Recorded at time: 64.847 world Broadcaster: /world\_frames\_connection\_2 Broadcaster: /world\_frames\_connection\_1 Average rate: 10.202 Hz Average rate: 10.192 Hz Most recent transform: 64.922 (-0.075 sec old) Most recent transform: 64.919 (-0.072 sec old) Buffer length: 4.901 sec Buffer length: 4.906 sec ur10\_2\_tf/world ur10\_1\_tf/world Broadcaster: /ur10\_1/robot\_state\_publisher Broadcaster: /ur10\_2/robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (64.847 sec old) Most recent transform: 0.000 (64.847 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ur10\_1\_tf/base\_link ur10\_2\_tf/base\_link Broadcaster: /ur10\_2/robot\_state\_publisher Broadcaster: /ur10 2/robot state publisher Broadcaster: /ur10\_1/robot\_state\_publisher Broadcaster: /ur10\_1/robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 50.162 Hz Average rate: 10000.000 Hz Average rate: 50.203 Hz Most recent transform: 0.000 (64.847 sec old) Most recent transform: 64.824 (0.023 sec old) Most recent transform: 64.816 ( 0.031 sec old) Most recent transform: 0.000 (64.847 sec old) Buffer length: 4.924 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.920 sec ur10\_2\_tf/base ur10\_1\_tf/base ur10\_1\_tf/shoulder\_link ur10\_2\_tf/shoulder\_link Broadcaster: /ur10\_1/robot\_state\_publisher Broadcaster: /ur10\_2/robot\_state\_publisher Average rate: 50.162 Hz Average rate: 50.203 Hz Most recent transform: 64.824 ( 0.023 sec old) Most recent transform: 64.816 (0.031 sec old) Buffer length: 4.924 sec Buffer length: 4.920 sec ur10\_1\_tf/upper\_arm\_link ur10\_2\_tf/upper\_arm\_link Broadcaster: /ur10\_1/robot\_state\_publisher Broadcaster: /ur10\_2/robot\_state\_publisher Average rate: 50.162 Hz Average rate: 50.203 Hz Most recent transform: 64.824 ( 0.023 sec old) Most recent transform: 64.816 ( 0.031 sec old) Buffer length: 4.924 sec Buffer length: 4.920 sec ur10\_2\_tf/forearm\_link 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view\_frames Result