### **Emission Coordinates**

```
x = \{1, 0, 0\};
      y = \{0, 1, 0\};
      z = \{0, 0, 1\};
       (*
      Rotation order: \theta \rightarrow \beta \rightarrow \chi
      *)
       (*
        y, x (rot about z)
        z, y (rot about x)
        x, z (rot about y)
      *)
      Clear [\alpha, \beta, \theta, \chi, \psi, \phi, k, \nu, \xi, k, kk, kx, ky, kz];
      Mchi = RotationMatrix[-\chi, {x, y}];
      Mbeta = RotationMatrix[\beta, {y, z}];
      Mtheta = RotationMatrix[-\theta, {z, x}];
            To get the velocity off the sample face in the sample coordinate frame,
      we need to perform passive rotations of the
            analyzer coordinate frame back to that of the sample. Throughout
       we use the PyARPES angular conventions. We also assume no
            angular offsets for the sample, i.e. we assume that the
       sample is glued perfectly to the face of the sample puck. This is
            almost but not quite identical to just choosing offsets in
        software that place \Gamma at the appropriate coordinates, and is valid
            so long as the offset angles between sample and puck normal are
       small angles (you can check this by working through the full coordinate
            transforms and applying the small angle approximation.
          *)
      Vemissionspherical = \{Cos[v] Sin[\xi], Sin[v] Sin[\xi], Cos[\xi]\};
       (* Spherical coordinates with declination angle \xi and azimuthal angle \gamma. *)
       (* Vemission = Mchi.Mbeta.Mtheta.Vanaframe; *)
      MatrixForm[Vemissionspherical]
      MatrixForm[Mchi.Mbeta.Mtheta]
Out[12]//MatrixForm=
        Cos[ν] Sin[ζ]
        Sin[\zeta] Sin[v]
           Cos[\zeta]
Out[13]//MatrixForm=
        \cos[\theta] \cos[\chi] - \sin[\beta] \sin[\theta] \sin[\chi] \cos[\beta] \sin[\chi] - \cos[\chi] \sin[\theta] - \cos[\theta] \sin[\beta] \sin[\xi]
        Cos[\beta] Sin[\theta]
                                                   Sin[\beta]
                                                                           Cos[\beta] Cos[\theta]
```

### Analyzer's Coordinates

The analyzer measures photoelectron velocities and records them in terms of three angles:  $\phi$  (along the slit),  $\psi$  (electrostatic slit deflector angle or analyzer motion angle) and  $\alpha$  (analyzer rotation). If temporarily we assume  $\alpha == 0$  then

```
In[14]:= Clear[\alpha, \phi, \psi]
            Vanaframe = EulerMatrix[\{\alpha, \phi, -\psi\}, \{3, 2, 1\}];
            MatrixForm[Vanaframe]
            MatrixForm[Vanaframe.z]
            Assuming[
               \{\alpha = 0\},
               MatrixForm[Simplify[Vanaframe.z]]
             ]
            Assuming[
               \{\alpha = \pi/2\},
               MatrixForm[Simplify[Vanaframe.z]]
Out[16]//MatrixForm=
               \mathsf{Cos}[\alpha] \; \mathsf{Cos}[\phi] \; \; -\mathsf{Cos}[\psi] \; \mathsf{Sin}[\alpha] \; -\mathsf{Cos}[\alpha] \; \mathsf{Sin}[\phi] \; \mathsf{Sin}[\psi] \; \; \mathsf{Cos}[\alpha] \; \mathsf{Cos}[\psi] \; \mathsf{Sin}[\phi] \; -\mathsf{Sin}[\alpha] \; \mathsf{Sin}[\psi]
               \mathsf{Cos}[\phi] \; \mathsf{Sin}[\alpha] \quad \mathsf{Cos}[\alpha] \; \mathsf{Cos}[\psi] - \mathsf{Sin}[\alpha] \; \mathsf{Sin}[\phi] \; \mathsf{Sin}[\psi] \quad \mathsf{Cos}[\psi] \; \mathsf{Sin}[\alpha] \; \mathsf{Sin}[\phi] + \mathsf{Cos}[\alpha] \; \mathsf{Sin}[\psi]
                    -Sin[φ]
                                                                 -\cos[\phi] \sin[\psi]
                                                                                                                                           Cos[\phi] Cos[\psi]
Out[17]//MatrixForm=
               Cos[\alpha] Cos[\psi] Sin[\phi] - Sin[\alpha] Sin[\psi]
               \mathsf{Cos}[\psi] \, \mathsf{Sin}[\alpha] \, \mathsf{Sin}[\phi] + \mathsf{Cos}[\alpha] \, \mathsf{Sin}[\psi]
                                    Cos[\phi] Cos[\psi]
               Cos[\psi] Sin[\phi]
                      Sin[\psi]
               Cos[\phi] Cos[\psi]
Out[19]//MatrixForm=
                    -Sin[\psi]
               Cos[\psi] Sin[\phi]
               Cos[\phi] Cos[\psi]
```

### **Momentum Conservation**

We know that the kinetic energy and momentum are related to the velocity and emission angles by

In[20]:= kc = Sqrt[2 \* m \* Ek] 
$$/\hbar$$
  
k = kc \* Vemissionspherical;  
MatrixForm[k]  
Out[20]=  $\frac{\sqrt{2} \sqrt{Ek m}}{\hbar}$   
Out[22]//MatrixForm=  $\frac{\sqrt{2} \sqrt{Ekm} \cos[v] \sin[\xi]}{\hbar}$   
 $\frac{\hbar}{\sqrt{2} \sqrt{Ekm} \sin[\xi] \sin[v]}$ 

# Inverting for the analyzer angles in terms of k

We now have a set of three equations coupling analyzer and scan angles to the momentum. In principle now, we can calculate the momentum directly from the experimental degrees of freedom. However, if our data is gridded, we need to convert backwards from momentum to angles in order to be able to interpolate. To do this, we will see a few special cases below.

```
In[23]:= momentum = kc * MatrixForm[(Mchi.Mbeta.Mtheta).(Vanaframe.z)]
                                                                        TransAna = kk * Mchi.Mbeta.Mtheta.(Vanaframe.z);
                                                                          MatrixForm[TransAna]
          \text{Out}[23] = \begin{array}{l} \frac{1}{\hbar} \sqrt{2} \ \sqrt{\mathsf{Ek}\,\mathsf{m}} \end{array} \left( \begin{array}{c} \mathsf{Cos}[\phi] \ \mathsf{Cos}[\psi] \ \left( -\mathsf{Cos}[\chi] \ \mathsf{Sin}[\theta] \ -\mathsf{Cos}[\theta] \ \mathsf{Sin}[\beta] \ \mathsf{Sin}[\chi] \right) + \mathsf{Cos}[\beta] \ \mathsf{Sin}[\chi] \ \left( \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Sin}[\beta] + \mathsf{Sin}[\theta] \ \mathsf{Sin}[\chi] \right) + \mathsf{Cos}[\beta] \ \mathsf{Cos}[\chi] \ \left( \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \ \mathsf{Cos}[\psi] \right) \right) 
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  Cos[\beta] Cos[\theta] Cos[\phi] Cos[\psi] + Sin[\beta] (Cos[\psi] Sir
Out[25]//MatrixForm=
                                                                                               \mathsf{kk} \; (\mathsf{Cos}[\phi] \; \mathsf{Cos}[\psi] \; (-\mathsf{Cos}[\chi] \; \mathsf{Sin}[\theta] \; - \mathsf{Cos}[\theta] \; \mathsf{Sin}[\beta] \; \mathsf{Sin}[\chi] \; ) \; + \; \mathsf{Cos}[\beta] \; \mathsf{Sin}[\chi] \; (\mathsf{Cos}[\psi] \; \mathsf{Sin}[\alpha] \; )
                                                                                        \mathsf{kk} \; (\mathsf{Cos}[\phi] \; \mathsf{Cos}[\psi] \; (-\mathsf{Cos}[\theta] \; \mathsf{Cos}[\chi] \; \mathsf{Sin}[\beta] \; + \; \mathsf{Sin}[\theta] \; \mathsf{Sin}[\chi]) \; + \; \mathsf{Cos}[\beta] \; \mathsf{Cos}[\chi] \; (\mathsf{Cos}[\psi] \; \mathsf{Sin}[\alpha] \; \mathsf{Sin}[
```

kk  $(Cos[\beta] Cos[\theta] Cos[\phi] Cos[\psi] + Sin[\beta] (Cos[\psi] Sin[\alpha] Sin[$ 

# Inverting a very simple case:

Fixed hemispherical analyzer with no sample or analyzer rotation

In this case, we can assume  $\{\alpha, \chi, \psi\}$  == 0. This gives a very simple relationship between the sample angles, a single analyzer angle  $\phi$  and the photoelectron momentum for horizontal slit analyzers.

```
In[26]:= Assuming[  \{\alpha == 0, \chi == 0, \psi == 0\},   \text{MatrixForm}[\{kx, ky, kz\}] == \text{MatrixForm}[\text{Simplify}[\text{TransAna}]]   ]   \text{Out}[26] = \begin{pmatrix} kx \\ ky \\ kz \end{pmatrix} = \begin{pmatrix} -kk \sin[\theta - \phi] \\ -kk \cos[\theta - \phi] \sin[\beta] \\ kk \cos[\beta] \cos[\theta - \phi] \end{pmatrix}
```

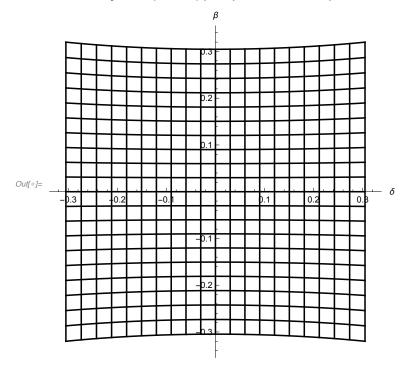
Using the kx and ky equations we can invert for the "scan coordinate"  $\beta$  and the analyzer coordinate  $\phi$ :

```
 \begin{aligned} & \text{Im}[27] &:= \text{ Assuming} \Big[ \\ & \{\alpha=0,\,\chi=0,\,\psi=0\}, \\ & \text{ FullSimplify} \Big[ \text{Solve} \Big[ \Big\{ \big( \text{Simplify} \big[ \text{TransAna} \big] . \text{x /. } (\theta-\phi) \to \delta \big) \ == \ \text{kx} \Big\}, \ \{\delta\} \Big] \Big] \\ & \text{ Assuming} \Big[ \\ & \{\alpha=0,\,\chi=0,\,\psi=0\}, \\ & \text{ FullSimplify} \Big[ \text{Solve} \Big[ \Big\{ \big( \text{Simplify} \big[ \text{TransAna} \big] . \text{y} \big) \ == \ \text{ky} \Big\}, \ \{\beta\} \Big] \Big] \Big] \\ & \text{Out}[27] &= \Big\{ \Big\{ \delta \to \text{ConditionalExpression} \Big[ - \text{ArcSin} \Big[ \frac{\text{kx}}{\text{kk}} \Big] + 2 \,\pi \,c_1, \,c_1 \in \mathbb{Z} \Big] \Big\}, \\ & \Big\{ \delta \to \text{ConditionalExpression} \Big[ - \text{ArcSin} \Big[ \frac{\text{ky Sec} [\theta-\phi]}{\text{kk}} \Big] + 2 \,\pi \,c_1, \,c_1 \in \mathbb{Z} \Big] \Big\} \Big\} \\ & \text{Out}[28] &= \Big\{ \Big\{ \beta \to \text{ConditionalExpression} \Big[ - \text{ArcSin} \Big[ \frac{\text{ky Sec} [\theta-\phi]}{\text{kk}} \Big] + 2 \,\pi \,c_1, \,c_1 \in \mathbb{Z} \Big] \Big\} \Big\} \end{aligned}
```

We can now plot what this looks like in terms of kx, ky:

In[ • ]:=

Evaluate [Table [Tooltip [
$$\{-ArcSin[\frac{kx}{kk}], -ArcSin[\frac{ky Sec[-ArcSin[\frac{kx}{kk}]]}{kk}]\}$$
, Row [ $\{"kx = ", kx\}$ ]],  $\{kx, -0.3, 0.3, 0.03\}$ ]],  $\{ky, -0.3, 0.3\}$ , PlotStyle  $\rightarrow$  {Black}, AspectRatio  $\rightarrow$  1, AxesLabel  $\rightarrow$  { $\delta$ ,  $\beta$ }], ParametricPlot [Evaluate [Table [Tooltip [ $\{-ArcSin[\frac{kx}{kk}], -ArcSin[\frac{ky Sec[-ArcSin[\frac{kx}{kk}]]}{kk}]\}$ }, Row [ $\{"ky = ", ky\}$ ]],  $\{ky, -0.3, 0.3, 0.03\}$ ]],  $\{kx, -0.3, 0.3\}$ , PlotStyle  $\rightarrow$  {Black}, AspectRatio  $\rightarrow$  1, AxesLabel  $\rightarrow$  { $\delta$ ,  $\beta$ }]]



### $\alpha$ = 0 and $\chi$ $\neq$ 0

#### The general horizontal slit

Here, the simplest thing to do is to rotate the momentum coordinates by  $-\chi$  and then apply our prior solution.

```
In[*]:= Assuming[
                \{\alpha=0,\ \psi=0\},
                MatrixForm[RotationMatrix[\chi, {x, y}].{kx, ky, kz}] ==
                   MatrixForm[Simplify[RotationMatrix[\chi, {x, y}].Simplify[TransAna]]]
\textit{Out[*]=} \left( \begin{array}{c} \mathsf{kx} \, \mathsf{Cos} \, [\chi] \, - \, \mathsf{ky} \, \mathsf{Sin} \, [\chi] \\ \mathsf{ky} \, \mathsf{Cos} \, [\chi] \, + \, \mathsf{kx} \, \mathsf{Sin} \, [\chi] \\ \mathsf{kz} \end{array} \right) = \left( \begin{array}{c} - \, \mathsf{Sin} \, [\theta - \phi] \\ - \, \mathsf{Cos} \, [\theta - \phi] \, \, \mathsf{Sin} \, [\beta] \\ \mathsf{Cos} \, [\beta] \, \, \mathsf{Cos} \, [\theta - \phi] \end{array} \right)
 ln[\bullet]:= kk = 1; \chi = \pi/12;
             \mathsf{Show}\big[\mathsf{ParametricPlot}\big[\mathsf{Evaluate}\big[\mathsf{Table}\big[\mathsf{Tooltip}\big[\big\{-\mathsf{ArcSin}\big[\frac{\big(\mathsf{kx}\,\mathsf{Cos}[\chi]\,-\,\mathsf{ky}\,\mathsf{Sin}[\chi]\big)}{\mathsf{kk}}\big]\big],
                               -\operatorname{ArcSin}\Big[\frac{\left(\operatorname{ky}\operatorname{Cos}[\chi]+\operatorname{kx}\operatorname{Sin}[\chi]\right)\operatorname{Sec}\left[-\operatorname{ArcSin}\left[\frac{\left(\operatorname{kx}\operatorname{Cos}[\chi]-\operatorname{ky}\operatorname{Sin}[\chi]\right)}{\operatorname{kk}}\right]\right]}{\operatorname{kk}}\Big]\Big\},
                             Row[{"kx = ", kx}]], {kx, -0.3, 0.3, 0.03}]], {ky, -0.3, 0.3},
                   PlotStyle \rightarrow {Black}, AspectRatio \rightarrow 1, AxesLabel \rightarrow {\phi - \theta, \beta}],
                {\sf ParametricPlot[Evaluate[Table[Tooltip[\{-ArcSin[\frac{\left(\mathsf{kx}\,\mathsf{Cos}[\chi]\,-\,\mathsf{ky}\,\mathsf{Sin}[\chi]\right)}{\mathsf{kk}}]}\,]}\,,
                               -\operatorname{ArcSin}\Big[\frac{\left(\operatorname{ky}\operatorname{Cos}[\chi]+\operatorname{kx}\operatorname{Sin}[\chi]\right)\operatorname{Sec}\big[-\operatorname{ArcSin}\big[\frac{\left(\operatorname{kx}\operatorname{Cos}[\chi]-\operatorname{ky}\operatorname{Sin}[\chi]\right)}{\operatorname{kk}}\big]\big]}{\operatorname{kk}}\Big]\Big],
                             Row[{"ky = ", ky}]], {ky, -0.3, 0.3, 0.03}]], {kx, -0.3, 0.3},
                   PlotStyle \rightarrow {Black}, AspectRatio \rightarrow 1, AxesLabel \rightarrow {\phi - \theta, \beta}]
Out[ • ]=
                                                                                                                                  ___ φ-θ
```

 $\alpha = \pi/2$  and  $\chi = 0$ 

```
ln[\bullet]:= kk = 1; \beta = 0;
        Show[ParametricPlot[Evaluate]
             Table \big[ Tooltip \big[ \big\{ -ArcSin \big[ \frac{\mathsf{kx} \, \sqrt{1 + \frac{\mathsf{kk}^2 + \mathsf{kx}^2 - 2\,\sqrt{\mathsf{kk}^2 - \mathsf{kx}^2 - \mathsf{ky}^2}}\,\, \mathsf{Abs}[\mathsf{ky}] \, \mathsf{Sin}[2\,\beta] + \big(\mathsf{kk}^2 - \mathsf{kx}^2 - 2\,\mathsf{ky}^2\big) \, \mathsf{Cos}[2\,\beta]}}{\mathsf{kk}} \\
                   Sign[ky] * π/4-ArcTan[
                            \frac{\sqrt{kk^2 + kx^2 - 2\sqrt{kk^2 - kx^2 - ky^2}} \text{ Abs[ky] Sin[2 \beta] + (kk^2 - kx^2 - 2 ky^2) \cos[2 \beta]}{\sqrt{2} \text{ kk}}
                    , Row[{"kx = ", kx}]], {kx, -0.3, 0.3, 0.03}]],
            \{ky, -0.3, 0.3\}, PlotStyle \rightarrow \{Black\}, AspectRatio \rightarrow 1,
            AxesLabel \rightarrow \{\theta, \phi\}], ParametricPlot[Evaluate]
             Table [Tooltip [\{-ArcSin[\frac{kx\sqrt{1+\frac{kk^2+kx^2-2\sqrt{kk^2-kx^2-ky^2}}{Abs[ky]}\frac{Sin[2\beta]+(kk^2-kx^2-2ky^2)}{2kk^2}}{kk}]}{kk}
                   Sign[ky] π/4-ArcTan[
                            \frac{\sqrt{kk^{2} + kx^{2} - 2\sqrt{kk^{2} - kx^{2} - ky^{2}}} \text{ Abs[ky] Sin[2 \beta] + (kk^{2} - kx^{2} - 2 ky^{2}) \cos[2 \beta]}}{\sqrt{2} \text{ kk}}
                    , Row[{"ky = ", ky}]], {ky, -0.3, 0.3, 0.03}]], {kx, -0.3, 0.3},
           PlotStyle \rightarrow {Black}, AspectRatio \rightarrow 1, AxesLabel \rightarrow {\theta, \phi}]]
```

Clear[ kk, β];

## $\alpha = \pi/2$ and $\chi = 0$

Small angle approximation version

```
In[*]:= Assuming[
                \{\alpha = \pi/2, \chi = 0, \psi = 0, \beta = 0\},\
                {\tt MatrixForm[\{kx, ky, kz\}] == MatrixForm[FullSimplify[TransAna] /. } \phi \rightarrow \phi - \beta]
Out[\bullet] = \begin{pmatrix} kx \\ ky \\ kz \end{pmatrix} == \begin{pmatrix} -kk \cos[\beta - \phi] \sin[\theta] \\ -kk \sin[\beta - \phi] \\ kk \cos[\theta] \cos[\beta - \phi] \end{pmatrix}
  In[●]:= Assuming[
                \{\alpha = \pi/2, \chi = 0, \psi = 0\},\
                FullSimplify[Solve[\{(-kk Sin[\beta - \phi]) = ky\}, \{\phi\}]]
\textit{Out[*]=} \left\{ \left\{ \phi \rightarrow \mathsf{ConditionalExpression} \left[ \beta + \mathsf{ArcCos} \left[ \frac{\mathsf{ky}}{\mathsf{kk}} \right] - \frac{1}{2} \pi \left( 3 + 4 \, \mathfrak{C}_1 \right) \right. , \, \mathfrak{C}_1 \in \mathbb{Z} \right] \right\},
                \left\{\phi \to \mathsf{ConditionalExpression}\left[\,\beta + \mathsf{ArcSin}\left[\,\frac{\mathsf{k} \mathsf{y}}{\mathsf{k} \mathsf{k}}\,\right] \, - \, 2\,\pi\,\,\mathtt{c}_{1}\,,\,\,\mathtt{c}_{1} \in \mathbb{Z}\,\right]\,\right\}
```

```
In[*]:= Assuming[
                   \{\alpha = \pi/2, \chi = 0, \psi = 0\},\
                   FullSimplify \left[ \text{Solve} \left[ \left\{ \left( -\text{kk Cos} \left[ \beta - \phi \right] \text{Sin} \left[ \theta \right] / \cdot \phi \rightarrow \left( \beta + \text{ArcSin} \left[ \frac{\text{ky}}{\text{kk}} \right] \right) \right) = \text{kx} \right\}, \{\theta\} \right] \right]
\textit{Out[*]=} \ \left\{ \left\{ \Theta \to \mathsf{ConditionalExpression} \left[ \, - \mathsf{ArcSin} \left[ \, \frac{\mathsf{kx}}{\mathsf{kk}} \, \right] \, + 2 \, \pi \, \mathbb{C}_1, \, \mathbb{C}_1 \in \mathbb{Z} \, \right] \right\},
                  \left\{ \theta \to \mathsf{ConditionalExpression} \left[ \pi + \mathsf{ArcSin} \left[ \frac{\mathsf{kx}}{\mathsf{kk}} \right] \right. + 2 \, \pi \, \mathbb{c}_1, \, \mathbb{c}_1 \in \mathbb{Z} \right] \right\} \right\}
```

```
ln[\bullet]:= kk = 1; \beta = \pi/20;
        Show[ParametricPlot[Evaluate]
              Table \left[ Tooltip \left[ \left\{ \beta + ArcSin \left[ \frac{ky}{kk} \right] \right., \right. \left. - ArcSin \left[ \frac{kx}{\sqrt{1 - \frac{ky^2}{kk^2}}} \right] \right\}, \\ Row \left[ \left\{ \text{"kx } = \text{", kx} \right\} \right] \right],
                 \{kx, -0.301, 0.299, 0.03\}], \{ky, -0.301, 0.299\},
            PlotStyle \rightarrow {Black}, AspectRatio \rightarrow 1, AxesLabel \rightarrow {\phi, \theta}],
           \text{ParametricPlot} \Big[ \text{Evaluate} \Big[ \text{Table} \Big[ \text{Tooltip} \Big[ \Big\{ \beta + \text{ArcSin} \Big[ \frac{\text{ky}}{\text{kk}} \Big] , - \text{ArcSin} \Big[ \frac{\text{kx}}{\text{kk}} \Big] \Big\} \Big] \Big\}, 
                   Row[{"ky = ", ky}]], {ky, -0.301, 0.299, 0.03}]], {kx, -0.301, 0.299},
            PlotStyle \rightarrow {Black}, AspectRatio \rightarrow 1, AxesLabel \rightarrow {\phi, \theta}]]
       Clear[
            kk,
            β];
                                θ
```

### $\alpha = \pi/2$ and $\chi \neq 0$

Small angle approximation for vertical slits and sample rotation

```
In[29]:= Assuming
                  \{\alpha=0\,,\ \psi=0\}\,,
                 MatrixForm[ RotationMatrix[\chi, {x, y}].{kx, ky, kz}] == MatrixForm[
                              {\tt Simplify} \big[ {\tt RotationMatrix} [\chi, \quad \{ x, \quad y \} ] \cdot \big( {\tt FullSimplify} [{\tt TransAna}] \; / \cdot \; \phi \to \; \phi - \beta \big) \, \big] \big]
 \text{Out} [29] = \left( \begin{array}{c} \mathsf{kx} \, \mathsf{Cos} \, [\chi] \, - \mathsf{ky} \, \mathsf{Sin} [\chi] \\ \mathsf{ky} \, \mathsf{Cos} \, [\chi] \, + \mathsf{kx} \, \mathsf{Sin} [\chi] \\ \mathsf{kz} \end{array} \right) = \left( \begin{array}{c} - \mathsf{kk} \, \mathsf{Sin} [\beta + \theta - \phi] \\ - \mathsf{kk} \, \mathsf{Cos} \, [\beta + \theta - \phi] \, \mathsf{Sin} [\beta] \\ \mathsf{kk} \, \mathsf{Cos} \, [\beta] \, \, \mathsf{Cos} \, [\beta + \theta - \phi] \end{array} \right)
```

Show[ParametricPlot[Evaluate[Table[ Tooltip[
$$\{\beta + \text{ArcSin}[\frac{\text{ky} \cos[\chi] + \text{kx} \sin[\chi]}{\text{kk}}\}$$
,  $-\text{ArcSin}[\frac{\text{kx} \cos[\chi] - \text{ky} \sin[\chi]}{\text{kk}}$ ],  $-\text{ArcSin}[\frac{\text{kx} \cos[\chi] - \text{ky} \sin[\chi]}{\text{kk}}$ ]}, 
$$\frac{\text{Row}[\{\text{"kx} = \text{", kx}\}]], \{\text{kx, -0.301, 0.299, 0.03}\}],}{\text{kk, -0.301, 0.299, 0.03}}, \{\text{ky, -0.301, 0.299}, \text{PlotStyle} \rightarrow \{\text{Black}\}, \text{AspectRatio} \rightarrow 1, \text{AxesLabel} \rightarrow \{\phi, \theta\}], \text{ParametricPlot}[\text{Evaluate}[\text{Table}[$$

$$\text{Tooltip}[\{\beta + \text{ArcSin}[\frac{\text{ky} \cos[\chi] + \text{kx} \sin[\chi]}{\text{kk}}], -\text{ArcSin}[\frac{\text{kx} \cos[\chi] - \text{ky} \sin[\chi]}{\text{kk}}]\},}{\text{kk}}$$

$$\text{Row}[\{\text{"ky} = \text{", ky}\}]], \{\text{ky, -0.301, 0.299, 0.03}\}], \{\text{kx, -0.301, 0.299}\},}$$

$$\text{PlotStyle} \rightarrow \{\text{Black}\}, \text{AspectRatio} \rightarrow 1, \text{AxesLabel} \rightarrow \{\phi, \theta\}]]$$

$$\text{Clear}[\text{kk, } \beta];}$$

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$$\alpha$$
 = 0,  $\chi$  = 0,  $\psi$  ≠0

ARToF and Scanning Deflector Hemispheres, Small Angle **Approximation** 

```
In[75]:= Clear [\alpha, \phi, \psi, \chi, \theta, \beta];
                  Assuming[
                                \{\alpha=0\,,\ \chi=0\,,\,\theta=0\}\,,
                                (* \phi here refers to \phi-\theta *)
                                MatrixForm[ {kx, ky, kz}] == MatrixForm[FullSimplify[TransAna]]
 \text{Out} [76] = \left( \begin{array}{c} \mathsf{kx} \\ \mathsf{ky} \\ \mathsf{kz} \end{array} \right) \ = \ \left( \begin{array}{c} \mathsf{kk} \, \mathsf{Cos} \, [\psi] \, \, \mathsf{Sin} \, [\phi] \\ \mathsf{kk} \, \left( - \, \mathsf{Cos} \, [\phi] \, \, \mathsf{Cos} \, [\psi] \, \, \mathsf{Sin} \, [\beta] \, + \, \mathsf{Cos} \, [\beta] \, \, \mathsf{Sin} \, [\psi] \right) \\ \mathsf{kk} \, \left( \mathsf{Cos} \, [\beta] \, \, \mathsf{Cos} \, [\phi] \, \, \mathsf{Cos} \, [\psi] \, \, + \, \mathsf{Sin} \, [\beta] \, \, \mathsf{Sin} \, [\psi] \right) \end{array} \right) 
                 Assuming[
                                \{\alpha = 0, \chi = 0, \beta = 0\},\
                                MatrixForm[{kx, ky, kz}] == MatrixForm[FullSimplify[TransAna] /. \psi \rightarrow \psi - \beta]
 \text{Out[68]=} \left( \begin{array}{c} \mathsf{kx} \\ \mathsf{ky} \\ \mathsf{kz} \end{array} \right) = \left( \begin{array}{c} -\mathsf{kk} \, \mathsf{Cos} \, [\beta - \psi] \, \, \mathsf{Sin} \, [\theta - \phi] \\ -\mathsf{kk} \, \mathsf{Sin} \, [\beta - \psi] \\ \mathsf{kk} \, \mathsf{Cos} \, [\theta - \phi] \, \, \mathsf{Cos} \, [\beta - \psi] \end{array} \right) 
  In[80]:= Assuming[
                                \{\alpha=0\,,\quad\chi=0\,,\,\beta=0\,,\,\theta=0\}\,,
                                Solve[\{-kk Sin[\beta - \psi] = ky\}, \{\psi\}]
 \text{Out}[80] = \left\{ \left\{ \psi \to \mathsf{ConditionalExpression} \left[ -\pi + \beta - \mathsf{ArcSin} \left[ \frac{\mathsf{ky}}{\mathsf{kk}} \right] - 2 \pi \, \mathbb{c}_1, \, \mathbb{c}_1 \in \mathbb{Z} \right] \right\},
                     \left\{\psi \to \mathsf{ConditionalExpression}\left[\beta + \mathsf{ArcSin}\left[\frac{\mathsf{ky}}{\mathsf{kk}}\right] - 2 \pi \, \mathbb{c}_1, \, \mathbb{c}_1 \in \mathbb{Z}\right]\right\}\right\}
  In[81]:= FullSimplify \left[-kk \cos \left(\beta - \psi\right) \sin \left(\theta - \phi\right) / \cdot \psi \rightarrow \beta + ArcSin \left(\frac{ky}{kk}\right)\right]
Out[81]= -kk\sqrt{1-\frac{ky^2}{kk^2}} Sin[\theta-\phi]
```

In[82]:= Assuming[ 
$$\{\alpha = 0, \ \chi = 0, \beta = 0, \theta = 0\},$$
 
$$Solve \left[ \left\{ -kk \sqrt{1 - \frac{ky^2}{kk^2}} \right. Sin[\theta - \phi] = kx \right\}, \{\phi\} \right]$$
 
$$\int _{\text{Out[82]}=} \left\{ \left\{ \phi \to \text{ConditionalExpression} \left[ -\pi + \theta - \text{ArcSin} \left[ \frac{kx}{kk \sqrt{\frac{kk^2 - ky^2}{kk^2}}} \right] - 2\pi \, \mathbb{c}_1, \, \mathbb{c}_1 \in \mathbb{Z} \right] \right\},$$
 
$$\left\{ \phi \to \text{ConditionalExpression} \left[ \theta + \text{ArcSin} \left[ \frac{kx}{kk \sqrt{\frac{kk^2 - ky^2}{kk^2}}} \right] - 2\pi \, \mathbb{c}_1, \, \mathbb{c}_1 \in \mathbb{Z} \right] \right\} \right\}$$

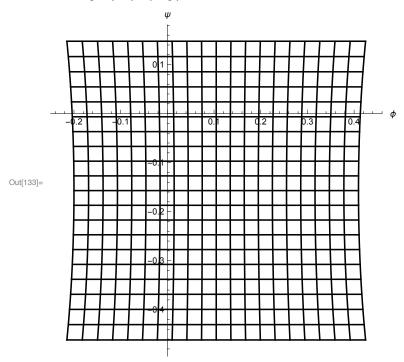
$$ln[132]:=$$
 kk = 1;  $\beta = -\pi/20$ ;  $\theta = \pi/30$ ;  $\chi = 0$ ; Show

$$\begin{aligned} \text{ParametricPlot} \big[ \text{Evaluate} \big[ \text{Table} \big[ \text{Tooltip} \big[ \big\{ \theta + \text{ArcSin} \big[ \frac{\mathsf{kx}}{\mathsf{kk}^2 - \mathsf{ky}^2} \big] \big\}, \ \beta + \text{ArcSin} \big[ \frac{\mathsf{ky}}{\mathsf{kk}} \big] \big\}, \end{aligned}$$

Row[{"kx = ", kx}]], {kx, -0.3, 0.3, 0.03}]], {ky, -0.3, 0.3}, PlotStyle 
$$\rightarrow$$
 {Black}, AspectRatio  $\rightarrow$  1, AxesLabel  $\rightarrow$  { $\phi$ ,  $\psi$ }],

$$\begin{aligned} \text{ParametricPlot} \big[ \text{Evaluate} \big[ \text{Table} \big[ \text{Tooltip} \big[ \big\{ \theta + \text{ArcSin} \big[ \frac{\mathsf{k} \mathsf{x}}{\mathsf{k} \mathsf{k}^2 - \mathsf{k} \mathsf{y}^2} \big] \big\} \,, \, \beta + \text{ArcSin} \big[ \frac{\mathsf{k} \mathsf{y}}{\mathsf{k} \mathsf{k}} \big] \big\} \,, \end{aligned}$$

Row[{"ky = ", ky}]], {ky, -0.3, 0.3, 0.03}]], {kx, -0.3, 0.3}, PlotStyle 
$$\rightarrow$$
 {Black}, AspectRatio  $\rightarrow$  1, AxesLabel  $\rightarrow$  { $\phi$ ,  $\psi$ }]] Clear[kk,  $\beta$ ,  $\theta$ ,  $\chi$ ];



In[98]:=

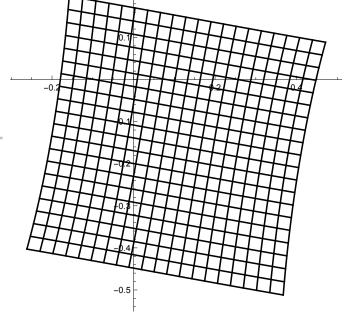
### $\alpha = 0, \chi \neq 0, \psi \neq 0$

ARToF and Scanning Deflector Hemispheres, General case

```
In[137]:= Clear [\alpha, \phi, \psi, \chi, \theta, \beta];
           Assuming[
                    \{\alpha = 0, \chi = 0, \theta = 0\},\
                   (* \phi here refers to \phi-\theta *)
                   MatrixForm[RotationMatrix[\chi, \{x, y\}].\{kx, ky, kz\}] ==
               MatrixForm[RotationMatrix[\chi, {x, y}].FullSimplify[TransAna]]
           ]
              kx Cos[\chi] - ky Sin[\chi]
Out[138]=
            ky Cos[\chi] + kx Sin[\chi]
                \mathsf{kk}\,\mathsf{Cos}[\chi]\,\mathsf{Cos}[\psi]\,\mathsf{Sin}[\phi]\,-\,\mathsf{kk}\,\mathsf{Sin}[\chi]\,\left(-\,\mathsf{Cos}[\phi]\,\mathsf{Cos}[\psi]\,\mathsf{Sin}[\beta]\,+\,\mathsf{Cos}[\beta]\,\mathsf{Sin}[\psi]\right)\,\mathsf{Volume}
                \mathsf{kk}\,\mathsf{Cos}[\psi]\,\mathsf{Sin}[\phi]\,\mathsf{Sin}[\chi]\,+\,\mathsf{kk}\,\mathsf{Cos}[\chi]\,\left(-\,\mathsf{Cos}[\phi]\,\mathsf{Cos}[\psi]\,\mathsf{Sin}[\beta]\,+\,\mathsf{Cos}[\beta]\,\mathsf{Sin}[\psi]\right)
                                                kk (Cos[\beta] Cos[\phi] Cos[\psi] + Sin[\beta] Sin[\psi])
```

$$\begin{split} & \text{Show} \big[ \text{ParametricPlot} \big[ \text{Evaluate} \big[ \text{Table} \big[ \\ & \text{Tooltip} \big[ \big\{ \theta + \text{ArcSin} \big[ \frac{\text{kx} \, \text{Cos}[\chi] - \text{ky} \, \text{Sin}[\chi]}{\text{kk}} \big], \, \beta + \text{ArcSin} \big[ \frac{\text{ky} \, \text{Cos}[\chi] + \text{kx} \, \text{Sin}[\chi]}{\text{kk}} \big] \big\}, \\ & \text{Row} \big[ \{ \text{"kx} = \text{", kx} \} \big], \, \left\{ \text{kx}, \, -0.3, \, 0.3, \, 0.03 \} \big] \big], \, \left\{ \text{ky}, \, -0.3, \, 0.3 \}, \\ & \text{PlotStyle} \rightarrow \, \left\{ \text{Black} \right\}, \, \text{AspectRatio} \rightarrow 1, \, \text{AxesLabel} \rightarrow \, \left\{ \phi, \, \psi \right\} \big], \\ & \text{ParametricPlot} \big[ \text{Evaluate} \big[ \text{Table} \big[ \text{Tooltip} \big[ \big\{ \theta + \text{ArcSin} \big[ \frac{\text{kx} \, \text{Cos}[\chi] - \text{ky} \, \text{Sin}[\chi]}{\text{kk}} \big]}{\text{kk}} \right] \big\}, \\ & \beta + \text{ArcSin} \big[ \frac{\text{ky} \, \text{Cos}[\chi] + \text{kx} \, \text{Sin}[\chi]}{\text{kk}} \big] \big\}, \, \text{Row} \big[ \{ \text{"ky} = \text{", ky} \} \big] \big], \, \left\{ \text{ky}, \, -0.3, \, 0.3, \, 0.03 \} \big] \big], \\ & \left\{ \text{kx}, \, -0.3, \, 0.3 \right\}, \, \text{PlotStyle} \rightarrow \, \left\{ \text{Black} \right\}, \, \text{AspectRatio} \rightarrow 1, \, \text{AxesLabel} \rightarrow \, \left\{ \phi, \, \psi \right\} \big] \big] \\ & \text{Clear} \big[ \text{kk}, \, \beta, \, \theta, \, \chi \big]; \\ \end{split}$$

Out[146]=



## $\alpha = \pi/2, \chi = 0, \psi \neq 0$

ARToFs and Scanning Slit Hemispheres

```
In[224]:= Clear[\alpha, \phi, \psi, \chi, \theta, \beta, kk];
               Assuming[
                           \{\alpha = \pi/2, \chi = 0, \theta = 0\},
                           MatrixForm[ {kx, ky, kz}] == Simplify[MatrixForm[TransAna]]
Out[225]= \begin{pmatrix} kx \\ ky \\ kz \end{pmatrix} == \begin{pmatrix} -kk \sin[\psi] \\ -kk \cos[\psi] \sin[\beta - \phi] \\ kk \cos[\beta - \phi] \cos[\psi] \end{pmatrix}
               \psi + \Theta and \beta - \psi
  In[220]:= Clear[\alpha, \phi, \psi, \chi, \theta, \beta, kk];
               Assuming
                           \{\alpha = \pi/2, \chi = 0, \beta = 0, \theta = 0\},\
                           MatrixForm[ {kx, ky, kz}] ==
                     TrigExpand[Simplify[MatrixForm[TransAna]] /. \psi \rightarrow \psi + \theta]
Out[221]= \begin{pmatrix} kx \\ ky \\ kz \end{pmatrix} == \begin{pmatrix} -kk \sin[\theta + \psi] \\ kk \cos[\theta + \psi] \sin[\phi] \\ kk \cos[\phi] \cos[\theta + \psi] \end{pmatrix}
  In[227]:= Assuming
                           \{\alpha = \pi/2, \chi = 0, \theta = 0\},\
                                     Solve[FullSimplify[TransAna].x == kx, \{\psi\}]
\mathsf{Out}[227] = \left\{ \left\{ \psi \to \mathsf{ConditionalExpression} \left[ -\mathsf{ArcSin} \left[ \frac{\mathsf{kx}}{\mathsf{kk}} \right] + 2 \pi \, \mathfrak{C}_1, \, \mathfrak{C}_1 \in \mathbb{Z} \right] \right\},
                  \left\{ \psi \to \mathsf{ConditionalExpression} \left[ \, \pi + \mathsf{ArcSin} \left[ \, \frac{\mathsf{kx}}{\mathsf{kk}} \, \right] \, + \, 2 \, \pi \, \, \mathbb{c}_1 \, , \, \, \mathbb{c}_1 \in \mathbb{Z} \, \right] \, \right\} \right\}
  In[228]:= Assuming
                           \{\alpha = \pi/2, \chi = 0, \theta = 0\},\
                           FullSimplify[
                     Solve [FullSimplify [ (FullSimplify [TransAna].y) /. \psi \rightarrow \left(-ArcSin\left[\frac{kx}{kk}\right]\right)] == ky, \{\phi\}]
 \text{Out} [228] = \left. \left\{ \left\{ \phi \to \mathsf{ConditionalExpression} \left[ \beta + \mathsf{ArcCos} \left[ \frac{\mathsf{ky}}{\mathsf{kk} \sqrt{1 - \frac{\mathsf{kx}^2}{\mathsf{kk}^2}}} \right] - \frac{1}{2} \pi \left( 3 + 4 \ \mathbb{c}_1 \right) \right. \right\}, \\ \left. \mathbb{C}_1 \in \mathbb{Z} \right] \right\}, 
                  \left\{\phi \to \mathsf{ConditionalExpression} \left[\, \beta + \mathsf{ArcSin} \! \left[\, \frac{\mathsf{ky}}{\mathsf{kk} \, \sqrt{1 - \frac{\mathsf{kx}^2}{\mathsf{kk}^2}}} \, \right] \, - \, 2 \, \pi \, \mathbb{c}_1, \, \mathbb{c}_1 \in \mathbb{Z} \, \right] \, \right\} \right\}
```

$$ln[229]:=$$
 kk = 1;  $\beta = -\pi/20$ ;  $\theta = \pi/30$ ;  $\chi = -\pi/18$ ; Show

ParametricPlot[Evaluate[Table[Tooltip[
$$\{\beta + \text{ArcSin}[\frac{\text{ky Cos}[\chi] + \text{kx Sin}[\chi]}{\text{kk}\sqrt{1 - \frac{(\text{kx Cos}[\chi] - \text{ky Sin}[\chi])^2}{\text{kk}^2}}}$$
],  $-\theta$ 

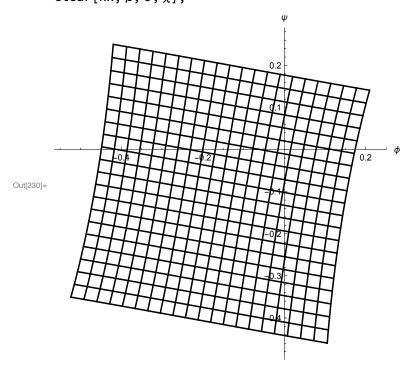
ArcSin[
$$\frac{kx \cos[\chi] - ky \sin[\chi]}{kk}$$
]}, Row[{"kx = ", kx}]], {kx, -0.3, 0.3, 0.03}]],

$$\{\text{ky, -0.3, 0.3}\}, \text{ PlotStyle} \rightarrow \{\text{Black}\}, \text{ AspectRatio} \rightarrow 1, \text{ AxesLabel} \rightarrow \{\phi, \psi\}$$
,

ParametricPlot[Evaluate[Table[Tooltip[
$$\{\beta + ArcSin[\frac{ky Cos[\chi] + kx Sin[\chi]}{kk \sqrt{1 - \frac{(kx Cos[\chi] - ky Sin[\chi])^2}{kk^2}}}], -\theta$$

ArcSin
$$\left[\frac{kx \cos[\chi] - ky \sin[\chi]}{kk}\right]$$
, Row $[\{"ky = ", ky\}]$ ,  $\{ky, -0.3, 0.3, 0.03\}$ ],

 $\{kx, -0.3, 0.3\}, PlotStyle \rightarrow \{Black\}, AspectRatio \rightarrow 1, AxesLabel \rightarrow \{\phi, \psi\}]$ Clear[kk,  $\beta$ ,  $\theta$ ,  $\chi$ ];



Out[232]= 
$$\sqrt{1-\phi^2}$$