Tree

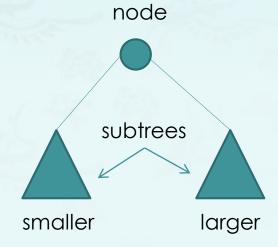
- introduction
- binary tree
- complete binary tree
 - max heap, min heap
 - Chapter 7 heap sorting
 - Chapter 9 priority queues
- binary search tree

Definition: A binary search tree is a binary tree in symmetric order.

- A binary tree is either
 - empty
 - a key-value pair and two binary trees [neither of which contain that key]

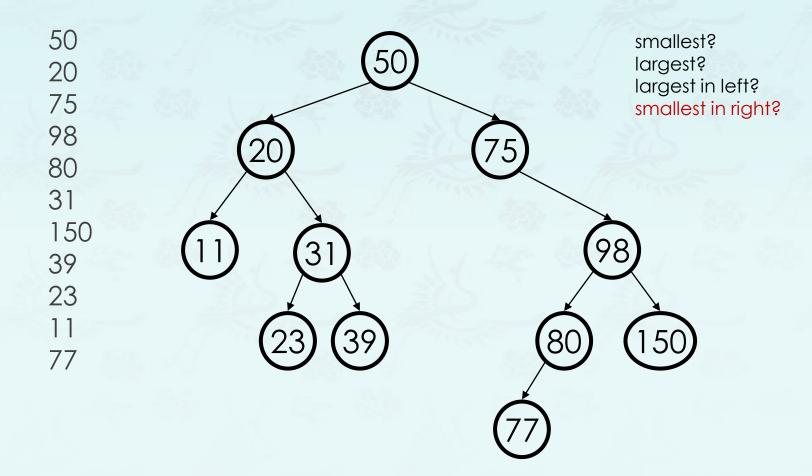
equal keys ruled out

- Symmetric order means that
 - every node has a key
 - every node's key is larger than all keys in its left subtree smaller than all keys in its right subtree



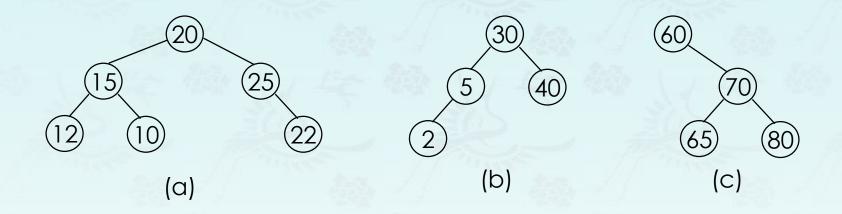
Operations: grow

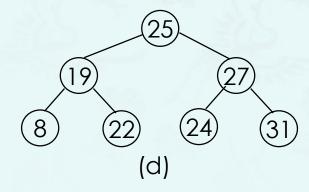
 Q: Draw what a binary search tree would look like if the following values were added to an initially empty tree in this order:



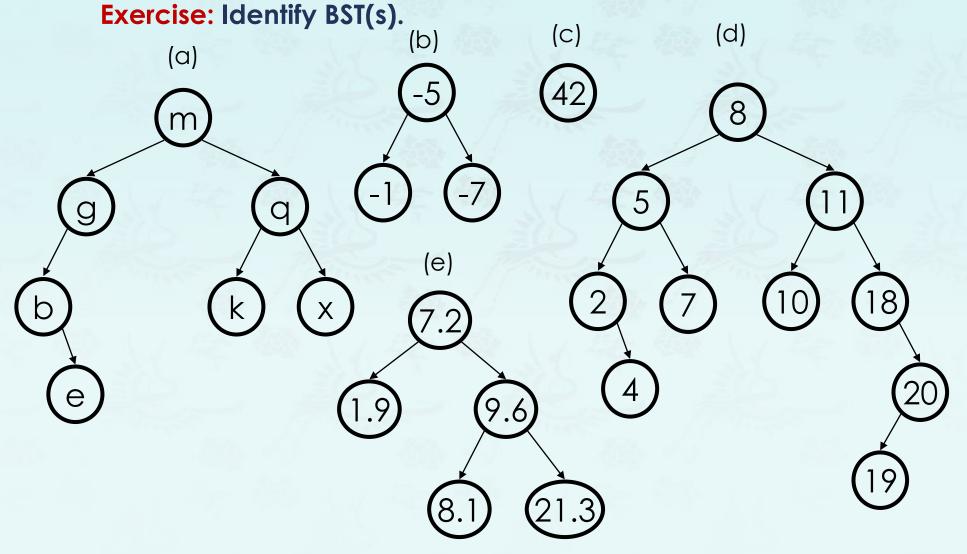
Definition: A binary search tree is a binary tree in symmetric order.

Exercise: Identify non-BST(s) and correct them if not.





Definition: A binary search tree is a binary tree in symmetric order.



Node structure:



Operations:

- Query search, min/max, successor, predecessor
- grow insert
- trim delete

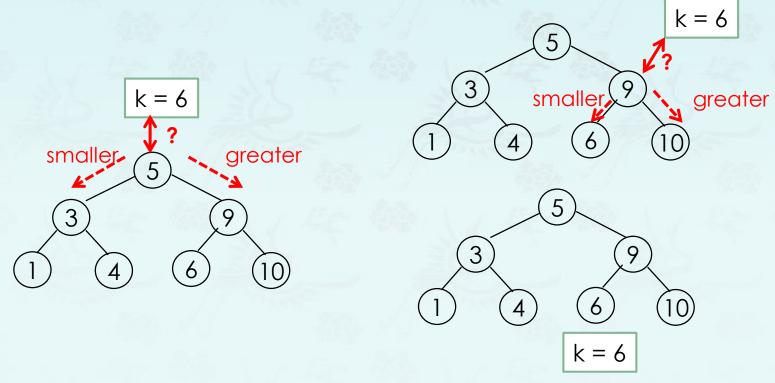
Binary search tree(BST) node structure:

```
key
tree left tree right
```

```
struct TreeNode {
  int key; // sorted by key
  TreeNode* left; // left child
  TreeNode* right; // right child
};
using tree = TreeNode*;
```

Operations: Search or "contains"

Search(T, k) – search the BST, T for a key k



❖ Search operation takes time O(h), where h is the height of a BST.

Operations: Search or "contains"

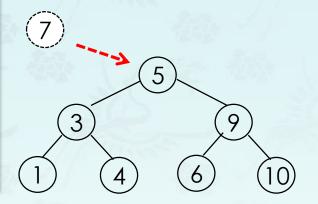
```
// does there exist a key-value pair with given key?
// search a key in binary search tree iteratively
int containsIteration(tree node, int key)
    if (node == nullptr) return false;
    while (node) {
        if (key == node->key) return true;
        if (key < node->key)
            node = node->left;
        else
            node = node->right;
    return false;
```

Operations: Search or "contains"

```
// does there exist a key-value pair with given key?
// search a key in binary search tree recursively
int contains(tree node, int key)
   if (node == nullptr) return false;
   if (key == node->key) return true;
   if (key < node->key)
       return contains(node->left, key);
   return contains(node->right, key);
```

Operations: grow

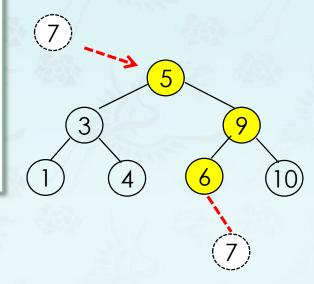
- grow(T, k)
 - Insert a node with Key = k into BST T
 - Time complexity? O(h)
- Step 1:
 if the tree is empty, then Root(T) = k
- Step 2: Pretending we are searching for k in BST, until we meet a nullptr node
- Step 3: Insert k



Q: Where is it inserted at?

Operations: grow

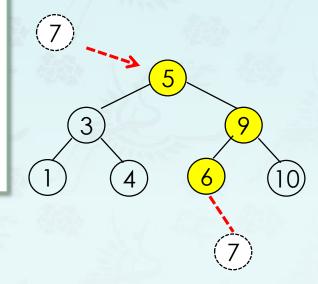
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The light nodes are compared with key.

Operations: grow

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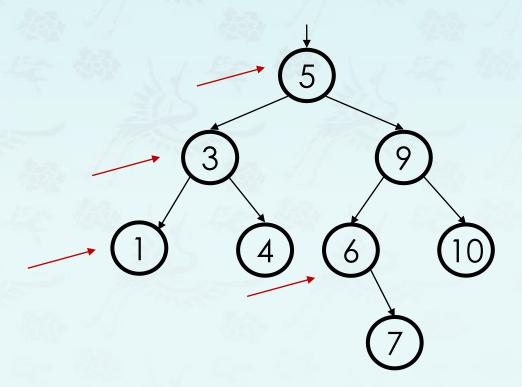


The light nodes are compared with key.

Q: Do you see the difference between the complete binary tree and binary search tree?

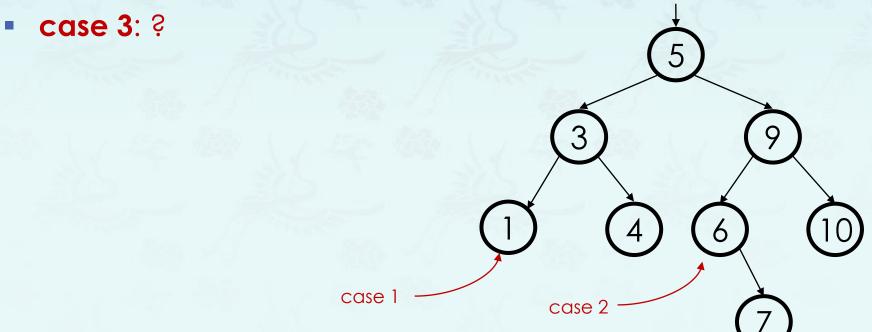
Operations: trim

- How can we trim a node from a BST in such a way as to maintain proper BST ordering?
 - trim(1);
 - trim(3);
 - trim(6);
 - trim(5);



Operations: trim

- case 1: leaf
 - a leaf replace with nullptr
- case 2: one child case
 - a node with a left child only replaced with left child
 - a node with a right child only replaced with right child



Operations: trim

case 3: two children case

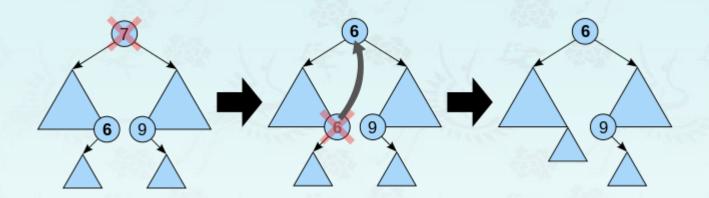
What can we replace 5 with?

What should be up here after the successful 000 deletion of 5, intuitively?

Operations: trim

case 3: two children case

Where is predecessor or successor of root 7?



- 1. The rightmost node in the left subtree, the inorder **predecessor 6**, is identified.
- 2. Its value is copied into the node being trimmed.
- 3. The inorder **predecessor** can then be trimd because it has at most one child.

NOTE: The same method works symmetrically using the inorder successor labelled 9.

Operations: trim

case 3: two children case

Idea: Replace the trimmed node with a value guaranteed to be between two child subtrees

Options:

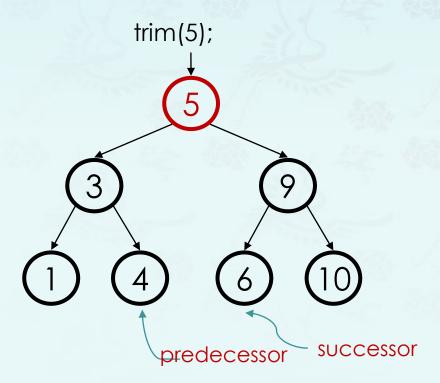
- predecessor from left subtree: maximum(node->left)
- successor from right subtree: minimum(node->right)
 - These are the easy cases of predecessor/successor

Now trim the original node containing successor or predecessor

It becomes leaf or one child case – easy cases of trim!

Operations: trim

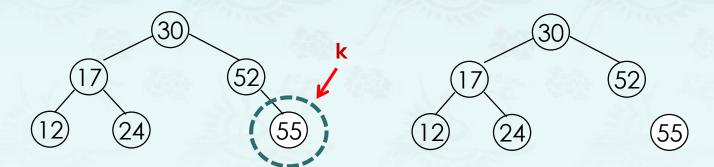
- case 3: two children case
 - Replace with min from right or max from left
 - Where is predecessor or successor of root 5?



Operations: trim

- trim(**T**, k)
 - trim a node with Key = k into BST T
 - Time complexity: O(h)

Case 1: k has no child

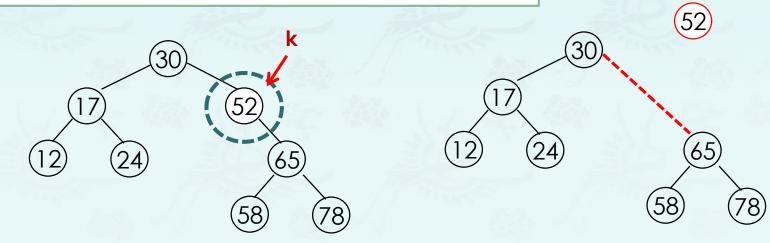


We can simply trim it from the tree

Operations: trim

- trim(**T**, k)
 - trim a node with Key = k into BST T
 - Time complexity: O(h)

Case 2: k has one child

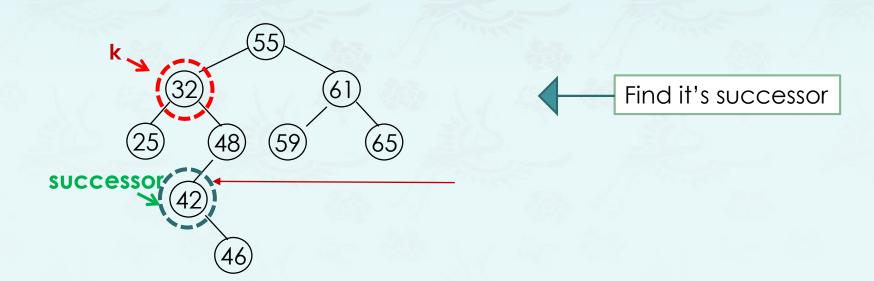


After removing it, connect it's subtree to it's parent node.

Operations: trim

- trim(**T**, k)
 - trim a node with Key = k into BST T
 - Time complexity: O(h)

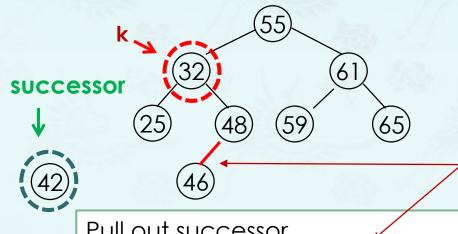
Case 3: k has two children



Operations: trim

- trim(**T**, k)
 - trim a node with Key = k into BST T
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Case 3: k has two children



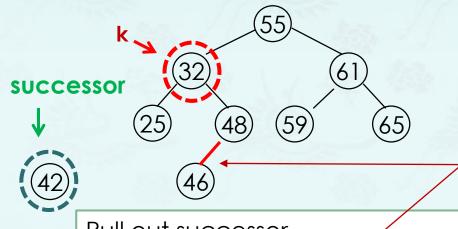
This is done by calling another trim() with succ key, recursively.

Pull out successor, and connect the tree with it's child

Operations: trim

- trim(T, k)
 - trim a node with Key = k into BST T
 - Time complexity: O(h)

Case 3: k has two children



```
int succ = value(minimum(root->right));
root->key = succ;
root->right = trim(root->right, succ);
```

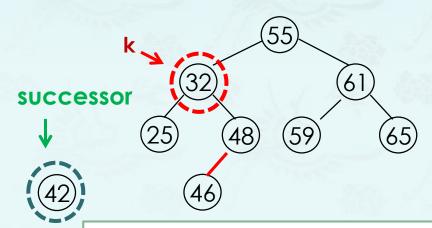
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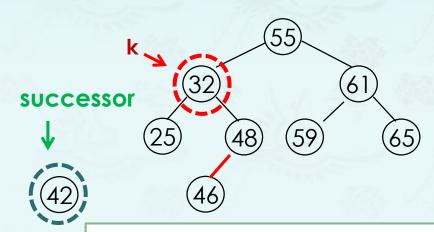
Pull out successor, and connect the tree with it's child

Q: What if successor has two children?

Operations: trim

- trim(T, k)
 - trim a node with Key = k into BST T
 - Time complexity: O(h)

Case 3: k has two children



A: Not possible!

Because if it has two nodes, at least one of them is less than it, then in the process of finding successor, we won't pick it!

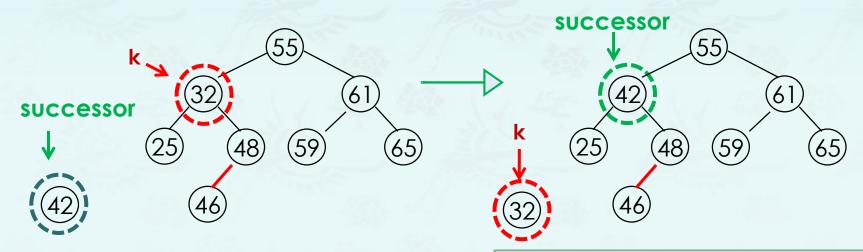
Pull out successor, and connect the tree with it's child

Q: What if successor has two children?

Operations: trim

- trim(**T**, k)
 - trim a node with Key = k into BST T
 - Time complexity: O(h)

Case 3: k has two children



Replace the **key** with it's successor

More Operations:

Query – search, min/max, successor, predecessor

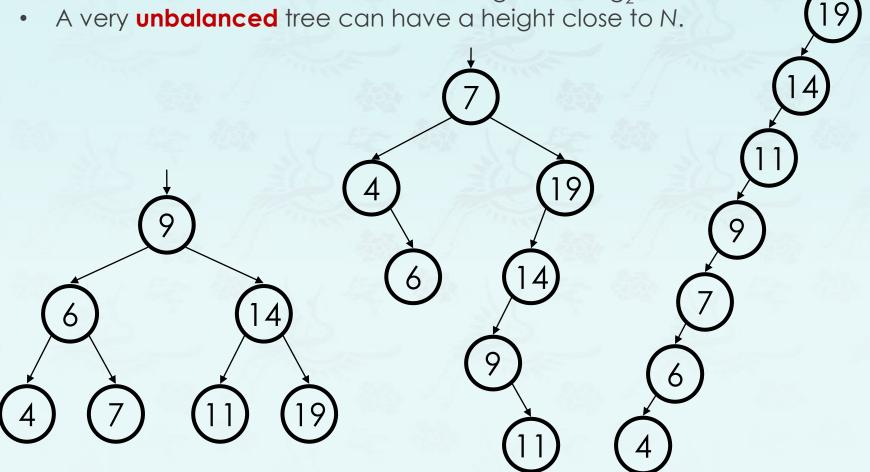
Min/max

- For min, we simply follow the left pointer until we find a nullptr node.
 Why?
- Similar for Max
- Time complexity: O(h)

Search operation takes time O(h), where h is the height of a BST.

Observations: What do you see in the following BSTs?

• A **balanced** tree of N nodes has a height of $\sim \log_2 N$.



Observations: What do you see in the following BSTs?

- Observation: The shallower the BST the better.
 - Average case height is O(log N)
 - Worst case height is O(N)
 - Simple cases such as adding (1, 2, 3, ..., N), or the opposite order, lead to the worst case scenario: height O(N).

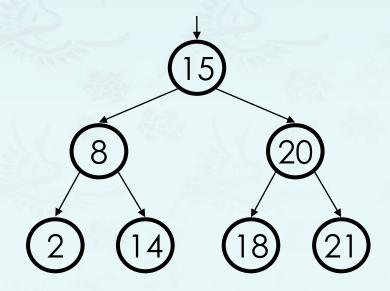
For binary tree of height h:

max # of leaves: 2^{h-1}

max # of nodes: 2^h - 1

min # of leaves:

min # of nodes: h

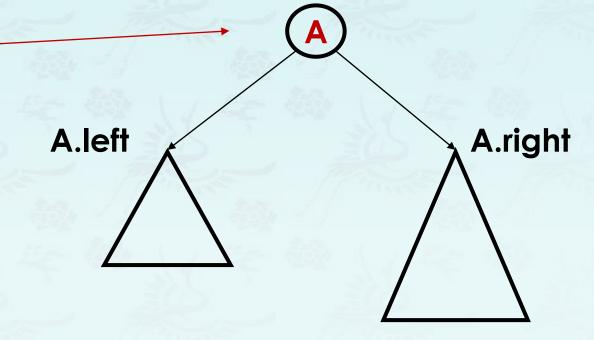


Q: Calculate tree height.

- Height is max number of nodes in path from root to any leaf.
 - height(nullptr) = 0
 - height(a leaf) = ?
 - height(A) = ?

Hint:

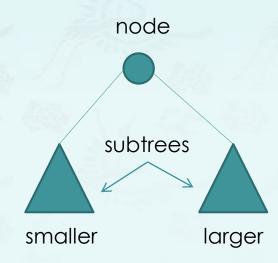
- use recursive.
- use max(a, b).



- A:
 - height(a leaf) = 1
 - height(A) = 1 + max(

Conclusion:

- If you have a sorted sequence, and we want to design a data structure for it
- Array or BST? and why?



Conclusion:

- If you have a sorted sequence, and we want to design a data structure for it
- Array or BST? and why?

Time Complexity	
BST	0(h)
Array	$O(\log n)$

Conclusion:

Q. When searching, we're traversing a path (since we're always moving to one of the children); since the length of the longest path is the height h of the binary search tree, then finding an element takes O(h).

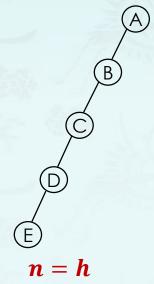
Since $h = \lg n$ (where n is the number of elements), then it's good! – right?

No, of course, it is wrong! Why?

A. The nodes could be arranged in linear sequence in BST, so the height h could be n. In worst case, it is O(n) instead of O(h).

Conclusion:

- We already know that n is fixed, but h differs from how we insert those elements!
- So why we still need BST?
 - Easier insertion and deletion
 - And with some optimization, we can avoid the worst case!



a skew binary search tree