

Installation

pip install taichi ti example

Quick start

import taichi as ti
ti.init()

@ti.kernel
def monte_carlo_pi() -> float:
 total = 0
 for i in range(100000):
 x = ti.random()
 y = ti.random()
 if (x*x + y*y) < 1:
 total += 1

 return 4 * total / n</pre>

Supported backends

ti.cpu, ti.cuda, ti.metal, ti.opengl, ti.vulkan Choose a backend

ti.init(arch=ti.cuda)

Run in debug mode

ti.init(debug=True)

Data types

primitive tyes

i8, i16, i32, i64, u8, u16, u32, u64, f16, f32, f64

types.vector(n, dtype)

vec3 = ti.types.vector(3, float)
v = vec3(1, 2, 3)

types.matrix(n, m, dtype)

mat2x2 = ti.types.matrix(2, 2, float)
m = mat2x2(1, 2, 3, 4)

types.struct(**kwargs)

sphere = ti.types.struct(center=vec3, radius=float)
s = sphere(vec3(1, 2, 3), 1.0)

Quant types

u5 = ti.types.quant.int(bits=5, signed=False)
fixed_a = ti.types.quant.fixed(bits=10, max_value=20.0)
float_b = ti.types.quant.float(exp=6, frac=9, signed=False)

typecating

```
x = 1.0
y = ti.u8(x)
v = vec3(0.5, 1.0, 1.5)
w = v.cast(int)
```

Operators

comparison operators ==,!=,>,<,>=,<=

logical operators not, or, and

bitwise operators

~, &, ^, |, «, »

Data container

field(dtype, shape, ...)

f = ti.field(int, shape=(3, 3, 3))

Vector.field(dim, dtype, shape, ...)

f = ti.Vector.field(3, float, (10, 10))

Matrix.field(dim, dtype, shape, ...)

f = ti.Matrix.field(3, 3, float, shape=(10, 10))

Struct.field(dict, shape)

sphere = ti.types.struct(center=vec3, radius=float)
s = sphere.field(shape=100)

fill(val) to set a field

f.fill(1)

from_numpy(arr) to copy data from a NumPy array

f.from_numpy(arr)

to_numpy(arr) to convert to a NumPy array

arr = f.to_numpy()

Kernels and functions

@ti.kernel: Called from Python scope. Require type hints for arguments and return values. Can return scalar, vector and matrix.

@ti.func: Called from Taichi scope. Recommend type hints for arguments and return values. Can return scalar, vector, matrix and struct.

Top level for loops in a kernel are automatically parallelized

Force a top level for loop to execute in serialize

```
x = ti.field(int, 100)
@ti.kernel
def example():
   ti.loop_config(serialize=True)
   for i in range(100):
    ...
...
```

Interactive with Numpy arrays

arr = numpy.arange(12).reshape(3, 4)
@ti.kernel
def example(x: ti.types.ndarray()):
 for i, j in ti.ndrange(arr.shape[0], arr.shape[1]):
 arr[i, j] = i + j

Data-oriented programming

data-oriented class

A data-oriented class is used when your data is actively updated in the Python scope (such as current time and user input events) and tracked in Taichi kernels.

```
@ti.data_oriented
class TiArray:
    def __init__(self, n):
        self.x = ti.field(dtype=ti.i32, shape=n)

    @ti.kernel # Defines Taichi kernels in the data-oriented
        Python class
    def inc(self):
        for i in self.x:
        self.x[i] += 1

a = TiArray(32)
a.inc()
```

dataclass

A dataclass is a wrapper of 'ti.types.struct'. You can define Taichi functions as its methods and call these methods in the Taichi scope.

```
@ti.dataclass
class Sphere:
    center: vec3
    radius: float

    @ti.func
    def area(self): # Defines a Taichi function as method
        return 4 * math.pi * self.radius**2

@ti.kernel
def test():
    sphere = Sphere(vec3(0), radius=1.0)
    print(sphere.area())
```

Commonly-used functions

 $\begin{array}{l} \text{ti.acos}(x), \, \text{ti.asin}(x), \, \text{ti.atan2}(x), \, \text{ti.ceil}(x), \\ \text{ti.clamp}(x, \, \text{xmin}, \, \text{xmax}), \, \text{ti.cos}(x), \, \text{ti.cross}(x, \, y), \, \text{ti.dot}(x, y), \\ \text{ti.exp}(x), \, \text{ti.floor}(x), \, \text{ti.fract}(x), \, \text{ti.inverse}(\text{mat}), \\ \text{ti.norm}(x), \, \text{ti.log}(x), \, \text{ti.max}(x, \, y, \, \ldots), \, \text{ti.min}(x, \, y, \, \ldots), \\ \text{tm.mod}(x, y), \, \text{tm.normalize}(x), \, \text{tm.pow}(x, \, a), \, \text{ti.round}(x), \\ \text{ti.sign}(x), \, \text{ti.sin}(x), \, \text{tm.smoothstep}(e0, \, e1, \, x), \, \text{ti.sqrt}(x), \\ \text{tm.step}(\text{edge}, \quad x), \, \text{ti.tan}(x), \quad \text{ti.tanh}(x), \quad \text{tm.degrees}(x), \\ \text{tm.radians}(x) \end{array}$

Global settings

Set default precision

```
ti.init(default_fp=ti.f64)
ti.init(default_ip=ti.i64)
```

Set random seed

```
ti.init(random_seed=0)
```

Visualization

GUI system

```
gui = ti.GUI('Window Title', (640, 360)) # Creates a window
while not gui.get_event(ti.GUI.ESCAPE, ti.GUI.EXIT):
    gui.show() # Displays the window
```

API

GGUI system

API

Performance tuning

Kernel profiler (CPU and CUDA only):

To analyze the performance of Taichi kernels

```
ti.init(ti.cpu, kernel_profiler=True)
ti.profiler.print_kernel_profiler_info()
```

Configure loops:

To serialize the outermost for loop that immediately follows the line

```
ti.loop_config(serialize=True)
```

To designate No. of threads on the CPU backend

```
ti.loop_config(parallelize=8)
```

To designate No. of threads in each block of the GPU backend

```
ti.loop_config(block_dim=16)
```

Debugging

Activate debug mode:

```
ti.init(arch=ti.cpu, debug=True)
```

Runtime print in Taichi scope:

```
@ti.kernel
def inside_taichi_scope():
    x = 256
    print('hello', x) #=> hello 256
```

Runtime assert in Taichi scope:

```
ti.init(arch=ti.cpu, debug=True)
x = ti.field(ti.f32, 128)
@ti.kernel
def do_sqrt_all():
    for i in x:
        assert x[i] >= 0
        x[i] = ti.sqrt(x[i])
```

Compile-time static-print:

```
x = ti.field(ti.f32, (2, 3))
y = 1

@ti.kernel
def inside_taichi_scope():
    ti.static_print(y) # => 1
    ti.static_print(x.shape) # => (2, 3)
    ti.static_print(x.dtype) # => DataType.float32
```

Compile-time static-assert:

```
@ti.func
def copy(dst: ti.template(), src: ti.template()):
    ti.static_assert(dst.shape == src.shape, "copy() needs
    src and dst fields to be same shape")
    for I in ti.grouped(src):
        dst[I] = src[I]
```

Serial execution:

To serialize the program

```
ti.init(arch=ti.cpu, cpu_max_num_threads=1)
```

To serializes the for loop that immediately follows the line

```
ti.loop_config(serialize=True)
```

Access a conciser version of traceback message:

```
import sys
sys.tracebacklimit = 0
```