# 15 PDEs comments

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## 1 15 PDEs: Miscellaneous comments on PDEs

# 1.1 Origin of the Jacobi algorithm in a diffusion problem

(see e.g., Numerical Recipes in C, Ch 19.5)

We want to solve the Laplace equation

$$\nabla^2 u = 0$$

with given boundary conditions.

Rewrite as a diffusion equation (with D = 1):

$$\nabla^2 u = \frac{\partial u}{\partial t}$$

The **equilibrium solution** of the diffusion equation (i.e., after very long t when relaxed to equilibrium)

$$\lim_{t \to +\infty} u(\mathbf{x}, t) \equiv u(\mathbf{x})$$

is the solution of the boundary value problem.

For a visualization of how the solution for the 2D "wire on the box" problem relaxes towards the static solution of the Laplace equation, see the SOR movie: the process looks like the 1D heat diffusion problem solution, with the y-axis of the electrostatic problem playing the role of time in the 1D diffusion problem.

Why do these two problems look similar?

#### 1.2 Jacobi algorithm rediscovered

Set up the finite difference scheme for the 2D diffusion equation, using  $u(x, y, t) = u(i\Delta, j\Delta, n\Delta t) = u_{ij}^n$ :

$$\begin{split} \frac{1}{\Delta^2} \left[ (u^n_{i+1,j} - 2u^n_{ij} + u^n_{i-1,j}) + (u^n_{i,j+1} - 2u^n_{ij} + u^n_{i,j-1}) \right] \\ &= \frac{1}{\Delta t} (u^{n+1}_{ij} - u^n_{ij}) \end{split}$$

In 2D, this leap frog algorithm is stable for

$$\frac{\Delta t}{\Delta^2} \le \frac{1}{4}$$

Let's assume that we can push our solution to the edge of stability and use  $\frac{\Delta t}{\Delta^2} = \frac{1}{4}$ . Then the finite difference scheme becomes

$$\frac{1}{4} \left( u_{i+1,j}^n + u_{i-1,j}^n \right) + \left( u_{i,j+1}^n + u_{i,j-1}^n \right) - u_{ij}^n = u_{ij}^{n+1} - u_{ij}^n$$

or when collecting terms, the Jacobi algorithm re-emerges

$$u_{ij}^{n+1} = \frac{1}{4} \left( u_{i+1,j}^n + u_{i-1,j}^n + u_{i,j+1}^n + u_{i,j-1}^n \right)$$

where you now interpret n as the step number in the iterations towards convergence.

## 1.3 Broad classes of physical behavior

(For real fields  $u(\mathbf{x}, t)$ .)

- elliptic PDE without time dependence: static boundary value problem (static, think F = 0)
- parabolic PDE with first time derivative: diffusion problem (friction, think F = -bv)
- hyperbolic PDE with second time derivative: wave problem (oscillator, think F = ma)

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