

# Using models of transcriptional regulation to uncover gene regulatory networks

Magnus Rattray

School of Computer Science, University of Manchester

joint work with Neil Lawrence and Antti Honkela

Imperial College, 15th February 2010

# Talk outline

- ▶ Quick introduction to transcriptional regulation
- ▶ Our overall strategy for regulatory network inference
- ▶ Using simple activation models for target identification
- ▶ Closing the system with Gaussian process inference
- ▶ Empirical results on Drosophila mesoderm development

# Transcriptional regulation of gene expression

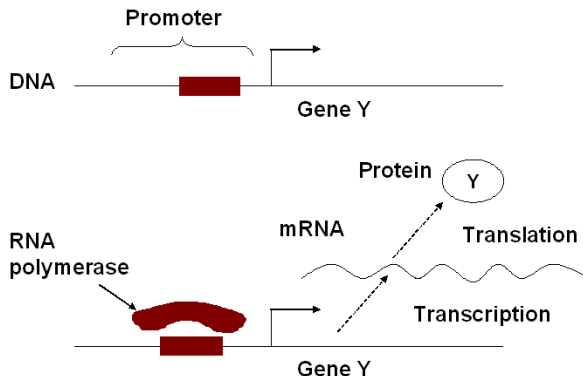


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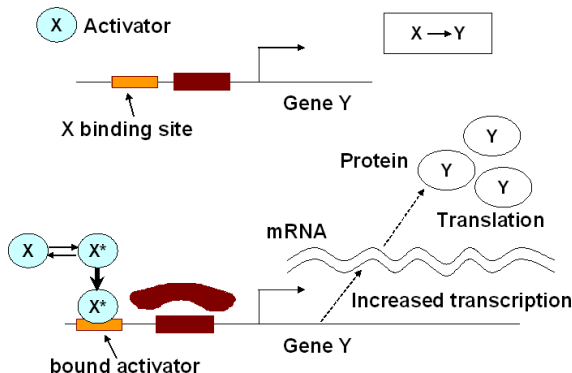


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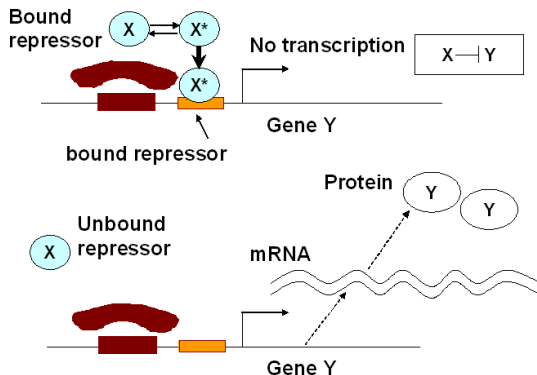
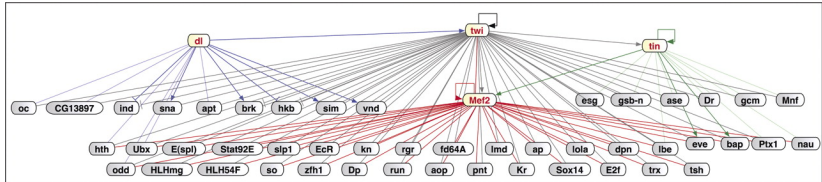


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# Gene regulatory networks

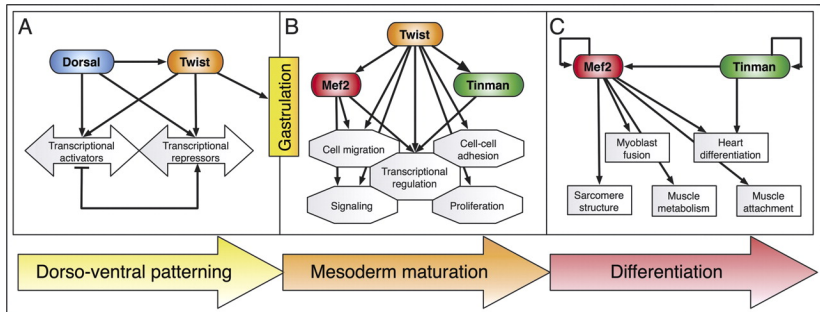
The core gene regulatory network controlling mesoderm development in *Drosophila*



Sandmann *et al.* Genes and Development 2007

# Gene regulatory networks

The inferred network is used to help model biological processes



Sandmann *et al.* Genes and Development 2007

# Inferring networks from data

- ▶ We have access to genome-wide data about...
  - ▶ Physical binding of transcription factors to DNA (ChIP)
  - ▶ Wild-type mRNA expression (microarrays/RNA-seq)
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Uncovering regulatory networks

Using models for target identification

Gaussian process inference

Empirical evaluation

Current work and conclusion

Transcriptional regulation

Gene regulatory networks

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# Modelling transcriptional regulation

Recall our simple picture of activation:

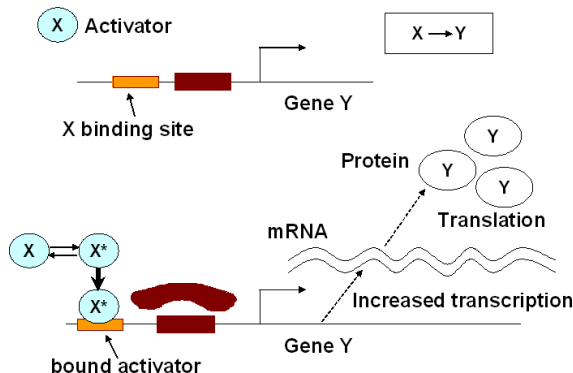


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# Modelling transcriptional regulation

We model transcription factor translation and target activation:

$$\begin{aligned}\frac{df(t)}{dt} &= m(t) - \delta f(t) \\ \frac{dy_i(t)}{dt} &= B_i + S_i f(t) - D_i y_i(t)\end{aligned}$$

- ▶  $m(t)$  – concentration of transcription factor mRNA
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- ▶  $y_i(t)$  – concentration of target gene  $i$ 's mRNA
- ▶ Application - identifying likely targets by their fit to the model
- ▶ Technical challenges - parameters  $\theta = \{B_i, D_i, S_i, \delta\}$  unknown, few time points, noisy data, “open” system because of  $m(t)$

## Model-based inference

- ▶ Target expression data  $Y = \{y_i(t_1), y_i(t_2), \dots, y_i(t_T)\}$



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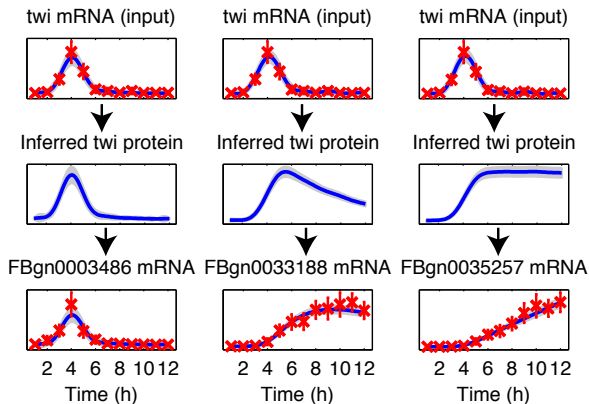
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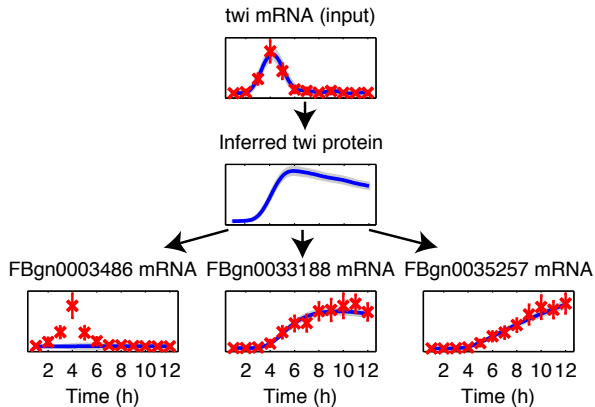
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- ▶ Use likelihood score for genome-wide ranking of all genes as putative targets

Gao *et al.* Bioinformatics 24(16), i70-i75 (2008)

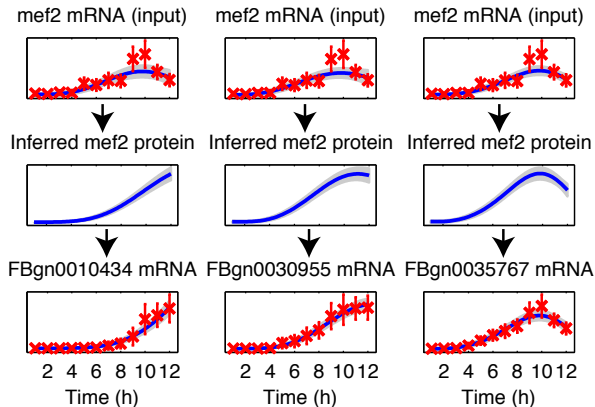
## Fitting the model to data - Twist and Mef2



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## Gaussian process: definition

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- ▶ A Gaussian Process (GP) is a distribution over functions  $m(t)$

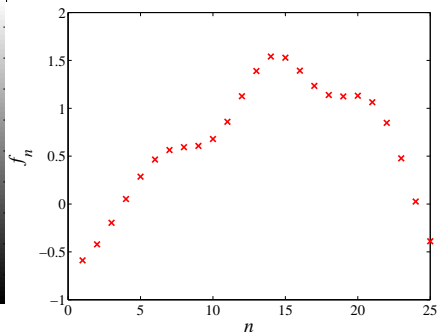
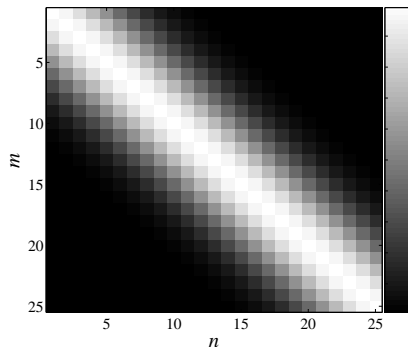
$$m(t) \sim \mathcal{GP}(\mu_m(t), k_m(t, t'))$$

- ▶ It is characterised by a mean and covariance function

$$\begin{aligned}\mu_m(t) &= \mathbb{E}[m(t)] \\ k_m(t, t') &= \mathbb{E}[(m(t) - \mu(t))(m(t') - \mu(t'))]\end{aligned}$$

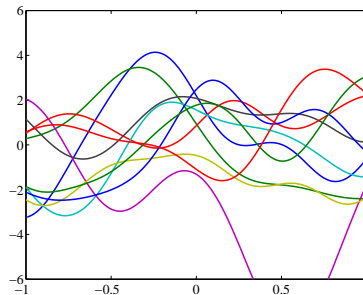
- ▶ Any finite set of points sampled from the function are Gaussian distributed with covariance matrix elements  $C_{ij} = k(t_i, t_j)$

# From a Gaussian distribution to a Gaussian process



## Covariance function for $m(t)$

We assume a squared exponential covariance function for  $m(t)$



$$\mu_m(t) = 0 \quad k_m(t, t') = h \exp\left(-\frac{(t - t')^2}{l^2}\right)$$

## Covariance function for the linear activation model

Recall the linear activation model

$$\begin{aligned}\frac{df(t)}{dt} &= m(t) - \delta f(t) \\ \frac{dy_i(t)}{dt} &= B_i + S_i f(t) - D_i y_i(t)\end{aligned}$$

This differential equation can be solved for  $f(t)$  and  $y_i(t)$  as

$$\begin{aligned}f(t) &= \int_0^t e^{-\delta(t-u)} m(u) du \\ y_i(t) &= \frac{B_i}{D_i} + S_i \int_0^t e^{-D_i(t-u)} f(u) du\end{aligned}$$

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*Note:* Both  $f(t)$  and  $y_i(t)$  are linear functions of  $m(t)$

# Covariance function for the linear activation model

Any linear operation on a GP  $\implies$  Related GP

$$m(t) \sim \mathcal{GP}(0, k_m(t, t')) \implies y_i(t) \sim \mathcal{GP}\left(\frac{B_i}{D_i}, k_{y_i}(t, t')\right).$$

The covariance of target gene mRNA  $y_i(t)$  is defined:

$$k_{y_i}(t, t') = S_i^2 \int_0^t \int_0^{t'} e^{-D_i(t-u) - D_i(t'-u')} k_f(u, u') du du'$$

in terms of covariance of the TF protein  $f(t)$  which is defined:

$$k_f(t, t') = \int_0^t \int_0^{t'} e^{-\delta(t-u) - \delta(t'-u')} k_m(u, u') du du'.$$

## Computing the likelihood

We have a 2D process for the target and transcription factor mRNA

$$p(y, m|\theta) = \mathcal{GP} \left( \begin{bmatrix} 0 \\ \frac{B}{D} \end{bmatrix}, \begin{bmatrix} k_m & k_{my} \\ k_{ym} & k_y \end{bmatrix} \right)$$

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with parameters  $\theta = \{\delta, h, l, B, S, D\}$ . Given noise-corrupted data  $\mathbf{x} = \{\hat{m}_1, \hat{m}_2, \dots, \hat{m}_T, \hat{y}_1, \hat{y}_2, \dots, \hat{y}_T\}$  then the data likelihood is:

$$\begin{aligned} L(\theta) &= \log p(\mathbf{x}|\theta) = \log \int p(\mathbf{x}|y, m) p(y, m|\theta) dy dm \\ &= \left[ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T C^{-1} (\mathbf{x} - \boldsymbol{\mu}) - \frac{1}{2} \log |C| \right] - T \log 2\pi \end{aligned}$$

where  $C_{ij} = k(x_i, x_j) + \delta_{ij} \sigma_i^2$  is the data covariance.

Uncovering regulatory networks  
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**Gaussian process inference**  
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Gaussian process: definition  
Covariance Function  
Computing the likelihood  
**Pros and cons of the Gaussian Process approach**  
Example fits for Twist and Mef2

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## Pros:

- ▶ The function  $m(t)$  is integrated (marginalized) out of the likelihood so only two new parameters introduced
- ▶ All parameters can be efficiently estimated by maximum likelihood, allowing for genome-wide coverage
- ▶ No requirement for equal spacing of times
- ▶ Unobserved functions can be inferred very naturally

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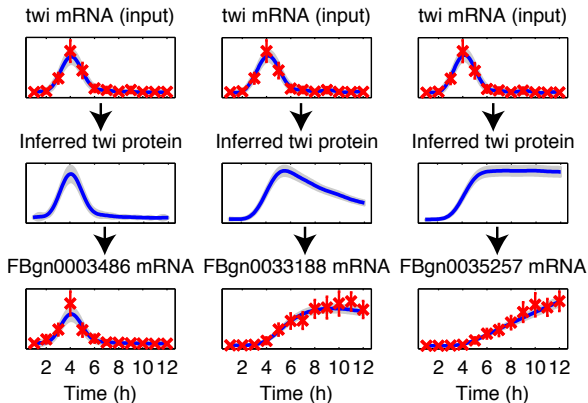
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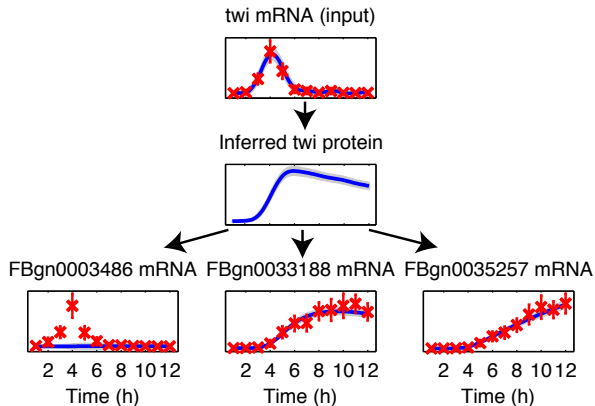
## Cons:

- ▶ Concentrations should really be constrained positive
- ▶ Non-linear models require approximate inference methods

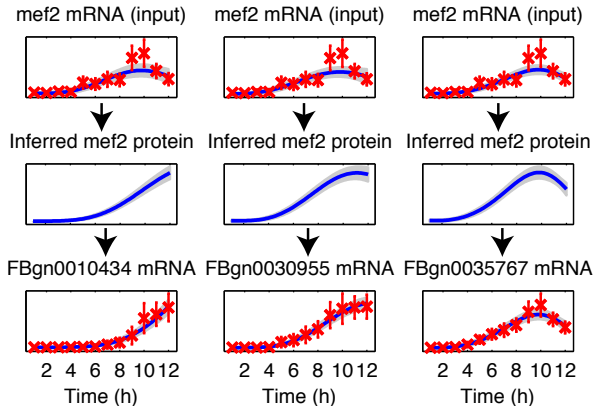
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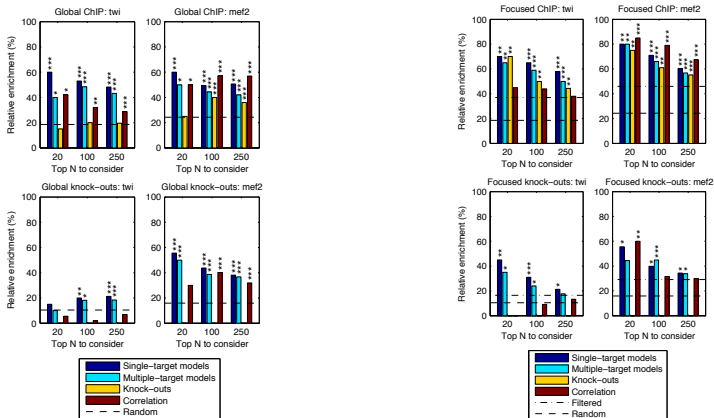


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# Ranking assessment

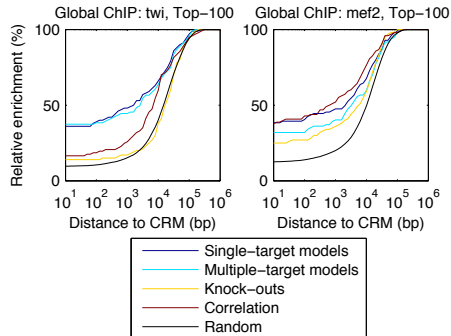
## Evaluation of model-based ranking using ChIP and knock-out data





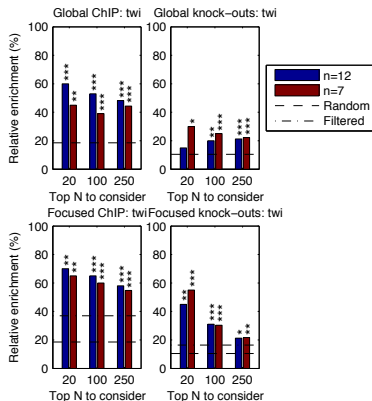
## Ranking assessment

Changing the distance threshold between CRM and positive targets



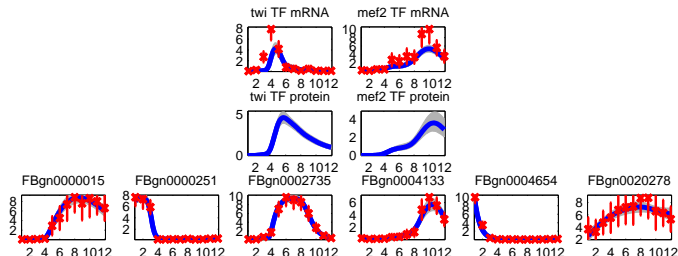
# Ranking assessment

## Changing the size of the dataset



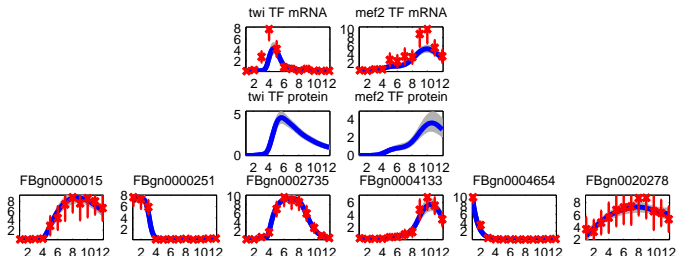
# Modelling combinatorial regulation

Many target genes are regulated by multiple transcription factors



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Network inference becomes much more challenging because the models become more complex and the space of models is huge.

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- ▶ When models don't fit the data then we learn something – and then we need new models and new experiments

# Acknowledgements

- ▶ Co-PIs: Neil Lawrence, Antti Honkela (HUT Finland)
- ▶ Experimental data: Eileen Furlong group (EMBL Heidelberg)

Funded by EPSRC award “Gaussian processes for systems identification with applications in Systems Biology”, PASCAL2 Network of Excellence and the Academy of Finland

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**Acknowledgements**

# Advertisement

