

General Rules when using time fields

$$T(\theta_1, \theta_2, \dots, \theta_n) \stackrel{\text{def}}{=} \max(T_1(\theta_1), T_2(\theta_2), \dots, T_n(\theta_n))$$

Overlaying the time fields

When overlaying time fields, every single field is plugged into the $\max()$ function

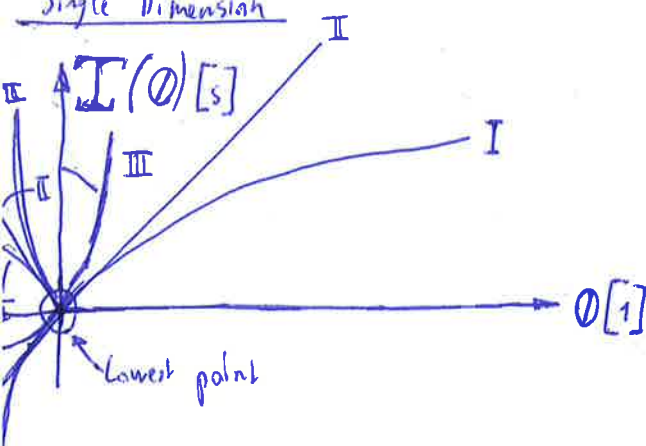
Problem is that $\max()$ ~~trans~~ returns a scalar function in most cases

$$\hookrightarrow \max(a_1, a_2, \dots, a_n)$$

$$= \begin{cases} a_1 & \text{if } (a_1 > a_2) \wedge (a_1 > a_3) \dots \wedge (a_1 > a_n) \\ a_2 & \text{if } (a_2 > a_1) \wedge (a_2 > a_3) \dots \wedge (a_2 > a_n) \\ \dots & \dots \\ a_n & \text{otherwise} \end{cases}$$

Optimisation

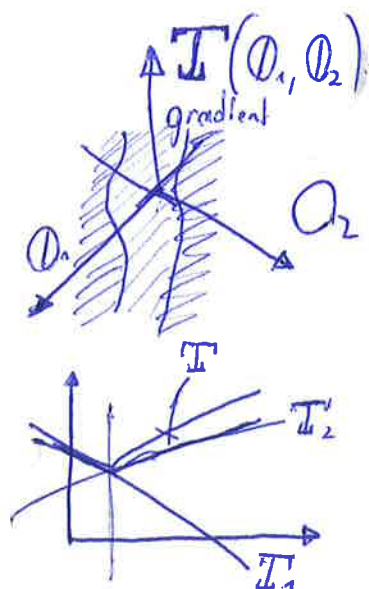
Single Dimension



Optimization in a single measurement does not make sense, as there are no parameters to play around

$$\underline{T(\theta) = 0}$$

Second Dimension



$$\theta_1 \iff \theta_2 \text{ dependent}$$

$$T_1(\theta_1) = T_2(\theta_2)$$

$$\Rightarrow \theta_1 = T_1^{-1}(T_2(\theta_2))$$

$$\Rightarrow \theta_1(\theta_2)$$