

* [help?](#) [contents?](#) [notes?](#) [previous](#) :: [next](#) slide 6/14
[restart?](#)

Quiz

Which of the following is true?

1. Unknown problem task environments are always only partially observable.
2. If a goal has depth n , the iterative deepening search can find the goal using $O(n)$ space.
3. Uniform cost search is a generalization of depth first search to the case where action costs may not always be 1.