## 10th International Conference, GRID'2023

# Balanced identification of mathematical models as a service of the Everest distributed computing platform

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This work was supported by the Russian Science Foundation under grant no. 22-11-00317, https://rscf.ru/project/22-11-00317/

#### **SvF-technology**

- SvF (Simplicity vs Fitting) a technology to support construction of mathematical models (structural, not regression only) based on experimental data.
- It has been successfully applied in biology, population dynamics, plant physiology, plasma physics, meteorology, ecology... Freely available in source code

#### https://github.com/distcomp/SvF

- Basic publications (A. Sokolov had used this method repeatedly several years before)
- 1. Sokolov A., Voloshinov V. Model Selection by Balanced Identification: the Interplay of Optimization and Distributed Computing // Open Computer Science, 2020
- Соколов А.В., Волошинов В.В. Выбор математической модели: баланс между сложностью и близостью к измерениям // International Journal of Open Information Technologies, 2018
- find other references here <a href="https://github.com/distcomp/SvF#references">https://github.com/distcomp/SvF#references</a>
- up-to-date User Manual <a href="https://github.com/.../SvF/SvF\_UserGuide.pdf">https://github.com/.../SvF/SvF\_UserGuide.pdf</a>
- The SvF computational scheme is based on solving special-type bi-level optimization problems. Here, at the lower level, it is necessary to solve <u>a set of independent</u> <u>optimization problems</u> similar to the inverse problems with the Tikhonov regularization.

#### **General flow-chart of SvF-technology**

The main problem: to construct and to validate mathematical model of a *phenomenon* by a set of experimental data

Inputs: Experimental data (relational DB tables \*.txt, \*.xls ... see User Manual)

Hypothesis about the structure of mathematical model and its formulation (as a set of equations, inequalities, may be integro-differential expressions) with explicit indications which parameters, or functions need to be determined (be identified).

#### All other steps may be performed automatically:

- 1. Formulation of bilevel optimization problem
- 2. Automatic discretization of optimization problems, if it is required, e.g. if differential and/or integral equations are presented in the model.
- 3. Automatic generation of SvF-computing scenario as a Python program
- 4. Implementation of SvF-scenario either locally, or in Everest distributed computing environment, <a href="http://everest.distcomp.org/">http://everest.distcomp.org/</a>

#### Example. "Inverse problem" for ODE

Identify a model of dynamic system by a set of trajectory points known with error.

Hypothesis: ODE (of order 1, 2). We need to identify right side of ODE.

$$\frac{\left\{\left(\tilde{x}_{d},t_{d}\right):d=1:N_{d}\right\},\tilde{x}_{d}=x(t_{d})\pm\operatorname{err}}{\dot{x}=F(t,x(t))\mid\ddot{x}=F(t,x(t)),\ t\in\left[t_{\mathbf{L}},t_{\mathbf{U}}\right]}\right\}\Rightarrow\boldsymbol{x}(t),\boldsymbol{F}(t,\boldsymbol{x})-?$$

SvF lower-level problem: cross-validation sub-problems

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$$\frac{\{(\tilde{x}_d, t_d) : d=1 : N_d\}, \tilde{x}_d = x(t_d) \pm \text{err}}{\dot{x} = F(t, x(t)) \mid \ddot{x} = F(t, x(t)), t \in [t_L, t_U]} \Rightarrow x(t), F(t, x) - ?$$
SyE CV lower-level problems: "training data-set"

SvF CV lower-level problems: "training data-set"

$$D_{k} = \{d=1:N_d, d\neq k\}, k=1:N_d$$

data **fitting** 

simplicity (smooth.)

$$\alpha = (\alpha_t, \alpha_r)$$

regularization

coefficients

$$\frac{1}{|\mathbf{D}_{k}|} \sum_{d \in \mathbf{D}_{k}} (\tilde{x}_{d} - x(t_{d}))^{2} + R(\boldsymbol{\alpha}, F(\cdot, \cdot)) \rightarrow \min_{x(\cdot), F(\cdot, \cdot)}, 
\dot{x} = F(x(t)) \mid \ddot{x} = F(x(t)), \ t \in [t_{\mathbf{L}}, t_{\mathbf{U}}], 
x(\cdot) \in \mathbf{C}^{2} [t_{\mathbf{L}}, t_{\mathbf{U}}], F(\cdot) \in \mathbf{C}^{2} [x_{\mathbf{L}}, x_{\mathbf{U}}]. 
R(\boldsymbol{\alpha}, F(\cdot, \cdot)) = 
\int_{t_{\mathbf{L}}}^{t_{\mathbf{U}}} \int_{x_{\mathbf{L}}} (\alpha_{t}^{2} (F_{tt}''(t, x))^{2} + 2\alpha_{t}\alpha_{x} (F_{tx}''(t, x))^{2} + \alpha_{x}^{2} (F_{xx}''(t, x))^{2}) dt dx$$

SvF lower-level problem: cross-validation sub-problems  $\mathcal{P}(D_k, \alpha) \Rightarrow x_{\iota}^{\alpha}(\cdot)$ 

$$\mathcal{P}(D_k, \alpha) \Rightarrow x_k^{\alpha}(\cdot)$$

## Example. Inverse problem for ODE. Solving bilevel opt. prob.

CV-error for a fixed 
$$\alpha = (\alpha_t, \alpha_x)$$
  $\mathcal{P}(D_k, \alpha) \Rightarrow x_k^{\alpha}(\cdot)$   $(k=1:N_d)$ 

$$\boldsymbol{\sigma}_{\text{cv}}(\boldsymbol{\alpha}) = \sqrt{\frac{1}{N_d} \sum_{k=1:N_d} (\tilde{x}_k - x_k^{\alpha}(t_k))^2}$$

SvF upper-level problem: minimize CV-error by lpha

$$m{\sigma_{\mathsf{mse}}}(m{lpha}^*) = \sqrt{rac{1}{N_d} \! \sum\limits_{m{k}=1:N_d} \! (m{ ilde{x}_k} - m{x}^*(m{t_k}))^2}$$
 Final result: Root Mean Squared Error

In current implementation all variational expressions are discretized to get finite dimensional Mathematical Programming Problems which may be solved by general purpose optimization solvers (we use lpopt and SCIP, optionally).

## Typical chain of optimization problems

## Why we need remote SvF-service & distributed computing

- SvF-toolkit may be run in local mode when all problems are solved at the same host where SvF-main script is run
- There may be dozens of rather hard optimization problems
- SvF-toolkit already can use Everest to solve a set of independent opt.
   problems on remote resources in parallel mode
- Even with the aid of Everest the SvF-scenario may be rather time consuming (a few hours) and all this time your comp. must be on.

It would be nice to have an option to run SvF-scenario in a mode "send data and wait notification by mail"...

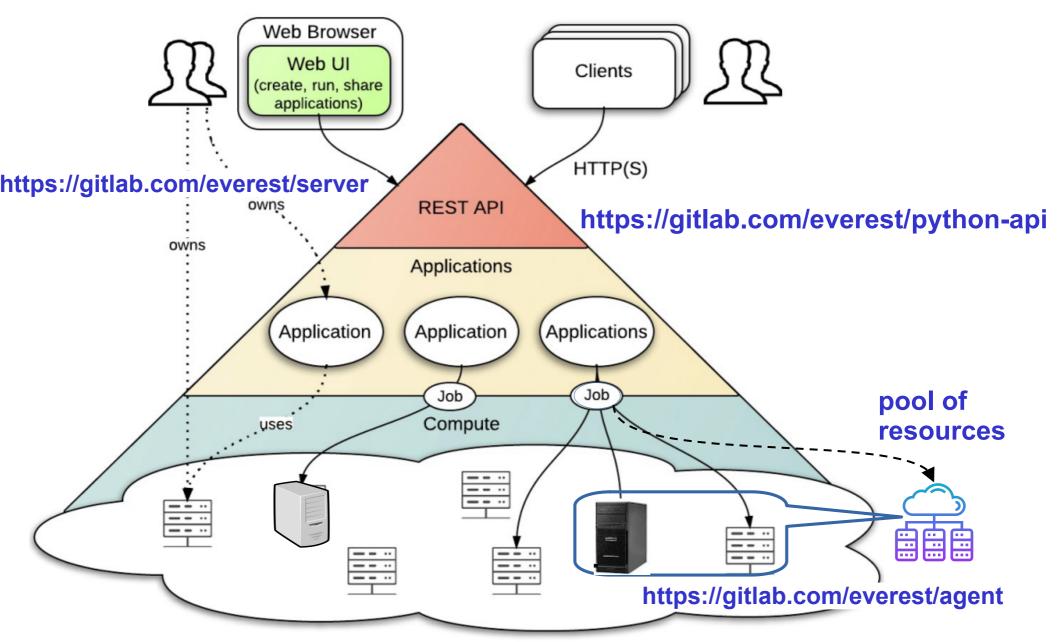
Maturity of SvF-toolkit enables to do that !

## Basic software components of SvF-technology

- Python 3.7+ basic language
- Pyomo toolkit, www.pyomo.org, PYthon Opt. Modeling Objects, Supports all basic types of Math. Programming problems: LP, QP, NLP, MILP, MINLP, Stochastic ..., DAE (Differential and Integral equations), ...
  - **Pyomo** supports most of all open source and commercial AMPL-compatible solvers **Ipopt**, **SCIP**, **CBC**, **CPLEX**, **Gurobi**, **COPT**, etc
- Everest platform, <a href="http://everest.distcomp.org/">http://everest.distcomp.org/</a>, and its Optimization Modeling
   Facet <a href="https://optmod.distcomp.org">https://optmod.distcomp.org</a>
  - Everest Python API (client side), <a href="https://gitlab.com/everest/python-api">https://gitlab.com/everest/python-api</a>
  - Everest Application, <a href="https://optmod.distcomp.org/apps/vladimirv/SSOP">https://optmod.distcomp.org/apps/vladimirv/SSOP</a> to solve a set of independent optimization problems
  - Everest App., <a href="https://optmod.distcomp.org/apps/vladimirv/svf-remote">https://optmod.distcomp.org/apps/vladimirv/svf-remote</a> to run the SvF-scenario in remote mode

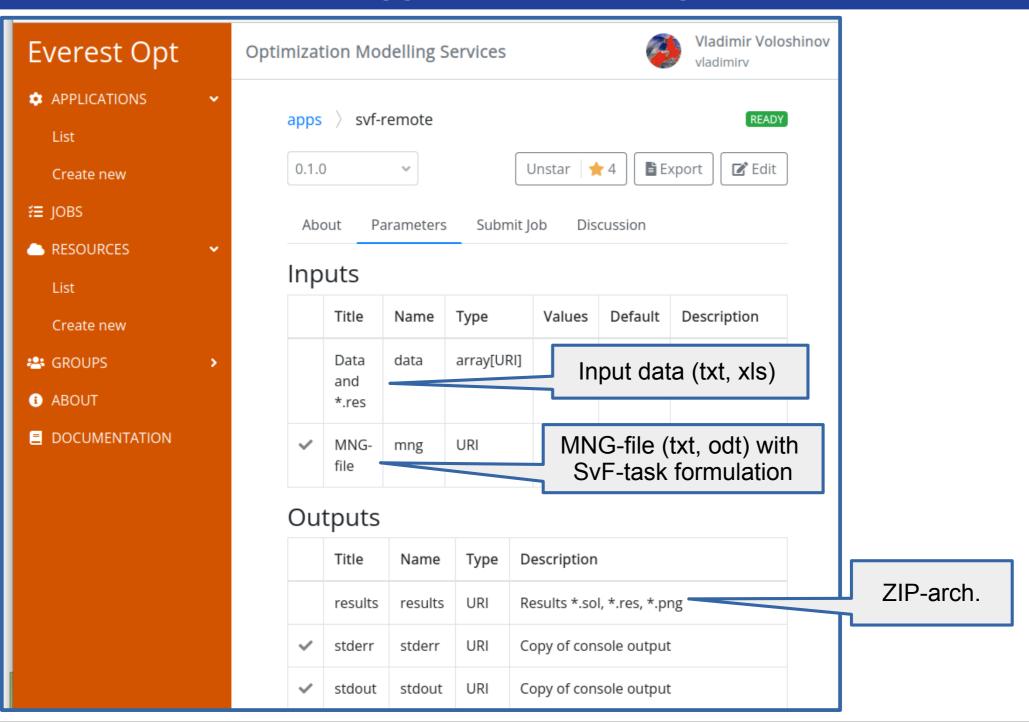
## **Everest platform architecture outlines**

Describe/Develop/Deploy REST-services representing existing applications

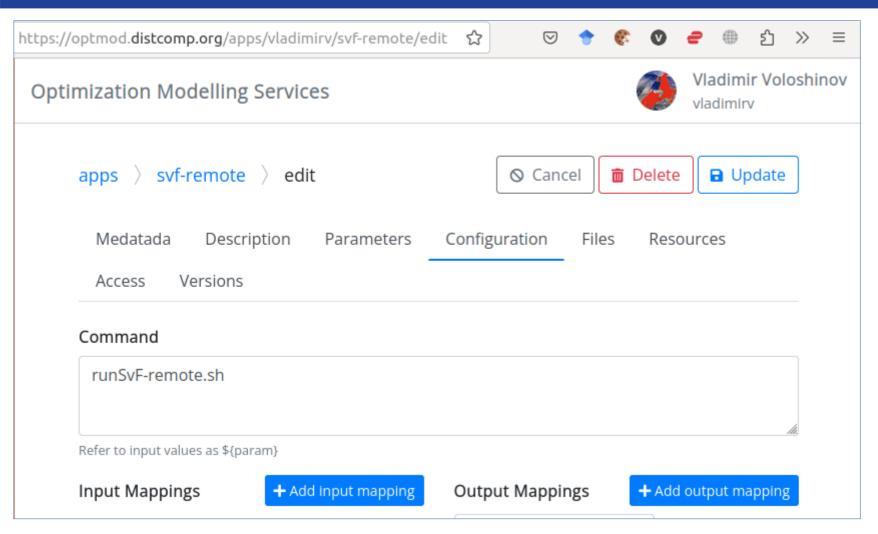


External Computing Resources (attached by users)

## svf-remote application in / out parameters



## svf-remote implementation is simple (due to SvF features)



#### #!/bin/bash

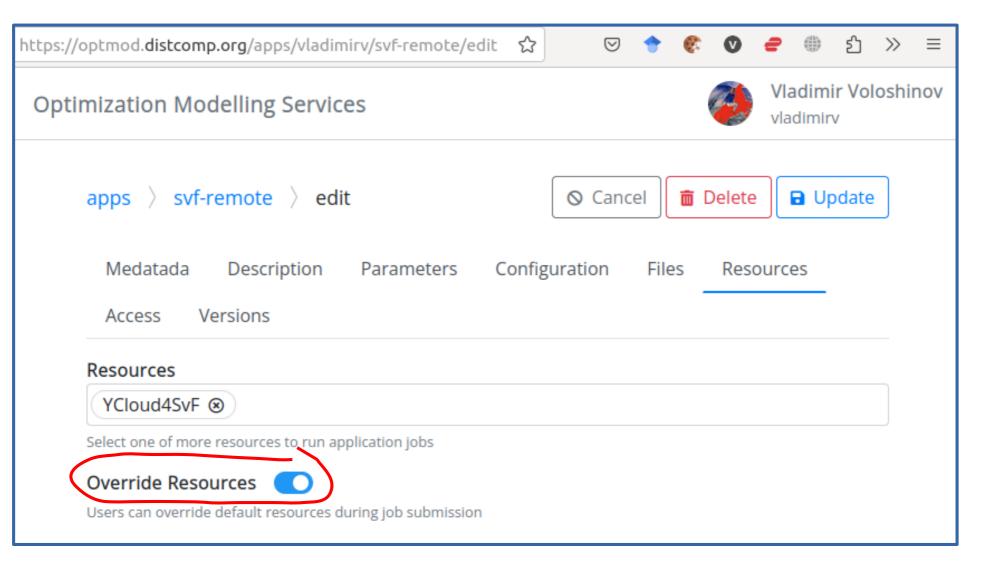
<PATH TO SvF Folder>/SvF/runSvF31.sh zip results.zip \*.sol \*.png \*.res

runSvF-remote.sh – somewhere in the \$PATH

#### svf-remote user can choose Everest resource to run

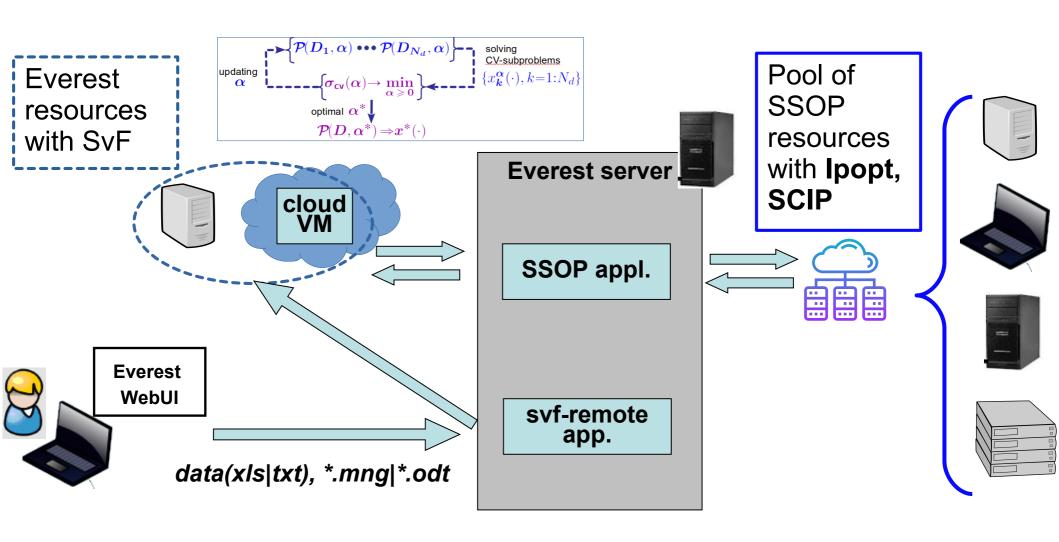
Everest user can select resource where SvF-remote job will be run Requirements:

SvF-toolkit is installed and runSvF-remote.sh is in the \$PATH



#### svf-remote flow chart

**svf-remote** service enables to use only browser to send data files and MNG-file with SvF-task to "executor". User can select resource to run **svf-remote** job.



## Example of MNG-file, \*.ODT format. Dumped oscillator.

```
Here you can place arbitrary text and pictures
BoF-SvF
Runmode = 'P&S'
SvF.DrawMode = 'File'
                                          #'File&Screen'
SvF.Resources = ["pool-scip-ipopt"] #["abc_pc" ]
               10 # Number of iter.
CVNumOfIter
CVstep
               21 # Numberof CV subproblems
Select x, t from Spring5.dat
GRID:
        t ∈ [ -1., 2.5, 0.025 ]
          x(t)
v(t)
Var:
                 # will be replaced to muu in Python code
           XΓ
SchemeD1 = Central
        d2/dt2(x) == - K * (x - xr) - muu * v
# E0:
        v == d/dt(x)
EQ:
        \frac{d^2}{dt^2}(x) == -K * (x - xr) - \mu * v
        v == \frac{d}{dt}(x)
OBJ:
        x.Complexity ( Penal[0]) + x.MSD()
Draw
EOF
Some remarks, figures, formulas may be added here
```

#### **Conclusions and future plans**

#### **Conclusions**

- svf-remote application reproduces all conveniences of current SvF-tookit:
  - symbolic formulation of identification task in MNG-file (ASCII text, OpenOffice \*.odt) with symbolic formulas
  - access to all Everest resources with optimization solvers
  - returns results in numerical and graphical form
- Ease of use from browser for a long calculations on the principle of "launch and wait for notification by mail"
- You can run svf-remote on any Everest resources (servers, desktops, VMs) where SvF-toolkit is installed

#### **Nearest future plans**

- Involve our IPPI servers as svf-remote deployment hosts
- Migrate from Everest "local" Agent on Yandex Cloud VM to Everest YCC Agent (for Yandex Cloud Container) (to save money)
- To try Jupyter as another user interface to SvF-toolkit, installed on remote host (SSOP will remain with us)

Thank you.

**Questions?** 

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#### Discretization of autonomous DE: polynomila + mesh

One of approach in SvF: outer function is replaced with polynomial with unknown coefficients, inner function — unknown values on a meshgrid (by t):

$$F(x) \sim \mathcal{P}(x) = \sum_{p=0}^{P} c_{p} \cdot x^{p} \qquad x(t) \sim \{(x_{i}, t_{k}) : i = 0 : N_{x}, k = 0 : N_{t}\},$$

$$x_{i} = x_{\mathbf{L}} + i \cdot \Delta x, \Delta x = \frac{x_{N_{x}} - x_{\mathbf{L}}}{N_{x}},$$

$$t_{k} = t_{\mathbf{L}} + k \cdot \Delta t, \Delta t = \frac{t_{N_{t}} - t_{\mathbf{L}}}{N_{t}},$$

$$\left\{\dot{x} = F(x(t))\right\} \sim \left\{\frac{x(t_{k}) - x(t_{k-1})}{\Delta t} = \sum_{p=0}^{P} c_{p} \cdot \left(\frac{x(t_{k}) + x(t_{k-1})}{2}\right)^{p}, k = 1 : N_{t}\right\}$$

$$\left\{\ddot{x} = F(x(t))\right\} \sim \left\{\frac{x(t_{k+1}) - 2x(t_{k}) + x(t_{k-1})}{\Delta t^{2}} = \sum_{p=0}^{P} c_{p} \cdot x(t_{k})^{p}, k = 1 : (N_{t} - 1)\right\}$$

$$x(t_{d}) \sim \hat{x}_{d} = \frac{t_{k} - t_{d}}{\Delta t} x(t_{k-1}) + \frac{t_{k-1} - t_{d}}{\Delta t} x(t_{k}), t_{d} \in [t_{k-1}, t_{k}]$$

$$\frac{1}{D} \sum_{d=1:D} (\tilde{x}_d - \hat{x}_d))^2 + \alpha \sum_{\dots} \left( \frac{\mathcal{P}(x_{i+1}) - 2\mathcal{P}(x_i) + \mathcal{P}(x_{i-1})}{\Delta x^2} \right)^2 \Delta x \to \min_{x_i, c_p}.$$

This we have **nonlinear mathematical programming problem** with polynomials of non-small degrees (up to 7, 8)

## Задания и подзадания SvF-расчета в Everest

