

All watched over by machines of loving grace

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Abstract

Modern operating systems are typically built around a trusted system component called the *kernel* which amongst other things is charged with enforcing system-wide security policies. Crucially, this component must be kept isolated from untrusted software at all times, which is facilitated by exploiting machine-oriented notions of separation: private memories, privilege levels, and similar.

Modern proof-assistants are typically built around a trusted system component called the *kernel* which is charged with enforcing system-wide soundness. Crucially, this component must be kept isolated from untrusted automation at all times, which is facilitated by exploiting programming-language notions of separation: module-private data structures, type-abstraction, and similar.

Whilst markedly different in purpose, in some essential ways operating system and proof-assistant kernels are tasked with the same job, namely enforcing system-wide invariants in the face of unbridled interaction with untrusted code. Yet the mechanisms through which the two types of kernel protect themselves are significantly different. In this paper, we introduce *Supervisory*, the kernel of a prototype programmable proof-checking system for Gordon’s HOL that is organised in a manner more reminiscent of operating systems than typical LCF-style proof-checkers. *Supervisory* implements a kernel that executes at a relative level of privilege compared to untrusted automation, with trusted and untrusted system components communicating across a limited system call boundary to indirectly manipulate kernel objects managed by the *Supervisory* kernel denoted by handles.

Unusually, *Supervisory* has no “metalanguage” in the LCF sense, as the language used to implement the kernel, and the language used to implement automation, need not be the same. *Any* programming language can be used to implement automation for *Supervisory*, providing the resulting binary respects the *Supervisory* kernel calling convention and binary interface, with no risk to system soundness. Further, we observe that *Supervisory* allows arbitrary programming languages to be endowed with facilities for proof-checking. Indeed, the handles that *Supervisory* uses to reference kernel objects under its management may be thought of as a form of *capability*, in the computer security sense. Moreover, these capabilities are extremely expressive, essentially capturing the full expressive power of HOL, and can potentially be used to enforce fine-grained correctness and security properties of programs at runtime.

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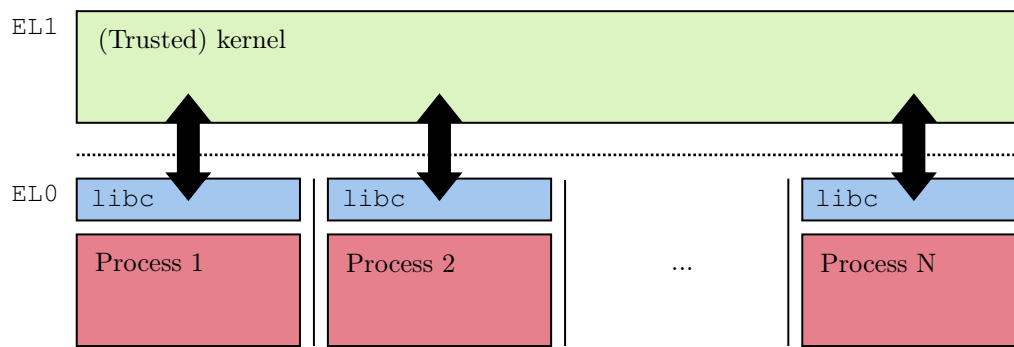
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1 Introduction

This paper studies the intersection of operating system design and implementations of the foundations of mathematics. Research into the confluence of these two topics is, admittedly, a rather moribund affair at the moment. Nevertheless, with this paper we hope to convince the reader that probing the intersection of these two areas is potentially very interesting by introducing *Supervisory*, a programmable proof-checking system for Gordon’s HOL. This system has a novel system design, with some interesting properties, and moreover some

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■ **Figure 1** A schematic of the typical system organization of a commodity operating system and its associated user-space. The kernel (in green) executes at a relative level of privilege, enforced by hardware, compared to processes executing in user-space (red)—we follow the Arm convention and show the kernel executing at **EL1** and user-space at **EL0**. The two communicate across a system call boundary (dashed line) using system calls (black arrows). User-space programs are typically written making use of an abstraction library, such as `libc` (blue), to abstract over this kernel interface.

45 interesting consequences. First, however, we begin with a scene-setting overview of common
46 principles in operating system design and implementation.

47 1.1 On operating systems

48 Most commodity operating systems—that is, Microsoft Windows and Unix-derivatives²—fit
49 a common pattern and are architected around a relatively self-contained, trusted component
50 typically called the system *kernel*.

51 The kernel is the sole component that can interface unfettered with all system resources,
52 including devices and other system hardware. Untrusted user-space applications make use of
53 kernel interfaces in order to make use of a device or any other system resource managed by
54 the kernel. As a result, the kernel is essentially a “pinch point” for gating access to system
55 resources. The kernel also introduces a process abstraction in user-space and is responsible
56 for ensuring the confidentiality and integrity of processes from other, concurrently executing
57 processes. The kernel is therefore *the* key component responsible for enforcing system-wide
58 security policies, and essentially forms the “root of all trust” within a computing system. It
59 is therefore imperative that the kernel is itself isolated sufficiently from user-space software
60 at all times, lest this role be undermined by a malefactor.

61 The kernel self-isolates by entering into a grand conspiracy with its host hardware. In
62 support of this conspiracy, mainstream microprocessors have, over the years, accreted a
63 variety of now-familiar security features that an operating system kernel can use to defend
64 itself from prying or interference. These include *exception levels* or *privilege rings*—as they
65 are variously called, depending on the instruction set architecture—which introduce a notion
66 of *privilege* into the system. Here, software executing at higher-privilege—in our case, an
67 operating system kernel³—gains permission to program sensitive system registers, controlling
68 how the system operates. Moreover, software executing at a higher-level of privilege can “peer

² *Commodity* here is used to guard against pedantic quibbling over research operating system designs—like exokernels and other oddities—which arguably do not fit this pattern

³ Note that “Cloud hosting” as a viable business proposition essentially rests on this trick being repeated again, with a hypervisor sat in a position of privilege compared to an operating system kernel—executing out of an even higher exception level—and enforcing separation betwixt operating system instances.

in” and potentially modify the runtime state of software executing at a relatively lower-level of privilege, reading data from, or writing data to, a buffer within the memory space of an untrusted user-space process, for example. In this sense, a kernel can “supervise” or “watch over” untrusted user-space—essentially the inspiration for the, possibly now archaic, alternative phrasing for an operating system kernel: *supervisor*.

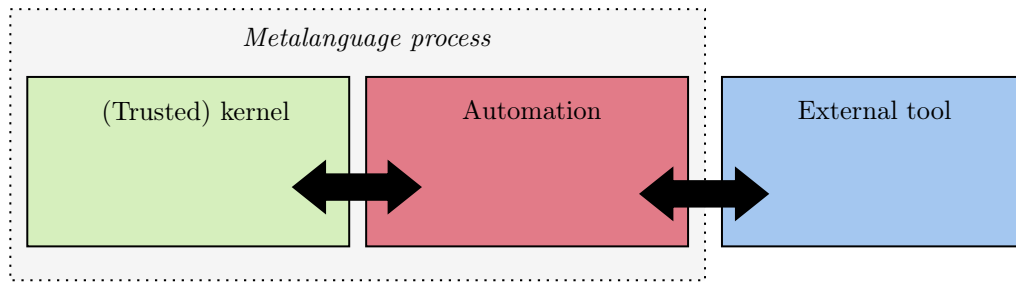
Moreover, modern microprocessors also provide a form of memory management built around page tables. These data structures have a dual role: primarily, they are used for the virtualisation of system memory via address translation, granting user-space software the illusion that it owns the entire physical address space of the machine, by presenting a virtual address space to user-space programs. Essentially, address translation induces a notion of *ownership* of pages of physical memory within the system, with a page of physical memory “owned” by a principal (either the operating system, or a user-space process) if it is “mapped in” to that principal’s address space. Moreover, page tables are also used for storing the attributes of pages of memory, including read-write-execute permissions. By correctly initialising and managing these tables the kernel is able to keep its own code and data structures isolated—in a kernel-private memory area—that only it can access, safe from prying or interference by untrusted user-space. As a result, for systems software on modern machines, isolation is enforced by a mix of low-level machine mechanisms: separate address spaces, private memory regions, and machine-enforced privilege checks on executing software.

To make itself useful, the kernel exposes a limited interface, used by user-space to request intercession by the kernel on its behalf—for example by granting user-space access to some device, the filesystem, a socket, or some other system resource under kernel management. Dealing in generalities, to do this, the kernel exposes a suite of *system calls* which can be invoked by user-space programs with dedicated machine instructions provided by the microprocessor—see Figure 1 for a diagrammatic schematic, for example. On Arm platforms, with which the author is most familiar, these instructions induce a type of processor exception, inducing a *context switch* which flips the flow of control into the kernel’s system call handler before eventually returning the flow of control back to the calling user-space program. From user-space’s point-of-view, system calls therefore have the appearance and effect of very CISC-like machine instructions, with the operating system kernel essentially presenting itself to user-space as “silicon by other means”, extending the user-space fragment of the instruction set architecture of the microprocessor with new instructions.

Note that for this two-way dance to work, user-space and the kernel must work together by adopting a series of joint conventions. These include a *calling convention* describing how arguments and results are passed back-and-forth across the system call interface, and a *binary interface* detailing how system calls are identified, how errors are reported back to user-space, and other miscellanea. To help programmers adhere to these conventions, the operating system typically provides an abstraction layer to user-space, which on Unix variants typically takes the form of the system’s C library, `libc`. Note that this is generally just a convenience, and user-space software can always invoke system calls directly if wanted by invoking the correct machine instruction and adhering to the appropriate calling convention.⁴

However, crucially, it is *generally* not the case that the operating system kernel and untrusted user-space applications need be written in the same programming language for

⁴ This is the case on Linux, though does not hold universally on all Unix derivatives. For example Apple’s MacOS and some BSD Unix variants generally consider the programming interface of the system C library as the interface of the kernel, proper, in some cases preventing any user-space code other than the system’s `libc` library from invoking system calls directly, as a security mechanism.



■ **Figure 2** A schematic of the system organisation of a typical LCF-style proof assistant. The trusted kernel (green) is linked against untrusted automation (red) existing within the same metalanguage process (dotted line) and communicate with each other using the kernel’s API (black arrow). External tools existing as separate processes (blue, must communicate with a shim layer written in the proof assistant’s metalanguage to access the kernel (black arrow).

112 this all to work. In particular, whilst most operating system kernels are written in C, or a
 113 C-language derivative, user-space programs can be written in a variety of languages, and are
 114 also commonly composed of multiple libraries, written in different programming languages,
 115 linked together. Despite this, all are able to make use of system resources exposed by the
 116 kernel’s system call interface by ensuring that they adhere to the calling convention and
 117 binary interface expected by the kernel. In this respect, for commodity operating systems,
 118 the C-language may have prominence as the favoured language of system implementation,
 119 but by-and-large it is not *special* or given an unduly prominent status by the kernel itself.

120 1.2 On programmable proof-checkers

121 Most modern proof-assistants—for example, systems in the wider HOL family, Coq, Matita,
 122 PRL, and similar—fit a common pattern and are architected around a relatively self-contained,
 123 trusted component typically called the system *kernel*.

124 The system kernel is the sole component that can authenticate claims as legitimate
 125 theorems of the implemented logic. Untrusted automation, residing outside of the kernel,
 126 must “drive” the kernel to derive a theorem on its behalf. The kernel is therefore *the*
 127 component responsible for ensuring system-wide soundness, and represents the “root of all
 128 trust” within the system. It is therefore imperative that the kernel is able to isolate itself
 129 sufficiently from untrusted automation at all times. This method of system organisation is
 130 known as *the LCF approach* after Milner’s eponymous system which first introduced it, and
 131 is now the most common way of organising proof-checking systems today. See Figure 2 for a
 132 diagrammatic representation.

133 Most modern proof-assistants tend to be written in a “metalanguage” which serves as the
 134 implementation language for both the kernel and the majority of the untrusted automation
 135 that modern proof-assistants provide to users. This metalanguage is typically a strongly-
 136 typed functional programming language, for example an ML derivative such as OCaml or
 137 SML, which offer strong modularity and abstraction features. The kernel exploits these
 138 programming language features to hide its own data structures from untrusted automation
 139 and moreover exposes a carefully limited API for proof-construction and manipulation.
 140 Notably, in an LCF-style system, the *only* mechanism automation has for constructing an
 141 authenticated theorem is by using this API, with the inference rules of the logic exposed as
 142 a suite of “smart constructors” manipulating an abstract type of theorems. As a result, the
 143 kernel is therefore a “pinch point” for any proof-construction activity within the system.

Untrusted automation and the system kernel are linked together, and reside side-by-side in the same process when the proof-assistant is executed. As a result, system soundness ultimately rests on the soundness of the implementation metalanguage’s type-system—specifically its ability to correctly isolate module-private data structures—that is, its ability to correctly enforce type abstraction. Moreover, the system metalanguage is, in a sense, unique amongst all programming languages, in that it is the *only* language capable of interfacing directly with the kernel, which is, after all, “just” a module written in that language, like any other. Whilst external tools, and automation written in other languages, can interface with the kernel, it must do so indirectly, making use of a shim layer written in the system metalanguage.

1.3 Introducing the Supervisory system

In many respects, as the text above intimates, the role of the kernel in both an operating system and in a proof-assistant is, at least in an abstract sense, the same: both components must enforce system-wide invariants in the face of unbridled interaction with untrusted code; both components also act as the “root of all trust” for their respective systems; both components act as “pinch points” that untrusted code cannot help interact with, if it wishes to engage in some kernel-gated activity. Consequently, both type of kernel need to correctly isolate their data structures and runtime state from interference by untrusted code. However, the two mechanisms through which this self-isolation are enforced are different: for operating system kernels⁵ self-isolation is enforced using machine-oriented mechanisms; for LCF-style proof-assistants, self-isolation is enforced using programming language-oriented mechanisms.

In this paper we introduce *Supervisory*, the kernel of a novel programmable proof-assistant for Gordon’s HOL.⁶ Whilst detailed further in Section 3, we note here that Supervisory’s system design has more in common with the typical system organisation of an operating system than comparable implementations of HOL. Specifically, the Supervisory kernel executes at a relative level of privilege compared to untrusted automation, which can be thought of as executing as a process in something akin to Supervisory’s version of “user space”. The trusted kernel, and untrusted user space, communicate across a system call boundary, and which must be carefully designed in order to ensure system soundness.

One consequence of this design is that the Supervisory kernel immediately takes on a different character to an LCF kernel. All of the paraphernalia of a typical HOL implementation—type-formers, types, constants, terms, and theorems—are managed as “kernel objects” kept safely under the management of the kernel itself, in kernel-private memory areas. These kernel objects are never exposed *directly* to user-space, rather, they are manipulated by the Supervisory kernel on user-space’s behalf. Handles—intuitively be thought of as pointers, pointing into Supervisory’s private memories—are used by a user-space process to identify kernel objects that the kernel should manipulate or query.

Notably, Supervisory is also not implemented in a typed functional programming language, as is typical of most programmable proof-assistants, but is rather implemented in the decidedly *unsafe* systems programming language, Rust. Note that this decision introduces

⁵ Barring unikernels, or library operating systems, like Mirage. If we are really pushing this analogy note that unikernels are in some respects quite similar to LCF-style proof-assistants in this regard, having their kernel linked with untrusted “user-space” and separated using programming language features like modules, rather than privilege and memory isolation.

⁶ Many of the ideas presented henceforth are logic-independent. Though we have chosen to use HOL in our prototype, the ideas presented herein can be applied to a wide variety of other logics and type theories with relatively minimal changes.

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no risk to system soundness, as Supervisory’s soundness ultimately rests on the continued separation of kernel-private data from Supervisory’s analogue of user-space—using privilege and private memories—and not on the type system of the implementation programming language. Moreover, as user-space and kernel communicate across a defined system call interface, untrusted user-space may also be written in *any* programming language capable of producing code that is binary-compatible with the Supervisory kernel. Supervisory therefore has no “metalanguage” in the LCF sense, but rather an implementation language, with automation potentially written in multiple languages—maybe even a mix.

For ease of implementation—and use!—we implement Supervisory as a WebAssembly (or Wasm, henceforth) host. Specifically, we extend a Wasm virtual machine with new system calls that perform a context switch into Supervisory—the *host*—which has its own memory isolated from the memory of the executing user-space Wasm process running under its supervision, and inaccessible to it. Note that this separation is only one way: the Supervisory kernel can still “peer in” to the runtime state of a running Wasm process and read from, and write to, its private memories. This decision means we may experiment with the fundamental ideas behind Supervisory—namely isolating the kernel using private memory areas, the split between kernel- and “user-space”, a kernel system call interface—without becoming bogged down in extraneous detail associated with the booting ceremony of a real machine. Moreover, we harness work on porting compiler and linker toolchains, allowing our “user space” to be written in any programming language with a toolchain capable of targeting Wasm.

Lastly, and more speculatively, Supervisory’s handles can be passed around a program, or even between different programs executing concurrently or sequentially under Supervisory’s management. Whilst this property is not unique to Supervisory—values of the abstract type of theorems may also be passed around within any LCF-style system, for example—the objects which these handles denote can themselves be *functions* of the runtime state of the program itself, or of the Supervisory kernel. Note that this *is* unique to Supervisory, as it rests on Supervisory’s dual status as a proof-assistant kernel, capable of generating theorems, and an extension of a general purpose virtual machine, capable of executing arbitrary programs, as well as the Supervisory kernel’s status as executing at a relative level of privilege compared to user-space software executing under it. Here, Supervisory once again represents a “pinch point” that user-space cannot help pass through in order to have any sort of computational effect—other than heating the CPU—on the machine, and Supervisory may also use its privileged status to “peer in” to the runtime state of any user-space process executing under its supervision and essentially check that the process is behaving correctly.

Whilst exploring this idea is future work, some ideas of how this idea could develop are discussed in Section 4. But quickly, here, consider one example where this may be useful: Supervisory could present an extended system call interface to user-space, including system calls for filesystem manipulation, socketed network communication, and all other services typical of an operating system. Prior to opening or modifying a file or other system resource on a program’s behalf, Supervisory could “challenge” the program to first produce a handle denoting a theorem object with a statement expressing some instantiation of a security or correctness policy enforced at runtime by Supervisory. In particular, the statement of these theorems can be parametric in the runtime state of the kernel, or of the arguments passed to the system call—a function of the filename of the file to be opened or modified, for example, or the content to be written to the file. Essentially now, Supervisory’s handles are transformed from simple pointers denoting kernel objects into *capabilities*, in

$$\begin{array}{c}
\frac{r : \tau}{\Gamma \vdash r = r} \quad \frac{\Gamma \vdash r = s}{\Gamma \vdash s = r} \quad \frac{\Gamma \vdash r = s \quad \Gamma' \vdash s = t}{\Gamma \cup \Gamma' \vdash r = t} \quad \frac{\phi \in \Gamma}{\Gamma \vdash \phi} \quad \frac{\Gamma \vdash \perp \quad \phi : \text{bool}}{\Gamma \vdash \phi} \\
\\
\frac{}{\Gamma \vdash \top} \quad \frac{\Gamma \vdash \phi \quad \Gamma' \vdash \psi}{\Gamma \cup \Gamma' \vdash \phi \wedge \psi} \quad \frac{\Gamma \vdash \phi \wedge \psi}{\Gamma \vdash \phi} \quad \frac{\Gamma \vdash \phi \wedge \psi}{\Gamma \vdash \psi} \quad \frac{\Gamma \cup \{\phi\} \vdash \psi \quad \phi : \text{bool}}{\Gamma \vdash \phi \longrightarrow \psi} \\
\\
\frac{\Gamma \vdash \phi \longrightarrow \psi \quad \Gamma' \vdash \phi}{\Gamma \cup \Gamma' \vdash \psi} \quad \frac{\Gamma \vdash \phi \quad \psi : \text{bool}}{\Gamma \vdash \phi \vee \psi} \quad \frac{\Gamma \vdash \psi \quad \phi : \text{bool}}{\Gamma \vdash \phi \vee \psi} \quad \frac{\Gamma \vdash \phi = \psi \quad \Gamma' \vdash \phi}{\Gamma \cup \Gamma' \vdash \psi} \\
\\
\frac{\Gamma \vdash \phi \vee \psi \quad \Gamma' \cup \{\phi\} \vdash \xi \quad \Gamma'' \cup \{\psi\} \vdash \xi}{\Gamma \cup \Gamma' \cup \Gamma'' \vdash \xi} \quad \frac{\Gamma \vdash \phi \longrightarrow \psi \quad \Gamma' \vdash \psi \longrightarrow \phi}{\Gamma \cup \Gamma' \vdash \phi = \psi} \\
\\
\frac{\Gamma \vdash \exists x_\tau. \phi \quad \Gamma \cup \{\phi[x_\tau := y_\tau]\} \vdash \psi \quad y_\tau \notin fv(\psi) \cup fv(\Gamma) \cup \{x_\tau\}}{\Gamma \vdash \psi} \quad \frac{\Gamma \vdash \phi = \psi \quad \Gamma' \vdash \psi}{\Gamma \cup \Gamma' \vdash \phi} \\
\\
\frac{\Gamma \cup \{\phi\} \vdash \perp \quad \phi : \text{bool}}{\Gamma \vdash \neg \phi} \quad \frac{\Gamma \vdash \neg \phi \quad \Gamma' \vdash \phi}{\Gamma \cup \Gamma' \vdash \perp} \quad \frac{\Gamma \vdash \forall x_\tau. \phi \quad r : \tau}{\Gamma \vdash \phi[x_\tau := r]} \\
\\
\frac{\Gamma \vdash \phi[x_\tau := r]}{\Gamma \vdash \exists x_\tau. \phi} \quad \frac{\Gamma \vdash \phi \quad x_\tau \notin fv(\Gamma)}{\Gamma \vdash \forall x_\tau. \phi} \quad \frac{s : \tau' \quad r : \tau}{\Gamma \vdash (\lambda x_\tau. s)r = s[x_\tau := r]} \quad \frac{\Gamma \vdash \exists x_\tau. \phi}{\Gamma \vdash \phi(\epsilon x_\tau. \phi)} \\
\\
\frac{f : \tau \Rightarrow \tau' \quad x_\tau \notin fv(f)}{\Gamma \vdash \lambda x_\tau. (f x) = f} \quad \frac{\Gamma \vdash \phi \quad r : \tau}{\Gamma[x_\tau := r] \vdash \phi[x_\tau := r]} \quad \frac{\Gamma \vdash \phi}{\Gamma[\alpha := \tau] \vdash \phi[\alpha := \tau]}
\end{array}$$

■ **Figure 3** The Natural Deduction relation for Gordon's HOL.

the hardware sense of the word, and which can be used by the system to enforce arbitrary security or correctness properties, written in HOL, of a running programs.

2 Implemented logic

Supervisory implements a variant of Gordon's HOL, a classical higher-order logic which can be intuitively understood as Church's Simple Theory of Types extended with ML-style top-level polymorphism. We introduce the basics of this logic here, introducing just enough material so that the unfamiliar reader can follow the rest of the paper.

We fix a set of *type variables* and use α, β, γ , and so on, to range arbitrarily over them. With these, we work with *simple types* generated by the following recursive grammar:

$$\tau, \tau', \tau'' ::= \alpha \mid f(\tau, \dots, \tau')$$

Here f is a *type-former* which has an associated *arity*—a natural number indicating the number of type arguments that it expects. If all type-formers within a type are applied to their a number of types matching their arity we call the type *well-formed*—that is, arities introduce a trivial or degenerate form of *kinding* for types. We will only ever work with well-formed types in Supervisory. We write $tv(\tau)$ for the *set of type-variables* appearing within a type, and write $\tau[\alpha := \tau']$ for the *type substitution* replacing all occurrences of α with τ' in the type τ . From the outset we assume two primitive type-formers built-in to the logic itself and necessary to bootstrap the rest of the logic: `bool`, the type-former of the Boolean type—and also the type of propositions—with arity 0, and $- \Rightarrow -$, the type-former

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of the HOL function space, with arity 2. Note we will abuse syntax and also write `bool` for the *type* of Booleans and propositions, and also write $\tau \Rightarrow \tau'$ for the function space type.

For each well-formed type τ we assume a countably infinite set of *variables* and *constant symbols*. We use x_τ, y_τ, z_τ , and so on, to range over the variables associated with type τ , and use C_τ, D_τ, E_τ , and so on, to also range over the constants associated with type τ . With these, we recursively define *terms* of the explicitly-typed λ -calculus, as follows:

$r, s, t ::= x_\tau \mid C_\tau \mid rs \mid \lambda x:\tau. r$

Note that there is an “obvious” simple-typing relation on terms, which we omit here, though we write $r : \tau$ to assert that term r has type τ according to this typing relation. We call any term with a type *well-typed*, and we will only ever work with well-typed terms in Supervisory. Further, we call a term with type `bool` a *formula* and use ϕ, ψ, ξ , and so on, to suggestively range over terms that should be understood as being formulae in the rest of the paper. We work with terms identified up-to α -equivalence, write $fv(r)$ for the set of *free variables* of the term r , write $r[x_\tau := t]$ for the usual *capture-avoiding substitution* on terms, and write $r[\alpha := \tau]$ for the recursive extension of the type substitution action to terms.

Like with type-formers, from the offset we assume a collection of typed constants needed to bootstrap the rest of the logic, summarised in the table below:

	$=$	$\alpha \Rightarrow \alpha \Rightarrow \text{bool}$
	\top, \perp	<code>bool</code>
	\neg	<code>bool</code> \Rightarrow <code>bool</code>
269	$\wedge, \vee, \longrightarrow$	<i>with type</i> <code>bool</code> \Rightarrow <code>bool</code> \Rightarrow <code>bool</code>
	\forall, \exists	$(\alpha \Rightarrow \text{bool}) \Rightarrow \text{bool}$
	ϵ	$(\alpha \Rightarrow \text{bool}) \Rightarrow \alpha$

Most of the constant above are the familiar logical constants and connectives of first-order logic, lifted into our higher-order setting, and are introduced without further explanation. Only the ϵ constant—Hilbert’s *description operator*, a form of choice—may be unfamiliar. In HOL, this can be used to “select”, or “choose” an element of a type according to some predicate, and is otherwise undefined if no such element exists. Note therefore that all HOL types are inhabited by at least one element, with the term $\epsilon x_\tau. \perp$ inhabiting every type. We adopt conventional associativity, fixity, and precedence levels when rendering terms using these constants, writing $\phi \longrightarrow \psi$ instead of $(\longrightarrow \phi)\psi$, for example, and also suppress explicit type substitutions required to make terms involving polymorphic types well-typed, for example writing $\forall x_\tau. \phi$ instead of $\forall[\alpha := \tau](\lambda x_\tau. \phi)$.

We call a finite set of formulae a *context*, ranged arbitrarily over by $\Gamma, \Gamma', \Gamma''$, and so on. We write $\Gamma[x_\tau := r]$ and $\Gamma[\alpha := \tau]$ for the pointwise-lifting of the capture-avoiding substitution and type substitution on terms to contexts, and write $fv(\Gamma)$ for the set $\bigcup\{fv(r) \mid r \in \Gamma\}$. We introduce a two-place *Natural Deduction relation* between contexts and formulae using the rules in Figure 3, and write $\Gamma \vdash \phi$ to assert that a derivation tree rooted at $\Gamma \vdash \phi$ and constructed according to the rules presented in this figure exists.

Note that our Natural Deduction relation can be simplified following the equational treatment of the quantifiers and connectives discovered by Quine and Henkin, and implemented in the HOL Light proof assistant. We prefer a more explicit treatment closer to a textbook presentation of Natural Deduction.

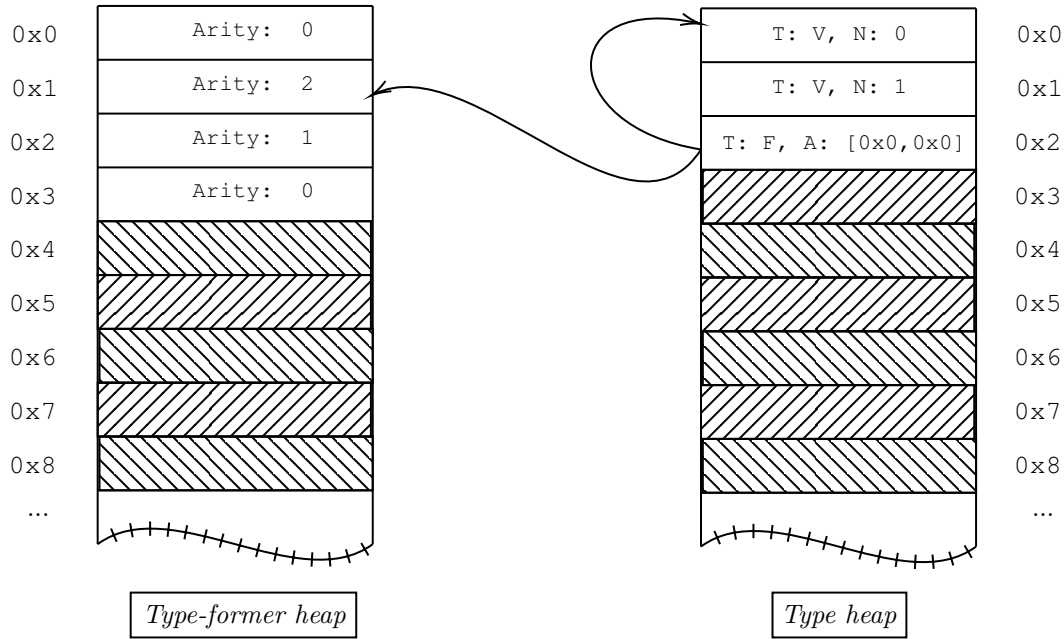


Figure 4 Entries within the Supervisory kernel’s type heap referencing entries within the type-former heap. Cross-hatched heap cells are as-yet unallocated by the kernel. The cell allocated at address 0x2 in the type heap is tagged with the F tag, indicating it is a type-former applied to a list of argument types, and points-to the cell at address 0x1 in the type-former heap, with arity 2. Two copies of the type stored in the cell with address 0x0, containing a type-variable with name 0, are used as the argument of the type-former to produce a complete, well-formed type. Adopting the convention that type-variable α is at 0x0 in the type heap, and the function-space type-former \Rightarrow is at 0x1 in the type-former heap, then this represents an encoding of the type $\alpha \Rightarrow \alpha$.

3 The Supervisory kernel state

Supervisory’s kernel manages a series of *heaps*, or private memories, in addition to other bits of book-keeping data. These heaps contain *kernel objects*, of various kinds: type-formers, types, constants, terms, and theorems. These follow the progression of the different kinds of HOL object, discussed in Section 2, and their interdependencies, and are discussed in turn.

3.1 The type-former heap

The most foundational of all of the heaps is the heap of type-formers, which is manipulated and queried using a series of dedicated system calls. Each cell within the heap is either *unallocated* or *allocated* and, in the latter case, contains a natural number *arity* for a type-former, encoded as an unsigned 64-bit machine word. New type-formers are registered within the heap by invoking a dedicated system call from user-space—`TypeFormer.Register`—which takes as input the arity of the type-former and in response allocates a fresh cell, returning the address of the cell back to user-space as the output of the system call. This address is the handle to the new type-former kernel object, now under management by the Supervisory kernel, and must be used by user-space to refer to this object henceforth. For example, a handle can be passed to the system call `TypeFormer.IsRegistered` system call to test whether a handle denotes a registered type-former. Alternatively, the `TypeFormer.Resolve` system call can be used to *dereference* a handle, in order to obtain an arity, providing that it does

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indeed denote a registered type-former, otherwise returning a defined error code.

Note that type-formers are essentially “named” by their handle: there may be many type-formers with the same arity registered with the kernel, and the particular meaning of any type-former is largely a convention of user-space, outside of the purview of the Supervisory kernel. However, there are exceptions to this rule. Two primitive type-formers are pre-registered within the type-former heap on system boot and hold special significance for the kernel. These are the `bool` type-former, registered at address `0x0` with arity 0, and the function-space type-former \Rightarrow , registered at address `0x1`, with arity 2. The existence of these pre-registered type-formers must be understood by user-space, and essentially forms part of the Supervisory system interface. Note that this is similar to how the distinguished file handles `stdout` and `stdin` are part of the POSIX system interface, and their hard-coded values must be understood by user-space to write or read from standard output and input.

3.2 The type heap

Building atop the heap of type-formers is the heap of types. This heap is queried and manipulated using another series of system calls. Note that the interface for working with types is much more complex than that for type-formers, so is only summarised here.

Recalling the grammar of HOL types, introduced in Section 2, we note that types are either a type-variable or a *combination* of a type-former applied to a list of types, and all entries within the type heap are therefore tagged indicating whether they are a type-variable or a combination. Type-variable entries only contain one datum: the *name* of the type-variable, which we take to be an unsigned 64-bit machine word. On the other hand, cells tagged with the combination tag also contain a pointer into the type-former heap, indicating which type-former is being applied, and contain a list of pointers back into the type heap itself, identifying the type arguments of the combination. Figure 4 shows a schematic diagram of dependencies between cells within the two heaps, wherein we use *V* to tag type-variables and *F* to tag combinations.

Like the type-former heap, Supervisory also boots with some entries in the type heap pre-registered, corresponding to common or useful types used to bootstrap the rest of the logic. These include the Boolean type, `bool`, common type variables— α and β , for example—as well as larger, more complex types such as the type of the polymorphic equality, $\alpha \Rightarrow \alpha \Rightarrow \text{bool}$. Again, the handles for all of these pre-registered entities must be understood by user-space.

Further derived types, built from primitive objects or otherwise, may be built using `Type.Register.Variable` and `Type.Register.Combination` system calls for constructing basic types. The first takes as input only a 64-bit machine word—the name of the variable—and immediately registers a new type in the type heap, returning the newly-allocated handle. On the other hand, `Type.Register.Combination` takes as input a handle pointing to a registered type-former in the type-former heap and a list of handles pointing back into the type heap. The system call fails if any of these handles dangle, or denote an object of the wrong kind, or if a list of type handles is presented with a length differing from the registered arity of the type-former. Lists of handles are passed to system calls by passing a base pointer, denoting the beginning of the list (or rather, array) with an explicit length. Substitutions, for the `Type.Substitution` system call, which performs a type-substitution, are passed as two lists: one for the domain of the substitution, another for the range.

It is sometimes convenient to test the structure of a type pointed-to by a handle. This can be done using system calls like `Type.Test.Combination` which takes a handle and returns a Boolean value indicating whether the corresponding type is a combination. A family of “splitting” system calls—`Type.Split.Variable`, for example—can also be used to

deconstruct a type. This takes a handle and returns the name of the variable pointed-to by the handle, if it is indeed a type-variable. Similar functions also exist for type combinations, and allow user-space to “pattern match” on types.

A system call, `Type.Variables`, also exists for computing the type-variables appearing within a term. Implementing this as a system call is a challenge, as the number of variables to be returned—and hence the size of buffer that user-space needs to set aside to hold them, and which Supervisory will write into—is unpredictable. To resolve this, the kernel exposes another system call, `Type.Size`, which computes the *size* of a type which bounds the number of variables appearing within a type. By querying this, user-space can first allocate sufficient memory within its own address space to hold the set of type-variables before calling `Type.Variables` with a pointer to the base of the allocated buffer.

Obviously, the Supervisory kernel must be careful in its management of its heaps, and this topic becomes pressing now we have introduced two heaps with dependencies between them. In particular, Supervisory maintains a series of *kernel invariants* which hold immediately out of boot and must be preserved by all system calls. One key invariant is the idea that heaps only ever *grow* monotonically, and allocated entries are immutable. Once an object is allocated into the heap it cannot be removed or modified in any way, lest we introduce an unsoundness for example, by modifying the `bool` type, or the truth constant, `⊤`, or something similarly catastrophic. Moreover, heaps should always remain “inductive”, in the sense that their cells do not contain any dangling pointers that do not point-to allocated cells in the same or other heaps. Essentially, this latter property forces the various objects under Supervisory’s management to correctly follow the grammar of types and terms introduced in Section 2, with larger objects being gradually “built up” out of smaller ones.

3.3 The constant and term heap

Building on the heap of types is the heap of constants, keeping track of registered term constants. Again, this is pre-provisioned with a series of primitive constants, corresponding to the logical constants and connectives, at boot-time. The system call interface for constants is similar to that for type-formers, exposing just three system calls for registering new constants, dereferencing handles, and testing whether a handle denotes a registered constant.

Another, further heap—the heap of terms—is also used to construct and manipulate terms. System calls for constructing, testing, and pattern matching on terms are provided, similar to those previously discussed within the context of other heaps. Further, new special-purposes system calls, for example `Term.Type.Infer` allow user-space to infer the type of a registered term, if any, whilst `Term.Substitute` performs a capture-avoiding substitution on a term. Note that handles for terms actually denote α -equivalence classes of terms—at present, we use a name-carrying syntax, but could implement this using De Bruijn indices or levels, leading to a more efficient implementation.⁷

3.4 The theorem heap

The final, and most important heap maintained by the Supervisory kernel is the heap of theorems. Every other Supervisory heap exists to support this heap, and Supervisory

⁷ Naturally, this would come at the mental cost of actually having to use De Bruijn indices.

395 3.5 Specifying kernel functions**396 3.6 Programming the kernel****397 4 Capabilities on steroids****398 5 Conclusions****399 5.1 Related work**

400 The closest related work to Supervisory is *VeriML*, an ML-like higher-order programming
401 language with native support for theorem proving in Gordon’s HOL. Essentially, VeriML
402 “internalises” a typical HOL kernel implementation within a higher-order programming
403 language, promoting the abstract type of theorems—typically *defined* within the system
404 metalanguage—into a native type of the language that can be queried and modified with
405 new, dedicated, domain-specific expressions for theorem construction and manipulation.

406 From the point-of-view of a typical HOL kernel implementation, VeriML essentially
407 “pushes the kernel down one layer” in the hierarchy of abstractions, moving the kernel
408 from a library within the language to a first-class programming language feature. However,
409 Supervisory “pushes” the kernel even further, moving support for theorem proving out of
410 the programming language and into the underlying operating system—or, in our case, virtual
411 machine. (As we will discuss below, in Subsection 5.2, this “pushing” of the kernel down
412 through the different layers of abstractions can be taken to its logical conclusion, by moving
413 the kernel into hardware.) Note, however, that despite the general idea behind the two
414 projects being essentially the same, the two differ markedly in where the kernel is “pushed
415 to”, and a myriad of design details which have some important consequences: for example,
416 automation in Supervisory is inherently programming-language agnostic, whereas VeriML
417 is inherently tied to one particular language—VeriML itself.

418 In Section 4 we observed that Supervisory’s handles can be reinterpreted as *capabilities*,
419 in the security sense. Note that capability machines are, at the present time, having a
420 minor resurgence, driven by the success of the CHERI capability extensions for MIPS, Arm
421 AArch64, and RISC-V. Capabilities in hardware have a long and storied history—dating
422 back at least to the Cambridge CAP machine developed in the 1960s—but capability-based
423 security has also previously been applied to software, including systems software like operating
424 systems. Whilst contemporary operating systems like seL4 and Google’s Fuchsia also have a
425 security model built around capabilities, perhaps the best well-known historical example of a
426 capability-based operating system was KeyKOS and its many derivatives, including EROS,
427 the Extremely Reliable Operating System.

428 However, despite this long history, the Supervisory conception of capabilities differs
429 markedly from other implementations. In particular, hardware-based capability systems like
430 CHERI, are relatively inexpressive, extending traditional pointer types with information on
431 valid memory regions within which they may point, and memory access permissions. This
432 is because existing hardware-based capability systems are optimised to prevent spatial and
433 temporal memory safety issues, inherent with widespread use of unsafe systems programming
434 languages like the C-language, and derivatives, and must also provide an easy “on ramp”
435 allowing existing software to adopt them. Supervisory’s conception of capabilities differs,
436 here, in being markedly more expressive, allowing complex security and correctness properties
437 to be expressed. Moreover, Supervisory’s capabilities are also much more intrusive:
438 software must be aware of the prevailing security or correctness policy in force at the time,
439 when trying to open a file for example, in order to be able to correctly answer the “challenge”.

Lastly, Supervisory, as an implementation of HOL, is closely related to several extant systems in the wider HOL family: Isabelle/HOL, HOL4, HOL Light, Candle, and so on. The kernels of all of these systems implement very similar logics, albeit with minor modification. However, unlike the aforementioned systems, Supervisory does not follow the typical LCF-style of system organization, nor is it written in an ML-derivative.

5.2 Future work

Supervisory has a dual role as both a proof-assistant kernel, capable of checking proofs in HOL, and also as a general-purpose virtual machine, capable of executing arbitrary programs. The consequences of this latter observation were explored previously, in Section 4, and is largely left for future work. In addition to this, below, we detail two further novel areas of future research enabled by Supervisory.

Hardware-accelerated proof-checking

As noted earlier, from the perspective of user-space software a system call presents as a suite of particularly CISC-like machine instructions with a rather unorthodox method of invocation. Indeed, the combination of the Supervisory system calls and the host Wasm instruction set can be, itself, thought of as a new, derived instruction set extending Wasm, with strange new domain-specific instructions for proof construction and management. Moreover, it should be quite clear that there is nothing Wasm-specific about Supervisory, and indeed Wasm was chosen merely as a relatively pain-free way of experimenting with the core ideas behind Supervisory. Indeed, Supervisory could have been implemented as real, privileged systems software for an existing instruction set in a relatively straightforward manner.

As a result, the Supervisory system call interface is already quite well-suited to an implementation in hardware, perhaps as an extension of an existing instruction set architecture like Arm AArch64 or RISC-V. The mechanism through which the Supervisory kernel isolates itself, via private memories, is rather “hardware like”, and maps nicely onto existing hardware features, and whilst the present Supervisory system call interface makes extensive use of “pointer-like” handles to refer to kernel objects, on a real hardware implementation these handles could *literally* be pointers into private memories, or similar. Moreover, the system call interface itself is also further carefully designed to avoid arbitrarily large recursive structures, difficult for an instruction set architecture to handle, from being passed across the kernel system call boundary.

We could therefore “push Supervisory down one layer” again, into the underlying instruction set implemented by hardware. With this, the ideas presented in Section 4 potentially take on a new light, as the underlying system hardware is now capable of expressing, and enforcing, arbitrarily complex security and correctness properties. We leave exploring this to future work.

Transferring theorems between systems

Assuming that an existing HOL implementation—HOL Light, for example—can be compiled into Wasm, we note that it should be possible to modify this HOL implementation by “ripping out” its kernel and replacing it with a shim layer exposing the same interface but calling Supervisory’s system calls to implement kernel functionality. From this, one can immediately “import” the entire HOL Light library directly into Supervisory, merely by having the system bootstrap itself, progressively registering new theorems in the kernel’s heaps as it executes via the Supervisory virtual machine and proves results.

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484 However, intriguingly, this approach could also be used to transfer results from one HOL
485 implementation to another by essentially performing the same shim trick with a second
486 system. Then, this second system can execute on an instance of the Supervisory virtual
487 machine *after* its heaps have already been populated by the first system. With this, the
488 second HOL implementation can make reference to results populated by the first system, or
489 build on top of them, if desired.

490 This method could not only provide a quick way of bootstrapping a library of formalized
491 mathematics for Supervisory, by essentially “borrowing” the library of another imple-
492 mentation, but also provides an alternative to OpenTheory for transferring results between
493 systems. We leave investigating this in more detail for future work.

494 5.3 Closing remarks