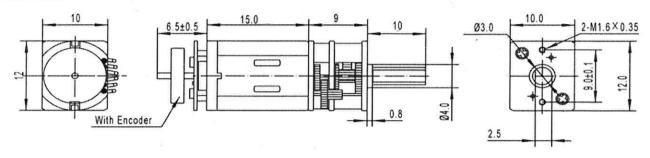
Micro Metal Gearmotor with 12CPR Encoder

Dimensions:

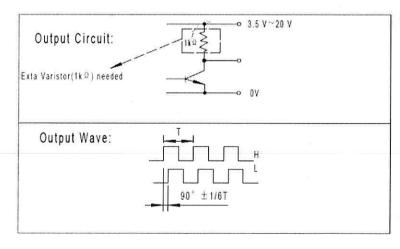


Micro Metal Gearmotor with 12CPR Encoder(Units in MM)

Two Channel Hall Effect Encoder Operating relative humidity $20\% \sim 85\%$ RH Operating temperature range $-10\% \sim +85\%$

ELECTRICAL CHARACTERISTICS

CHARACTERISTICS	SYMBOL	TEST CONDITIONS	MIN.	REF.	MAX.	UNITS
Input Voltage	Vcc		3.5		20	Ÿ
Output Saturation Voltage	Vce(sat)	Vcc=14V;fc=20mA		300	700	mV
Output Leakage Current	lcex	Vce=14V;Vcc=14V		< 0.1	10	μV
Input Current	Ice	Vcc=20V; Output open	-	5	10	mA
Output Rise Time	tr	Vcc=14V;RL=820Ω;CL=20pF	=	0.3	1.5	μS
Output Fall Time	t _f	Vcc=14V;RL=820Ω;Q =20pF		0.3	1.5	μS



Connectors: JST PHR-6

Two Channel Encoder

Connecttions:

1. Black: -motor

2 Red : +motor

3. Brown: HALL SENSOR Vcc

4. Green : HALL SENSOR GND

5. Blue: HALL SENSOR A Vout

6. Purple: HALL SENSOR B Vout