

# Getting Started with KuttyPy

Jithin B.P

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## Network

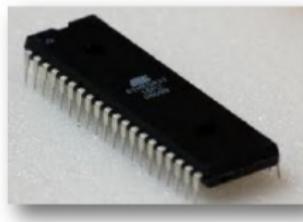
connect to wifi network 'homepc' , password 'industry4.0'

## Download Zip

- open a web browser
- 10.42.0.1:4000/kuttypy.zip

# What is the Microcontroller ?

A microcontroller is an integrated chip that is often part of an embedded system. The microcontroller includes a **CPU, RAM, ROM, I/O** ports, and **timers** like a standard computer, but because they are designed to execute only a single specific task to control a single system, they are much smaller and simplified so that they can include all the functions required on a single chip.



- Found in almost every appliance/gadget. E.g. microwaves, music players, automatic doors, elevators, cars, lab instruments etc
- Designed to efficiently handle simple tasks such as monitoring a switch and taking appropriate action after checking for other parameters.

## What is a development board?

A development board is a circuit board which has minimal external components required by a microcontroller such as

- Connectors for easily accessing the pins
- power supply socket and voltage regulator
- A crystal oscillator which decides the speed of operation of the program.



# KuttyPy

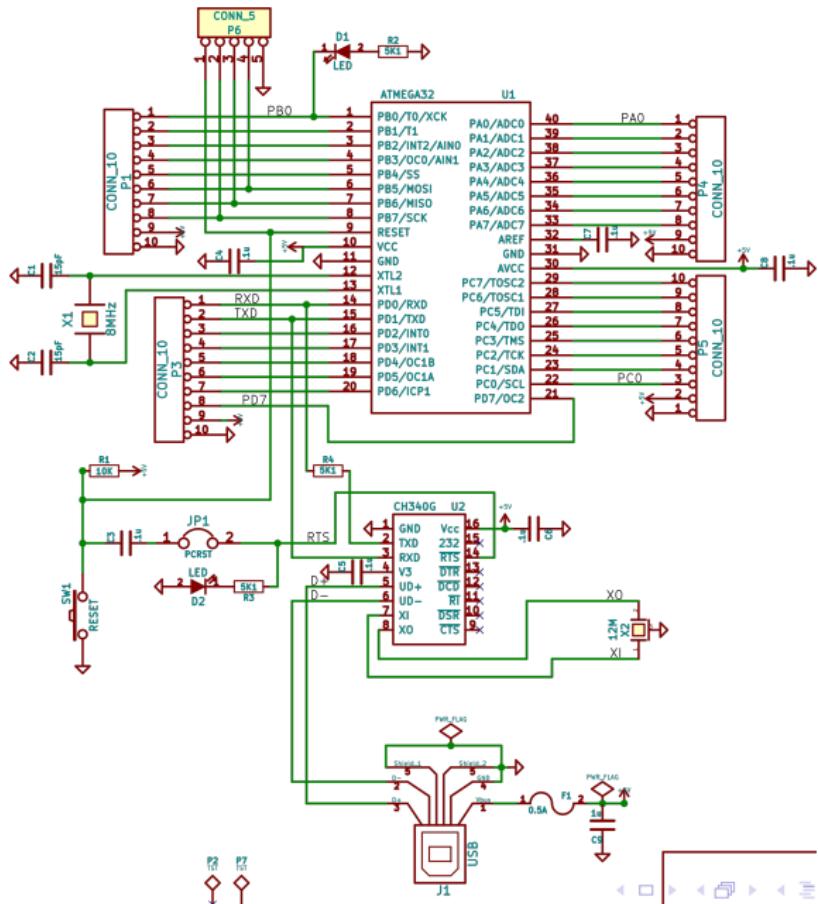
INTERACTIVE PLAYGROUND  
[ MICROCONTROLLER TRAINING UTILITY ]



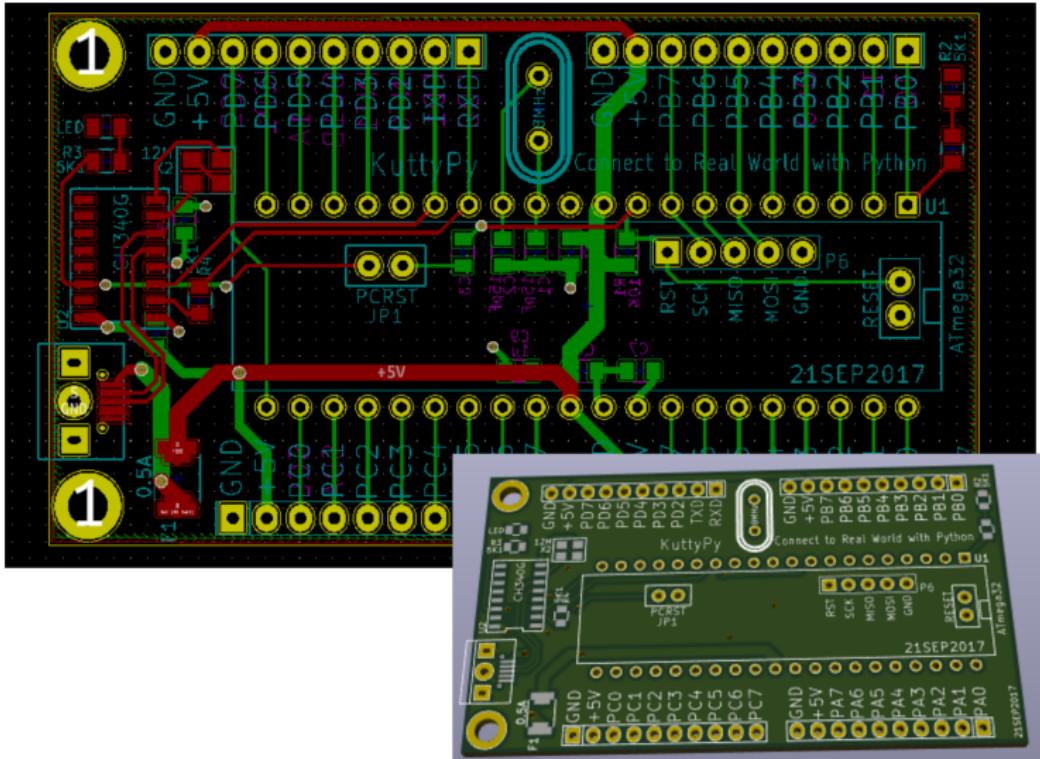
- \* Software-RealWorld Bridge
- \* Bootloader with built-in register R/W access
- \* Functions as a regular Atmega32 microcontroller development board
- \* A tool for learning microcontrollers



# Schematic



# Layout



# I/O pins: organisation

BLUE LED PD7 (OC2)	21	20	(ICP1) PD6
PC0 (SCL)	22	19	(OC1A) PD5 GREEN LED
PC1 (SDA)	23	18	(OC1B) PD4
PC2 (TCK)	24	17	(INT1) PD3
PC3 (TMS)	25	16	(INT0) PD2
PC4 (TDO)	26	15	(TXD) PD1
PC5 (TDI)	27	14	(RXD) PD0
PC6 (TOSC1)	28	13	XTAL1
PC7 (TOSC2)	29	12	XTAL2
AVCC	30	11	GND
GND	31	10	VCC
AREF	32	9	RESET
PA7 (ADC7)	33	8	(SCK) PB7
PA6 (ADC6)	34	7	(MISO) PB6
PA5 (ADC5)	35	6	(MOSI) PB5
PA4 (ADC4)	36	5	(SS) PB4
PA3 (ADC3)	37	4	(OC0/AIN1) PB3 RED LED
PA2 (ADC2)	38	3	(INT2/AIN0) PB2
PA1 (ADC1)	39	2	(T1) PB1
PA0 (ADC0)	40	1	(XCK/T0) PB0

12-BIT ADC

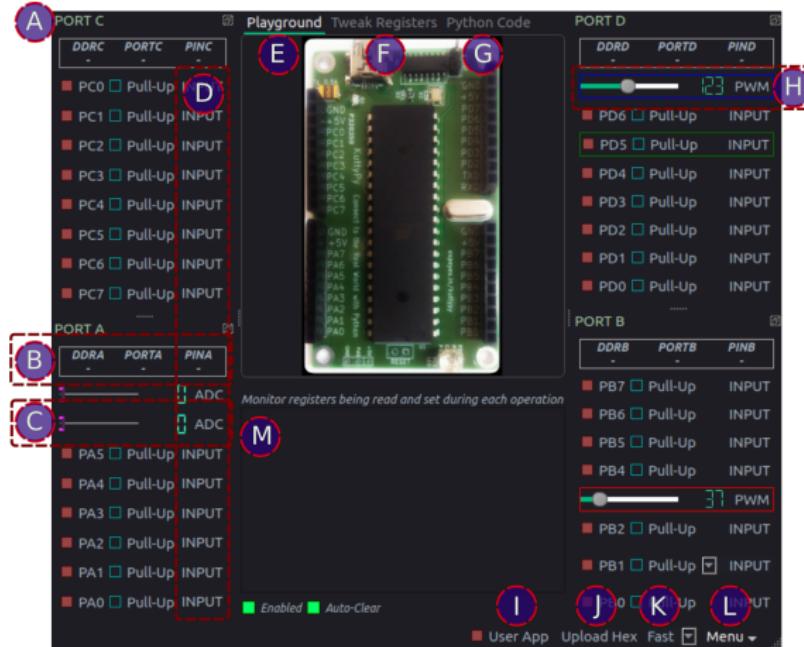
UART

SPI



All pins are grouped into their respective ports

Each port is a 10 pin berg socket with 8 I/O pins, 5V, and Ground.



Python based control and communication library, and GUI

All register manipulations carried out via the GUI are clearly displayed in the log window.

# Differences with Arduino: Bootloader specifics

## BOOTLOADER

- + Read hex files via the serial port, and write to flash.
- + Start executing user code if no serial data is received during boot



User code area:  
~30kB free

ARDUINO  
FLASH MEMORY

## BOOTLOADER

- + Interpret serial commands for reading and writing registers associated with the microcontroller (setReg, getReg). Study registers without the compile-upload hassle.
- + User the Python library to make kuttypy a software - real\_world bridge.

+ Read hex files via the serial port, and write to flash.

- + Start executing user code if no serial data is received during boot



User code area:  
~30kB free

KUTTYPY  
FLASH MEMORY

## Arduino

- Code must be compiled and uploaded to test behaviour
- PORTS and bit manipulations are replaced with pin numbers and high level functions, thereby hiding the microcontroller architecture.

## KuttyPy

- Real-time manipulation and readback of registers via the serial communication port.
- Graphical utility for quickly checking behaviour.
- Controlled via Python running on a traditional PC. Python modules can be used to develop complex projects.
- Code can also be compiled and uploaded for standalone operation.
- PORTS are classified as is, and students are encouraged to use bit manipulation and understand the relevance of binary.

# The importance of binary

**Microcontroller programming revolves around binary, and registers ( variables whose bits have specific hardware duties )**

Tweak Registers								
Add A New Register								
DDRB								Auto-Refresh
00001111								WRITE ↓
PORTB	7	6	5	4	3	2	1	0
6	7	6	5	4	3	2	1	0
	128	64	32	16	8	4	2	1

## Binary

$$00001111 = 0 + 0 + 0 + 0 + 8 + 4 + 2 + 1 = 15$$

**DDRx** : Each bit decides if the corresponding pin is input(0) , or output (1)

**DDRB** = 15 = 00001111 => PB7, PB6, PB5, PB4 are inputs.  
PB3, PB2, PB1, PB0 are outputs

**PORTx** : Each bit decides if the corresponding pin is connected to 5V(1) , or Ground(0) .

**DDRB** = 6 = 00001100 => PB7, PB6, PB5, PB4 are inputs.  
PB3 , PB0 are at 0 Volts  
PB2, PB1 are at 5Volts

# Project ideas using kuttyPy with Python

combined with various visualization and analytical modules of Python, several applications can be thought of.

- OpenCV : This image processing tool can be used to interpret webcam data, and create a motion tracking tool with KuttyPy. Moving camera mounts can be made using stepper motors controlled by KuttyPy.
- Matplotlib: This simple plotting tool can be used to create a voltage data logging tool with a few lines of code. The ADC of the kuttypy reads voltages in a 0-5Volts range, and returns a proportional number in the 0 - 1023 range.
- pymouse : Use an analog joystick connected to the kuttypy to move the mouse cursor. This can be used to develop assisted input technologies.
- Healthcare : Pulse monitoring, and automated, continuous analysis.

