





FlexiBLAS

A BLAS and LAPACK wrapper library with runtime exchangable backends

Martin Köhler

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asyBuild tech talks III: FlexiBLAS

Basic Linear Algebra Subprograms (BLAS)

"The BLAS (Basic Linear Algebra Subprograms) are routines that provide standard building blocks for performing basic vector and matrix operations. ... Because the BLAS are efficient, portable, and widely available, they are commonly used in the development of high quality linear algebra software, LAPACK for example." 1

¹From: http://www.netlib.org/blas/faq.html — What and where are the RI AS?



Let α , β be scalars, x, y be vectors, A, B, C be matrices.

level	included operations	data	flops
1	αx , $\alpha x + y$, x^*y , $ x _2$, $ x _1$, $ x _{\infty}$	$\mathcal{O}(n)$	$\mathcal{O}(n)$
2	$\alpha Ax + \beta y$, $\alpha A^*x + \beta y$, $A + \alpha xy^*$, $A + \alpha xx^*$, $A + \alpha xy^* + \beta yx^*$	$\mathcal{O}(n^2)$	$\mathcal{O}(n^2)$
3	$\alpha AB + \beta C$, $\alpha AB^* + \beta C$, $\alpha A^*B^* + \beta C$, $\alpha AA^* + \beta C$, $\alpha A^*A + \beta C$ rank k updates $\alpha A^*B + \beta C$, $\alpha B^*A + \beta C$ rank $2k$ updates	$\mathcal{O}(n^2)$	$\mathcal{O}(n^3)$



Open Source

- NetLib BLAS: http://www.netlib.org/blas/
- OpenBLAS: http://www.openblas.net/
- Automatically Tuned Linear Algebra Software (ATLAS): http://math-atlas.sourceforge.net/
- BLIS (BLAS-like Library Instantiation Software Framework): https://github.com/flame/blis

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Hardware Vendor Implementations

- Intel[®] Math kernel library (MKL): http://software.intel.com/en-us/intel-mkl/
- AMD Core Math Library (ACML): ... discontinued
- Apple Accelerate, IBM ESSL, ARM Perfromance Libraries . . .

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Why do we need yet another BLAS library?

Hardwai

Intel

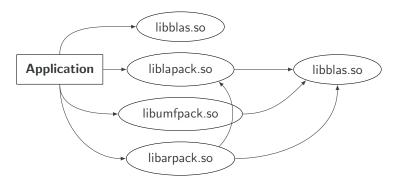
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Example application:



Compiled with:

\$ gcc -o application app.o -larpack -lumfpack \leftarrow -llapack -lblas

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```
$ ldd ./application
linux-vdso.so.1 => (0x00007ffc2d1de000)
libarpack.so.2.1.0 => /.../libarpack.so.2.1.0
libumfpack.so.5.7.1 => /.../libumfpack.so.5.7.1
liblapack.so.3 => /.../liblapack.so.3
libblas.so.3 => /.../libblas.so.3
libc.so.6 => /.../libc.so.6
```

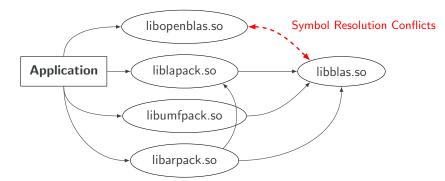
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Why do we need yet another BLAS library? Linker Problems – Now: quick test with another BLAS library ...

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liblapack.so.3 => /.../liblapack.so.3
libopenblas.so.0 => /.../libopenblas.so.0
libc.so.6 => /.../libc.so.6
libm.so.6 => /.../libm.so.6
libblas.so.3 => /.../libblas.so.3
...
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Why do we need yet another BLAS library?

Linker Problems: Existing Solutions

- LD_LIBRARY_PATH / LD_PRELOAD only applicable for single file implementations (i.e. NOT Intel® MKL, or ATLAS)
- static libraries drastically increased binary sizes, often complicated linking, painful in large projects
- update-alternatives (Debian/Ubuntu/Suse) requires super-user privileges and has similar restrictions as LD_LIBRARY_PATH / LD_PRELOAD
- eselect / pkg-config (Gentoo) requires super-user privileges and switches at build-time only
- *BSD ports/pkgsrc/dports Links agains libblas.so if already installed otherwise installs some BLAS implementation depending on the maintainer.



Why do we need yet another BLAS library? Compatibility Issues

gfortran vs g77/intel interface style

- different calling sequences: gfortran and g77/f2c/intel return complex numbers as additional function parameters.
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auxiliary routines

■ Intel[®] MKL and OpenBLAS extend the BLAS routine set by: xAXPBY, xOMATCOPY,



Why do we need yet another BLAS library? Compatibility Issues

dependency detection problems

Correct/reliable detection of alternative BLAS implementations not guaranteed for many software packages:

- faulty autotools scripts,
- old CMake versions,
- hard-coded library names,
- non-standard library locations.



Our Solution - FlexiBLAS

- Initial idea: Summer 2013 after struggling with the linking issue
- First release: December 2013 (BLAS and CBLAS only)
- 2017: Version 2.x wraps LAPACK, switching the BLAS library from the inside of an application
- 2020: Version 3.0.x hooks can be installed around BLAS calls
- October 2020: default BLAS in Fedora 33+ (thanks to Iñaki Ucar)
- Provides interfaces for BLAS, CBLAS, and LAPACK.
- Automatic code generation for the wrappers
- API interface for GNU Octave
- API interface for R (thanks to Iñaki Ucar²)
- Latest version: 3.0.4 October 22nd, 2020
- **License:** GPLv3+ with linking exception

²Twitter/Github: @Enchufa2



Long Story Short

We employ a plugin-like framework on top of the POSIX features for dynamic loading of shared libraries at runtime.



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POSIX.1 2001 d1*-family

- dlopen add a shared library and its dynamic dependencies to the current address space.
- dlclose close a previously opened shared library if no other references
 to the library exist.
- dlerror provide human readable error messages.



dlopen based issues to solve

- 1. dlopen only integrates selected parts of the library: Each required BLAS call needs to be initialized separately.
- 2. Dynamically (runtime) loaded symbols can not be resolved while linking a program.
- dlopen only loads a single file:Multi-file implementations require additional treatment.



attribute((constructor))

- automatically executed before the program starts.
- replaces deprecated _init().
- Here used to read configuration and explicitly resolve all BLAS-routines to make sure they get loaded by dlopen as an initialization stage.



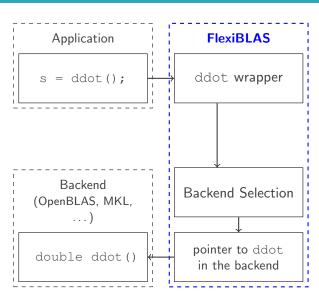
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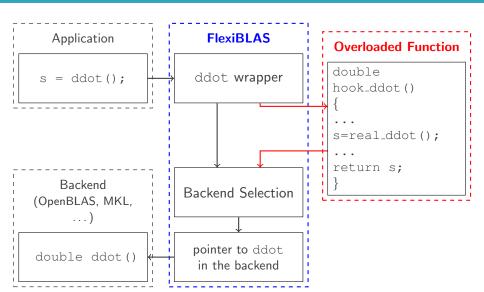
_attribute__((destructor))

- automatically executed after the main program exits.
- replaces deprecated _fini().
- Here used to cleanly close the loaded shared library and potentially print profiling data.

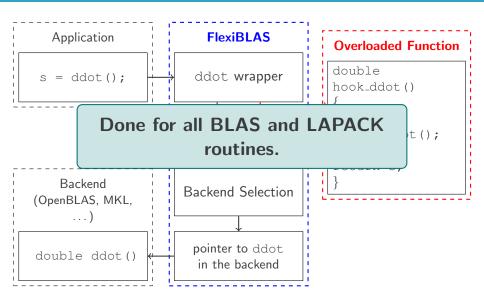














Python based code-gen

- NumPy's f2py module allows to parse f77/f90 function headers.
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From

```
SUBROUTINE DAXPY(N, ALPHA, X, INCX, Y, INCY)
we obtain

void daxpy_(Int *N, double *ALPHA, double *X,
   Int *INCX, double *Y, Int * INCY) {
        ...
      fncall_daxypy = backend->daxpy.ffunction;
      fncall_daxpy(N, ALPHA, X, INCX, Y, INCY);
      ... }
```



Remaining Question

How do we treat BLAS libraries consisting of multiple files (e.g. MKL and some versions of ATLAS), when the dl*-family can only use single file shared object libraries?



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Simple trick

Place an additional surrogate library between FlexiBLAS and, e.g., MKL that references all necessary symbols in MKL and behaves like a Netlib-BLAS interface from the view of the dynamic linker.

Intel MKL provides the *mkl-builder* makefile to create such dummy libraries containing arbitrary BLAS symbols.



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Never use the libmkl_rt.so library!





How is it used?

We provide a tool that closely follows Gentoo's eselect syntax. To check for backends, do

flexiblas list

To select the active backend, use

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config files: /etc/flexiblasrc, ~/.flexiblasrc, and
~/.flexiblasrc.\$(hostname)



Other environment variables to control the behavior:

FLEXIBLAS_VERBOSE Turn on additional debug outputs.

FLEXIBLAS_NOLAPACK Do not load LAPACK from the backend. Only the internal NETLIB version is used.

FLEXIBLAS_COLOR_OUTPUT Switch the color output in verbose mode.

 ${\tt FLEXIBLAS_CONFIG} \ \ {\tt specify} \ \ {\tt a} \ \ {\tt different} \ \ {\tt flexiblasrc} \ \ {\tt file}$

FLEXIBLAS_LIBRARY_PATH specify additional library search paths



What is the Overhead?

Test Setup

- Ubuntu 20.04, gcc 9.3, Intel Core i5-8500, OpenBLAS/OpenMP
- Measure the shortest successful return path of a BLAS routine, i.e. size zero inputs, with rdtsc:

average over 100 000 000 runs



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RDTSC ticks Linked with			
until return	OpenBLAS/OpenMP	FlexiBLAS	Difference
DAXPY	19.03	24.19	5.16
DGEMV	22.92	37.03	14.11
DGEMM	28.40	44.47	16.07



Overloading Functions

All BLAS and LAPACK routines can be overloaded:

- build profiling frameworks,
- dynamically offload them to accelerators, (first experiments done)
- introduce faulty behavior for debugging purpose,
- several hooks can be chained,
- original BLAS implementation is callable by a separate pointer.

Example - DASUM with perturbed output

```
double hook_dasum(Int *N, double *X, Int *INCX) {
  double res = flexiblas_chain_dasum(N, X, INCX);
  return res + ((*N)*2.2e-16);
}
```



Functionality:

- measures cumulative the runtime of each BLAS call
- counts the number of calls to each BLAS routine

Usage:

FLEXIBLAS_HOOK=libflexiblas_hook_profile.so ./yourapp

or

FLEXIBLAS_HOOK=PROFILE ./yourapp



```
function [x] = conjgrad(A, b, x)
  r = b - A * x;
  p = r:
  rsold = r' * r;
  for i = 1:length(b)
   Ap = A * p;
    alpha = rsold / (p' * Ap);
    x = x + alpha * p;
    r = r - alpha * Ap;
    rsnew = r' * r;
    if sqrt(rsnew) < 1e-10</pre>
     break:
    end:
    p = r + (rsnew / rsold) * p;
   rsold = rsnew;
  end
end
A = full(sprandsym(1000, 1.0));
b = A * ones (1000, 1);
x = conjgrad(A,b,zeros(1000,1));
norm (A*x-b) /norm (b)
```



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Profiling:

Subroutine	# Calls	acc. Time
ddot	1000	1.11e-03s
dgemv	1003	4.04e-01s
dsyrk	1001	5.61e-03s
dlamch	5	2.69e-05s

Observations

- Vector addition/scaling/norms not mapped to BLAS.
- Where does the symmetric rank-*k* update come from?



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Inspecting:

DSYRK computes

$$\begin{split} C := \alpha A \cdot A^T + \beta C & \text{ if trans='N'} \\ \text{or} & C := \alpha A^T A + \beta C, & \text{ if trans='T'} \\ \text{with } A \in \mathbb{R}^{n \times k} & \text{ or } A \in \mathbb{R}^{k \times n} \text{ and } \\ C \in \mathbb{R}^{n \times n}. \end{split}$$

All 1001 DSYRK calls use:

- trans = 'T'
- n = 1, k = 1000,
- $\alpha = 1.0$, and $\beta = 0$



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 \rightarrow Misuse of DSYRK to compute the squared 2-norm of a vector.



Bug Description: (OpenBLAS up to version 0.2.20)

The DTRMV routine computes

$$x := \alpha T x$$

with $\alpha \in \mathbb{R}$, $x \in \mathbb{R}^n$, and $T \in \mathbb{R}^{n \times n}$ upper or lower triangular.

In an application we store T with leading dimension 64 and increase n from 1 to 64 during an iterative process:

- if n > 16 the result x gets perturbed,
- and if n > 32 the result x is completely wrong.



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Hook for DTRSV – Compute with OpenBLAS + Netlib and compare:

```
Cor. RESULT: DTRMV(U,N,N, 16, A, 64, X, 1) MAXERR = 0.00D+00
Pert. RESULT: DTRMV(U,N,N, 17, A, 64, X, 1) MAXERR = 0.56D-13
```

```
Pert. RESULT: DTRMV(U,N,N, 32, A, 64, X, 1) MAXERR = 0.58D-10 Wrong RESULT: DTRMV(U,N,N, 33, A, 64, X, 1) MAXERR = 0.59D+06
```



Overloading Functions OpenBLAS – Issue #1332

Bu Race-Condition: The error only appears if OpenBLAS uses multithreading on highly optimized platforms. **First Workaround:** Threading for xTRMV is deactivated. wit **Current Situation:** In a ■ Seems to exist more than 10 years. 64 ■ Longish discussion (more than 60 comments). Still not clear where the race condition comes from. Affects also a other race condition on the OpenPOWER 8 platform. Ho ■ The DAXPY operation seems to be involved as well. Per Pert. RESULI: DIRMY (U, N, N, 32, A, 04, A, I) MAKERR - U.SOD-IO

Wrong RESULT: DTRMV(U,N,N, 33, A, 64, X, 1) MAXERR = 0.59D+06



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Cor	- RESULT: DIRMV(II N N 17 & 64 X 1) MAXERE = 0.56D-12		
2 01	Finding such errors is easier with FlexiBLAS.		
Per	CL. RESULI: DIRMV(U,N,N, 32, A, 04, A, I) MAKERR - U.SOD-IU		
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- meta-data logging hook ready, but no cool analysis tools yet
 - planned: replay tool for correctness and accuracy checking
 - planned: replay tool for application-driven performance optimization
- MacOS X support in testing
- planned: suffixed symbols (in a consistent way)
- planned: per application BLAS selection
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Details



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Thank you very much for your attention!

MacOS X support for the software package visit:

http://www.mpi-magdeburg.mpg.de/projects/flexiblas https://github.com/mpimd-csc/flexiblas/





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