a[ N ], b[ N ], c[N];
104
105 int main()
106 {
107     scanf( "%d", &n );
108     n = 1 << n;
109
110     int x;
111     for ( int i = 0; i < n; ++i )
112         scanf( "%d", &A[ i ] );
113     for ( int i = 0; i < n; ++i )
114         scanf( "%d", &B[ i ] );
115
116     // OR
117     for ( int i = 0; i < n; ++i )
118         a[ i ] = A[ i ], b[ i ] = B[ i ];
119     FWT::OR( a, n );
120     FWT::OR( b, n );
121     for ( int i = 0; i < n; ++i )
122         c[ i ] = mul( a[ i ], b[ i ] );
123     FWT::IOR( c, n );
124
125     for ( int i = 0; i < n - 1; ++i )
126         printf( "%d ", c[ i ] );
127     printf( "%d\n", c[ n - 1 ] );
128
129     // AND
130     for ( int i = 0; i < n; ++i )
131         a[ i ] = A[ i ], b[ i ] = B[ i ];
132     FWT::AND( a, n );
133     FWT::AND( b, n );
134     for ( int i = 0; i < n; ++i )
135         c[ i ] = mul( a[ i ], b[ i ] );
136     FWT::IAND( c, n );
137     for ( int i = 0; i < n - 1; ++i )
138         printf( "%d ", c[ i ] );
139     printf( "%d\n", c[ n - 1 ] );
140
141     // XOR
142     for ( int i = 0; i < n; ++i )
143         a[ i ] = A[ i ], b[ i ] = B[ i ];
144     FWT::XOR( a, n );
145     FWT::XOR( b, n );
146     for ( int i = 0; i < n; ++i )
147         c[ i ] = mul( a[ i ], b[ i ] );
148     FWT::IXOR( c, n );
149     for ( int i = 0; i < n - 1; ++i )
150         printf( "%d ", c[ i ] );
151     printf( "%d\n", c[ n - 1 ] );
152     return 0;
153 }

```

3.14 LinearBasis

```

1 struct LinearBasis {
2     static const int B = 62;
3     ll b[B];
4     int tot, n;
5
6     LinearBasis() {
7         tot = 0; n = 0;
8         memset(b, 0, sizeof(b));
9     }
10

```

```
11 bool insert(ll x) {
12     ++n;
13     for (int i = B - 1; i >= 0; --i) {
14         if (!(x >> i)) continue;
15         if (!b[i]) {
16             ++tot;
17             b[i] = x;
18             break;
19         }
20         x ^= b[i];
21     }
22     return x > 0;
23 }
24
25 bool query(ll x) {
26     for (int i = B - 1; i >= 0; --i) {
27         if (!(x >> i)) continue;
28         if (!b[i]) return false;
29         x ^= b[i];
30     }
31     return x == 0;
32 }
33
34 ll queryMax() {
35     ll res = 0;
36     for (int i = B - 1; i >= 0; --i) {
37         if ((res ^ b[i]) > res) res ^= b[i];
38     }
39     return res;
40 }
41
42 ll queryMin() {
43     for (int i = 0; i < B; ++i) if (b[i]) return b[i];
44     return -1;
45 }
46
47 ll count() {
48     return 1LL << tot;
49 }
50
51 void rebuild() {
52     for (int i = B - 1; i >= 0; --i) {
53         for (int j = i - 1; j >= 0; --j) {
54             if (b[i] & (1LL << j))
55                 b[i] ^= b[j];
56         }
57     }
58 }
59
60 // need rebuild first
61 ll queryKth(int k) {
62     if (k == 1 && tot < n) return 0;
63     if (tot < n) --k;
64     if (k > (1LL << tot) - 1) return -1;
65     ll res = 0;
66     for (int i = 0; i < B; ++i) {
67         if (b[i]) {
68             if (k & 1) res ^= b[i];
69             k >>= 1;
70         }
71     }
72     return res;
73 }
74 };
```

3.15 Lucas

```

1 namespace Backlight {
2
3 // use this when n, m is really large and p is small
4 namespace Lucas {
5     inline ll pow(ll a, ll b, ll p) {
6         ll res = 1;
7         a %= p;
8         while(b) {
9             if (b & 1) res = res * a % p;
10            a = a * a % p;
11            b >>= 1;
12        }
13        return res;
14    }
15
16    inline ll inv1(ll n, ll p) { return pow(n, p - 2, p); }
17
18    inline ll C1(ll n, ll m, ll p) {
19        if (m > n) return 0;
20        if (m > n - m) m = n - m;
21        ll u = 1, d = 1;
22        for (ll i = 1; i <= m; ++i) {
23            u = u * (n - i + 1) % p;
24            d = d * i % p;
25        }
26        return u * inv1(d, p) % p;
27    }
28
29 // solve n choose m (mod p) while p is a prime
30 ll lucas(ll n, ll m, ll p) {
31     if (m == 0) return 1;
32     return C1(n % p, m % p, p) * lucas(n / p, m / p, p) % p;
33 }
34
35
36 ll exgcd(ll a, ll b, ll& x, ll& y) {
37     if (b == 0) {
38         x = 1; y = 0;
39         return a;
40     }
41     ll d = exgcd(b, a % b, x, y);
42     ll z = x; x = y; y = z - y * (a / b);
43     return d;
44 }
45
46 inline ll inv2(ll n, ll p) {
47     ll x, y;
48     ll d = exgcd(n, p, x, y);
49     return d == 1 ? (p + x % p) % p : -1;
50 }
51
52 // n! mod pk without pi^x
53 ll f(ll n, ll pi, ll pk) {
54     if (!n) return 1;
55     ll res = 1;
56     if (n / pk) {
57         for (ll i = 2; i <= pk; ++i)
58             if (i % pi) res = res * i % pk;
59         res = pow(res, n / pk, pk);
60     }
61     for (ll i = 2; i <= n % pk; ++i)
62         if (i % pi) res = res * i % pk;
63     return res * f(n / pi, pi, pk) % pk;

```

```

64     }
65
66     ll C2(ll n, ll m, ll p, ll pi, ll pk) {
67         if (m > n) return 0;
68         ll a = f(n, pi, pk), b = f(m, pi, pk), c = f(n - m, pi, pk);
69         ll k = 0;
70         for (ll i = n; i; i /= pi) k += i / pi;
71         for (ll i = m; i; i /= pi) k -= i / pi;
72         for (ll i = n - m; i; i /= pi) k -= i / pi;
73         ll ans = a * inv2(b, pk) % pk * inv2(c, pk) % pk * pow(pi, k, pk) % pk;
74         ans = ans * (p / pk) % p * inv2(p / pk, pk) % p;
75         return ans;
76     }
77
78     // solve n choose m (mod p) while p might not be a prime
79     ll exlucas(ll n, ll m, ll p) {
80         ll x = p;
81         ll ans = 0;
82         for (ll i = 2; i <= p; ++i) {
83             if (x % i == 0) {
84                 ll pk = 1;
85                 while(x % i == 0) pk *= i, x /= i;
86                 ans = (ans + C2(n, m, p, i, pk)) % p;
87             }
88         }
89         return ans;
90     }
91 } // namespace Lucas
92
93
94 } // namespace Backlight

```

3.16 min25

```

1  #include <bits/stdc++.h>
2
3  using namespace std;
4  using ll = int64_t;
5
6  const int MOD = 1e9 + 7;
7
8  template < typename T >
9  inline int mint( T x )
10 {
11     x %= MOD;
12     if ( x < 0 )
13         x += MOD;
14     return x;
15 }
16 inline int add( int x, int y )
17 {
18     return x + y >= MOD ? x + y - MOD : x + y;
19 }
20 inline int mul( int x, int y )
21 {
22     return 1ll * x * y % MOD;
23 }
24 inline int sub( int x, int y )
25 {
26     return x < y ? x - y + MOD : x - y;
27 }
28 inline int qp( int x, int y )
29 {
30     int r = 1;

```

```

31     for ( ; y; y >>= 1 )
32     {
33         if ( y & 1 )
34             r = mul( r, x );
35         x = mul( x, x );
36     }
37     return r;
38 }
39 inline int inv( int x )
40 {
41     return qp( x, MOD - 2 );
42 }
43 inline int dvd( int x, int y )
44 {
45     return 1ll * x * qp( y, MOD - 2 ) % MOD;
46 }
47 inline void inc( int &x, int y )
48 {
49     x += y;
50     if ( x >= MOD )
51         x -= MOD;
52 }
53 inline void dec( int &x, int y )
54 {
55     x -= y;
56     if ( x < 0 )
57         x += MOD;
58 }
59
60 namespace min25
61 {
62     /*
63     calc the prefix sum of multiplicative function.
64     Requirements:
65         Assume p is a prime number.
66         1. f(p) is a polygon with small deg or can be calc quickly.
67         2. f(p^e) can be calc quickly.
68     Time complexity:  $O(\frac{n^{0.75}}{\log n})$ 
69     Steps: assume  $\deg(f(p)) = n$ .
70         1. split f(p) into n parts.
71         2. calc them separately.
72         3. then sum them up.
73     e.g.:  $f(p) = \phi(p) = p - 1$ 
74         1. calc ans0 for f(p) = p.
75         2. calc ans1 for f(p) = 1.
76         3. ans = ans0 - ans1.
77     */
78     const int LIM = 2e5 + 9;
79
80     ll gn, w[ LIM ];
81     int rt, lim, id1[ LIM ], id2[ LIM ];
82     #define idx( v ) ( v <= rt ? id1[ v ] : id2[ gn / v ] )
83
84     // inline int &idx( ll v )
85     // {
86     //     if ( v <= rt )
87     //         return id1[ v ];
88     //     return id2[ gn / v ];
89     // }
90
91     int pcnt, prime[ LIM ];
92     bool isp[ LIM ];
93
94     //  $sp_{i,j} = \sum_{k=1}^j [p \text{ is a prime}] p^i$ 
95     int sp1[ LIM ];

```

```

96
97 void seive( const int &n )
98 {
99     pcnt = 0;
100     fill(isp, isp + n + 1, true);
101     for ( int i = 2; i <= n; ++i )
102     {
103         if ( isp[ i ] )
104         {
105             ++pcnt;
106             prime[ pcnt ] = i;
107         }
108         for ( int j = 1; j <= pcnt; ++j )
109         {
110             ll nxt = 1ll * i * prime[ j ];
111             if ( nxt > n )
112                 break;
113             isp[ nxt ] = false;
114             if ( i % prime[ j ] == 0 )
115                 break;
116         }
117     }
118     for ( int i = 1; i <= pcnt; ++i )
119         sp1[ i ] = add( sp1[ i - 1 ], prime[ i ] );
120 }
121
122 int G[ LIM ][ 2 ], H[ LIM ];
123
124 void initG0( const ll &n )
125 {
126     lim = 0;
127     int inv2 = inv( 2 );
128     for ( ll i = 1, j, v; i <= n; i = n / j + 1 )
129     {
130         j = n / i;
131
132         w[ ++lim ] = j;
133         idx( j ) = lim;
134
135         v = j % MOD;
136
137         // init  $G_0 = \sum_{i=2}^n g(i)$ 
138         G[ lim ][ 0 ] = sub( v, 1 );
139         G[ lim ][ 1 ] = mul( mul( mint( v + 2 ), mint( v - 1 ) ), inv2 );
140     }
141 }
142
143 void calCH()
144 {
145     for ( int k = 1; k <= pcnt; ++k )
146     {
147         const int p = prime[ k ];
148         const ll p2 = 1ll * p * p;
149         for ( int i = 1; w[ i ] >= p2; ++i )
150         {
151             const ll v = w[ i ] / p;
152             int id = idx( v );
153             dec( G[ i ][ 0 ], sub( G[ id ][ 0 ], k - 1 ) );
154             dec( G[ i ][ 1 ], mul( p, sub( G[ id ][ 1 ], sp1[ k - 1 ] ) ) );
155         }
156     }
157     for ( int i = 1; i <= lim; ++i )
158         H[ i ] = sub( G[ i ][ 1 ], G[ i ][ 0 ] );
159 }
160

```

```

161 //  $f(p^e)$ 
162 inline int fpe( const int &p, const int &e )
163 {
164     return p xor e ;
165 }
166
167 int F( const int &k, const ll &n )
168 {
169     if ( n < prime[ k ] || n <= 1 )
170         return 0;
171
172     int r1 = 0;
173     for ( int i = k; i <= pcnt; ++i )
174     {
175         ll pi = prime[ i ];
176         if ( 1ll * pi * pi > n )
177             break;
178         ll pc = pi, pc2 = pi * pi;
179         for ( int c = 1; pc2 <= n; ++c )
180         {
181             inc( r1, add( mul( fpe( pi, c ), F( i + 1, n / pc ) ), fpe( pi, c + 1 ) ) );
182             pc = pc2;
183             pc2 = pc2 * pi;
184         }
185     }
186
187     //  $H(n) - H(p_{k-1})$ 
188     const int id = idx( n );
189     int r2 = sub( H[ id ], sub( sp1[ k - 1 ], k - 1 ) );
190     if ( k == 1 )
191         inc( r2, 2 );
192     int ans = add( r1, r2 );
193     return ans;
194 }
195
196 int solve( ll n )
197 {
198     gn = n;
199     rt = sqrt( gn );
200     seive( rt + 5 );
201     initG0( gn );
202     calcH();
203     return add( F( 1, n ), 1 );
204 }
205 } // namespace min25
206
207 int main()
208 {
209     ll n;
210     scanf( "%lld", &n );
211     printf( "%d\n", min25::solve( n ) );
212     return 0;
213 }

```

3.17 Mint

```

1 // Author: tourist
2 template <typename T>
3 T inverse(T a, T m) {
4     T u = 0, v = 1;
5     while ( a != 0 ) {
6         T t = m / a;
7         m -= t * a; swap(a, m);
8         u -= t * v; swap(u, v);

```

```

9     }
10    assert(m == 1);
11    return u;
12 }
13
14 template <typename T>
15 class Modular {
16 public:
17     using Type = typename decay<decltype(T::value)>::type;
18
19     constexpr Modular() : value() {}
20     template <typename U>
21     Modular(const U& x) {
22         value = normalize(x);
23     }
24
25     template <typename U>
26     static Type normalize(const U& x) {
27         Type v;
28         if (-mod() <= x && x < mod()) v = static_cast<Type>(x);
29         else v = static_cast<Type>(x % mod());
30         if (v < 0) v += mod();
31         return v;
32     }
33
34     const Type& operator()() const { return value; }
35     template <typename U>
36     explicit operator U() const { return static_cast<U>(value); }
37     constexpr static Type mod() { return T::value; }
38
39     Modular& operator+=(const Modular& other) { if ((value += other.value) >= mod()) value -= mod(); return *this; }
40     Modular& operator-=(const Modular& other) { if ((value -= other.value) < 0) value += mod(); return *this; }
41     template <typename U> Modular& operator+=(const U& other) { return *this += Modular(other); }
42     template <typename U> Modular& operator-=(const U& other) { return *this -= Modular(other); }
43     Modular& operator++() { return *this += 1; }
44     Modular& operator--() { return *this -= 1; }
45     Modular operator++(int) { Modular result(*this); *this += 1; return result; }
46     Modular operator--(int) { Modular result(*this); *this -= 1; return result; }
47     Modular operator-() const { return Modular(-value); }
48
49     template <typename U = T>
50     typename enable_if<is_same<typename Modular<U>::Type, int>::value, Modular>::type& operator*=(const Modular& rhs) {
51 #ifdef _WIN32
52     uint64_t x = static_cast<int64_t>(value) * static_cast<int64_t>(rhs.value);
53     uint32_t xh = static_cast<uint32_t>(x >> 32), x1 = static_cast<uint32_t>(x), d, m;
54     asm(
55         "divl %4; \n\t"
56         : "=a" (d), "=d" (m)
57         : "d" (xh), "a" (x1), "r" (mod())
58     );
59     value = m;
60 #else
61     value = normalize(static_cast<int64_t>(value) * static_cast<int64_t>(rhs.value));
62 #endif
63     return *this;
64 }
65     template <typename U = T>
66     typename enable_if<is_same<typename Modular<U>::Type, long long>::value, Modular>::type& operator*=(const Modular& rhs) {
67         long long q = static_cast<long long>(static_cast<long double>(value) * rhs.value / mod());
68         value = normalize(value * rhs.value - q * mod());
69         return *this;
70     }
71     template <typename U = T>
72     typename enable_if<!is_integral<typename Modular<U>::Type>::value, Modular>::type& operator*=(const Modular& rhs) {
73         value = normalize(value * rhs.value);

```



```

74     return *this;
75 }
76
77 Modular& operator/=(const Modular& other) { return *this *= Modular(inverse(other.value, mod())); }
78
79 friend const Type& abs(const Modular& x) { return x.value; }
80
81 template <typename U>
82 friend bool operator==(const Modular<U>& lhs, const Modular<U>& rhs);
83
84 template <typename U>
85 friend bool operator<(const Modular<U>& lhs, const Modular<U>& rhs);
86
87 template <typename V, typename U>
88 friend V& operator>>(V& stream, Modular<U>& number);
89
90 private:
91     Type value;
92 };
93
94 template <typename T> bool operator==(const Modular<T>& lhs, const Modular<T>& rhs) { return lhs.value == rhs.value; }
95 template <typename T, typename U> bool operator==(const Modular<T>& lhs, U rhs) { return lhs == Modular<T>(rhs); }
96 template <typename T, typename U> bool operator==(U lhs, const Modular<T>& rhs) { return Modular<T>(lhs) == rhs; }
97
98 template <typename T> bool operator!=(const Modular<T>& lhs, const Modular<T>& rhs) { return !(lhs == rhs); }
99 template <typename T, typename U> bool operator!=(const Modular<T>& lhs, U rhs) { return !(lhs == rhs); }
100 template <typename T, typename U> bool operator!=(U lhs, const Modular<T>& rhs) { return !(lhs == rhs); }
101
102 template <typename T> bool operator<(const Modular<T>& lhs, const Modular<T>& rhs) { return lhs.value < rhs.value; }
103
104 template <typename T> Modular<T> operator+(const Modular<T>& lhs, const Modular<T>& rhs) { return Modular<T>(lhs) += rhs; }
105 template <typename T, typename U> Modular<T> operator+(const Modular<T>& lhs, U rhs) { return Modular<T>(lhs) += rhs; }
106 template <typename T, typename U> Modular<T> operator+(U lhs, const Modular<T>& rhs) { return Modular<T>(lhs) += rhs; }
107
108 template <typename T> Modular<T> operator-(const Modular<T>& lhs, const Modular<T>& rhs) { return Modular<T>(lhs) -= rhs; }
109 template <typename T, typename U> Modular<T> operator-(const Modular<T>& lhs, U rhs) { return Modular<T>(lhs) -= rhs; }
110 template <typename T, typename U> Modular<T> operator-(U lhs, const Modular<T>& rhs) { return Modular<T>(lhs) -= rhs; }
111
112 template <typename T> Modular<T> operator*(const Modular<T>& lhs, const Modular<T>& rhs) { return Modular<T>(lhs) *= rhs; }
113 template <typename T, typename U> Modular<T> operator*(const Modular<T>& lhs, U rhs) { return Modular<T>(lhs) *= rhs; }
114 template <typename T, typename U> Modular<T> operator*(U lhs, const Modular<T>& rhs) { return Modular<T>(lhs) *= rhs; }
115
116 template <typename T> Modular<T> operator/(const Modular<T>& lhs, const Modular<T>& rhs) { return Modular<T>(lhs) /= rhs; }
117 template <typename T, typename U> Modular<T> operator/(const Modular<T>& lhs, U rhs) { return Modular<T>(lhs) /= rhs; }
118 template <typename T, typename U> Modular<T> operator/(U lhs, const Modular<T>& rhs) { return Modular<T>(lhs) /= rhs; }
119
120 template<typename T, typename U>
121 Modular<T> power(const Modular<T>& a, const U& b) {
122     assert(b >= 0);
123     Modular<T> x = a, res = 1;
124     U p = b;
125     while (p > 0) {
126         if (p & 1) res *= x;
127         x *= x;
128         p >>= 1;
129     }
130     return res;
131 }
132
133 template <typename T>
134 bool IsZero(const Modular<T>& number) {
135     return number() == 0;
136 }
137
138 template <typename T>

```

```

139 string to_string(const Modular<T>& number) {
140     return to_string(number());
141 }
142
143 // U == std::ostream? but done this way because of fastoutput
144 template <typename U, typename T>
145 U& operator<<(U& stream, const Modular<T>& number) {
146     return stream << number();
147 }
148
149 // U == std::istream? but done this way because of fastinput
150 template <typename U, typename T>
151 U& operator>>(U& stream, Modular<T>& number) {
152     typename common_type<typename Modular<T>::Type, long long>::type x;
153     stream >> x;
154     number.value = Modular<T>::normalize(x);
155     return stream;
156 }
157
158 /*
159 using ModType = int;
160
161 struct VarMod { static ModType value; };
162 ModType VarMod::value;
163 ModType& md = VarMod::value;
164 using Mint = Modular<VarMod>;
165 */
166
167 const int md = 998244353;
168 using Mint = Modular<std::integral_constant<decay<decltype(MOD)>::type, MOD>>;
169
170 /*
171 vector<Mint> fact(1, 1);
172 vector<Mint> inv_fact(1, 1);
173
174 Mint C(int n, int k) {
175     if (k < 0 || k > n) {
176         return 0;
177     }
178     while ((int) fact.size() < n + 1) {
179         fact.push_back(fact.back() * (int) fact.size());
180         inv_fact.push_back(1 / fact.back());
181     }
182     return fact[n] * inv_fact[k] * inv_fact[n - k];
183 }
184 */

```

3.18 Mobius

```

1 int primes[N], pcnt;
2 bool is[N];
3 int mu[N]; // 莫比乌斯函数, 在这里是其前缀和
4 void seive() {
5     pcnt = 0; mu[1] = 1;
6     for (int i = 2; i < N; ++i) is[i] = true;
7     for (int i = 2; i < N; ++i) {
8         if (is[i]) primes[++pcnt] = i, mu[i] = -1;
9         for (int j = 1; j <= pcnt; ++j) {
10             ll nxt = 1ll * i * primes[j];
11             if (nxt >= N) break;
12             is[nxt] = false;
13             if (i % primes[j] == 0) {
14                 mu[nxt] = 0;
15                 break;

```

```

16         }
17         mu[nxt] = -mu[i];
18     }
19 }
20 for (int i = 1; i < N; ++i) mu[i] += mu[i - 1];
21 }

```

3.19 Modular

```

1  const int MOD = 1e9 + 7;
2
3  template < typename T >
4  inline int mint( T x )
5  {
6      x %= MOD;
7      if ( x < 0 )
8          x += MOD;
9      return x;
10 }
11 inline int add( int x, int y )
12 {
13     return x + y >= MOD ? x + y - MOD : x + y;
14 }
15 inline int mul( int x, int y )
16 {
17     return 1ll * x * y % MOD;
18 }
19 inline int sub( int x, int y )
20 {
21     return x < y ? x - y + MOD : x - y;
22 }
23 inline int qp( int x, int y )
24 {
25     int r = 1;
26     for ( ; y; y >>= 1 )
27     {
28         if ( y & 1 )
29             r = mul( r, x );
30         x = mul( x, x );
31     }
32     return r;
33 }
34 inline int inv( int x )
35 {
36     return qp( x, MOD - 2 );
37 }
38 inline int dvd( int x, int y )
39 {
40     return 1ll * x * qp( y, MOD - 2 ) % MOD;
41 }
42 inline void inc( int &x, int y )
43 {
44     x += y;
45     if ( x >= MOD )
46         x -= MOD;
47 }
48 inline void dec( int &x, int y )
49 {
50     x -= y;
51     if ( x < 0 )
52         x += MOD;
53 }

```

3.20 NTT

```

1 namespace Backlight {
2
3 namespace NTT {
4     // 998244353, 1004535809
5     const int P = 998244353, G = 3, Gi = 332748118;
6
7     inline ll pow(ll a, ll b) {
8         ll res = 1; a %= P;
9         while(b) {
10             if (b & 1) res = res * a % P;
11             a = a * a % P;
12             b >>= 1;
13         }
14         return res;
15     }
16
17     int N, L;
18     vector<ll> r;
19     void init(vector<ll>& a, vector<ll>& b) {
20         int l = a.size() + b.size();
21         N = 1; L = 0; while(N < l) N <= 1, ++L;
22         a.resize(N); b.resize(N); r.resize(N);
23         for (int i = 0; i < N; ++i)
24             r[i] = (r[i >> 1] >> 1) | ((i & 1) << (L - 1));
25     }
26
27     void work(vector<ll>& a, int flag) {
28         for(int i = 0; i < N; i++)
29             if(i < r[i]) swap(a[i], a[r[i]]);
30         for(int mid = 1; mid < N; mid <= 1) {
31             ll wn = pow(flag == 1 ? G : Gi, (P - 1) / (mid << 1));
32             for(int j = 0; j < N; j += (mid << 1)) {
33                 ll w = 1;
34                 for(int k = 0; k < mid; k++, w = (w * wn) % P) {
35                     int x = a[j + k], y = w * a[j + k + mid] % P;
36                     a[j + k] = (x + y) % P,
37                     a[j + k + mid] = (x - y + P) % P;
38                 }
39             }
40         }
41     }
42
43     inline void NTT(vector<ll>& a) { work(a, 1); }
44     inline void INTT(vector<ll>& a) { work(a, -1); }
45
46     vector<ll> convolution(vector<ll> a, vector<ll> b) {
47         init(a, b);
48         NTT(a); NTT(b);
49         for (int i = 0; i < N; ++i) a[i] = a[i] * b[i] % P;
50         INTT(a);
51         ll inv = pow(N, P - 2);
52         for (int i = 0; i < N; ++i) a[i] = a[i] * inv % P;
53         return a;
54     }
55 } // namespace NTT
56
57 } // namespace Backlight

```

3.21 PollardRho

```

1 namespace Backlight {
2
3 namespace Pollard_Rho {
4     typedef long long ll;
5     typedef pair<ll, ll> PLL;
6     mt19937 rnd(chrono::steady_clock::now().time_since_epoch().count());
7
8     const int N = 1010000;
9     ll C, fac[10010], n, mut, a[1001000];
10    int T, cnt, i, l, prime[N], p[N], psize, _cnt;
11    ll _e[100], _pr[100];
12    vector<ll> d;
13
14    inline ll mul(ll a, ll b, ll p) {
15        if (p <= 1000000000) return a * b % p;
16        else if (p <= 1000000000000ll) return (((a*(b>>20)%p)<<20)+(a*(b&((1<<20)-1))))%p;
17        else {
18            ll d = (ll)floor(a*(long double)b / p + 0.5);
19            ll ret = (a * b - d * p) % p;
20            if (ret < 0) ret += p;
21            return ret;
22        }
23    }
24
25    void prime_table(){
26        int i, j, tot, t1;
27        for (i = 1; i <= psize; i++) p[i] = i;
28        for (i = 2, tot = 0; i <= psize; i++) {
29            if (p[i] == i) prime[++tot] = i;
30            for (j = 1; j <= tot && (t1 = prime[j] * i) <= psize; j++){
31                p[t1] = prime[j];
32                if (i % prime[j] == 0) break;
33            }
34        }
35    }
36
37    void init(int ps) {
38        psize = ps;
39        prime_table();
40    }
41
42    ll powl(ll a, ll n, ll p) {
43        ll ans = 1;
44        for (; n; n >>= 1) {
45            if (n & 1) ans = mul(ans, a, p);
46            a = mul(a, a, p);
47        }
48        return ans;
49    }
50
51    bool witness(ll a, ll n) {
52        int t = 0;
53        ll u = n - 1;
54        for (; ~u&1; u >>= 1) t++;
55        ll x = powl(a, u, n), _x = 0;
56        for (; t; t--) {
57            _x = mul(x, x, n);
58            if (_x == 1 && x != 1 && x != n - 1) return 1;
59            x = _x;
60        }
61        return _x != 1;
62    }
63

```

```

64 bool miller(ll n) {
65     if (n < 2) return 0;
66     if (n <= psize) return p[n] == n;
67     if (~n & 1) return 0;
68     for (int j = 0; j <= 7; j++) if (witness(rnd() % (n - 1) + 1, n)) return 0;
69     return 1;
70 }
71
72 ll gcd(ll a, ll b) {
73     ll ret = 1;
74     while (a != 0) {
75         if ((~a&1) && (~b&1)) ret <= 1, a >= 1, b >= 1;
76         else if (~a&1) a >= 1;
77         else if (~b&1) b >= 1;
78         else {
79             if (a < b) swap(a, b);
80             a -= b;
81         }
82     }
83     return ret * b;
84 }
85
86 ll rho(ll n) {
87     for (;;) {
88         ll X = rnd() % n, Y, Z, T = 1, *lY = a, *lX = lY;
89         int tmp = 20;
90         C = rnd() % 10 + 3;
91         X = mul(X, X, n) + C; *(lY++) = X; lX++;
92         Y = mul(X, X, n) + C; *(lY++) = Y;
93         for (; X != Y;) {
94             ll t = X - Y + n;
95             Z = mul(T, t, n);
96             if (Z == 0) return gcd(T, n);
97             tmp--;
98             if (tmp == 0) {
99                 tmp = 20;
100                 Z = gcd(Z, n);
101                 if (Z != 1 && Z != n) return Z;
102             }
103             T = Z;
104             Y = *(lY++) = mul(Y, Y, n) + C;
105             Y = *(lY++) = mul(Y, Y, n) + C;
106             X = *(lX++);
107         }
108     }
109 }
110
111 void _factor(ll n) {
112     for (int i = 0; i < cnt; i++) {
113         if (n % fac[i] == 0) n /= fac[i], fac[cnt++] = fac[i];
114     }
115     if (n <= psize) {
116         for (; n != 1; n /= p[n]) fac[cnt++] = p[n];
117         return;
118     }
119     if (miller(n)) fac[cnt++] = n;
120     else {
121         ll x = rho(n);
122         _factor(x); _factor(n / x);
123     }
124 }
125
126 void dfs(ll x, int dep) {
127     if (dep == _cnt) d.push_back(x);
128     else {

```

```

129         dfs(x, dep+1);
130         for (int i = 1; i <= _e[dep]; i++) dfs(x * _pr[dep], dep + 1);
131     }
132 }
133
134 void norm() {
135     sort(fac, fac + cnt);
136     _cnt = 0;
137     for(int i = 0; i < cnt; ++i)
138         if (i == 0 || fac[i] != fac[i-1]) _pr[_cnt] = fac[i], _e[_cnt++] = 1;
139         else _e[_cnt-1]++;
140 }
141
142 vector<ll> getd() {
143     d.clear();
144     dfs(1, 0);
145     return d;
146 }
147
148 /*****
149
150 // Attention: call init() before use
151
152 // get all factors
153 vector<ll> factorA(ll n) {
154     cnt = 0;
155     _factor(n);
156     norm();
157     vector<ll> d = getd();
158     sort(d.begin(), d.end());
159     return d;
160 }
161
162 // get prime factors
163 vector<ll> factorP(ll n) {
164     cnt = 0;
165     _factor(n);
166     norm();
167     vector<ll> d(_cnt);
168     for (int i = 0; i < _cnt; ++i) d[i] = _pr[i];
169     return d;
170 }
171
172 // get prime factors, n = pr_i^e_i
173 vector<PLL> factorG(ll n) {
174     cnt = 0;
175     _factor(n);
176     norm();
177     vector<PLL> d(_cnt);
178     for (int i = 0; i < _cnt; ++i) d[i] = make_pair(_pr[i], _e[i]);
179     return d;
180 }
181
182 bool is_primitive(ll a, ll p) {
183     assert(miller(p));
184     vector<PLL> D = factorG(p - 1);
185     for (int i = 0; i < (int)D.size(); ++i) if (powl(a, (p-1) / D[i].first, p) == 1) return 0;
186     return 1;
187 }
188 }
189
190 }

```

3.22 poly-struct

```

1  constexpr int P = 998244353;
2  vector<int> rev, roots{0, 1};
3  int power(int a, int b) {
4      int r = 1;
5      while(b) {
6          if (b & 1)
7              r = 1ll * r * a % P;
8          a = 1ll * a * a % P;
9          b >>= 1;
10     }
11     return r;
12 }
13 void dft(vector<int> &a) {
14     int n = a.size();
15     if (int(rev.size()) != n) {
16         int k = __builtin_ctz(n) - 1;
17         rev.resize(n);
18         for (int i = 0; i < n; ++i)
19             rev[i] = rev[i >> 1] >> 1 | (i & 1) << k;
20     }
21     for (int i = 0; i < n; ++i)
22         if (rev[i] < i)
23             swap(a[i], a[rev[i]]);
24     if (int(roots.size()) < n) {
25         int k = __builtin_ctz(roots.size());
26         roots.resize(n);
27         while ((1 << k) < n) {
28             int e = power(3, (P - 1) >> (k + 1));
29             for (int i = 1 << (k - 1); i < (1 << k); ++i) {
30                 roots[2 * i] = roots[i];
31                 roots[2 * i + 1] = 1ll * roots[i] * e % P;
32             }
33             ++k;
34         }
35     }
36     for (int k = 1; k < n; k *= 2) {
37         for (int i = 0; i < n; i += 2 * k) {
38             for (int j = 0; j < k; ++j) {
39                 int u = a[i + j];
40                 int v = 1ll * a[i + j + k] * roots[k + j] % P;
41                 int x = u + v;
42                 if (x >= P)
43                     x -= P;
44                 a[i + j] = x;
45                 x = u - v;
46                 if (x < 0)
47                     x += P;
48                 a[i + j + k] = x;
49             }
50         }
51     }
52 }
53 void idft(vector<int> &a) {
54     int n = a.size();
55     reverse(a.begin() + 1, a.end());
56     dft(a);
57     int inv = power(n, P - 2);
58     for (int i = 0; i < n; ++i)
59         a[i] = 1ll * a[i] * inv % P;
60 }
61 struct poly {
62     vector<int> a;
63 }

```



```

64     poly() {}
65     poly(int f0) { a = {f0}; }
66     poly(const vector<int> &f) : a(f) {
67         while (!a.empty() && !a.back())
68             a.pop_back();
69     }
70     poly(const vector<int> &f, int n) : a(f) {
71         a.resize(n);
72     }
73     int size() const {
74         return a.size();
75     }
76     int deg() const {
77         return a.size() - 1;
78     }
79     int operator[](int idx) const {
80         if (idx < 0 || idx >= size())
81             return 0;
82         return a[idx];
83     }
84     void input(int n) {
85         a.resize(n);
86         FE(v, a) rd(v);
87     }
88     void output(int n) {
89         for (int i = 0; i < n - 1; ++i) printf("%d ", (*this)[i]);
90         printf("%d\n", (*this)[n - 1]);
91     }
92     poly mulxk(int k) const {
93         auto b = a;
94         b.insert(b.begin(), k, 0);
95         return poly(b);
96     }
97     poly modxk(int k) const {
98         k = min(k, size());
99         return poly(std::vector<int>(a.begin(), a.begin() + k));
100    }
101    poly alignxk(int k) const {
102        return poly(a, k);
103    }
104    poly divxk(int k) const {
105        if (size() <= k)
106            return poly();
107        return poly(vector<int>(a.begin() + k, a.end()));
108    }
109    friend poly operator+(const poly& f, const poly& g) {
110        int k = max(f.size(), g.size());
111        vector<int> res(k);
112        for (int i = 0; i < k; ++i) {
113            res[i] = f[i] + g[i];
114            if (res[i] >= P)
115                res[i] -= P;
116        }
117        return poly(res);
118    }
119    friend poly operator - (const poly& f, const poly &g) {
120        int k = max(f.size(), g.size());
121        vector<int> res(k);
122        for (int i = 0; i < k; ++i) {
123            res[i] = f[i] - g[i];
124            if (res[i] < 0)
125                res[i] += P;
126        }
127        return poly(res);
128    }

```

```

129 friend poly operator * (const poly& f, const poly& g) {
130     int sz = 1, k = f.size() + g.size() - 1;
131     while (sz < k) sz *= 2;
132     vector<int> p = f.a, q = g.a;
133     p.resize(sz); q.resize(sz);
134     dft(p); dft(q);
135     for (int i = 0; i < sz; ++i)
136         p[i] = 1ll * p[i] * q[i] % P;
137     idft(p);
138     return poly(p);
139 }
140 friend poly operator / (const poly& f, const poly& g) {
141     return f.divide(g).first;
142 }
143 friend poly operator % (const poly& f, const poly& g) {
144     return f.divide(g).second;
145 }
146 poly &operator += (const poly& f) {
147     return (*this) = (*this) + f;
148 }
149 poly &operator -= (const poly& f) {
150     return (*this) = (*this) - f;
151 }
152 poly &operator *= (const poly& f) {
153     return (*this) = (*this) * f;
154 }
155 poly &operator /= (const poly& f) {
156     return (*this) = divide(f).first;
157 }
158 poly &operator %= (const poly& f) {
159     return (*this) = divide(f).second;
160 }
161 poly derivative() const {
162     if (a.empty()) return poly();
163     int n = a.size();
164     vector<int> res(n - 1);
165     for (int i = 0; i < n - 1; ++i)
166         res[i] = 1ll * (i + 1) * a[i + 1] % P;
167     return poly(res);
168 }
169 poly integral() const {
170     if (a.empty()) return poly();
171     int n = a.size();
172     vector<int> res(n + 1);
173     for (int i = 0; i < n; ++i)
174         res[i + 1] = 1ll * a[i] * power(i + 1, P - 2) % P;
175     return poly(res);
176 }
177 poly rev() const {
178     return poly(vector<int>(a.rbegin(), a.rend()));
179 }
180 poly inv(int m) const {
181     poly x(power(a[0], P - 2));
182     int k = 1;
183     while (k < m) {
184         k *= 2;
185         x = (x * (2 - modxk(k) * x)).modxk(k);
186     }
187     return x.modxk(m);
188 }
189 poly log(int m) const {
190     return (derivative() * inv(m)).integral().modxk(m);
191 }
192 poly exp(int m) const {
193     poly x(1);

```

```

194     int k = 1;
195     while (k < m) {
196         k *= 2;
197         x = (x * (1 - x.log(k) + modxk(k))).modxk(k);
198     }
199     return x.modxk(m);
200 }
201 poly sqrt(int m) const {
202     poly x(1);
203     int k = 1;
204     while (k < m) {
205         k *= 2;
206         x = (x + (modxk(k) * x.inv(k)).modxk(k)) * ((P + 1) / 2);
207     }
208     return x.modxk(m);
209 }
210 poly sin() const {
211     int g = 3; // g: the ord of P
212     int i = power(g, (P - 1) / 4);
213     poly p = i * (*this);
214     p = p.exp(p.size());
215
216     poly q = (P - i) * (*this);
217     q = q.exp(q.size());
218
219     poly r = (p - q) * power(2 * i % P, P - 2);
220     return r;
221 }
222 poly cos() const {
223     int g = 3; // g: the ord of P
224     int i = power(g, (P - 1) / 4);
225     poly p = i * (*this);
226     p = p.exp(p.size());
227
228     poly q = (P - i) * (*this);
229     q = q.exp(q.size());
230
231     poly r = (p + q) * power(2, P - 2);
232     return r;
233 }
234 poly tan() const {
235     return sin() / cos();
236 }
237 poly cot() const {
238     return cos() / sin();
239 }
240 poly arcsin() {
241     poly sq = (*this) * (*this).modxk(size());
242     for (int i = 0; i < size(); ++i) sq.a[i] = sq.a[i] ? P - sq.a[i] : 0;
243     sq.a[0] = 1 + sq.a[0];
244     if (sq.a[0] >= P) sq.a[0] -= P;
245     poly r = (derivative() * sq.sqrt(size()).inv(size())).integral();
246     return r;
247 }
248 poly arccos() {
249     poly r = arcsin();
250     for (int i = 0; i < size(); ++i) r.a[i] = r.a[i] ? P - r.a[i] : 0;
251     return r;
252 }
253 poly arctan() {
254     poly sq = (*this) * (*this).modxk(size());
255     sq.a[0] = 1 + sq.a[0];
256     if (sq.a[0] >= P) sq.a[0] -= P;
257     poly r = (derivative() * sq.inv(size())).integral();
258     return r;

```

```

259     }
260     poly arccot() {
261         poly r = arctan();
262         for (int i = 0; i < size(); ++i) r.a[i] = r.a[i] ? P - r.a[i] : 0;
263         return r;
264     }
265     poly mulT(const poly& b) const {
266         if (b.size() == 0)
267             return poly();
268         int n = b.size();
269         return ((*this) * b.rev()).divxk(n - 1);
270     }
271     pair<poly, poly> divide(const poly& g) const {
272         int n = a.size(), m = g.size();
273         if (n < m) return make_pair(poly(), a);
274
275         poly fR = rev();
276         poly gR = g.rev().alignxk(n - m + 1);
277         poly gRI = gR.inv(gR.size());
278
279         poly qR = (fR * gRI).modxk(n - m + 1);
280
281         poly q = qR.rev();
282
283         poly r = ((*this) - g * q).modxk(m - 1);
284
285         return make_pair(q, r);
286     }
287     vector<int> eval(vector<int> x) const {
288         if (size() == 0)
289             return vector<int>(x.size(), 0);
290         const int n = max(int(x.size()), size());
291         vector<poly> q(4 * n);
292         vector<int> ans(x.size());
293         x.resize(n);
294         function<void(int, int, int)> build = [&](int p, int l, int r) {
295             if (r - l == 1) {
296                 q[p] = vector<int>{1, (P - x[l]) % P};
297             } else {
298                 int m = (l + r) / 2;
299                 build(2 * p, l, m);
300                 build(2 * p + 1, m, r);
301                 q[p] = q[2 * p] * q[2 * p + 1];
302             }
303         };
304         build(1, 0, n);
305         function<void(int, int, int, const poly &)> work = [&](int p, int l, int r, const poly &num) {
306             if (r - l == 1) {
307                 if (l < int(ans.size()))
308                     ans[l] = num[0];
309             } else {
310                 int m = (l + r) / 2;
311                 work(2 * p, l, m, num.mulT(q[2 * p + 1]).modxk(m - 1));
312                 work(2 * p + 1, m, r, num.mulT(q[2 * p]).modxk(r - m));
313             }
314         };
315         work(1, 0, n, mulT(q[1].inv(n)));
316         return ans;
317     }
318 };

```

3.23 Poly

```

1 namespace Poly {
2     const int N = ...;
3     const int MAXN = N << 3;
4     const int P = 998244353;
5     const int G = 3;
6
7     ll qp(ll a, ll b) {
8         ll res = 1; a %= P;
9         while(b) {
10             if (b & 1) res = res * a % P;
11             a = a * a % P;
12             b >>= 1;
13         }
14         return res;
15     }
16
17     const int Gi = qp(G, P - 2);
18     const int I2 = qp(2, P - 2);
19     int r[MAXN];
20     ll t1[MAXN], t2[MAXN], t3[MAXN], t4[MAXN], t5[MAXN], t6[MAXN], t7[MAXN];
21
22     // int N, L;
23     // void init(int n) {
24     //     int N = 1, L = -1; while(N <= n << 1) N <<= 1, L++;
25     //     for(int i = 1; i < N; ++i) r[i] = (r[i >> 1] >> 1) | ((i & 1) << L);
26     // }
27
28     void inplaceNTT(ll *a, int n, int op) {
29         for(int i = 0; i < n; ++i) if(i < r[i]) swap(a[i], a[r[i]]);
30         for(int m2 = 2, m = 1; m2 <= n; m = m2, m2 <<= 1) {
31             ll wn = qp(op == 1 ? G : Gi, (P - 1) / m2), x, y;
32             for(int l = 0; l < n; l += m2) {
33                 ll w = 1;
34                 for(int i = l; i < l + m; ++i) {
35                     x = a[i], y = w * a[i + m] % P;
36                     a[i] = (x + y) % P;
37                     a[i + m] = (x + P - y) % P;
38                     w = w * wn % P;
39                 }
40             }
41         }
42         if (op == -1) {
43             ll inv = qp(n, P - 2);
44             for(int i = 0; i < n; ++i) a[i] = a[i] * inv % P;
45         }
46     }
47     inline void NTT(ll *a, int n) { inplaceNTT(a, n, 1); }
48     inline void INTT(ll *a, int n) { inplaceNTT(a, n, -1); }
49
50     // 多项式微分 (求导)
51     inline void Derivative(ll *a, ll *b, int n) {
52         for(int i = 0; i < n; ++i) b[i] = a[i + 1] * (i + 1) % P;
53         b[n - 1] = 0;
54     }
55
56     // 多项式积分
57     inline void Integral(ll *a, ll *b, int n) {
58         for(int i = 0; i < n; ++i) b[i + 1] = a[i] * qp(i + 1, P - 2) % P;
59         b[0] = 0;
60     }
61
62     // 多项式翻转
63     //  $b(x) = x^n a(\frac{1}{x})$ 

```

```

64 inline void Reverse(ll *a, ll *b, int n) {
65     for (int i = 0; i < n; ++i) b[i] = a[n - i - 1];
66 }
67
68 // 多项式乘法逆
69 //  $b(x) = a^{-1}(x) \bmod x^n$ 
70 void __Inverse(ll *a, ll *b, int n) {
71     if(n == 1) {
72         b[0] = qp(a[0], P - 2);
73         return;
74     }
75
76     __Inverse(a, b, (n + 1) >> 1);
77
78     int N = 1, l = -1; while(N <= n << 1) N <=&= 1, l++;
79     for(int i = 1; i < N; ++i) r[i] = (r[i >> 1] >> 1) | ((i & 1) << 1);
80
81     memcpy(t1, a, sizeof(a[0]) * n); fill(t1 + n, t1 + N, 0);
82
83     NTT(t1, N); NTT(b, N);
84     for(int i = 0; i < N; ++i) b[i] = ((b[i] << 1) % P + P - t1[i] * b[i] % P * b[i] % P) % P;
85     INTT(b, N);
86
87     fill(b + n, b + N, 0);
88 }
89
90 inline void Inverse(ll *a, ll *b, int n) {
91     fill(b, b + (n << 2), 0);
92     __Inverse(a, b, n);
93 }
94
95 // 多项式对数函数
96 //  $b(x) = \ln a(x) \bmod x^n$ 
97 void Ln(ll *a, ll *b, int n) {
98     #define aD t3
99     #define aI t4
100
101     Derivative(a, aD, n); Inverse(a, aI, n);
102     int N = 1, l = -1; while(N <= n << 1) N <=&= 1, l++;
103     for(int i = 1; i < N; ++i) r[i] = (r[i >> 1] >> 1) | ((i & 1) << 1);
104     NTT(aD, N); NTT(aI, N);
105     for(int i = 0; i < N; ++i) aD[i] = aD[i] * aI[i] % P;
106     INTT(aD, N); Integral(aD, b, n);
107
108     #undef aD
109     #undef aI
110 }
111
112 // 多项式指数函数
113 //  $b(x) = \exp a(x) \bmod x^n$ 
114 void Exp(ll *a, ll *b, int n) {
115     #define Lnb t2
116
117     if(n == 1) {
118         b[0] = 1;
119         return;
120     }
121     Exp(a, b, (n + 1) >> 1);
122     Ln(b, Lnb, n);
123     int N = 1, l = -1; while(N <= n << 1) N <=&= 1, l++;
124     for(int i = 1; i < N; ++i) r[i] = (r[i >> 1] >> 1) | ((i & 1) << 1);
125
126     memcpy(t1, a, sizeof(a[0]) * n); fill(t1 + n, t1 + N, 0);
127     fill(Lnb + n, Lnb + N, 0);
128

```

```

129     for(int i = 0; i < N; ++i) t1[i] = ((t1[i] - Lnb[i]) % P + P) % P;
130     ++t1[0];
131     NTT(b, N); NTT(t1, N);
132     for(int i = 0; i < N; ++i) b[i] = b[i] * t1[i] % P;
133     INTT(b, N);
134
135     fill(b + n, b + N, 0);
136     #undef Lnb
137 }
138
139 // 多项式乘法 (卷积)
140 //  $c(x) = a(x) * b(x) \bmod x^{(n+m)}$ 
141 //  $\deg c = n + m - 1$ 
142 void Convolution(ll *a, int n, ll *b, int m, ll *c) {
143     int N = 1, l = -1; while(N <= (n + m) << 1) N <<= 1, l++;
144     for(int i = 1; i < N; ++i) r[i] = (r[i] >> 1) >> 1 | ((i & 1) << 1);
145
146     memcpy(t1, a, sizeof(a[0]) * n); fill(t1 + n, t1 + N, 0);
147     memcpy(t2, b, sizeof(b[0]) * m); fill(t2 + m, t2 + N, 0);
148
149     NTT(t1, N); NTT(t2, N);
150     for (int i = 0; i < N; ++i) c[i] = t1[i] * t2[i] % P;
151     INTT(c, N);
152     fill(c + n + m, c + N, 0);
153 }
154 #define Multiply Convolution
155
156 // 多项式除法
157 //  $a(x) = b(x)Q(x) + R(x)$ 
158 //  $\deg Q = n - m + 1$ 
159 //  $\deg R = m - 1$ 
160 void Divide(ll *a, int n, ll *b, int m, ll *Q, ll *R) {
161     #define aR t3
162     #define bR t4
163     #define bRi t5
164     #define QR t6
165     #define bQ t7
166
167     int degQ = n - m + 1;
168     int degR = m - 1;
169
170     Reverse(a, aR, n); Reverse(b, bR, m);
171     for (int i = degQ; i < m; ++i) bR[i] = 0;
172
173     // get Q(x)
174     Inverse(bR, bRi, degQ);
175     Multiply(aR, n, bRi, degQ, QR);
176     Reverse(QR, Q, degQ);
177
178     // get R(x)
179     Multiply(b, m, Q, degQ, bQ);
180     for (int i = 0; i < degR; ++i) R[i] = (a[i] - bQ[i] + P) % P;
181
182     #undef aR
183     #undef bR
184     #undef bRi
185     #undef QR
186 }
187
188 // 多项式求平方根
189 //  $b^{\{2\}}(x) = a(x)$ 
190 #define bI t3
191 void __Sqrt(ll *a, ll* b, int n) {
192     if (n == 1) {
193         b[0] = 1;

```

```

194         return;
195     }
196
197     __Sqrt(a, b, (n + 1) >> 1);
198
199     Inverse(b, bI, n);
200     Multiply(a, n, bI, n, bI);
201     for (int i = 0; i < n; ++i) b[i] = (b[i] + bI[i]) * I2 % P;
202 }
203 inline void Sqrt(ll *a, ll *b, int n) {
204     fill(bI, bI + (n << 2), 0);
205     __Sqrt(a, b, n);
206 }
207 #undef bI
208
209 struct poly {
210     vector<ll> a;
211     int size() const { return a.size(); }
212     int deg() const { return size() - 1; }
213     ll& operator [] (int i) { assert(i < size()); return a[i]; }
214     ll operator [] (int i) const { return i < size() ? a[i] : 0LL; }
215     void reverse() { std::reverse(a.begin(), a.end()); }
216     void resize(int n) { a.resize(n); }
217     poly(int n = 0) : a(n, 0) {}
218
219     void DEBUG() {
220         cerr << "Poly DEBUG: " << endl;
221         for (const ll& v: a) cerr << v << " ";
222         cerr << endl;
223     }
224
225     void DEBUG() const {
226         cerr << "Poly DEBUG: " << endl;
227         for (const ll& v: a) cerr << v << " ";
228         cerr << endl;
229     }
230
231     void input() {
232         for (ll& x: a) read(x);
233     }
234
235     void output() {
236         if (a.empty()) { puts(""); return; }
237         int n = a.size();
238         for (int i = 0; i < n - 1; ++i) printf("%lld ", a[i]);
239         printf("%lld\n", a[n - 1]);
240     }
241
242     void output() const {
243         if (a.empty()) { puts(""); return; }
244         int n = a.size();
245         for (int i = 0; i < n - 1; ++i) printf("%lld ", a[i]);
246         printf("%lld\n", a[n - 1]);
247     }
248
249     poly inv(int n = -1) const {
250         if (n == -1) n = size();
251         static ll f[MAXN], g[MAXN];
252         for (int i = 0; i < n; ++i) f[i] = a[i];
253         Inverse(f, g, n);
254         poly res(n);
255         for (int i = 0; i < n; ++i) res[i] = g[i];
256         return res;
257     }
258 }

```



```

259
260     poly rev() const {
261         int n = size();
262         poly r(n);
263         for (int i = 0; i < n; ++i) r[i] = a[n - i - 1];
264         return r;
265     }
266
267     poly sqrt() {
268         int n = a.size();
269         static ll f[MAXN], g[MAXN];
270         for (int i = 0; i < n; ++i) f[i] = a[i];
271         Sqrt(f, g, n);
272         poly res(n);
273         for (int i = 0; i < n; ++i) res[i] = g[i];
274         return res;
275     }
276 };
277
278 poly operator + (const poly& a, const poly& b) {
279     int k = max(a.size(), b.size());
280     poly c(k);
281     for (int i = 0; i < k; ++i) c[i] = (a[i] + b[i]) % P;
282     return c;
283 }
284
285 poly operator - (const poly& a, const poly& b) {
286     int k = max(a.size(), b.size());
287     poly c(k);
288     for (int i = 0; i < k; ++i) c[i] = (a[i] - b[i] + P) % P;
289     return c;
290 }
291
292 poly operator * (const poly& a, const poly& b) {
293     static ll ta[MAXN], tb[MAXN];
294     int n = a.size(), m = b.size(), k = n + m - 1;
295     for (int i = 0; i < n; ++i) ta[i] = a[i];
296     for (int i = 0; i < m; ++i) tb[i] = b[i];
297
298     Multiply(ta, n, tb, m, ta);
299
300     poly c(k);
301     for (int i = 0; i < k; ++i) c[i] = ta[i];
302     return c;
303 }
304
305 pair<poly, poly> Divide(const poly& a, const poly& b) {
306     static ll ta[MAXN], tb[MAXN], tq[MAXN], tr[MAXN];
307     int n = a.size(), m = b.size();
308     if (n < m) return make_pair(poly(0), a);
309
310     int degQ = n - m + 1, degR = m - 1;
311     for (int i = 0; i < n; ++i) ta[i] = a[i];
312     for (int i = 0; i < m; ++i) tb[i] = b[i];
313
314     Divide(ta, n, tb, m, tq, tr);
315
316     poly q(degQ); for (int i = 0; i < degQ; ++i) q[i] = tq[i];
317     poly r(degR); for (int i = 0; i < degR; ++i) r[i] = tr[i];
318
319     return make_pair(q, r);
320 }
321
322 poly operator / (const poly &a, const poly &b) { return Divide(a, b).first; }
323 poly operator % (const poly &a, const poly &b) { return Divide(a, b).second; }

```

```

324
325
326
327 // given a(x), deg a = n
328 // calc y_i = a(x_i) for i in [0, m), O(n \log^2 n)
329 poly t[N << 2], p[N];
330 void build(int o, int l, int r) {
331     if (l == r) {
332         t[o] = p[l];
333         return;
334     }
335     int mid = (l + r) >> 1;
336     build(o << 1, l, mid);
337     build(o << 1 | 1, mid + 1, r);
338     t[o] = t[o << 1] * t[o << 1 | 1];
339 }
340 void __calcValue(int o, int l, int r, const poly& f, ll *x, ll *y) {
341     // if (l == r) {
342     //     y[l] = f[0];
343     //     return;
344     // }
345     if (r - l <= 75) { // 降低常数 (魔法)
346         for (int i = l; i <= r; ++i) {
347             ll v = 0;
348             for (int j = f.size() - 1; j >= 0; --j)
349                 v = (v * x[i] % P + f[j]) % P;
350             y[i] = v;
351         }
352         return;
353     }
354
355     int mid = (l + r) >> 1, lc = o << 1, rc = o << 1 | 1;
356     __calcValue(lc, l, mid, f % t[lc], x, y);
357     __calcValue(rc, mid + 1, r, f % t[rc], x, y);
358 }
359 void calcValue(const poly& f, ll *x, ll *y, int m) {
360     for (int i = 1; i <= m; ++i) {
361         p[i].resize(2);
362         p[i][0] = P - x[i];
363         p[i][1] = 1;
364     }
365     build(1, 1, m);
366     __calcValue(1, 1, m, f % t[1], x, y);
367 }
368 }

```

3.24 Simplex

```

1 /**
2  * Simplex Algorithm:
3  * solve  $\max z = \sum_{j=1}^n c_j x_j$ 
4  * with restrictions like:  $\sum_{j=1}^n a_{ij} x_j = b_j, i = 1, 2, \dots, m$ 
5  *  $x_j \geq 0$ 
6  * in  $O(knm)$ , where  $k$  is a const number.
7  *
8  * Tips: 1.  $\min \Rightarrow -\min \Rightarrow \max$ 
9  *        2.  $x_1 + 2x_2 \leq 9 \Rightarrow x_1 + x_2 + x_3 = 9, x_3 \geq 0$ 
10 *        3.  $x_k$  without restrictions  $\Rightarrow x_k = x_m - x_m$  and  $x_m, x_n \geq 0$ 
11 *
12 * Notes: 1.  $c = A_{\{0\}}$ 
13 *          2.  $z = \max cx$ 
14 *          3.  $Ax = b$ 
15 */
16 enum {

```

```

17     OK = 1,
18     UNBOUNDED = 2,
19     INFEASIBLE = 3
20 };
21 struct Simplex {
22     constexpr static double eps = 1e-10;
23
24     int n, m;
25     int flag;
26     double z;
27     vector<vector<double>> A;
28     vector<double> b, x;
29     vector<int> idx, idy;
30
31     Simplex(int _n, int _m) : n(_n), m(_m) {
32         A = vector<vector<double>>(m + 1, vector<double>(n + 1));
33         b = vector<double>(m + 1);
34         x = vector<double>(n + 1);
35         idx = vector<int>(m + 1);
36         idy = vector<int>(n + 1);
37     }
38
39     void input() {
40         for (int i = 1; i <= n; ++i) read(A[0][i]); // A_{0,i} = c_i
41         for (int i = 1; i <= m; ++i) {
42             for (int j = 1; j <= n; ++j) read(A[i][j]);
43             read(b[i]);
44         }
45     }
46
47     void pivot(int x, int y) {
48         swap(idx[x], idy[y]);
49
50         double k = A[x][y];
51         for (int i = 1; i <= n; ++i) A[x][i] /= k;
52         b[x] /= k;
53         A[x][y] = 1 / k;
54
55         for (int i = 0; i <= m; ++i) if (i != x) {
56             k = A[i][y];
57             b[i] -= k * b[x];
58             A[i][y] = 0;
59             for (int j = 1; j <= n; ++j) A[i][j] -= k * A[x][j];
60         }
61     }
62
63     void init() {
64         flag = OK;
65         idx[0] = INT_MAX; for (int i = 1; i <= m; ++i) idx[i] = n + i;
66         idy[0] = INT_MAX; for (int i = 1; i <= n; ++i) idy[i] = i;
67
68         for(;;) {
69             int x = 0, y = 0;
70             for (int i = 1; i <= m; ++i) if (b[i] < -eps && idx[i] < idx[x]) x = i;
71             if (!x) break;
72
73             for (int i = 1; i <= n; ++i) if (A[x][i] < -eps && idy[i] < idy[y]) y = i;
74             if (!y) { flag = INFEASIBLE; break; }
75
76             pivot(x, y);
77         }
78     }
79
80     void simplex() {
81         for(;;) {

```

```

82     int x = 0, y = 0;
83     for (int i = 1; i <= n; ++i) if (A[0][i] > eps && idy[i] < idy[y]) y = i;
84     if (!y) break;
85
86     for (int i = 1; i <= m; ++i) if (A[i][y] > eps) {
87         if (!x) x = i;
88         else {
89             double delta = b[i] / A[i][y] - b[x] / A[x][y];
90             if (delta < -eps) x = i;
91             else if (delta < eps && idx[i] < idx[x]) x = i;
92         }
93     }
94     if (!x) { flag = UNBOUNDED; break; }
95
96     pivot(x, y);
97 }
98 z = -b[0];
99 }
100
101 void work() {
102     init();
103     if (flag == OK) simplex();
104     if (flag == OK) {
105         for (int i = 1; i <= n; ++i) {
106             x[i] = 0;
107             for (int j = 1; j <= m; ++j) if (idx[j] == i) { x[i] = b[j]; break; }
108         }
109     }
110 }
111
112 void DEBUG() {
113     cerr << fixed << setprecision(3);
114     cerr << "Simplex Debug: \n";
115     for (int i = 1; i <= m; ++i) {
116         for (int j = 1; j <= n; ++j) {
117             cerr << A[i][j] << " ";
118         }
119         cerr << "\n";
120     }
121     for (int i = 1; i <= n; ++i) cerr << x[i] << " ";
122     cerr << endl;
123     cerr << "Z = " << z << endl;
124 }
125 };

```

3.25 SimpsonIntegral

```

1 namespace SimpsonIntegral {
2     // calculate  $\int_l^r f(x) dx$ 
3
4     double f(double x) {
5         return (c * x + d) / (a * x + b);
6     }
7
8     double simpson(double l, double r) {
9         double mid = (l + r) / 2;
10        return (r - l) * (f(l) + 4 * f(mid) + f(r)) / 6;
11    }
12
13    double integral(double l, double r, double eps, double ans) {
14        double mid = (l + r) / 2;
15        double fl = simpson(l, mid), fr = simpson(mid, r);
16        if (abs(fl + fr - ans) <= 15 * eps)
17            return fl + fr + (fl + fr - ans) / 15;

```

```

18     return integral(l, mid, eps / 2, fl) + integral(mid, r, eps / 2, fr);
19 }
20
21 double integral(double l, double r, double eps = 1e-8) {
22     return integral(l, r, eps, simpson(l, r));
23 }
24 }

```

4 other

4.1 BFPRT

```

1  /**
2   * BFPRT: find the kth element of an array in  $O(n)$  using Divide and Conquer method.
3   * you can use std::nth_element(a, a + k, a + n) instead
4   */
5  namespace BFPRT {
6      template<typename T, typename Cmp>
7      T kth_index(T* a, int l, int r, int k, Cmp cmp);
8
9      template<typename T, typename Cmp>
10     int insert_sort(T* a, int l, int r, Cmp cmp) {
11         for (int i = l + 1; i <= r; ++i) {
12             int tmp = a[i];
13             int j = i - 1;
14             while(j >= l && a[j] > tmp) {
15                 a[j + 1] = a[j];
16                 --j;
17             }
18             a[j + 1] = tmp;
19         }
20         return l + (r - l) / 2;
21     }
22
23     template<typename T, typename Cmp>
24     int pivot(T* a, int l, int r, Cmp cmp) {
25         if (r - l < 5) return insert_sort(a, l, r, cmp);
26         int lst = l - 1;
27         for (int i = l; i + 4 <= r; i += 5) {
28             int p = insert_sort(a, i, i + 4, cmp);
29             swap(a[++lst], a[p]);
30         }
31         return kth_index<T>(a, l, lst, (lst - l + 1) / 2 + 1, cmp);
32     }
33
34     template<typename T, typename Cmp>
35     int partition(T* a, int l, int r, Cmp cmp) {
36         int p = pivot(a, l, r, cmp);
37         swap(a[p], a[r]);
38         int lst = l - 1;
39         for (int i = l; i < r; ++i) {
40             if (cmp(a[i], a[r])) swap(a[++lst], a[i]);
41         }
42         swap(a[++lst], a[r]);
43         return lst;
44     }
45
46     template<typename T, typename Cmp>
47     T kth_index(T* a, int l, int r, int k, Cmp cmp) {
48         int p = partition(a, l, r, cmp);
49         int d = p - l + 1;
50         if (d == k) return a[p];
51         else if (d < k) return kth_index(a, p + 1, r, k - d, cmp);

```

```

52     else return kth_index(a, l, p - 1, k, cmp);
53 }
54
55 template<typename T>
56 T kth_index(T* a, int l, int r, int k) {
57     return kth_index(a, l, r, k, less<T>());
58 }
59 };

```

4.2 cpp-header

```

1  #include <bits/stdc++.h>
2  using namespace std;
3
4  using ll = int64_t;
5  using ull = uint64_t;
6  using uint = uint32_t;
7  using VI = vector<int>;
8  using VL = vector<ll>;
9  using VVI = vector<vector<int>>>;
10 using VVL = vector<vector<ll>>>;
11 using PII = pair<int, int>;
12 using PLL = pair<ll, ll>;
13
14 #define REP(i, __, __) for (int i = (__); i < (__); ++i)
15 #define PER(i, __, __) for (int i = (__ - 1); i >= (__); --i)
16 #define FOR(i, __, __) for (int i = (__); i <= (__); ++i)
17 #define ROF(i, __, __) for (int i = (__); i >= (__); --i)
18 #define FC(v, V) for (const auto& v : V)
19 #define FE(v, V) for (auto& v : V)
20
21 #define EB emplace_back
22 #define PB push_back
23 #define MP make_pair
24 #define FI first
25 #define SE second
26 #define SZ(x) (int((x).size()))
27 #define ALL(x) (x).begin(), (x).end()
28 #define LLA(x) (x).rbegin(), (x).rend()
29
30 #define rd read
31 #define pr print
32 #define pf printf
33 #define ps prints
34 #define pln println
35
36 #ifdef BACKLIGHT
37 #include "debug.h"
38 #else
39 #define debug(...)
40 #endif
41
42 template <typename T>
43 T MIN(T a, T b)
44 {
45     return min(a, b);
46 }
47
48 template <typename First, typename... Rest>
49 First MIN(First f, Rest... r)
50 {
51     return min(f, MIN(r...));
52 }
53

```

```
54 template <typename T>
55 T MAX(T a, T b)
56 {
57     return max(a, b);
58 }
59
60 template <typename First, typename... Rest>
61 First MAX(First f, Rest... r)
62 {
63     return max(f, MAX(r...));
64 }
65
66 template <typename T>
67 inline void umin(T& a, const T& b)
68 {
69     if (a > b)
70         a = b;
71 }
72
73 template <typename T>
74 inline void umax(T& a, const T& b)
75 {
76     if (a < b)
77         a = b;
78 }
79
80 ll FIRSTTRUE(ll l, ll r, function<bool(ll)> f)
81 {
82     ll res = l - 1, mid;
83     while (l <= r)
84     {
85         mid = (l + r) >> 1;
86         if (f(mid))
87             r = mid - 1, res = mid;
88         else
89             l = mid + 1;
90     }
91     return res;
92 }
93
94 ll LASTTRUE(ll l, ll r, function<bool(ll)> f)
95 {
96     ll res = l - 1, mid;
97     while (l <= r)
98     {
99         mid = (l + r) >> 1;
100         if (f(mid))
101             l = mid + 1, res = mid;
102         else
103             r = mid - 1;
104     }
105     return res;
106 }
107
108 const int __BUFFER_SIZE__ = 1 << 20;
109 bool NEOF = 1;
110 int __top;
111 char __buf[__BUFFER_SIZE__], *__p1 = __buf, *__p2 = __buf, __stk[996];
112 inline char nc()
113 {
114     if (!NEOF)
115         return EOF;
116     if (__p1 == __p2)
117     {
118         __p1 = __buf;
```

```
119     __p2 = __buf + fread(__buf, 1, __BUFFER_SIZE__, stdin);
120     if (__p1 == __p2)
121     {
122         NEOF = 0;
123         return EOF;
124     }
125 }
126 return *__p1++;
127 }
128
129 #define rd read
130 template <typename T>
131 inline bool read(T& x)
132 {
133     char c = nc();
134     bool f = 0;
135     x = 0;
136     while (!isdigit(c)) c == '-' && (f = 1), c = nc();
137     while (isdigit(c)) x = (x << 3) + (x << 1) + (c ^ 48), c = nc();
138     if (f)
139         x = -x;
140     return NEOF;
141 }
142
143 inline bool need(char c) { return (c != '\n') && (c != ' '); }
144
145 inline bool read(char& a)
146 {
147     while ((a = nc()) && need(a) && NEOF)
148         ;
149     return NEOF;
150 }
151
152 inline bool read(char* a)
153 {
154     while ((*a = nc()) && need(*a) && NEOF) ++a;
155     *a = '\0';
156     return NEOF;
157 }
158
159 inline bool read(double& x)
160 {
161     bool f = 0;
162     char c = nc();
163     x = 0;
164     while (!isdigit(c))
165     {
166         f |= (c == '-');
167         c = nc();
168     }
169     while (isdigit(c))
170     {
171         x = x * 10.0 + (c ^ 48);
172         c = nc();
173     }
174     if (c == '.')
175     {
176         double temp = 1;
177         c = nc();
178         while (isdigit(c))
179         {
180             temp = temp / 10.0;
181             x = x + temp * (c ^ 48);
182             c = nc();
183         }
```



```
184     }
185     if (f)
186         x = -x;
187     return NEOF;
188 }
189
190 template <typename First, typename... Rest>
191 inline bool read(First& f, Rest&... r)
192 {
193     read(f);
194     return read(r...);
195 }
196
197 template <typename T>
198 inline void print(T x)
199 {
200     if (x < 0)
201         putchar('-'), x = -x;
202     if (x == 0)
203     {
204         putchar('0');
205         return;
206     }
207     __top = 0;
208     while (x)
209     {
210         __stk[++__top] = x % 10 + '0';
211         x /= 10;
212     }
213     while (__top)
214     {
215         putchar(__stk[__top]);
216         --__top;
217     }
218 }
219
220 template <typename First, typename... Rest>
221 inline void print(First f, Rest... r)
222 {
223     print(f);
224     putchar(' ');
225     print(r...);
226 }
227
228 template <typename T>
229 inline void prints(T x)
230 {
231     print(x);
232     putchar(' ');
233 }
234
235 template <typename T>
236 inline void println(T x)
237 {
238     print(x);
239     putchar('\n');
240 }
241
242 template <typename First, typename... Rest>
243 inline void println(First f, Rest... r)
244 {
245     print(f);
246     putchar(' ');
247     println(r...);
248 }
```

```

249
250 template <typename T>
251 void println(const vector<T>& V)
252 {
253     for (const auto& v : V) print(v), putchar(' ');
254     putchar('\n');
255 }
256
257 mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
258 int rnd(int l, int r) { return l + rng() % (r - l + 1); }
259
260 const int N = 5e5 + 5;
261 const int M = 3e6 + 5;
262 const int K = 1e7 + 5;
263 const int MOD = 1e9 + 7; // 998244353 1e9 + 7
264 const int INF = 0x3f3f3f3f; // 1e9 + 7 0x3f3f3f3f
265 const ll LLINF = 0x3f3f3f3f3f3f3f3f; // 1e18 + 9 0x3f3f3f3f3f3f3f3f
266 const double EPS = 1e-8;
267 const double PI = acos(-1.0);
268
269 int qp(int a, int b, int p = MOD)
270 {
271     int r = 1;
272     for (; b; b >>= 1)
273     {
274         if (b & 1)
275             r = 1ll * r * a % p;
276         a = 1ll * a * a % p;
277     }
278     return r;
279 }
280
281 void solve(int Case)
282 {
283     /* write code here */
284     /* gl & hf */
285 }
286
287 int main()
288 {
289     #ifdef BACKLIGHT
290         freopen("a.in", "r", stdin);
291         // freopen("a.out", "w", stdout);
292         auto begin = std::chrono::steady_clock::now();
293     #endif
294     int T = 1;
295     rd(T);
296     for (int _ = 1; _ <= T; _++) solve(_);
297
298     #ifdef BACKLIGHT
299         auto end = std::chrono::steady_clock::now();
300         auto duration =
301             std::chrono::duration_cast<std::chrono::milliseconds>(end - begin);
302         cerr << "\033[32mTime Elapsed: " << duration.count() << " ms\033[0m"
303              << endl;
304     #endif
305     return 0;
306 }

```

4.3 debug

```

1 #include <bits/stdc++.h>
2 using namespace std;
3

```

```

4 using ll = int64_t;
5 using ull = uint64_t;
6 using uint = uint32_t;
7 using VI = vector<int>;
8 using VL = vector<ll>;
9 using VVI = vector<vector<int>>;
10 using VVL = vector<vector<ll>>;
11 using PII = pair<int, int>;
12 using PLL = pair<ll, ll>;
13
14 #define REP(i, __, __) for (int i = (__); i < (__); ++i)
15 #define PER(i, __, __) for (int i = (__ - 1); i >= (__); --i)
16 #define FOR(i, __, __) for (int i = (__); i <= (__); ++i)
17 #define ROF(i, __, __) for (int i = (__); i >= (__); --i)
18 #define FC(v, V) for (const auto& v : V)
19 #define FE(v, V) for (auto& v : V)
20
21 #define EB emplace_back
22 #define PB push_back
23 #define MP make_pair
24 #define FI first
25 #define SE second
26 #define SZ(x) (int((x).size()))
27 #define ALL(x) (x).begin(), (x).end()
28 #define LLA(x) (x).rbegin(), (x).rend()
29
30 #define rd read
31 #define pr print
32 #define pf printf
33 #define ps prints
34 #define pln println
35
36 #ifdef BACKLIGHT
37 #include "debug.h"
38 #else
39 #define debug(...)
40 #endif
41
42 template <typename T>
43 T MIN(T a, T b)
44 {
45     return min(a, b);
46 }
47
48 template <typename First, typename... Rest>
49 First MIN(First f, Rest... r)
50 {
51     return min(f, MIN(r...));
52 }
53
54 template <typename T>
55 T MAX(T a, T b)
56 {
57     return max(a, b);
58 }
59
60 template <typename First, typename... Rest>
61 First MAX(First f, Rest... r)
62 {
63     return max(f, MAX(r...));
64 }
65
66 template <typename T>
67 inline void umin(T& a, const T& b)
68 {

```

```

69     if (a > b)
70         a = b;
71 }
72
73 template <typename T>
74 inline void umax(T& a, const T& b)
75 {
76     if (a < b)
77         a = b;
78 }
79
80 ll FIRSTTRUE(ll l, ll r, function<bool(ll)> f)
81 {
82     ll res = l - 1, mid;
83     while (l <= r)
84     {
85         mid = (l + r) >> 1;
86         if (f(mid))
87             r = mid - 1, res = mid;
88         else
89             l = mid + 1;
90     }
91     return res;
92 }
93
94 ll LASTTRUE(ll l, ll r, function<bool(ll)> f)
95 {
96     ll res = l - 1, mid;
97     while (l <= r)
98     {
99         mid = (l + r) >> 1;
100        if (f(mid))
101            l = mid + 1, res = mid;
102        else
103            r = mid - 1;
104    }
105    return res;
106 }
107
108 const int __BUFFER_SIZE__ = 1 << 20;
109 bool NEOF = 1;
110 int __top;
111 char __buf[__BUFFER_SIZE__], *__p1 = __buf, *__p2 = __buf, __stk[996];
112 inline char nc()
113 {
114     if (!NEOF)
115         return EOF;
116     if (__p1 == __p2)
117     {
118         __p1 = __buf;
119         __p2 = __buf + fread(__buf, 1, __BUFFER_SIZE__, stdin);
120         if (__p1 == __p2)
121         {
122             NEOF = 0;
123             return EOF;
124         }
125     }
126     return *__p1++;
127 }
128
129 #define rd read
130 template <typename T>
131 inline bool read(T& x)
132 {
133     char c = nc();

```

```
134     bool f = 0;
135     x = 0;
136     while (!isdigit(c)) c == '-' && (f = 1), c = nc();
137     while (isdigit(c)) x = (x << 3) + (x << 1) + (c ^ 48), c = nc();
138     if (f)
139         x = -x;
140     return NEOF;
141 }
142
143 inline bool need(char c) { return (c != '\n') && (c != ' '); }
144
145 inline bool read(char& a)
146 {
147     while ((a = nc()) && need(a) && NEOF)
148         ;
149     return NEOF;
150 }
151
152 inline bool read(char* a)
153 {
154     while ((*a = nc()) && need(*a) && NEOF) ++a;
155     *a = '\0';
156     return NEOF;
157 }
158
159 inline bool read(double& x)
160 {
161     bool f = 0;
162     char c = nc();
163     x = 0;
164     while (!isdigit(c))
165     {
166         f |= (c == '-');
167         c = nc();
168     }
169     while (isdigit(c))
170     {
171         x = x * 10.0 + (c ^ 48);
172         c = nc();
173     }
174     if (c == '.')
175     {
176         double temp = 1;
177         c = nc();
178         while (isdigit(c))
179         {
180             temp = temp / 10.0;
181             x = x + temp * (c ^ 48);
182             c = nc();
183         }
184     }
185     if (f)
186         x = -x;
187     return NEOF;
188 }
189
190 template <typename First, typename... Rest>
191 inline bool read(First& f, Rest&... r)
192 {
193     read(f);
194     return read(r...);
195 }
196
197 template <typename T>
198 inline void print(T x)
```

```
199 {
200     if (x < 0)
201         putchar('-'), x = -x;
202     if (x == 0)
203     {
204         putchar('0');
205         return;
206     }
207     __top = 0;
208     while (x)
209     {
210         __stk[++__top] = x % 10 + '0';
211         x /= 10;
212     }
213     while (__top)
214     {
215         putchar(__stk[__top]);
216         --__top;
217     }
218 }
219
220 template <typename First, typename... Rest>
221 inline void print(First f, Rest... r)
222 {
223     print(f);
224     putchar(' ');
225     print(r...);
226 }
227
228 template <typename T>
229 inline void prints(T x)
230 {
231     print(x);
232     putchar(' ');
233 }
234
235 template <typename T>
236 inline void println(T x)
237 {
238     print(x);
239     putchar('\n');
240 }
241
242 template <typename First, typename... Rest>
243 inline void println(First f, Rest... r)
244 {
245     print(f);
246     putchar(' ');
247     println(r...);
248 }
249
250 template <typename T>
251 void println(const vector<T>& V)
252 {
253     for (const auto& v : V) print(v), putchar(' ');
254     putchar('\n');
255 }
256
257 mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
258 int rnd(int l, int r) { return l + rng() % (r - l + 1); }
259
260 const int N = 5e5 + 5;
261 const int M = 3e6 + 5;
262 const int K = 1e7 + 5;
263 const int MOD = 1e9 + 7;                // 998244353 1e9 + 7
```

```

264 const int INF = 0x3f3f3f3f;           // 1e9 + 7 0x3f3f3f3f
265 const ll LLINF = 0x3f3f3f3f3f3f3f3f; // 1e18 + 9 0x3f3f3f3f3f3f3f3f
266 const double EPS = 1e-8;
267 const double PI = acos(-1.0);
268
269 int qp(int a, int b, int p = MOD)
270 {
271     int r = 1;
272     for (; b; b >>= 1)
273     {
274         if (b & 1)
275             r = 1ll * r * a % p;
276         a = 1ll * a * a % p;
277     }
278     return r;
279 }
280
281 void solve(int Case)
282 {
283     /* write code here */
284     /* gl & hf */
285 }
286
287 int main()
288 {
289     #ifdef BACKLIGHT
290         freopen("a.in", "r", stdin);
291         // freopen("a.out", "w", stdout);
292         auto begin = std::chrono::steady_clock::now();
293     #endif
294     int T = 1;
295     rd(T);
296     for (int _ = 1; _ <= T; _++) solve(_);
297
298     #ifdef BACKLIGHT
299         auto end = std::chrono::steady_clock::now();
300         auto duration =
301             std::chrono::duration_cast<std::chrono::milliseconds>(end - begin);
302         cerr << "\033[32mTime Elapsed: " << duration.count() << " ms\033[0m"
303              << endl;
304     #endif
305     return 0;
306 }

```

4.4 java-header

```

1 import java.io.*;
2 import java.util.*;
3 import java.math.*;
4
5 public class Main {
6     public static void main(String[] args) {
7         InputStream inputStream = System.in;
8         OutputStream outputStream = System.out;
9         InputReader in = new InputReader(inputStream);
10        PrintWriter out = new PrintWriter(outputStream);
11        Task solver = new Task();
12
13        int T = 1;
14        // T = in.nextInt();
15        for (int i = 1; i <= T; ++i)
16            solver.solve(i, in, out);
17
18        out.close();

```

```
19     }
20
21     static class Task {
22         public void solve(int testNumber, InputReader in, PrintWriter out) {
23             // write your solution here
24             out.println("Hello World");
25         }
26     }
27
28     static class InputReader {
29         public BufferedReader reader;
30         public StringTokenizer tokenizer;
31
32         public InputReader(InputStream stream) {
33             reader = new BufferedReader(new InputStreamReader(stream), 32768);
34             tokenizer = null;
35         }
36
37         public String next() {
38             while (tokenizer == null || !tokenizer.hasMoreTokens()) {
39                 try {
40                     tokenizer = new StringTokenizer(reader.readLine());
41                 } catch (IOException e) {
42                     throw new RuntimeException(e);
43                 }
44             }
45             return tokenizer.nextToken();
46         }
47
48         public int nextInt() {
49             return Integer.parseInt(next());
50         }
51     }
52 }
53 }
```

4.5 SimulateAnneal

```
1 struct SimulateAnneal {
2     constexpr static double p = 0.996;
3     inline double Rand() { return 1.0 * rand() / RAND_MAX; }
4
5     int n;
6     vector<int> X, Y, W;
7     double ax, ay;
8
9     SimulateAnneal(int _n) : n(_n), X(n), Y(n), W(n) {}
10
11     void input() {
12         for (int i = 0; i < n; ++i) {
13             read(X[i], Y[i], W[i]);
14         }
15     }
16
17     double cost(double x, double y) {
18         double res = 0;
19         for (int i = 0; i < n; ++i) {
20             double dx = X[i] - x;
21             double dy = Y[i] - y;
22             double d = sqrt(dx * dx + dy * dy);
23             res += d * W[i];
24         }
25         return res;
26     }
27 }
```



```

27
28 void init() {
29     ax = 0; ay = 0;
30     for (int i = 0; i < n; ++i) ax += X[i], ay += Y[i];
31     ax /= n; ay /= n;
32 }
33
34 void simulate_anneal() {
35     srand(time(0));
36     double T = 1e6, TE = 1e-8;
37     double cx = ax, cy = ay, cc = cost(cx, cy);
38     while(T > TE) {
39         double nx = ax + (2 * Rand() - 1) * T;
40         double ny = ay + (2 * Rand() - 1) * T;
41
42         double nc = cost(nx, ny);
43         double d = nc - cc;
44
45         if (d < 0) cc = nc, ax = cx = nx, ay = cy = ny;
46         else if (exp(-d / T) > Rand()) {
47             cx = nx;
48             cy = ny;
49         }
50
51         T *= p;
52     }
53 }
54
55 void work() {
56     init();
57     // try a try, AC is ok.
58     simulate_anneal();
59     simulate_anneal();
60     simulate_anneal();
61     simulate_anneal();
62 }
63 };

```

5 string

5.1 ACAM

```

1 namespace ACAM {
2     const int __N = 3e5 + 5;
3     const int __M = 26;
4     int tot, tr[__N][__M], fail[__N], last[__N];
5     int f[__N], e[__N];
6
7     int eid[__N];
8     multiset<int> st[__N];
9
10    inline int idx(const char& c) { return c - 'a'; }
11
12    inline void init() {
13        tot = 0;
14        memset(tr[0], 0, sizeof(tr[0]));
15        f[0] = e[0] = 0;
16    }
17
18    inline int newnode() {
19        ++tot;
20        memset(tr[tot], 0, sizeof(tr[tot]));
21        f[tot] = e[tot] = 0;

```

```

22     return tot;
23 }
24
25 void insert(char* s, int n, int id) {
26     int p = 0, c;
27     for (int i = 0; i < n; ++i) {
28         c = idx(s[i]);
29         if (!tr[p][c]) tr[p][c] = newnode();
30         p = tr[p][c];
31         ++f[p];
32     }
33     ++e[p];
34
35     eid[id] = p;
36     st[p].insert(0);
37 }
38
39 // 字典图优化
40 // void getfail() {
41 //     queue<int> q;
42 //     for (int i = 0; i < __M; ++i) if (tr[0][i]) fail[tr[0][i]] = 0, q.push(tr[0][i]);
43 //     while(!q.empty()) {
44 //         int p = q.front(); q.pop();
45 //         for (int c = 0; c < __M; ++c) {
46 //             int nxt = tr[p][c];
47 //             if (nxt) fail[nxt] = tr[fail[p]][c], q.push(nxt);
48 //             else nxt = tr[fail[p]][c];
49 //         }
50 //     }
51 // }
52
53 // int query(char* t) {
54 //     int n = strlen(t), p = 0, res = 0;
55 //     for (int i = 0; i < n; ++i) {
56 //         p = tr[p][t[i] - 'a'];
57 //         for (int j = p; j && e[j] != -1; j = fail[j]) res += e[j], e[j] = -1;
58 //     }
59 //     return res;
60 // }
61
62 // 跳 fail 链
63 void getfail() {
64     queue<int> q;
65     fail[0] = 0;
66     for (int c = 0; c < __M; ++c) if (tr[0][c]) fail[tr[0][c]] = last[tr[0][c]] = 0, q.push(tr[0][c]);
67     while(!q.empty()) {
68         int p = q.front(); q.pop();
69         for (int c = 0; c < __M; ++c) {
70             int u = tr[p][c];
71             if (u) {
72                 q.push(u);
73                 int v = fail[p];
74                 while(v && !tr[v][c]) v = fail[v];
75                 fail[u] = tr[v][c];
76                 last[u] = e[fail[u]] ? fail[u] : last[fail[u]];
77             }
78         }
79     }
80 }
81
82 int queryMax(char* t, int n) {
83     int p = 0, res = -1, c;
84     for (int i = 0; i < n; ++i) {
85         c = idx(t[i]);

```

```

87         while(p && !tr[p][c]) p = fail[p];
88         p = tr[p][c];
89         for (int j = p; j; j = last[j]) if (e[j]) updMax(res, (*st[j].rbegin()));
90     }
91     return res;
92 }
93 } // namespace ACAM

```

5.2 GSAM

```

1 namespace GSAM {
2     using T = char;
3
4     inline int idx(T c) { return c - 'a'; }
5
6     const int __N = N << 1;
7     const int __M = 26;
8
9     int tot, next[__N][__M];
10    int len[__N], fail[__N];
11
12    inline void init() {
13        tot = 0;
14        fail[0] = -1; len[0] = 0;
15        memset(next[0], 0, sizeof(next[0]));
16    }
17
18    inline int newnode() {
19        ++tot;
20        fail[tot] = 0; len[tot] = 0;
21        memset(next[tot], 0, sizeof(next[tot]));
22        return tot;
23    }
24
25    void insertTrie(const T* s, int n) {
26        int p = 0, c;
27        for (int i = 0; i < n; ++i) {
28            c = idx(s[i]);
29            if (!next[p][c]) next[p][c] = newnode();
30            p = next[p][c];
31        }
32    }
33
34    int extendSAM(int last, int c) {
35        int cur = next[last][c];
36        if (len[cur]) return cur;
37        len[cur] = len[last] + 1;
38
39        int p = fail[last];
40        while(p != -1) {
41            if (!next[p][c]) next[p][c] = cur;
42            else break;
43            p = fail[p];
44        }
45
46        if (p == -1) {
47            fail[cur] = 0;
48            return cur;
49        }
50
51        int q = next[p][c];
52        if (len[p] + 1 == len[q]) {
53            fail[cur] = q;
54            return cur;

```

```

55     }
56
57     int clone = newnode();
58     for (int i = 0; i < __M; ++i)
59         next[clone][i] = len[next[q][i]] ? next[q][i] : 0;
60
61     len[clone] = len[p] + 1;
62     while(p != -1 && next[p][c] == q) {
63         next[p][c] = clone;
64         p = fail[p];
65     }
66     fail[clone] = fail[q];
67     fail[cur] = clone;
68     fail[q] = clone;
69     return cur;
70 }
71
72 void build() {
73     queue<pair<int, int>> q;
74     for (int i = 0; i < __M; ++i)
75         if (next[0][i]) q.push(make_pair(0, i));
76
77     while(!q.empty()) {
78         pair<int, int> u = q.front(); q.pop();
79         int last = extendSAM(u.first, u.second);
80         for (int i = 0; i < __M; ++i)
81             if (next[last][i]) q.push(make_pair(last, i));
82     }
83 }
84
85 // 多模式串--本质不同子串数
86 ll count() {
87     ll res = 0;
88     for (int i = 1; i <= tot; ++i)
89         res += len[i] - len[fail[i]];
90     return res;
91 }
92 }

```

5.3 KMP

```

1 namespace KMP {
2     // pi_i = s[0...i] 最长 border
3     void getPi(char* s, int n, int* pi) {
4         pi[0] = 0;
5         for (int i = 1; i < n; ++i) {
6             int j = pi[i - 1];
7             while(j > 0 && s[j] != s[i]) j = pi[j - 1];
8             if (s[i] == s[j]) ++j;
9             pi[i] = j;
10        }
11    }
12
13    vector<int> getAllMatchPosition(char* s, int n, int* pi, char* t, int m) {
14        s[n] = '#'; s[n + 1] = 0; ++n;
15        KMP::getPi(s, n, pi);
16
17        vector<int> ans;
18
19        int p = 0;
20        for (int i = 0; i < m; ++i) {
21            while(p > 0 && t[i] != s[p]) p = pi[p - 1];
22            if (t[i] == s[p]) {
23                ++p;

```

```

24         if (p == n - 1) {
25             ans.push_back(i + 2 - n);
26         }
27     }
28 }
29
30 return ans;
31 }
32
33 int getPeriod(int n, int* pi) {
34     return n - pi[n - 1];
35 }
36 }

```

5.4 Manacher

```

1 namespace Manacher {
2     // 1-based
3
4     const int __N = N << 1;
5
6     char s[__N];
7     int n, len[__N];
8
9     // @ t1 t2 t3 \0
10    // ==> @ # t1 # t2 # t3 # \0
11    inline void init(char* t, int m) {
12        n = 2 * m + 1;
13        s[0] = '@'; s[n] = '#'; s[n + 1] = 0;
14        for (int i = 1; i <= m; ++i) {
15            s[2 * i - 1] = '#';
16            s[2 * i] = t[i];
17        }
18    }
19
20    // s[i-len[i]...i+len[i]] is palindromic
21    // len[i]-1 is palindromic length in t
22    void manacher(char* t, int m) {
23        init(t, m);
24        for (int i = 1, l = 0, r = 0, k; i <= n; ++i) {
25            k = i > r ? 1 : min(r - i, len[l + r - i]);
26            while(s[i - k] == s[i + k]) ++k;
27            len[i] = k--;
28            if (i + k > r) {
29                l = i - k;
30                r = i + k;
31            }
32        }
33    }
34
35    int getMaxPalindromicLength(char* t, int m) {
36        manacher(t, m);
37        int ma = 0;
38        for (int i = 1; i <= n; ++i) updMax(ma, len[i]);
39        return ma - 1;
40    }
41 }

```

5.5 PAM

```

1 //最长双倍回文串长度
2 #include<bits/stdc++.h>

```

```

3 using namespace std;
4
5 typedef long long ll;
6 const int N = 5e5 + 5;
7
8 struct Palindromic_Automaton{
9     //0 偶根 1 奇根 range[2-tot]
10    int s[N << 1],now;
11    int next[N << 1][26], fail[N << 1], len[N << 1], last, tot;
12    int cnt[N << 1]; //状态 i 表示的回文串数目
13
14    // extend
15    int trans[N << 1];
16
17    void init(){
18        s[0]=len[1]=-1;
19        fail[0]=tot=now=1;
20        last=len[0]=0;
21        memset(next[0],0,sizeof(next[0]));
22        memset(next[1],0,sizeof(next[1]));
23    }
24    int newnode(){
25        tot++;
26        memset(next[tot],0,sizeof(next[tot]));
27        fail[tot]=cnt[tot]=len[tot]=0;
28        return tot;
29    }
30    int getfail(int x){
31        while(s[now-len[x]-2]!=s[now-1])x=fail[x];
32        return x;
33    }
34    void extend(int c){
35        s[now++]=c;
36        int cur=getfail(last);
37        if(!next[cur][c]){
38            int p=newnode();len[p]=len[cur]+2;
39            fail[p]=next[getfail(fail[cur])][c];
40            next[cur][c]=p;
41
42            // extend
43            if(len[p]<=2)trans[p]=fail[p];
44            else{
45                int tmp=trans[cur];
46                while(s[now-len[tmp]-2] != s[now-1] || (len[tmp]+2)*2>len[p])tmp=fail[tmp];
47                trans[p]=next[tmp][c];
48            }
49        }
50        last=next[cur][c];
51        cnt[last]++;
52    }
53    int count(){return tot-1;}
54    void calc(){
55        for(int i=tot;i>=2;--i) cnt[fail[i]]+=cnt[i];
56        cnt[0]=cnt[1]=0;
57    }
58    int getans(){
59        int ans=0;
60        for(int i=2;i<=tot;i++){
61            if(len[i]>ans && len[trans[i]]*2==len[i] && len[trans[i]]%2==0)ans=len[i];
62        }
63        return ans;
64    }
65 }pam;
66
67 char t[N];

```

```

68
69 int main()
70 {
71     int n;
72     scanf("%d",&n);
73     scanf("%s",t);
74     pam.init();
75     for(int i=0;i<n;++i){
76         pam.extend(t[i]-'a');
77     }
78     printf("%d\n",pam.getans());
79     return 0;
80 }

```

5.6 SA

```

1 namespace SA {
2     // 0 based, 倍增法构建, O(nlogn)
3     int height[N], c[N], x[N], y[N], sa[N], rk[N];
4     void build_sa(int* s, int n) {
5         n++;
6         int i, j, k, m = 256; //m 为字符集大小, max(s[i])<m
7         for (i = 0; i < m; i++) c[i] = 0;
8         for (i = 0; i < n; i++) c[x[i] = s[i]]++;
9         for (i = 1; i < m; i++) c[i] += c[i - 1];
10        for (i = n - 1; i >= 0; i--) sa[--c[x[i]]] = i;
11        for (j = 1; j <= n; j <= 1) {
12            k = 0;
13            for (i = n - j; i < n; i++) y[k++] = i;
14            for (i = 0; i < n; i++) if (sa[i] >= j) y[k++] = sa[i] - j;
15            for (i = 0; i < m; i++) c[i] = 0;
16            for (i = 0; i < n; i++) c[x[y[i]]]++;
17            for (i = 1; i < m; i++) c[i] += c[i - 1];
18            for (i = n - 1; i >= 0; i--) sa[--c[x[y[i]]]] = y[i];
19            swap(x, y);
20            m = 0;
21            x[sa[0]] = m++;
22            for (i = 1; i < n; i++) {
23                if (y[sa[i]] == y[sa[i - 1]] && y[sa[i] + j] == y[sa[i - 1] + j])
24                    x[sa[i]] = m - 1;
25                else
26                    x[sa[i]] = m++;
27            }
28            if (m >= n) break;
29        }
30        k = 0;
31        for (i = 0; i < n; i++) rk[sa[i]] = i;
32        for (i = 0; i < n - 1; i++) {
33            if (k) k--;
34            j = sa[rk[i] - 1];
35            while (s[i + k] == s[j + k]) k++;
36            height[rk[i]] = k;
37        }
38    }
39 }

```

5.7 SAIS

```

1 namespace SAIS {
2     // 1 based, O(n)
3     int s[N << 1], t[N << 1], height[N], sa[N], rk[N], p[N], c[N], w[N];
4     inline int trans(int n, int* S)

```

```

5  {
6      int m = *max_element(S + 1, S + 1 + n);
7      for (int i = 1; i <= n; ++i)
8          rk[S[i]] = 1;
9      for (int i = 1; i <= m; ++i)
10         rk[i] += rk[i - 1];
11     for (int i = 1; i <= n; ++i)
12         s[i] = rk[S[i]];
13     return rk[m];
14 }
15 #define ps(x) sa[w[s[x]]--] = x
16 #define pl(x) sa[w[s[x]]++] = x
17 inline void radix(int* v, int* s, int* t, int n, int m, int n1)
18 {
19     memset(sa, 0, n + 1 << 2);
20     memset(c, 0, m + 1 << 2);
21     for (int i = 1; i <= n; ++i)
22         ++c[s[i]];
23     for (int i = 1; i <= m; ++i)
24         w[i] = c[i] + c[i - 1];
25     for (int i = n1; i; --i)
26         ps(v[i]);
27     for (int i = 1; i <= m; ++i)
28         w[i] = c[i - 1] + 1;
29     for (int i = 1; i <= n; ++i)
30         if (sa[i] > 1 && t[sa[i] - 1])
31             pl(sa[i] - 1);
32     for (int i = 1; i <= m; ++i)
33         w[i] = c[i];
34     for (int i = n; i; --i)
35         if (sa[i] > 1 && !t[sa[i] - 1])
36             ps(sa[i] - 1);
37 }
38 inline void SAIS(int n, int m, int* s, int* t, int* p)
39 {
40     int n1 = 0, ch = rk[1] = 0, *s1 = s + n;
41     t[n] = 0;
42     for (int i = n - 1; i; --i)
43         t[i] = s[i] == s[i + 1] ? t[i + 1] : s[i] > s[i + 1];
44     for (int i = 2; i <= n; ++i)
45         rk[i] = t[i - 1] && !t[i] ? (p[++n1] = i, n1) : 0;
46     radix(p, s, t, n, m, n1);
47     for (int i = 1, x, y; i <= n; ++i)
48         if (x = rk[sa[i]]) {
49             if (ch <= 1 || p[x + 1] - p[x] != p[y + 1] - p[y])
50                 ++ch;
51             else
52                 for (int j = p[x], k = p[y]; j <= p[x + 1]; ++j, ++k)
53                     if ((s[j] << 1 | t[j]) ^ (s[k] << 1 | t[k])) {
54                         ++ch;
55                         break;
56                     }
57             s1[y = x] = ch;
58         }
59     if (ch < n1)
60         SAIS(n1, ch, s1, t + n, p + n1);
61     else
62         for (int i = 1; i <= n1; ++i)
63             sa[s1[i]] = i;
64     for (int i = 1; i <= n1; ++i)
65         s1[i] = p[sa[i]];
66     radix(s1, s, t, n, m, n1);
67 }
68 inline void build_sa(int* S, int n)
69 {

```



```

70     int m = trans(++n, S);
71     SAIS(n, m, s, t, p);
72     for (int i = 1; i < n; ++i)
73         rk[sa[i] = sa[i + 1]] = i;
74     for (int i = 1, j, k = 0; i < n; ++i)
75         if (rk[i] > 1) {
76             for (j = sa[rk[i] - 1]; S[i + k] == S[j + k]; ++k)
77                 ;
78             if (height[rk[i]] = k)
79                 --k;
80         }
81     }
82 }

```

5.8 SAM

```

1  //广义后缀自动机: insert 后重新将 last 赋 1 (复杂度好像有可能退化)
2  #include<bits/stdc++.h>
3  using namespace std;
4
5  typedef long long ll;
6  const int maxn=1e6+5;
7
8  char s[maxn];
9  struct Suffix_Automaton
10 {
11     //初始状态为 0, range[0...tot-1]
12     struct state{
13         int len, link;
14         map<char, int> next;
15     }st[maxn<<1];
16     int last, tot;
17
18     void init(){
19         st[0].len=0; st[0].link=-1;
20         tot++;
21         last=0;
22     }
23
24     void extend(char c){
25         int cur=tot++;
26         st[cur].len=st[last].len+1;
27         int p=last;
28         while(p!=-1 && !st[p].next.count(c)){
29             st[p].next[c]=cur;
30             p=st[p].link;
31         }
32         if(p==-1) st[cur].link=0;
33         else{
34             int q=st[p].next[c];
35             if(st[p].len+1==st[q].len) st[cur].link=q;
36             else{
37                 int clone=tot++;
38                 st[clone].len=st[p].len+1;
39                 st[clone].next=st[q].next;
40                 st[clone].link=st[q].link;
41                 while(p!=-1 && st[p].next[c]==q){
42                     st[p].next[c]=clone;
43                     p=st[p].link;
44                 }
45                 st[q].link=st[cur].link=clone;
46             }
47         }
48         last=cur;

```

```

49     }
50
51     ll count(){
52         ll res=0;
53         for(int i=0;i<tot;i++)res+=st[i].len-st[st[i].link].len;
54         return res;
55     }
56 } sam;
57
58 int main()
59 {
60     scanf("%s",s);
61     sam.init();
62     for(int i=0;s[i]!=0;i++)sam.extend(s[i]);
63     printf("%lld\n",sam.count());
64     return 0;
65 }

```

5.9 SqAM

```

1  /**
2   * 识别一个串的子序列,  $O(n^2)$ 
3   * 用法类似后缀自动机
4   */
5  struct SqAM{
6      int next[N << 1][26], pre[N << 1], lst[26];
7      int root, tot;
8      void init(){
9          root = tot = 1;
10         for(int i = 0; i < 26; i++) lst[i] = 1;
11     }
12
13     void extend(int c){
14         int p = lst[c], np = ++tot;
15         pre[np] = p;
16         for (int i = 0; i < 26; i++)
17             for (int j = lst[i]; j && !next[j][c]; j = pre[j])
18                 next[j][c] = np;
19         lst[c]=np;
20     }
21 };

```

5.10 string-hash

```

1  namespace Hash {
2      // 1 based, double hash
3      typedef long long ll;
4      const ll P1 = 29;
5      const ll P2 = 131;
6      const ll MOD1 = 1e9 + 7;
7      const ll MOD2 = 1e9 + 9;
8      ll p1[N], p2[N], h1[N], h2[N];
9      void init_hash(char* s, int n) {
10         p1[0] = p2[0] = 1;
11         for(int i = 1; i <= n; i++) p1[i] = (p1[i - 1] * P1) % MOD1;
12         for(int i = 1; i <= n; i++) p2[i] = (p2[i - 1] * P2) % MOD2;
13         for(int i = 1; i <= n; i++) h1[i] = (h1[i - 1] * P1 + s[i]) % MOD1;
14         for(int i = 1; i <= n; i++) h2[i] = (h2[i - 1] * P2 + s[i]) % MOD2;
15     }
16
17     ll get_hash(int l, int r) {
18         ll H1 = ((h1[r] - h1[l - 1] * p1[r - l + 1]) % MOD1 + MOD1) % MOD1;

```

```

19         ll H2 = ((h2[r] - h2[l - 1] * p2[r - 1 + 1]) % MOD2 + MOD2) % MOD2;
20         return H1 * MOD2 + H2;
21     }
22 }

```

5.11 SuffixBST

```

1  /**
2   * 1. 在当前字符串的后面插入字符
3   * 2. 在当前字符串的后面删除字符
4   * 3. 询问字符串 t 作为连续子串在当前字符串中出现了几次
5   */
6  #include <bits/stdc++.h>
7  using namespace std;
8
9  const int    N    = 8e5 + 5;
10 const double INF = 1e18;
11
12 void decode( char* s, int len, int mask )
13 {
14     for ( int i = 0; i < len; ++i )
15     {
16         mask = ( mask * 131 + i ) % len;
17         swap( s[ i ], s[ mask ] );
18     }
19 }
20
21 int q, n, na;
22 char a[ N ], t[ N ];
23
24 // SuffixBST(SGT Ver)
25
26 // 顺序加入，查询时将询问串翻转
27 // 以 i 结束的前缀，对应节点的编号为 i
28 // 注意：不能写懒惰删除，否则可能会破坏树的结构
29 const double alpha = 0.75;
30 int root;
31 int sz[ N ], L[ N ], R[ N ];
32 double tag[ N ];
33 int buffer_size, buffer[ N ];
34
35 bool cmp( int x, int y )
36 {
37     if ( t[ x ] != t[ y ] )
38         return t[ x ] < t[ y ];
39     return tag[ x - 1 ] < tag[ y - 1 ];
40 }
41
42 void init()
43 {
44     root = 0;
45 }
46
47 void new_node( int& rt, int p, double lv, double rv )
48 {
49     rt = p;
50     sz[ rt ] = 1;
51     tag[ rt ] = ( lv + rv ) / 2;
52     L[ rt ] = R[ rt ] = 0;
53 }
54
55 void push_up( int x )
56 {
57     if ( !x )

```

```
58     return;
59     sz[ x ] = sz[ L[ x ] ] + 1 + sz[ R[ x ] ];
60 }
61
62 bool balance( int rt )
63 {
64     return alpha * sz[ rt ] > max( sz[ L[ rt ] ], sz[ R[ rt ] ] );
65 }
66
67 void flatten( int rt )
68 {
69     if ( !rt )
70         return;
71     flatten( L[ rt ] );
72     buffer[ ++buffer_size ] = rt;
73     flatten( R[ rt ] );
74 }
75
76 void build( int& rt, int l, int r, double lv, double rv )
77 {
78     if ( l > r )
79     {
80         rt = 0;
81         return;
82     }
83     int mid = ( l + r ) >> 1;
84     double mv = ( lv + rv ) / 2;
85
86     rt = buffer[ mid ];
87     tag[ rt ] = mv;
88     build( L[ rt ], l, mid - 1, lv, mv );
89     build( R[ rt ], mid + 1, r, mv, rv );
90     push_up( rt );
91 }
92
93 void rebuild( int& rt, double lv, double rv )
94 {
95     buffer_size = 0;
96     flatten( rt );
97     build( rt, 1, buffer_size, lv, rv );
98 }
99
100 void insert( int& rt, int p, double lv, double rv )
101 {
102     if ( !rt )
103     {
104         new_node( rt, p, lv, rv );
105         return;
106     }
107
108     if ( cmp( p, rt ) )
109         insert( L[ rt ], p, lv, tag[ rt ] );
110     else
111         insert( R[ rt ], p, tag[ rt ], rv );
112
113     push_up( rt );
114     if ( !balance( rt ) )
115         rebuild( rt, lv, rv );
116 }
117
118 void remove( int& rt, int p, double lv, double rv )
119 {
120     if ( !rt )
121         return;
122 }
```

```

123     if ( rt == p )
124     {
125         if ( !L[ rt ] || !R[ rt ] )
126         {
127             rt = ( L[ rt ] | R[ rt ] );
128         }
129         else
130         {
131             // 找到 rt 的前驱来替换 rt
132             int nrt = L[ rt ], fa = rt;
133             while ( R[ nrt ] )
134             {
135                 fa = nrt;
136                 sz[ fa ]--;
137                 nrt = R[ nrt ];
138             }
139             if ( fa == rt )
140             {
141                 R[ nrt ] = R[ rt ];
142             }
143             else
144             {
145                 L[ nrt ] = L[ rt ];
146                 R[ nrt ] = R[ rt ];
147                 R[ fa ] = 0;
148             }
149             rt = nrt;
150             tag[ rt ] = ( lv + rv ) / 2;
151         }
152     }
153     else
154     {
155         double mv = ( lv + rv ) / 2;
156         if ( cmp( p, rt ) )
157             remove( L[ rt ], p, lv, mv );
158         else
159             remove( R[ rt ], p, mv, rv );
160     }
161
162     push_up( rt );
163     if ( !balance( rt ) )
164         rebuild( rt, lv, rv );
165 }
166
167 bool cmp1( char* s, int len, int p )
168 {
169     for ( int i = 1; i <= len; ++i, --p )
170     {
171         if ( s[ i ] < t[ p ] )
172             return true;
173         if ( s[ i ] > t[ p ] )
174             return false;
175     }
176 }
177
178 int query( int rt, char* s, int len )
179 {
180     if ( !rt )
181         return 0;
182     if ( cmp1( s, len, rt ) )
183         return query( L[ rt ], s, len );
184     else
185         return sz[ L[ rt ] ] + 1 + query( R[ rt ], s, len );
186 }
187

```

```
188 void solve( int Case )
189 {
190     n = 0;
191     scanf( "%d", &q );
192     init();
193
194     scanf( "%s", a + 1 );
195     na = strlen( a + 1 );
196     for ( int i = 1; i <= na; ++i )
197     {
198         t[ ++n ] = a[ i ];
199         insert( root, n, 0, INF );
200     }
201
202     int mask = 0;
203     char op[ 10 ];
204     for ( int i = 1; i <= q; ++i )
205     {
206         scanf( "%s", op );
207         if ( op[ 0 ] == 'A' )
208         {
209             scanf( "%s", a + 1 );
210             na = strlen( a + 1 );
211             decode( a + 1, na, mask );
212
213             for ( int i = 1; i <= na; ++i )
214             {
215                 t[ ++n ] = a[ i ];
216                 insert( root, n, 0, INF );
217             }
218         }
219         else if ( op[ 0 ] == 'D' )
220         {
221             int x;
222             scanf( "%d", &x );
223             while ( x )
224             {
225                 remove( root, n, 0, INF );
226                 --n;
227                 --x;
228             }
229         }
230         else if ( op[ 0 ] == 'Q' )
231         {
232             scanf( "%s", a + 1 );
233             na = strlen( a + 1 );
234             decode( a + 1, na, mask );
235
236             reverse( a + 1, a + 1 + na );
237
238             a[ na + 1 ] = 'Z' + 1;
239             a[ na + 2 ] = 0;
240             int ans = query( root, a, na + 1 );
241
242             --a[ na ];
243             ans -= query( root, a, na + 1 );
244
245             printf( "%d\n", ans );
246             mask ^= ans;
247         }
248     }
249 }
250
251 int main()
252 {
```

```

253     int T = 1;
254     for ( int i = 1; i <= T; ++i )
255         solve( i );
256     return 0;
257 }

```

5.12 Trie

```

1  namespace Trie {
2      // 1-based
3      const int __N = 4e6 + 5;
4      const int __M = 26;
5      int tot;
6      int ch[__N][__M];
7      int f[__N], e[__N];
8
9      inline void init() {
10         tot = 0;
11         memset(ch[0], 0, sizeof(ch[0]));
12         f[0] = e[0] = 0;
13     }
14
15     inline int newnode() {
16         ++tot;
17         memset(ch[tot], 0, sizeof(ch[tot]));
18         f[tot] = e[tot] = 0;
19         return tot;
20     }
21
22     inline int idx(char c) { return c - 'a'; }
23
24     void insert(char* s) {
25         int n = strlen(s + 1), p = 0, c;
26         for (int i = 1; i <= n; ++i) {
27             c = idx(s[i]);
28             if (!ch[p][c]) ch[p][c] = newnode();
29             p = ch[p][c];
30             ++f[p];
31         }
32         ++e[p];
33     }
34
35     int query(char* s) {
36         int p = 0, n = strlen(s + 1), c;
37         for(int i = 1; i <= n; i++){
38             c = idx(s[i]);
39             if(!ch[p][c]) return 0;
40             p = ch[p][c];
41         }
42         return e[p];
43     }
44 }

```

5.13 ZAlgorithm

```

1  namespace ZAlgorithm {
2      // 1-based
3
4      // z_i = LCP(s, s[i..n])
5      void getZ(char* s, int n, int* z) {
6          z[1] = n;
7          for (int i = 2, l = 0, r = 0; i <= n; ++i) {

```

```
8         if (i <= r) z[i] = min(r - i + 1, z[i - 1 + 1]);
9         else z[i] = 0;
10        while(i + z[i] <= n && s[z[i] + 1] == s[i + z[i]]) ++z[i];
11        if (i + z[i] - 1 > r) l = i, r = i + z[i] - 1;
12    }
13 }
14
15 // p_i = LCP(s, t[i...m])
16 void EXKMP(char* s, int n, int* z, char* t, int m, int* p) {
17     getZ(s, n, z);
18     for (int i = 1, l = 0, r = 0; i <= m; ++i) {
19         if (i <= r) p[i] = min(r - i + 1, z[i - 1 + 1]);
20         else p[i] = 0;
21         while(i + p[i] <= m && s[p[i] + 1] == t[i + p[i]]) ++p[i];
22         if (i + p[i] - 1 > r) l = i, r = i + p[i] - 1;
23     }
24 }
25 }
```
