

All watched over by machines of loving grace

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Abstract

Modern operating systems are typically built around a trusted system component called the *kernel* which amongst other things is charged with enforcing system-wide security policies. Crucially, this component must be kept isolated from untrusted software at all times, which is facilitated by exploiting machine-oriented notions of separation: private memories, privilege levels, and similar.

Modern proof-checkers are typically built around a trusted system component called the *kernel* which is charged with enforcing system-wide soundness. Crucially, this component must be kept isolated from untrusted automation at all times, which is facilitated by exploiting programming-language notions of separation: module-private data structures, type-abstraction, and similar.

Whilst markedly different in purpose, in some essential ways operating system and proof-checker kernels are tasked with the same job, namely enforcing system-wide invariants in the face of unbridled interaction with untrusted code, yet the mechanisms through which the two types of kernel protect themselves are significantly different. In this paper, we introduce *Supervisory*, a prototype programmable proof-checking system for Gordon’s HOL that is organized in a manner more reminiscent of operating systems than typical LCF-style proof-checkers. In particular, *Supervisory* implements a kernel that executes at a relative level of privilege compared to untrusted automation, with trusted and untrusted system components communicating across a limited system call boundary to indirectly manipulate kernel objects managed by the *Supervisory* kernel via handles.

Unusually, *Supervisory* has no “metalanguage” in the LCF sense, as the language used to implement the kernel, and the language used to implement automation, need not be the same. Indeed, *any* programming language can be used to implement automation for *Supervisory* providing the resulting binary respects the *Supervisory* kernel calling convention and binary interface, with no risk to system soundness. Moreover, we observe that *Supervisory* allows arbitrary programming languages to be endowed with facilities for proof-checking, not only dedicated languages like Idris and Agda. Indeed, the handles that *Supervisory* uses to reference kernel objects under its management may be thought of as a form of *capability*, in the hardware sense. However, unlike typical capabilities, *Supervisory*’s capabilities are extremely expressive, essentially capturing the full expressive power of HOL, and could be used to enforce fine-grained correctness and security properties at runtime.

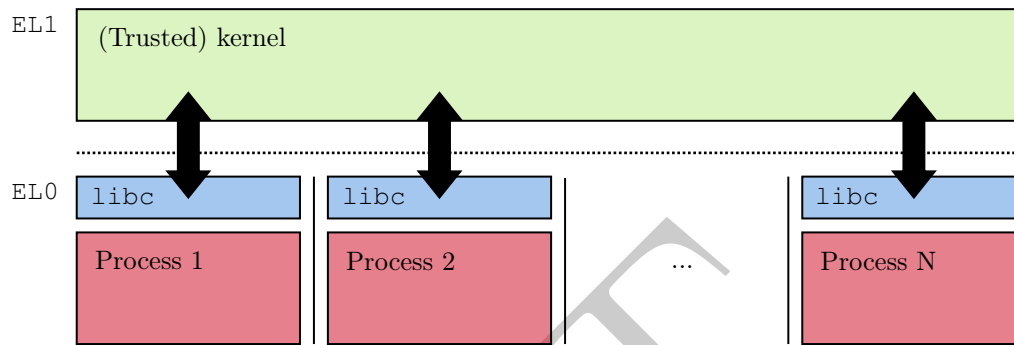
2012 ACM Subject Classification

Keywords and phrases Proof assistant design, operating systems, LCF, *Supervisory*, capabilities

Digital Object Identifier 10.4230/LIPIcs...

1 Introduction

This paper probes the intersection of operating system design and implementations of the foundations of mathematics. This is, admittedly, a rather unorthodox mix of subjects, and indeed this paper is rather unorthodox in its progression—especially for a submission to a venue dedicated to type theory—beginning first with a general overview of common principles in operating system implementation before getting to the main meat of the paper, wherein we propose a new and potentially very interesting way of writing proof-checking software.



■ **Figure 1** A schematic of the typical system organization of a commodity operating system and its associated user-space. The kernel (in green) executes at a relative level of privilege compared to user-space (red) enforced by hardware—here, we follow the Arm convention and show the kernel executing at EL1 and user-space at EL0. The two communicate across a system call boundary (dashed line) using system calls (black arrows), with user-space typically making use of a library such as `libc` (blue) to abstract over this process.

1.1 On operating systems

Most commodity operating systems—that is, Microsoft Windows and Unix-derivatives²—fit a common pattern and are architected around a relatively self-contained, trusted component typically called the system *kernel*.

At system initialisation, the kernel takes control of all system resources. Thereafter, untrusted user-space applications wishing to make use of a device, for example, must pass through the kernel in order to do so, which can either choose to gate or allow access. Moreover, the kernel introduces a process abstraction in user-space, and the kernel tasks itself with ensuring that processes are always isolated from each other. The kernel is therefore *the* key component responsible for enforcing system-wide policies. It is therefore imperative that the kernel is able to isolate itself sufficiently from untrusted user-space software at all times.

To help the kernel self-isolate, modern microprocessors are equipped with a number of features dedicated to this task. One key feature are *exception levels*³ which introduce a notion of *privilege* into the system. Here, software executing at a relative level of privilege—for example, an operating system kernel—is allowed to program sensitive system registers, controlling how the system operates, and “peer in” and potentially modify the runtime state of software executing at a lower-level of privilege. The kernel may read data from, or write data to, a buffer ostensibly within the memory space of an untrusted user-space process, for example. In this sense, a kernel can “supervise” or “watch over” untrusted user-space.

Moreover, modern microprocessors also provide a form of memory management built around page tables. These data structures are used for virtualisation of the system memory—granting user-space software the illusion that they own the entire physical address space—and also for memory access and permissions checks. By correctly initialising and managing these page tables the kernel’s own data structures and scratch space can be kept isolated from untrusted user-space, and user-space processes can be kept isolated from each other.

¹ All work done whilst at Arm Research

² “Commodity”: to guard against pedantic quibbling over research operating system designs like exokernels and similar which can be argued not to fit this pattern

³ This is Arm-specific terminology. *Privilege rings* are the analogous feature on Intel platforms

Note that for systems software, isolation is therefore enforced by low-level machine mechanisms: namely separate address spaces, private parts of memory, and machine-enforced privilege checks on executing software.

Finally the kernel, by necessity, must expose a limited interface to untrusted user-space, which can be used to request access to system resources, or make other similar requests for intercession by the kernel. To do this, operating system kernels commonly exposes a suite of *system calls* to untrusted user-space, which can be invoked with dedicated machine instructions. On Arm platforms—with which the author is most familiar—these instructions induce a processor exception, which causes a *context switch* into the kernel, which handles the system call appropriately, before exiting the exception and returning the flow of program control back to the calling user-space program. In this respect, from user-space’s point-of-view, system calls have the appearance of very CISC-like machine instructions, and the operating system kernel essentially presents itself as “silicon by other means”.

For all of this to work, user-space and the kernel must work together, and adopt a common calling convention describing how arguments and results are passed back-and-forth across the system call interface, agree on a binary interface detailing how system calls are identified and errors are reported, and so on and so forth. However, crucially, it is *generally* not the case that the operating system kernel and untrusted user-space applications need be written in the same programming language for this all to work. Whilst most operating system kernels are written in some C-language derivative, user-space programs can be written in a variety of languages, and can all make use of system resources exposed by the kernel’s system call interface as long as they are capable of adhering to the calling convention and binary interface expected by the kernel. Whilst—on Linux at least⁴—this system call interface is abstracted over by the C library, `libc`, this is generally just a convenience, and user-space software can always invoke system calls directly if wanted by invoking the correct machine instruction and adhering to the appropriate calling convention. In this respect, the C-language may have prominence of the favoured language of system implementation, but by-and-large it is not *special* or given an unduly prominent status by the kernel itself.

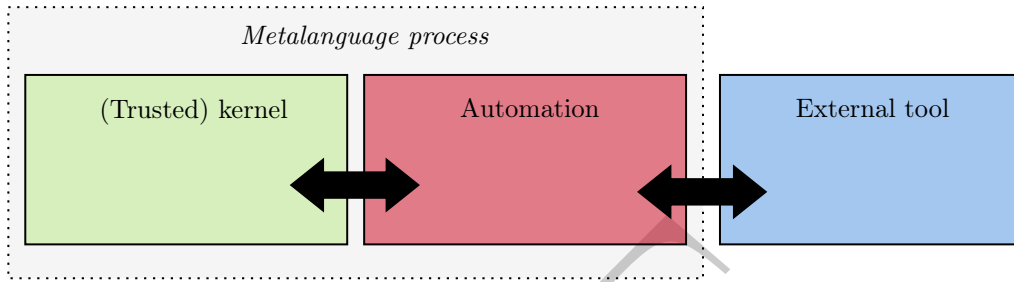
1.2 On programmable proof-checkers

Most modern proof assistants—that is, systems in the wider HOL family, Coq, Matita, PRL, and similar—fit a common pattern and are architected around a relatively self-contained, trusted component typically called the system *kernel*.

The system kernel is the sole component that can authenticate claims as legitimate theorems of the implemented logic. Untrusted automation, residing outside of the kernel, must “drive” the kernel to derive a theorem on its behalf. The kernel is therefore *the* component responsible for ensuring system-wide soundness. It is therefore imperative that the kernel is able to isolate itself sufficiently from untrusted automation at all times. This method of system organisation is known as *the LCF approach* after the system which introduced it, and is the most common way of organising proof-checking systems today.

Most modern proof assistants tend to be written in a “metalanguage”, typically a strongly-typed functional programming language, for example an ML derivative such as OCaml or SML. These types of programming language offer strong modularity and abstraction features, which the kernel exploits to hide its own data structures from untrusted automation and

⁴ Note that this is not the case on some variants of BSD Unix, for example Apple MacOS, which generally consider the programming interface of the system C library as the interface of the kernel, proper



■ **Figure 2** A schematic of the system organisation of a typical LCF-style proof assistant. The trusted kernel (green) is linked against untrusted automation (red) existing within the same metalanguage process (dotted line) and communicate with each other using the kernel’s API (black arrow). External tools existing as separate processes (blue, must communicate with a shim layer written in the proof assistant’s metalanguage to access the kernel (black arrow).

110 expose a carefully limited API for proof-construction and manipulation. Notably, in an
 111 LCF-style system, the *only* mechanism automation has for constructing an authenticated
 112 theorem is by using this API, with the inference (or typing) rules of the logic exposed as
 113 “smart constructors” manipulating an abstract type of theorems or well-typed terms.

114 Untrusted automation and the system kernel are linked together, and reside side-by-side
 115 in the same process when the system is executed. As a result, system soundness ultimately
 116 rests on the soundness of the implementation metalanguage’s type-system—specifically its
 117 ability to correctly isolate module-private data structures, that is its ability to correctly
 118 enforce type abstraction. Moreover, the system metalanguage is, in a sense, unique amongst
 119 all programming languages, in that it is the only language capable of interfacing with the
 120 kernel, which is, after all, “just” a module written within that language like any other. Whilst
 121 external tools, and automation written in other languages, can interface with the kernel, it
 122 must do so indirectly, making use of a shim layer written in the system metalanguage.

123 1.3 The Supervisory system

124 In many respects, as the text above intimates, the role of the kernel in an operating system
 125 and the role of the kernel in a proof-checker is, abstractly, *essentially* the same. Namely,
 126 both components must enforce system-wide invariants in the face of—and correctly isolate
 127 themselves from—unbridled interaction with untrusted code. However, the two mechanisms
 128 through which these different types of kernel self-isolate are very different: for operating
 129 system kernels⁵ self-isolation is enforced using machine-oriented mechanisms; for LCF-style
 130 proof-checkers, self-isolation is enforced using programming language-oriented mechanisms.

131 In this paper we introduce *Supervisory*, a novel programmable proof-checker for
 132 Gordon’s HOL whose design will be further discussed in detail in Section 2. (Note that
 133 many of the ideas presented henceforth are logic-independent, and though we have chosen
 134 to use HOL in our prototype, can be applied to a wide array of other logics with minimal
 135 changes.) Of note, Supervisory’s system design has more in common with the typical system
 136 organisation of an operating system than comparable implementations of HOL. Specifically,
 137 the Supervisory kernel executes at a relative level of privilege when compared to untrusted
 138 automation, which can be thought of as executing in something akin to Supervisory’s

⁵ Barring unikernels like Mirage, which are in some respects quite similar to LCF-style proof-checkers in this regard

version of “user space”. The trusted kernel, and untrusted user space, communicate across a system call boundary, which must be carefully designed in order to ensure system soundness.

One immediate consequence of this design is that the Supervisory kernel immediately takes on a very different character to the typical LCF kernel. Specifically, all of the typical paraphernalia of a HOL implementation—type formers, types, constants, terms, and theorems—are kept safely under the management of the Supervisory kernel itself, in private memory areas, and never exposed directly to user-space but rather referenced indirectly by handles. These handles may be thought of as somewhat akin to pointers into Supervisory’s private memories, or analogous to file handles in typical systems software, and are used by user-space software to denote a kernel object that the Supervisory kernel should manipulate or query on user-space’s behalf.

Remarkably, Supervisory is also not implemented in a typed functional programming language, as is typical of most programmable proof-checkers, but rather in the *unsafe* systems programming language, Rust. Note that this implementation decision introduces no risk to system soundness which ultimately rests on the separation of kernel-private data from user-space, using privilege and private memories, not on programming language features. Moreover, as user-space and kernel communicate across a defined system call interface, untrusted user-space may also be written in *any* programming language capable of producing code that is binary-compatible with the Supervisory kernel. Supervisory therefore has no “metalanguage” in the sense understood by users of LCF-style provers, but rather an implementation language, with automation potentially written in multiple languages.

We implement Supervisory as a WebAssembly (or Wasm, henceforth) host. This allows us to experiment with the essential ideas behind Supervisory—namely isolating the kernel using private memory areas, which the “user-space” Wasm program executing under the host cannot access, and which exposes services via system call-like interface—without become bogged down in extraneous detail associated with booting a real machine, and interacting with real hardware. Moreover, we harness work on porting compiler and linker toolchains, allowing our “user space” to be written in any language capable of targeting Wasm.

2 Kernel design

2.1 Implemented logic

Supervisory implements a variant of Gordon’s HOL, a classical higher-order logic which can be intuitively understood as Church’s Simple Theory of Types extended with ML-style top-level polymorphism. We introduce the basics of this logic here, introducing just enough material so that the unfamiliar reader can follow the rest of the paper.

We fix a set of *type variables* and use α, β, γ , and so on, to range arbitrarily over them. With these, we work with a grammar of *types* generated by the following recursive grammar:

$$\tau, \tau', \tau'' ::= \alpha \mid f(\tau, \dots, \tau')$$

Here f is a *type-former* which has an associated *arity*—a natural number indicating the number of type arguments that it expects. If all type-formers within a type are applied to their expected number of types we call the type *well-formed*—that is, arities introduce a trivial or degenerate form of *kinding* for types. We will only ever work with well-formed types in Supervisory. We write $tv(\tau)$ for the *set of type-variables* appearing within a type, and write $\tau[\alpha := \tau']$ for the *type substitution* replacing all occurrences of α with τ' in the type τ . From the outset we assume two primitive type-formers—essentially built-in to the logic itself, and necessary to bootstrap the rest of the logic: `bool`, the type-former of the

$\frac{(r : \tau)}{\Gamma \vdash r = r}$	$\frac{\Gamma \vdash r = s}{\Gamma \vdash s = r}$	$\frac{\Gamma \vdash r = s \quad \Gamma \vdash s = t}{\Gamma \vdash r = t}$	$\frac{(\phi \in \Gamma)}{\Gamma \vdash \phi}$	$\frac{\Gamma \vdash \perp \quad (\phi : \text{bool})}{\Gamma \vdash \phi}$
$\frac{}{\Gamma \vdash \top}$	$\frac{\Gamma \vdash \phi \quad \Gamma' \vdash \psi}{\Gamma \cup \Gamma' \vdash \phi \wedge \psi}$	$\frac{\Gamma \vdash \phi \wedge \psi}{\Gamma \vdash \phi}$	$\frac{\Gamma \vdash \phi \wedge \psi}{\Gamma \vdash \psi}$	$\frac{\Gamma \cup \{\phi\} \vdash \psi \quad (\phi : \text{bool})}{\Gamma \vdash \phi \longrightarrow \psi}$
$\frac{\Gamma \vdash \phi \longrightarrow \psi \quad \Gamma \vdash \phi}{\Gamma \vdash \psi}$	$\frac{\Gamma \vdash \phi \quad (\psi : \text{bool})}{\Gamma \vdash \phi \vee \psi}$	$\frac{\Gamma \vdash \psi \quad (\phi : \text{bool})}{\Gamma \vdash \phi \vee \psi}$	$\frac{\Gamma \vdash \phi = \psi \quad \Gamma' \vdash \phi}{\Gamma \cup \Gamma' \vdash \psi}$	$\frac{\Gamma \vdash \phi \vee \psi \quad \Gamma' \cup \{\phi\} \vdash \xi \quad \Gamma'' \cup \{\psi\} \vdash \xi}{\Gamma \cup \Gamma' \cup \Gamma'' \vdash \xi}$
$\frac{\Gamma \vdash \phi \vee \psi \quad \Gamma' \cup \{\phi\} \vdash \xi \quad \Gamma'' \cup \{\psi\} \vdash \xi}{\Gamma \cup \Gamma' \cup \Gamma'' \vdash \xi}$	$\frac{\Gamma \vdash \phi \longrightarrow \psi \quad \Gamma \vdash \psi \longrightarrow \phi}{\Gamma \vdash \phi = \psi}$	$\frac{\Gamma \vdash \exists x_\tau. \phi \quad \Gamma \cup \{\phi[x_\tau := y_\tau]\} \quad \psi \quad (y_\tau \notin fv(\psi) \cup fv(\Gamma) \cup \{x_\tau\})}{\Gamma \vdash \psi}$	$\frac{\Gamma \vdash \phi = \psi \quad \Gamma' \vdash \psi}{\Gamma \cup \Gamma' \vdash \phi}$	$\frac{\Gamma \cup \{\phi\} \vdash \perp \quad (\phi : \text{bool})}{\Gamma \vdash \neg \phi}$
$\frac{\Gamma \cup \{\phi\} \vdash \perp \quad (\phi : \text{bool})}{\Gamma \vdash \neg \phi}$	$\frac{\Gamma \vdash \neg \phi \quad \Gamma' \vdash \phi}{\Gamma \cup \Gamma' \vdash \perp}$	$\frac{\Gamma \vdash \forall x_\tau. \phi \quad (r : \tau)}{\Gamma \vdash \phi[x_\tau := r]}$	$\frac{\Gamma \vdash \phi[x_\tau := r]}{\Gamma \vdash \exists x_\tau. \phi}$	$\frac{\Gamma \vdash \phi \quad (x_\tau \notin fv(\Gamma))}{\Gamma \vdash \forall x_\tau. \phi}$
$\frac{\Gamma \vdash \phi[x_\tau := r]}{\Gamma \vdash \exists x_\tau. \phi}$	$\frac{\Gamma \vdash \phi \quad (x_\tau \notin fv(\Gamma))}{\Gamma \vdash \forall x_\tau. \phi}$	$\frac{(s : \tau', r : \tau)}{\Gamma \vdash (\lambda x_\tau. s)r = s[x_\tau := r]}$	$\frac{\Gamma \vdash \epsilon x_\tau. \phi \quad (f : \tau \Rightarrow \tau', x \notin fv(f))}{\Gamma \vdash \phi(\epsilon x_\tau. \phi)}$	$\frac{\Gamma \vdash \phi \quad (r : \tau)}{\Gamma[x_\tau := r] \vdash \phi[x_\tau := r]}$
$\frac{\Gamma \vdash \epsilon x_\tau. \phi \quad (f : \tau \Rightarrow \tau', x \notin fv(f))}{\Gamma \vdash \phi(\epsilon x_\tau. \phi)}$	$\frac{\Gamma \vdash \lambda x_\tau. (f \ x) = f}{\Gamma \vdash \lambda x_\tau. (f \ x) = f}$	$\frac{\Gamma \vdash \phi \quad (r : \tau)}{\Gamma[x_\tau := r] \vdash \phi[x_\tau := r]}$	$\frac{\Gamma \vdash \phi}{\Gamma[\alpha := \tau] \vdash \phi[\alpha := \tau]}$	

■ **Figure 3** The Natural Deduction relation for Gordon's HOL.

185 Boolean type (and in HOL, also propositions), with arity 0, and $- \Rightarrow -$, the type-former of
 186 the HOL function space, with arity 2. Note we will abuse syntax and also write **bool** for the
 187 *type* of Booleans and propositions, and also write $\tau \Rightarrow \tau'$ for the function space type.

188 For each well-formed type τ we assume a countably infinite set of *variables* and *constant*
 189 *symbols*. We use x_τ, y_τ, z_τ , and so on, to range over the variables associated with type τ ,
 190 and use C_τ, D_τ, E_τ , and so on, to also range over the constants associated with type τ . With
 191 these, we recursively define *terms* of the explicitly-typed λ -calculus, as follows:

$$192 \quad r, s, t ::= x_\tau \mid C_\tau \mid rs \mid \lambda x:\tau. r$$

193 Note that there is an “obvious” simple-typing relation on terms, which we omit here, though
 194 we write $r : \tau$ to assert that term r has type τ . We call any term with a type *well-typed*.
 195 We will only ever work with well-typed terms in Supervisory, and call terms with type
 196 **bool** *formulae*. We will use ϕ, ψ, ξ , and so on, to suggestively range over terms that should
 197 be understood as being formulae. We work with terms up-to α -equivalence, write $fv(r)$
 198 for the set of *free variables* appearing within the term r , write $r[x_\tau := t]$ for the usual
 199 *capture-avoiding substitution* on terms, and write $r[\alpha := \tau]$ for the recursive extension of the
 200 type substitution action to terms.

201 Like with type-formers, from the offset we assume a collection of typed constants needed
 202 to bootstrap the rest of the logic, summarised in the table below:

	=		$\alpha \Rightarrow \alpha \Rightarrow \text{bool}$
	\top, \perp		bool
	\neg		$\text{bool} \Rightarrow \text{bool}$
203	$\wedge, \vee, \longrightarrow$	with type	$\text{bool} \Rightarrow \text{bool} \Rightarrow \text{bool}$
	\forall, \exists		$(\alpha \Rightarrow \text{bool}) \Rightarrow \text{bool}$
	ϵ		$(\alpha \Rightarrow \text{bool}) \Rightarrow \alpha$

204 The majority of the constants above correspond to the usual logical constants and connectives
 205 of first- or higher-order logic and are introduced without further explanation. Only the latter
 206 ϵ constant—Hilbert’s description operator, a form of choice—may be unfamiliar. In HOL,
 207 this can be used to “select”, or “choose” an element of a type according to some predicate,
 208 and is otherwise undefined if no such element exists. Note that all HOL types are inhabited
 209 by at least one element. We adopt usual mathematical conventions and precedence levels
 210 when writing terms making use of these constants, writing $\phi \longrightarrow \psi$ instead of $(\longrightarrow \phi)\psi$,
 211 for example. We also suppress explicit type substitutions required to make terms involving
 212 polymorphic types well-typed, writing $\forall x_\tau. \phi$ instead of $\forall[\alpha := \tau](\lambda x_\tau. \phi)$, for example.

213 We call a finite set of formulae a *context*, ranged arbitrarily over by $\Gamma, \Gamma', \Gamma''$, and so on.
 214 We write $\Gamma[x_\tau := r]$ and $\Gamma[\alpha := \tau]$ for the pointwise-lifting of the capture-avoiding substitution
 215 and type substitution on terms to contexts, and write $fv(\Gamma)$ for the set $\bigcup\{fv(r) \mid r \in \Gamma\}$.
 216 We introduce a two-place *Natural Deduction relation* between contexts and formulae using
 217 the rules in Figure 3, and write $\Gamma \vdash \phi$ to assert that a derivation tree rooted at $\Gamma \vdash \phi$ and
 218 constructed according to the rules presented in this figure exists.

219 Note that our Natural Deduction relation can be simplified following the equational treat-
 220 ment of the quantifiers and connectives discovered by Quine and Henkin, and implemented
 221 in the HOL Light proof assistant. We prefer a more explicit treatment.

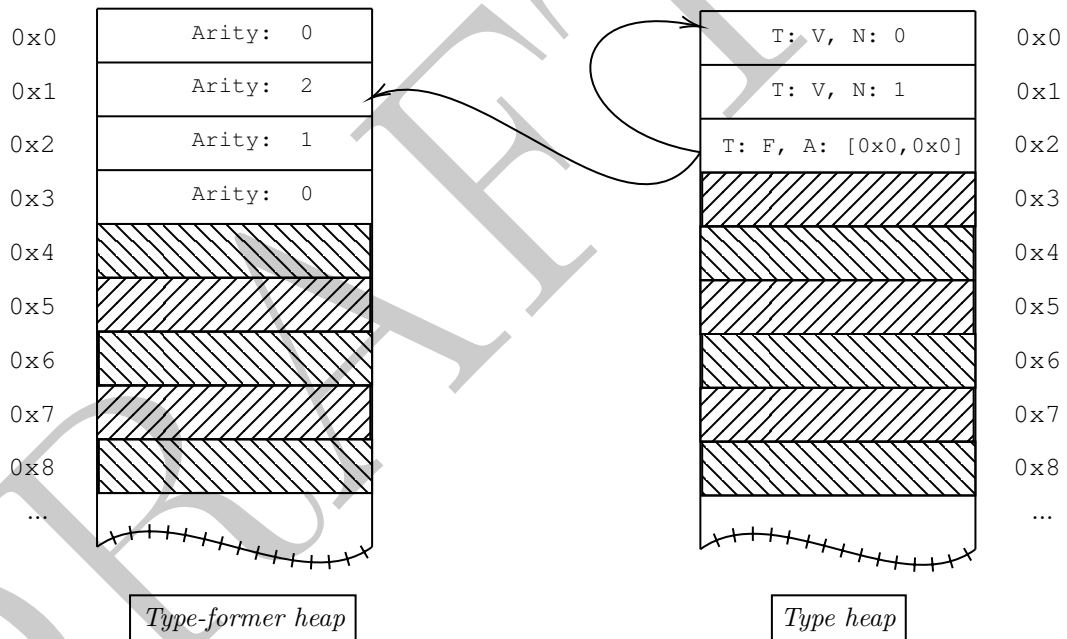
222 2.2 The kernel state

223 The type-former heap

224 Supervisory’s kernel manages a series of *heaps*, or private memories. These heaps contain
 225 different *kernel objects*, of various kinds: type-formers, types, constants, terms, and theorems.

226 The most foundational of all of the heaps is the heap of type-formers. Each cell within
 227 the heap is either *unallocated* or *allocated* and, in the latter case, contains a natural num-
 228 ber *arity* for a type-former, encoded as an unsigned 64-bit machine word. New type-
 229 formers are registered within the heap by invoking a dedicated system call from user-space—
 230 **TypeFormer.Register**—which takes as input the arity of the type-former and in response
 231 allocates a fresh cell, returning the address of the cell back to user-space. This address is the
 232 handle to the new type-former kernel object, now under management by the Supervisory
 233 kernel, and must be used by user-space to refer to this object henceforth—perhaps to query
 234 the arity of the type-former stored at a particular address in Supervisory’s heap, via the
 235 **TypeFormer.Arity** system call, for example, which exists for this purpose and takes a handle
 236 as input, returning either an arity or a defined error code back to user-space, indicating that
 237 the input handle is *dangling*, and cannot be *dereferenced* to obtain an arity.

238 Note that type-formers are essentially “named” by their handle: there may be many
 239 type-formers with the same arity registered with the kernel, and the particular meaning of any
 240 type-former is largely a convention of user-space, outside of the purview of the Supervisory
 241 kernel. Yet, there are exceptions to this rule: two primitive type-formers are pre-registered
 242 within the type-former heap on system boot: the **bool** type-former, registered at address **0x0**
 243 and with arity 0, and the function-space type-former \Rightarrow , registered at address **0x1**, with arity



■ **Figure 4** Entries within the Supervisory kernel's type heap referencing entries within the type-former heap. Cross-hatched heap cells are as-yet unallocated by the kernel. The cell allocated at address `0x2` in the type heap is tagged with the **F** tag, indicating it is a type-former applied to a list of argument types, and points-to the cell at address `0x1` in the type-former heap, with arity 2. Two copies of the type stored in the cell with address `0x0`, containing a type-variable with name 0, are used as the argument of the type-former to produce a complete, well-formed type. Adopting the convention that type-variable α is at `0x0` in the type heap, and the function-space type-former \Rightarrow is at `0x1` in the type-former heap, then this represents an encoding of the type $\alpha \Rightarrow \alpha$.

244 2. The existence of these pre-registered type-formers must be understood by user-space, and
 245 essentially forms part of the Supervisory system interface, in a similar vein to how the
 246 distinguished file handles `stdout` and `stdin` are part of the POSIX system interface, too.

247 The type heap

248 Building atop the heap of type-formers is another heap: the heap of types. Referring back
 249 to the grammar of HOL types introduced in Subsection 2.1, all allocated entries within
 250 this heap are tagged either with a `V`, indicating that they are a type-variable, or with an `F`,
 251 indicating that they are a “combination” of a type-former applied to a list of argument types.

252 Type-variable entries only contain one datum: the *name* of the type-variable, which
 253 we take to be an unsigned 64-bit machine word. On the other hand, cells tagged with
 254 the combination tag also contain a pointer into the type-former heap, indicating which
 255 type-former is being applied, and contain a list of pointers back into the type heap itself,
 256 identifying the type arguments of the combination. Figure 4 shows a schematic diagram of
 257 dependencies between cells within the two heaps.

258 Like the type-former heap, Supervisory also boots with some entries in the type heap
 259 pre-registered, corresponding to common or useful types used to bootstrap the rest of the logic.
 260 These include the Boolean type, `bool`, common type variables— α and β , for example—as well
 261 as larger, more complex types such as the type of the polymorphic equality, $\alpha \Rightarrow \alpha \Rightarrow \text{bool}$.
 262 Again, the handles for all of these pre-registered entities must be understood by user-space.

263 Obviously, the Supervisory kernel must be careful in its management of its heaps, and
 264 this topic becomes pressing now we have introduced two heaps with dependencies between
 265 them. In particular, Supervisory maintains a series of *kernel invariants* which hold
 266 immediately out of boot and must be preserved by all system calls. One key invariant is the
 267 idea that heaps only ever *grow* monotonically, and allocated entries are immutable—once
 268 an object is allocated into the heap it cannot be removed or modified in any way, lest we
 269 introduce an unsoundness (by e.g., modifying the `bool` type, or the truth constant, `⊤`, or
 270 similar). Moreover, heaps should always remain “inductive”, in the sense that their cells do
 271 not contain any dangling pointers that do not point-to allocated cells in the same or other
 272 heaps. Essentially, this latter property forces the various objects under Supervisory’s
 273 management to correctly follow the grammar of types and terms introduced in Subsection 2.1,
 274 with larger objects being gradually “built up” out of smaller ones.

275 Note that the Supervisory ABI for working with types is much more well-developed
 276 than for type-formers. In addition to basic system calls for registering new types with the
 277 kernel, Supervisory also provides a suite of more complex system calls for computing
 278 the variables appearing in a type, performing a type-substitution on a type, and similar.
 279 This latter call—`Type.Substitute`—is interesting for two reasons: first, as mentioned above,
 280 once kernel objects are registered in a heap they are immutable. As a result, this system call
 281 allocates a new type, the result of the substitution, in the type heap upon success. Moreover,
 282 the substitution to be applied to the type can be arbitrarily large, consisting of an unbound
 283 number of type variable-to-type mappings. As a result, this system call takes a pair of base
 284 pointers and a pair of lengths, one each for a buffer of variables and a buffer of handles
 285 pointing-to types in the type heap. These base pointers point-into a buffer in the calling
 286 user-space program’s memory space, which the Supervisory kernel reads to

287 **2.3 The kernel system call interface**

288 **2.4 Programming the kernel**

289 **2.5 Specifying kernel functions**

290 **3 Capabilities on steroids**

291 **4 Conclusions**

292 **4.1 Related work**

293 **4.2 Future work**

294 Aside from the inherent amusement in structuring a proof-assistant in this way, Supervisory
295 also opens up several interesting new lines of future work.

296 **Hardware-accelerated proof-checking**

297 As mentioned earlier, from the perspective of user-space software an operating system's
298 system call interface presents as a suite of particularly CISC-like machine instructions with a
299 rather strange method of invocation. Indeed, the combination of the Supervisory system
300 calls and the host Wasm instruction set can be, itself, thought of as a new, derived instruction
301 set extending Wasm with new instructions for proof construction and management.

302 As a result, note that the Supervisory system call interface is already particularly
303 well-suited to being implemented as an extension to the Arm instruction set or RISC-V
304 instruction sets, for example. Already, the mechanism through which Supervisory isolates
305 itself, via private memories, is rather “hardware like”, and maps nicely onto existing hardware
306 features. Whilst the present Supervisory system call interface makes extensive use of
307 “pointer-like” handles to refer to kernel objects, on a real hardware implementation these
308 handles could *literally* be pointers into private memories. Moreover, the system call interface
309 itself is also further carefully designed to avoid arbitrarily large recursive structures, difficult
310 for an instruction set architecture to handle, from being passed to the kernel. Rather, kernel
311 objects are gradually built up out of smaller, already-existing objects. We believe that this
312 idea maps nicely onto an instruction set architecture, and implementing a hardware-based
313 proof-checker for HOL using the ideas in Supervisory is future work.

314 **Transferring theorems between systems**

315 Consider compiling another implementation of HOL—for example, HOL Light—into Wasm.
316 The Supervisory implementation of HOL is sufficiently similar that it should be possible to
317 “rip out” the HOL Light kernel and replace it with a shim layer that exposes the same interface
318 but simply calls into Supervisory's system calls to implement kernel functionality, with
319 some extra internal book-keeping for handle management. From this, one can immediately
320 “import” the entire HOL Light library directly into Supervisory, merely by having HOL
321 Light bootstrap itself.

322 This approach can be used to transfer results from one HOL implementation to another.
323 In particular, consider doing the same kernel shim modification with *another* implementation
324 of HOL, for example, HOL4, written in a different programming language to HOL Light.
325 This too, can also be compiled to Wasm, and can bootstrap itself using Supervisory. Now,
326 the HOL4 kernel is “sitting on top” of a series of heaps populated already by HOL Light,
327 and can make reference to these existing results, or build on top of them, if desired.

328 Note that this provides an alternative method of transferring results between implementa-
329 tions of HOL, in contrast to existing approaches like OpenTheory. All results, independent of
330 which system ultimately generated them, are derived within a single, common logical system
331 implemented by Supervisory. Essentially, the two systems makes use of Supervisory's
332 heaps as their joint "source of truth" to transfer results.

333 **Enforcing runtime correctness and security properties**

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