

src/action\_server\_node.cpp



```
graph TD; A[src/action_server_node.cpp] --> B[ros/ros.h]; A --> C[nurse-bot/task_action_server.hpp];
```

The diagram illustrates the dependencies of the file `src/action_server_node.cpp`. It is represented as a box at the top with two arrows pointing downwards to two other boxes. The left box contains `ros/ros.h` and the right box contains `nurse-bot/task_action_server.hpp`.

ros/ros.h

nurse-bot/task\_action  
\_server.hpp