view\_frames Result Recorded at time: 412.139 odom Broadcaster: /gazebo Average rate: 100.216 Hz Most recent transform: 412.135 (0.004 sec old) Buffer length: 4.630 sec footprint Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (412.139 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 48.380 Hz Average rate: 48.380 Hz Most recent transform: 0.000 (412.139 sec old) Most recent transform: 0.000 (412.139 sec old) Most recent transform: 412.134 (0.005 sec old) Most recent transform: 412.134 (0.005 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.630 sec Buffer length: 4.630 sec caster\_wheel left\_wheel sensor\_base right\_wheel Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (412.139 sec old) Buffer length: 0.000 sec hokuyo\_link\_0