

param_navigation

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1 Appending & navigating simulations with given parameters

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1.1 Dependences

```
[1]: import pandas as pd
import matplotlib.pyplot as plt
import numpy as np
from cadCAD.configuration import Experiment
from cadCAD.configuration.utils import config_sim
from cadCAD.engine import ExecutionMode, ExecutionContext, Executor
```

1.2 Definitions

1.2.1 Initial conditions and parameters

```
[2]: initial_conditions = {
    'prey_population': 100,
    'predator_population': 15
}

params = {
    "prey_birth_rate": [1.0],
    "predator_birth_rate": [0.01],
    "predator_death_const": [1.0],
    "prey_death_const": [0.03],
    "dt": [0.01, 0.1, 0.05] # Precision of the simulation. Lower is more
    ↪ accurate / slower
}

simulation_parameters = {
    'N': 7,
    'T': range(200),
    'M': params
}
```

1.2.2 Policies

```
[3]: def p_predator_births(params, step, sL, s):
    dt = params['dt']
    predator_population = s['predator_population']
    prey_population = s['prey_population']
    birth_fraction = params['predator_birth_rate'] + np.random.random() * 0.0002
    births = birth_fraction * prey_population * predator_population * dt
    return {'add_to_predator_population': births}

def p_prey_births(params, step, sL, s):
    dt = params['dt']
    population = s['prey_population']
    birth_fraction = params['prey_birth_rate'] + np.random.random() * 0.1
    births = birth_fraction * population * dt
    return {'add_to_prey_population': births}

def p_predator_deaths(params, step, sL, s):
    dt = params['dt']
    population = s['predator_population']
    death_rate = params['predator_death_const'] + np.random.random() * 0.005
    deaths = death_rate * population * dt
    return {'add_to_predator_population': -1.0 * deaths}

def p_prey_deaths(params, step, sL, s):
    dt = params['dt']
    death_rate = params['prey_death_const'] + np.random.random() * 0.1
    prey_population = s['prey_population']
    predator_population = s['predator_population']
    deaths = death_rate * prey_population * predator_population * dt
    return {'add_to_prey_population': -1.0 * deaths}
```

1.2.3 State update functions

```
[4]: def s_prey_population(params, step, sL, s, _input):
    y = 'prey_population'
    x = s['prey_population'] + _input['add_to_prey_population']
    return (y, x)

def s_predator_population(params, step, sL, s, _input):
    y = 'predator_population'
    x = s['predator_population'] + _input['add_to_predator_population']
    return (y, x)
```

1.2.4 State update blocks

```
[5]: partial_state_update_blocks = [
    {
        'policies': {
            'predator_births': p_predator_births,
            'prey_births': p_prey_births,
            'predator_deaths': p_predator_deaths,
            'prey_deaths': p_prey_deaths,
        },
        'variables': {
            'predator_population': s_prey_population,
            'prey_population': s_predator_population
        }
    }
]
```

1.2.5 Configuration and Execution

```
[6]: sim_config = config_sim(simulation_parameters)

exp = Experiment()
exp.append_configs(sim_configs=sim_config,
                  initial_state=initial_conditions,
                  partial_state_update_blocks=partial_state_update_blocks)

from cadCAD import configs
exec_mode = ExecutionMode()
exec_context = ExecutionContext(exec_mode.local_mode)
executor = Executor(exec_context=exec_context, configs=configs)
(records, tensor field, _) = executor.execute()
```

by cadCAD

```
Execution Mode: local_proc
Configuration Count: 3
Dimensions of the first simulation: (Timesteps, Params, Runs, Vars) = (200, 5, 7, 2)
Execution Method: local_simulations
SimIDs      : [0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 2, 2, 2, 2, 2, 2, 2, 2]
```

```
SubsetIDs: [0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 2, 2, 2, 2, 2, 2, 2]
Ns        : [0, 1, 2, 3, 4, 5, 6, 0, 1, 2, 3, 4, 5, 6, 0, 1, 2, 3, 4, 5, 6]
ExpIDs    : [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0]
Execution Mode: parallelized
Total execution time: 0.43s
```

1.2.6 Results

```
[7]: import plotly.express as px
```

```
[8]: df = pd.DataFrame(records)

# Drop all intermediate substeps
first_ind = (df.substep == 0) & (df.timestep == 0)
last_ind = df.substep == max(df.substep)
inds_to_drop = (first_ind | last_ind)
df = df.loc[inds_to_drop].drop(columns=['substep'])

# Attribute parameters to each row
df = df.assign(**configs[0].sim_config['M'])
for i, (_, n_df) in enumerate(df.groupby(['simulation', 'subset', 'run'])):
    df.loc[n_df.index] = n_df.assign(**configs[i].sim_config['M'])

fig = px.line(df.query('dt == 0.1'),
              x=df.prey_population,
              y=df.predator_population,
              color=df.run.astype(str))

fig.show()
```