

Start-up steps of LD06 LiDar

1、 Operating environment

Operating system: Ubuntu 18.04 LTS

ROS version: melodic

Equipment: jetson nano, raspberry pie, PC

First transplant the function package to the workspace; select any one of the following test methods.

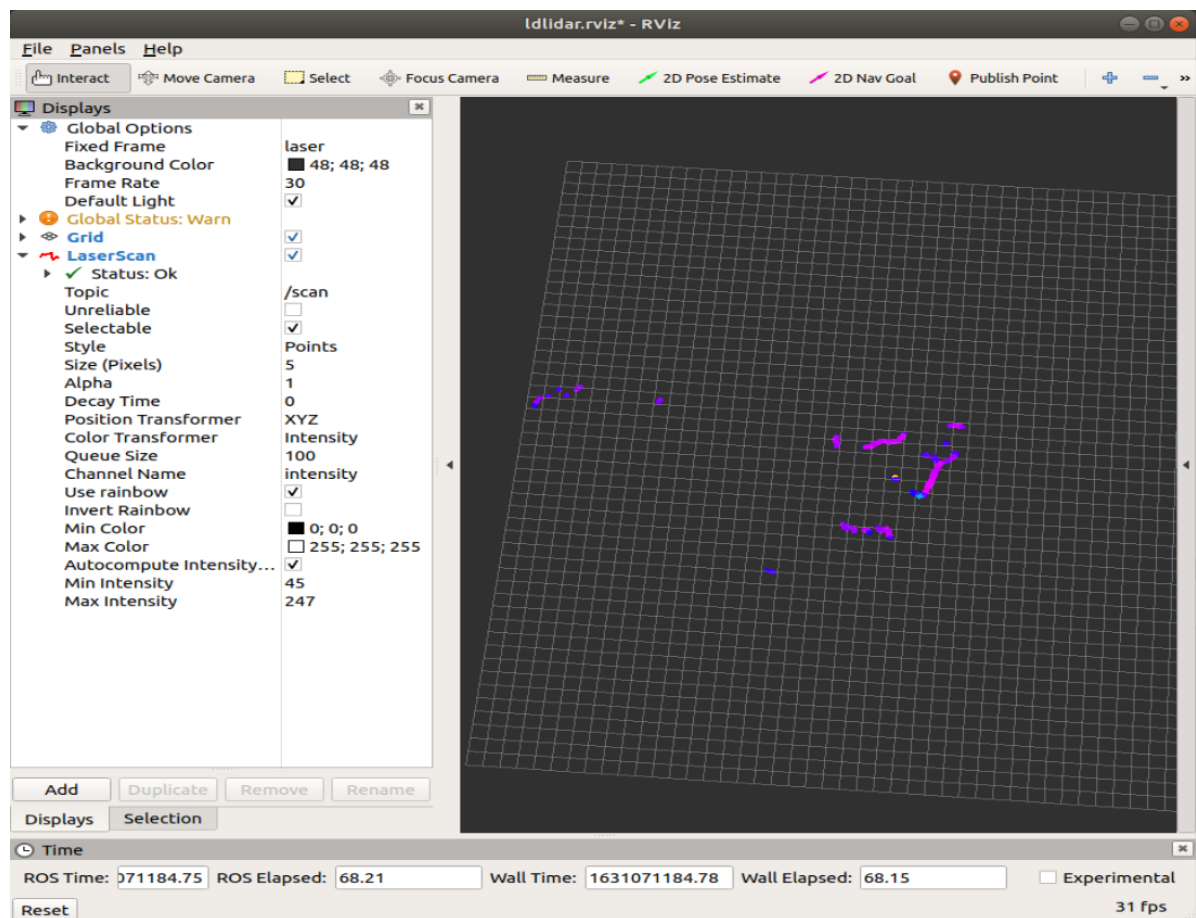
```
catkin_make          # Compile workspace
source devel/setup.bash # Update environment variables
```

2、 LiDar test steps

```
roslaunch ldlidar ld06.launch
# or
roslaunch ldlidar ldlidar
```

Satrt rviz

```
roslaunch ldlidar rviz_ld06.launch
```



3、 Construction test steps

Install gmapping function package

```
sudo apt install ros-melodic-gmapping
```

Start up

```
roslaunch ldlidar test_gmapping.launch
```

