Chapter 14 Solusion

https://github.com/frc123/CLRS

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14.1

14.1-1

recursion	x.key	r	i
1	26	13	10
2	17	8	10
3	21	3	2
4	19	1	2
5	20	1	1

The result is 20.

14.1-2

iteration	y.key	r		
1	35	1		
2	38	1		
3	30	3		
4	41	3		
5	26	16		
The result is 16.				

14.1-3

```
{
                      subtree_root_node = subtree_root_node->left;
11
                 }
12
                 else
13
                 {
14
                     subtree_root_node = subtree_root_node->right;
                     rank -= root_rank;
16
                 }
                 root_rank = subtree_root_node->left->size + 1;
18
             }
             return subtree_root_node;
        }
14.1 - 4
        template <class Key, class T>
        size_t OrderStatisticsTree<Key, T>::Rank(Node* node)
        {
 3
             if (node == root_)
                 return node->left->size + 1;
             else if (node == node->parent->left)
 6
                 return Rank(node->parent) - node->right->size - 1;
             else
                 return Rank(node->parent) + node->left->size + 1;
        }
14.1-5
  r = \text{OS-Rank}(T, x)
   succ = OS-Select(T.root, r + i)
    The result is succ.
14.1-6
For RB-INSERT(T, z), set z. rank = 1, and change the while loop to the following code:
   while x \neq T. nil
1
2
       y = x
3
       if z. key < x. key
            x. rank = x. rank + 1
4
            x = x.left
5
```

6

else x = x.right

For RB-Delete(T, z), add the following code right befire line 18 (in the else branch):

```
y.rank = z.rank
```

And invoke RB-Delete-Fix-Rank(T, x) right before line 21.

```
RB-Delete-Fix-Rank(T, x)
```

```
1 while x \neq T. root

2 if x == x. p. left

3 x. p. rank = x. p. rank - 1

4 x = x. p
```

For Left-Rotate (T, x), add the following code to the end of the procedure:

```
y. rank = y. rank + x. rank
```

For RIGHT-ROTATE(T, y), add the following code to the end of the procedure:

```
y. rank = y. rank - x. rank
```

14.1-7

```
template <typename Key>
       size_t CountInversions(std::vector<Key> array)
            size_t inversions, i, rank;
            OrderStatisticsTree<Key, int> tree;
5
            std::pair<typename OrderStatisticsTree<Key, int>::Iterator, bool> insert_result;
6
            inversions = 0;
            for (i = 0; i < array.size(); ++i)
            {
                insert_result = tree.Insert({array[i], 0});
10
                rank = tree.Rank(insert_result.first);
11
                inversions += (1 + i - rank);
            }
13
           return inversions;
14
       }
```

14.1-8

```
size_t CountIntersections(std::vector<Chord> chords)
{
size_t intersections, i, rank_a, rank_b, rank_diff_1, rank_diff_2;
```

```
OSTree tree;
            std::pair<typename OSTree::Iterator, bool> insert_result_a, insert_result_b;
            intersections = 0;
            for (i = 0; i < chords.size(); ++i)</pre>
            {
                insert_result_a = tree.Insert({chords[i].endpoint_a, 0});
                insert_result_b = tree.Insert({chords[i].endpoint_b, 0});
10
                rank_a = tree.Rank(insert_result_a.first);
11
                rank_b = tree.Rank(insert_result_b.first);
12
                if (rank_a > rank_b) std::swap (rank_a, rank_b);
                // rank_a must smaller than rank_b
                rank_diff_1 = rank_b - rank_a - 1;
15
                rank_diff_2 = tree.Size() - rank_b + rank_a - 1;
16
                intersections += std::min(rank_diff_1, rank_diff_2);
17
            }
            return intersections;
19
       }
20
```

14.2

14.2-1

Add prev and succ attributes to each node in the tree. Let prev points to predecessor of the node, and let succ points to successor of the node. Let T.nil.succ points to the minumum element in the tree, and let T.nil.prev points to the maximum element in the tree. A circular doubly linked list is formed.

In order to maintain these informations, we just need to modify RB-INSERT and RB-DELETE. For RB-INSERT(T, z), modify line 9 - 13 to the following code:

```
if y == T. nil
 2
         T.root = z
 3
         z.succ = T.nil
         z.prev = T.nil
 4
    elseif z.key < y.key
 5
 6
         y.left = z
 7
         z.succ = y
 8
         z.prev = y.prev
9
    else y.right = z
10
         z.prev = y
11
         z.succ = y.succ
12
    z.succ.prev = z
13
    z.prev.succ = z
```

For RB-Delete(T, z), add the following code right before line 21:

```
1 	 z. prev. succ = z. succ

2 	 z. succ. prev = z. prev
```

14.2 - 2

We can maintain black-heights of nodes without affecting the asymptotic performance since a change to x. bh propagates only to ancestors of x in the tree.

For RB-INSERT(T, z), add the following code right before line 17:

$$z.bh = 1$$

For RB-Insert-Fixup (T, z), add the following code right before line 8 (in the if branch) (case 1):

$$z. p. p. bh = z. p. p. bh + 1$$

For RB-DELETE-FIXUP(T, z), add the following code right before line 11 (in the if branch) (case 2):

$$x.\,p.\,bh\,=\,x.\,p.\,bh-1$$

And add the following code right before line 21 (in the else branch) (case 4):

$$x.p.bh = x.p.bh - 1$$

 $x.p.p.bh = x.p.p.bh + 1$

We cannot maintain depths of nodes without affecting the asymptotic performance since a change to x. bh propagates to descendants of x in the tree.

14.2-3

After the rotation on x is performed, run the following code:

```
1 x.p.f = x.f
2 x.f = x.left.f \otimes x.right.f \otimes x.a
```

Apply to the size attributes in order-statistic trees, we just need to change f to size, change \otimes to +, and attibute a of each node will be 1; the code will be:

```
 \begin{array}{ll} 1 & x. \, p. \, size \, = \, x. \, size \\ 2 & x. \, size \, = \, x. \, left. \, size \, + \, x. \, right. \, size \, + \, 1 \end{array}
```

14.2 - 4

The following procedure takes $\Theta(m + \lg n)$ time (to understand this asymptotic performance, refer to theorem 12.1 and exercise 12.2-8):

```
RB-Enumerate(x, a, b)
```

```
1 if a \le x. key and x. key \le b
```

- 2 Output(x)
- 3 **if** $a \le x$. key and x. left $\ne T$. nil
- 4 RB-ENUMERATE(x. left, a, b)
- 5 **if** $x. key \le b$ and $x. right \ne T. nil$
- 6 RB-ENUMERATE(x. right, a, b)

Note that we need to implement RB-ENUMERATE(x, a, b) in $\Theta(m + \lg n)$ time, so it does not meet the requirement of the question if we implement the procedure in the following ways (augment the tree in the way of exercise 14.2-1) since it takes $\Theta(m)$ time only:

RB-ENUMERATE(T, a, b)

- $1 \quad k = a$
- 2 Output(k)
- 3 repeat
- 4 k = k.succ
- 5 Output(k)
- 6 until k == b

14.3

14.3 - 1

Add the following lines to the end of Left-Rotate(T, x):

```
1 y.max = x.max
2 x.max = max(x.int.high, x.left.max, x.right.max)
```

14.3-2

```
INTERVAL-SEARCH(T, i)
   x = T.root
   while x \neq T.nil and i does not overlap x.int
        if x. left \neq T. nil and x. left. max > i. low
3
4
              x = x. left
        else x = x.right
5
   return x
14.3-3
Iterative version:
INTERVAL-SEARCH-MIN(T, i)
 1 \quad x = T.root
    smallest = T.nil
    while x \neq T. nil
 3
          if x. left \neq T. nil and x. left. max \geq i. low
 4
               if i overlaps x.int
 5
                    smallest = x
 6
               x = x.left
 7
 8
          else if i overlaps x.int
 9
                    return x
10
               x = x.right
11
    {f return}\ smallest
Recursive version:
     Invoke Interval-Search-Min(T, T. root, i)
INTERVAL-SEARCH-MIN(T, x, i)
    if x. left \neq T. nil and x. left. max \geq i. low
 2
          smallest = Interval-Search-Min(T, x. left, i)
 3
          \textbf{if} \ smallest \neq T.nil
 4
               {f return}\ smallest
          elseif i overlaps x.int
 5
 6
               return x
          else return T. nil
     else if i overlaps x.int
 8
 9
               return x
          else return Interval-Search-Min(T, x. right, i)
10
```

14.3-4

```
LIST-OVERLAP-INTERVAL(T, x, i)

1 if x.int overlaps i

2 OUTPUT(x)

3 if x.left \neq T.nil and x.left.max \geq i.low

4 LIST-OVERLAP-INTERVAL(T, x.left, i)

5 if x.right \neq T.nil and x.right.max \geq i.low and x.int.low < i.high

6 LIST-OVERLAP-INTERVAL(T, x.right, i)
```

14.3-5

```
Interval-Search-Exactly(T, i)
     x = T.root
     while x \neq T. nil and (x.int.low \neq i.low \text{ or } x.int.high \neq i.high)
 3
          if i.high > x.max
               x = T.nil
 4
 5
          elseif i.low < x.low
 6
               x = x. left
 7
          elseif i. low > x. low
 8
               x = x.right
 9
          else x = T.nil
```

14.3-6

return x

10

Consider to augment the red-black tree by adding attibute min-gap, min, and max to every node.

min-qap is the minimum gap in the subtree rooted at the node.

min is the minimum key in the subtree rooted at the node.

max is the maximum key in the subtree rooted at the node.

When MIN-GAP(Q) is called, we just need to return Q.root.min-gap, which takes O(1) time.

Let x be arbitrary node in the red-black tree Q. In order to maintain min-gap in $O(\lg n)$, we want x.min-gap depends on only the information in nodes x, x.left, and x.right.

```
x.min-gap = \min(x.left.min-gap, x.right.min-gap, x.key - x.left.max, x.right.min - x.key) Q.nil.min-gap = \infty Q.nil.min = \infty Q.nil.max = -\infty
```

Notice when there is no left subtree of x (x.left == Q.nil), x.prev will be the ancestor of x, and the gap between x.prev and x will be compared by x.prev, so the gap will not be neglected. (recall that x.min-gap only contains the minimum gap in the subtree rooted at x)

We can maintain min and max in $O(\lg n)$ also since x.min and x.max depends only on only the information in nodes x, x.left, and x.right.

```
x.min = min(x.left.min, x.key)

x.max = max(x.right.max, x.key)
```

Notice that if $x.left \neq Q.nil$, x.left.min < x.key must be true; if $x.right \neq Q.nil$, x.right.max > x.key must be true.

14.3-7

```
bool DetermineOverlapRectangles(const std::vector<Rectangle>& rectangles)
       {
            bool found_overlap;
3
            RectangleWithXCoordIndex *alloc_ptr, *now;
            std::allocator<RectangleWithXCoordIndex> alloc;
            std::vector<RectangleWithXCoordIndex*> heap;
            Tree tree; // interval tree
            found_overlap = false;
            // sort the x-coordinates with the minimum heap
            alloc_ptr = ConstructHeap(rectangles, heap);
            while (heap.size() > 0)
            {
12
                now = HeapExtractMin(heap);
13
                if (now->coord_pos == RectangleWithXCoordIndex::LEFT)
14
                {
                    if (tree.Find(now->rectangle->y_int) != tree.End())
16
                    {
17
                        found_overlap = true;
18
                        break;
19
                    }
20
                    now->relate.right->relate.left =
21
                        tree.Insert({now->rectangle->y_int, 0}).first;
22
                }
23
                else
24
                {
25
                    tree.Delete(now->relate.left);
26
                }
27
            }
28
            DestructHeap(alloc_ptr, rectangles.size());
29
            return found_overlap;
       }
```

Chapter 14 Problems

14-1

(a)

Proof. Let [a, b] be the interval of maximum overlap. In other word, [a, b] is the intersection of the overlap segments. This says all points in [a, b] have the same number of overlap segments. Notice a and b must be one of the endpoint of a segment that is included in the intersection. Hence there will always be a point of maximum overlap that is an endpoint of the segments.

```
(b)
       struct Node
            Node* parent;
3
            Node* left;
            Node* right;
            enum { BLACK, RED } color;
            T mapped_value; // only lower endpoint
            const Key key;
            enum { LOWER = +1, HIGHER = -1 } endpoint_type;
            Node* related_endpoint; // other endpoint of the current interval
10
11
             *x.type\_sum = x.left.type\_sum + x.endpoint\_type + x.right.type\_sum
13
            int type_sum;
14
            /**
15
             * x.left_max_overlap_num = x.left_max_overlap_num
             * x.overlap_num = x.left.type_sum + x.endpoint_type
             * x.right_max_overlap_num = x.overlap_num + x.right.max_overlap_num
18
             * x.max_overlap_num =
19
                    max(x.left_max_overlap_num, x.overlap_num, x.right_max_overlap_num)
20
             * Notice that overlap_num only consider local overlap
                    (in the subtree root at the node)
23
             * This says overlap_num is relatively
24
25
            // node with endpoint which has maximum number of overlap segments
            Node* max_overlap_node;
            // maximum number of overlap segments
28
            int max_overlap_num;
29
```

```
30
            Node() : key(Key()) {}
31
            Node(const Key& key) : key(key) {}
32
       };
33
34
       template <class Key, class T>
       bool IntervalTreePOM<Key, T>::MaintainAugmentedAttributesOfSingleNode(Node *node)
36
37
            int type_sum, max_overlap_num, overlap_num, right_max_overlap_num;
38
            Node *max_overlap_node;
            bool modified;
            /* maintain type_sum */
41
            type_sum = node->left->type_sum + node->endpoint_type + node->right->type_sum;
42
            /* maintain max_overlap */
43
            overlap_num = node->left->type_sum + node->endpoint_type;
44
            if (node->left != nil_ && node->left->max_overlap_num > overlap_num)
            {
46
                max_overlap_num = node->left->max_overlap_num;
47
                max_overlap_node = node->left->max_overlap_node;
48
            }
49
            else
            {
51
                max_overlap_num = overlap_num;
52
                max_overlap_node = node;
53
            }
            if (node->right != nil_)
55
            {
56
                right_max_overlap_num = overlap_num + node->right->max_overlap_num;
57
                if (right_max_overlap_num > max_overlap_num)
                {
                    max_overlap_num = right_max_overlap_num;
                    max_overlap_node = node->right->max_overlap_node;
61
                }
62
            }
63
            /* do modify */
            modified = false;
               (node->type_sum != type_sum)
66
            {
67
                node->type_sum = type_sum;
68
                modified = true;
```

```
}
                (node->max_overlap_num != max_overlap_num)
            {
                 node->max_overlap_num = max_overlap_num;
73
                modified = true;
74
            }
               (node->max_overlap_node != max_overlap_node)
76
            {
                 node->max_overlap_node = max_overlap_node;
                 modified = true;
            }
            return modified;
81
        }
82
83
        // start to check augmented attributes from node->parent to root_
        template <class Key, class T>
        void IntervalTreePOM<Key, T>::FixAugmentedAttributes(Node* node)
86
        {
            Key max;
            while (node != root_)
            {
                node = node->parent;
91
                 if (MaintainAugmentedAttributesOfSingleNode(node) == false) break;
92
            }
93
        }
        template <class Key, class T>
96
        std::pair<typename IntervalTreePOM<Key, T>::Iterator, bool>
97
            IntervalTreePOM<Key, T>::Insert(const ValueType& value)
        {
99
            Node **node_ptr, *lower_node, *higher_node,
            node_ptr = FindNodePtrByLowerKey(value.interval.low, &parent);
101
            if (*node_ptr == nil_)
102
            {
103
                 /* insert lower endpoint */
                 lower_node = new Node(value.interval.low);
105
                 *node_ptr = lower_node;
106
                 lower_node->parent = parent;
107
                 lower_node->left = nil_;
108
                 lower_node->right = nil_;
109
```

```
lower_node->color = Node::RED;
110
                 lower_node->mapped_value = value.mapped_value;
111
                 lower_node->endpoint_type = Node::LOWER;
112
                 MaintainAugmentedAttributesOfSingleNode(lower_node);
113
                 FixAugmentedAttributes(lower_node);
114
                 InsertFixup(lower_node);
                 /* insert higher endpoint */
116
                 node_ptr = FindLeafNodePtrToInsertByKey(value.interval.high, &parent);
117
                 higher_node = new Node(value.interval.high);
118
                 *node_ptr = higher_node;
119
                 lower_node->related_endpoint = higher_node;
120
                 higher_node->related_endpoint = lower_node;
121
                 higher_node->parent = parent;
122
                 higher_node->left = nil_;
123
                 higher_node->right = nil_;
124
                 higher_node->color = Node::RED;
125
                 higher_node->endpoint_type = Node::HIGHER;
126
                 MaintainAugmentedAttributesOfSingleNode(higher_node);
127
                 FixAugmentedAttributes(higher_node);
128
129
                 InsertFixup(higher_node);
                 return std::make_pair(Iterator(lower_node, this), true);
             }
131
             else
132
             {
133
                 return std::make_pair(Iterator(nil_, this), false);
134
             }
        }
136
137
        template <class Key, class T>
138
        void IntervalTreePOM<Key, T>::Delete(Iterator pos)
139
        {
             DeleteNode(pos.node_->related_endpoint);
141
             DeleteNode(pos.node_);
142
        }
143
144
        template <class Key, class T>
        void IntervalTreePOM<Key, T>::DeleteNode(Node *node)
146
147
             Node *replaced, *replaced_replaced;
148
             bool is_black_deleted;
149
```

```
replaced = node;
             is_black_deleted = replaced->color == Node::BLACK;
151
             if (replaced->left == nil_)
152
             {
153
                 replaced_replaced = replaced->right;
154
                 Transplant(replaced, replaced_replaced);
                 FixAugmentedAttributes(replaced_replaced); // replaced_replaced will NOT be check
156
             }
157
             else if (replaced->right == nil_)
158
             {
                 replaced_replaced = replaced->left;
                 Transplant(replaced, replaced_replaced);
161
                 FixAugmentedAttributes(replaced_replaced);// replaced_replaced will NOT be check
162
             }
163
             else
164
             {
165
                 replaced = TreeMinimum(node->right);
166
                 is_black_deleted = replaced->color == Node::BLACK;
167
                 replaced_replaced = replaced->right;
168
                 if (replaced->parent == node)
169
                 {
                     replaced_replaced->parent = replaced;
171
                 }
172
                 else
173
                 {
174
                     Transplant(replaced, replaced_replaced);
175
                     replaced->right = node->right;
176
                     replaced->right->parent = replaced;
177
                 }
                 Transplant(node, replaced);
179
                 replaced->left = node->left;
                 replaced->left->parent = replaced;
181
                 replaced->color = node->color;
182
                 FixAugmentedAttributes(replaced_replaced); // replaced_replaced will NOT be check
183
                 FixAugmentedAttributes(replaced->right); // so replaced will be checked
             }
185
             if (is_black_deleted)
186
                 DeleteFixup(replaced_replaced);
187
             delete node;
188
        }
189
```

```
190
        template <class Key, class T>
191
        Key IntervalTreePOM<Key, T>::FindPOM()
192
193
            return root_->max_overlap_node->key;
194
195
14-2
(a)
        /**
        * running time: O(mn)
        * caller is responsible to deallocate the return value
         * n, m must greater than 0
        */
        std::vector<int>* GetJosephusPermutation(int n, int m)
        {
            Node *nodes, **ptr;
            std::vector<int>* result;
            int i;
            /* allocate nodes */
11
            nodes = new Node[n];
12
            /* build circular singly linked list */
13
            for (i = 0; i < n - 1; ++i)
14
            {
                 nodes[i].key = i + 1;
16
                 nodes[i].next = &(nodes[i + 1]);
17
            }
18
            nodes[i].key = i + 1;
            nodes[i].next = nodes;// &(nodes[0])
            /* allocate vector */
21
            result = new std::vector<int>;
22
            result->reserve(n);
23
            /* output */
            /* find the m-th key */
^{25}
            ptr = &(nodes[n - 1].next);
26
            for (i = 1; i < m; ++i) ptr = &((*ptr)->next);
27
            while (true)
28
            {
                 /* add the key into the permutation */
```

```
result->push_back((*ptr)->key);
                /* remove the key */
32
                if (*ptr == (*ptr)->next) break;
33
                *ptr = (*ptr)->next;
34
                /* find the next m-th key */
35
                for (i = 1; i < m; ++i) ptr = &((*ptr)->next);
            }
37
            /* deallocate nodes */
38
            delete[] nodes;
39
            /* return */
40
            return result;
       }
(b)
        /**
        * running time: O(nlgn)
        * caller is responsible to deallocate the return value
        * n, m must greater than 0
       std::vector<int>* GetJosephusPermutation(int n, int m)
            int i, rank;
            OrderStatisticsTree<int, int> ostree;
            OrderStatisticsTree<int, int>::Iterator it;
10
            std::vector<int>* result;
            /* build order statistics tree: O(nlqn) */
            for (i = 1; i <= n; ++i) ostree.Insert(std::make_pair(i, 0));</pre>
13
            /* allocate vector */
            result = new std::vector<int>;
15
            result->reserve(n);
16
            /* output: O(nlgn) */
            rank = m;
18
            for (i = n; i > 0; --i)// n \ times
19
20
                rank = ((rank - 1) \% i) + 1;
21
                it = ostree.Select(rank);// O(lgn)
                result->push_back(it->first);
23
                ostree.Delete(it);// O(lqn)
24
                rank += (m - 1);
25
```

```
26      }
27      return result;
28  }
```