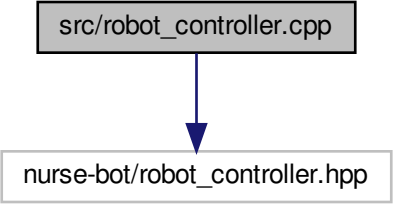


src/robot\_controller.cpp



```
graph TD; A[src/robot_controller.cpp] --> B[nurse-bot/robot_controller.hpp]
```

nurse-bot/robot\_controller.hpp