

Erriez TM1638 library for Arduino  
1.0.0

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# Contents

<b>1</b>	<b>Optimized TM1637 library for Arduino</b>	<b>1</b>
<b>2</b>	<b>Class Index</b>	<b>5</b>
2.1	Class List . . . . .	5
<b>3</b>	<b>File Index</b>	<b>7</b>
3.1	File List . . . . .	7
<b>4</b>	<b>Class Documentation</b>	<b>9</b>
4.1	TM1637 Class Reference . . . . .	9
4.1.1	Detailed Description . . . . .	10
4.1.2	Constructor & Destructor Documentation . . . . .	10
4.1.2.1	TM1637(uint8_t clkPin, uint8_t dioPin, bool displayOn=true, uint8_t brightness=5)	10
4.1.3	Member Function Documentation . . . . .	11
4.1.3.1	getKeys() . . . . .	11
4.1.3.2	readByte() . . . . .	11
4.1.3.3	setBrightness(uint8_t brightness) . . . . .	11
4.1.3.4	writeByte(uint8_t data) . . . . .	11
4.1.3.5	writeData(uint8_t address, uint8_t data) . . . . .	12
4.1.3.6	writeData(uint8_t address, const uint8_t *buf, uint8_t len) . . . . .	12
<b>5</b>	<b>File Documentation</b>	<b>13</b>
5.1	TM1637.cpp File Reference . . . . .	13
5.1.1	Detailed Description . . . . .	13
5.2	TM1637.h File Reference . . . . .	13
5.2.1	Detailed Description . . . . .	15
	<b>Index</b>	<b>17</b>



# Chapter 1

## Optimized TM1637 library for Arduino

This is a 2-pin serial [TM1637](#) chip library for Arduino, optimized for size and speed. It supports a combined LED driver controller and key-scan interface to detect one key press.

### Chip features

- Power CMOS process
- Display mode (8 segments × 6 digits), support common anode LED output
- Key scan (8 × 2-bit), enhanced anti-jamming button recognition circuit
- Brightness adjustment circuit (adjustable duty cycle 8)
- Two-wire serial interface (CLK, DIO)
- Oscillation mode: Built-in RC oscillator
- Built-in power-on reset circuit
- Built-in automatic blanking circuit
- Package: DIP20 / SOP20

### Hardware

Connect power and 2 data pins to an Arduino board DIGITAL pins:

- VDD (Power 3.3V - 5V)
- GND (Ground)
- CLK (Clock)
- DIO (Bi-directional data input/output)

The following [TM1637](#) pins should be connected to LED's and buttons in a matrix:

- K1~K2 (Key-scan data input to read one key press after each other)
- SEG/GRID (Output for LED matrix)

### Pins

Pin	TM1637	Arduino UNO / Nano / Micro / Pro Micro / Leonardo / Mega2560	WeMos D1 & R2 / Node MCU	WeMos LOLIN32
1	VCC	5V (or 3.3V)	3V3	3V3
2	GND	GND	GND	GND
3	CLK	2 (DIGITAL pin)	D2	0
4	DIO	3 (DIGITAL pin)	D3	4

- Check maximum regulator / diode current to prevent a burnout when using lots of LED's. Some boards can provide only 100mA, others 800mA max.

## Two-wire serial interface

The [TM1637](#) communicates with a MCU serial by using two wires:

- DIO (bi-directional input/output pin)
- SCL (Clock pin)

**Note:** The serial interface is not compatible with I2C or TWI, because no device address with read/write bit is used.

## Example

Arduino IDE | Examples | Erriez [TM1637](#) button and LED driver:

[TM1637](#)

## Documentation

- [Doxygen online HTML](#)
- [Doxygen PDF](#)
- [TM1637 Datasheet \(Chinese\)](#)

## Usage

### Initialization

```

1 {c++}
2 // Include TM1637 library
3 #include "TM1637.h"
4
5 // Connect display pins to the Arduino DIGITAL pins
6 #define TM1637_CLK_PIN 2
7 #define TM1637_DIO_PIN 3
8
9 // Create tml637 object
10 TM1637 tml637(TM1637_CLK_PIN, TM1637_DIO_PIN);
11
12 void setup()
13 {
14     // Initialize TM1637
15     tml637.begin();
16 }
```

## Display on/off

```
1 {c++}
2 // Turn display off
3 tm1637.displayOff();
4
5 // Turn display on
6 tm1637.displayOn();
```

## Turn all LED's off

```
1 {c++}
2 // Turn all LED's off
3 tm1637.clear();
```

## Get keys

```
1 {c++}
2 // Get 8-bit key-scan
3 uint8_t keys = tm1637.getKeys();
```

## Write Byte to display register

```
1 {c++}
2 // Write segment LED's to the first display registers 0x00..0x0F with value 0x00..0xff to
3 // display numbers and characters. Just an example which depends on the hardware:
4 tm1637.writeData(0x01, 0x01);
```

## Write buffer to display registers

```
1 {c++}
2 // Creat buffer with LED's
3 uint8_t buf[] = { 0b10000110, 0b00111111, 0b00111111, 0b00111111, 0b00111111, 0b00111111};
4
5 // Write buffer to TM1637
6 tm1637.writeData(0x00, buf, sizeof(buf));
```

## Optimized timing

The library uses optimized pin control for AVR targets. Other targets uses the default `digitalRead()` and `digitalWrite()` pin control functions.

Output **Benchmark** example:

Board	CLK	Read keys	Write Byte	Write 16 Bytes buffer	Clear display
Pro Mini 8MHz	84kHz	352us	344us	1080us	1072us
UNO 16MHz	170kHz	156us	152us	496us	480us
WeMos D1 & R2 80MHz	205kHz	261us	137us	396us	396us
WeMos D1 & R2 160MHz	300kHz	233us	96us	275us	271us

Arduino Pro-Mini 8MHz

Arduino UNO 16MHz

WeMos D1 & R2 80MHz

WeMos D1 & R2 160MHz

### Library dependencies

- The [Benchmark](#) example uses [Erriez Timestamp](#) library.

### Library installation

Please refer to the [Wiki](#) page.

### Other Arduino Libraries and Sketches from Erriez

- [Erriez Libraries and Sketches](#)



## Chapter 2

# Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">TM1637</a>	
<a href="#">TM1637</a> class . . . . .	<a href="#">9</a>



## Chapter 3

# File Index

### 3.1 File List

Here is a list of all documented files with brief descriptions:

<a href="#">TM1637.cpp</a>		
<a href="#">TM1637</a>	library for Arduino . . . . .	<a href="#">13</a>
<a href="#">TM1637.h</a>		
<a href="#">TM1637</a>	library for Arduino . . . . .	<a href="#">13</a>



## Chapter 4

# Class Documentation

### 4.1 TM1637 Class Reference

TM1637 class.

```
#include <TM1637.h>
```

#### Public Member Functions

- **TM1637** (uint8\_t clkPin, uint8\_t dioPin, bool **displayOn**=true, uint8\_t brightness=5)  
*TM1637 constructor.*
- virtual void **begin** ()  
*Initialize TM1637 controller.*
- virtual void **end** ()  
*Release TM1637 pins.*
- virtual void **displayOn** ()  
*Turn Display on.*
- virtual void **displayOff** ()  
*Turn display off.*
- virtual void **setBrightness** (uint8\_t brightness)  
*Set brightness LED's.*
- virtual void **clear** ()  
*Turn all LED's off.*
- virtual void **writeData** (uint8\_t address, uint8\_t data)  
*Write display register.*
- virtual void **writeData** (uint8\_t address, const uint8\_t \*buf, uint8\_t len)  
*Write buffer to multiple display registers.*
- virtual uint8\_t **getKeys** ()  
*Get key states.*

## Protected Member Functions

- virtual void [writeDisplayControl](#) ()  
*Write display control register.*
- virtual void [writeCommand](#) (uint8\_t cmd)  
*Write command to [TM1637](#).*
- virtual void [start](#) ()  
*Generate start condition.*
- virtual void [stop](#) ()  
*Generate stop condition.*
- virtual void [writeByte](#) (uint8\_t data)  
*Write byte to [TM1637](#).*
- virtual uint8\_t [readByte](#) ()  
*Read byte from [TM1637](#).*

## Protected Attributes

- uint8\_t [\\_clkPin](#)  
*Clock pin.*
- uint8\_t [\\_dioPin](#)  
*Data pin.*
- bool [\\_displayOn](#)  
*Display on and off status for display control register.*
- uint8\_t [\\_brightness](#)  
*Display brightness for display control register.*

### 4.1.1 Detailed Description

[TM1637](#) class.

Definition at line 141 of file [TM1637.h](#).

### 4.1.2 Constructor & Destructor Documentation

4.1.2.1 [TM1637::TM1637](#) ( uint8\_t *clkPin*, uint8\_t *dioPin*, bool *displayOn* = true, uint8\_t *brightness* = 5 )

[TM1637](#) constructor.

Constructor with pin arguments: C-D (Clock, Data)

#### Parameters

<i>clkPin</i>	<a href="#">TM1637</a> CLK pin.
<i>dioPin</i>	<a href="#">TM1637</a> DIO pin.
<i>displayOn</i>	true: Turn display on (default) false: Turn display off
<i>brightness</i>	Display brightness value 0..7

Definition at line 49 of file TM1637.cpp.

### 4.1.3 Member Function Documentation

#### 4.1.3.1 `uint8_t TM1637::getKeys ( )` `[virtual]`

Get key states.

##### Returns

0xFF: All keys up 0x00..0x0F: Key 0..15 down

Definition at line 191 of file TM1637.cpp.

#### 4.1.3.2 `uint8_t TM1637::readByte ( )` `[protected]`, `[virtual]`

Read byte from [TM1637](#).

##### Returns

8-bit value.

Definition at line 316 of file TM1637.cpp.

#### 4.1.3.3 `void TM1637::setBrightness ( uint8_t brightness )` `[virtual]`

Set brightness LED's.

##### Parameters

<i>brightness</i>	Display brightness value 0..7
-------------------	-------------------------------

Definition at line 124 of file TM1637.cpp.

#### 4.1.3.4 `void TM1637::writeByte ( uint8_t data )` `[protected]`, `[virtual]`

Write byte to [TM1637](#).

##### Parameters

<i>data</i>	8-bit value.
-------------	--------------

Definition at line 276 of file TM1637.cpp.

4.1.3.5 void TM1637::writeData ( uint8\_t *address*, uint8\_t *data* ) [virtual]

Write display register.

Parameters

<i>address</i>	Display address 0x00..0x05
<i>data</i>	Value 0x00..0xFF

Definition at line 151 of file TM1637.cpp.

4.1.3.6 void TM1637::writeData ( uint8\_t *address*, const uint8\_t\* *buf*, uint8\_t *len* ) [virtual]

Write buffer to multiple display registers.

Write buffer to TM1638 with auto address increment

Parameters

<i>address</i>	Display address 0x00..0x05
<i>buf</i>	Buffer
<i>len</i>	Buffer length

Definition at line 172 of file TM1637.cpp.

The documentation for this class was generated from the following files:

- [TM1637.h](#)
- [TM1637.cpp](#)



## Chapter 5

# File Documentation

### 5.1 TM1637.cpp File Reference

[TM1637](#) library for Arduino.

```
#include "TM1637.h"
```

#### 5.1.1 Detailed Description

[TM1637](#) library for Arduino.

Source: <https://github.com/Erriez/ErriezTM1637> Documentation: <https://erriez.github.io/ErriezTM1637>

### 5.2 TM1637.h File Reference

[TM1637](#) library for Arduino.

```
#include <Arduino.h>
```

#### Classes

- class [TM1637](#)  
[TM1637](#) class.

## Macros

- #define `TM1637_CMD_DATA` 0x40  
*Display data command.*
- #define `TM1637_CMD_CTRL` 0x80  
*Display control command.*
- #define `TM1637_CMD_ADDR` 0xc0  
*Display address command.*
- #define `TM1637_DATA_WRITE` 0x00  
*Write data.*
- #define `TM1637_DATA_READ_KEYS` 0x02  
*Read keys.*
- #define `TM1637_DATA_AUTO_INC_ADDR` 0x00  
*Auto increment address.*
- #define `TM1637_DATA_FIXED_ADDR` 0x04  
*Fixed address.*
- #define `TM1637_CTRL_PULSE_1_16` 0x00  
*Pulse width 1/16.*
- #define `TM1637_CTRL_PULSE_2_16` 0x01  
*Pulse width 2/16.*
- #define `TM1637_CTRL_PULSE_4_16` 0x02  
*Pulse width 4/16.*
- #define `TM1637_CTRL_PULSE_10_16` 0x03  
*Pulse width 10/16.*
- #define `TM1637_CTRL_PULSE_11_16` 0x04  
*Pulse width 11/16.*
- #define `TM1637_CTRL_PULSE_12_16` 0x05  
*Pulse width 12/16.*
- #define `TM1637_CTRL_PULSE_13_16` 0x06  
*Pulse width 13/16.*
- #define `TM1637_CTRL_PULSE_14_16` 0x07  
*Pulse width 14/16.*
- #define `TM1637_CTRL_DISPLAY_OFF` 0x00  
*Display off.*
- #define `TM1637_CTRL_DISPLAY_ON` 0x08  
*Display on.*
- #define `TM1637_NUM_GRIDS` 6  
*Number of grid registers.*
- #define `TM1637_CLK_LOW`() { digitalWrite(\_clkPin, LOW); }  
*CLK pin low.*
- #define `TM1637_CLK_HIGH`() { digitalWrite(\_clkPin, HIGH); }  
*CLK pin high.*
- #define `TM1637_CLK_INPUT`() { pinMode(\_clkPin, INPUT); }  
*CLK pin input.*
- #define `TM1637_CLK_OUTPUT`() { pinMode(\_clkPin, OUTPUT); }  
*CLK pin output.*
- #define `TM1637_DIO_LOW`() { digitalWrite(\_dioPin, LOW); }  
*DIO pin low.*
- #define `TM1637_DIO_HIGH`() { digitalWrite(\_dioPin, HIGH); }  
*DIO pin high.*
- #define `TM1637_DIO_INPUT`() { pinMode(\_dioPin, INPUT); }

- DIO pin input.*
  - `#define TM1637_DIO_OUTPUT() { pinMode(_dioPin, OUTPUT); }`
- DIO pin output.*
  - `#define TM1637_DIO_READ() ( digitalRead(_dioPin) )`
- DIO pin read.*
  - `#define TM1637_PIN_DELAY()`
- Delay between pin changes.*

### 5.2.1 Detailed Description

TM1637 library for Arduino.

Source: <https://github.com/Erriez/ErriezTM1637> Documentation: <https://erriez.github.io/ErriezTM1637>

Command / register definitions

MSB							LSB	
7	6	5	4	3	2	1	0	
-----								
0	1	-	-	-	-	-	-	Data command
1	0	-	-	-	-	-	-	Display control command
1	1	-	-	-	-	-	-	Address command

#### 7.1 Data Command Set

MSB							LSB	
7	6	5	4	3	2	1	0	
-----								
0	1	0	0	0	-	0	0	Write display data
0	1	0	0	0	-	1	0	Read key scan data
0	1	0	0	0	0	-	-	Auto address increment
0	1	0	0	0	1	-	-	Fixed address

#### 7.2 Address command set

MSB							LSB	
7	6	5	4	3	2	1	0	
-----								
1	1	0	-	A	A	A	A	Address 0x00..0x0F

#### 7.3 Display Control

MSB							LSB	
7	6	5	4	3	2	1	0	
-----								
1	0	0	0	-	0	0	0	Set the pulse width of 1 / 16
1	0	0	0	-	0	0	1	Set the pulse width of 2 / 16
1	0	0	0	-	0	1	0	Set the pulse width of 4 / 16
1	0	0	0	-	0	1	1	Set the pulse width of 10 / 16
1	0	0	0	-	1	0	0	Set the pulse width of 11 / 16
1	0	0	0	-	1	0	1	Set the pulse width of 12 / 16
1	0	0	0	-	1	1	0	Set the pulse width of 13 / 16
1	0	0	0	-	1	1	1	Set the pulse width of 14 / 16
1	0	0	0	0	-	-	-	Display off
1	0	0	0	1	-	-	-	Display on



# Index

- getKeys
  - TM1637, [11](#)
- readByte
  - TM1637, [11](#)
- setBrightness
  - TM1637, [11](#)
- TM1637, [9](#)
  - getKeys, [11](#)
  - readByte, [11](#)
  - setBrightness, [11](#)
  - TM1637, [10](#)
  - writeByte, [11](#)
  - writeData, [11](#), [12](#)
- TM1637.cpp, [13](#)
- TM1637.h, [13](#)
- writeByte
  - TM1637, [11](#)
- writeData
  - TM1637, [11](#), [12](#)