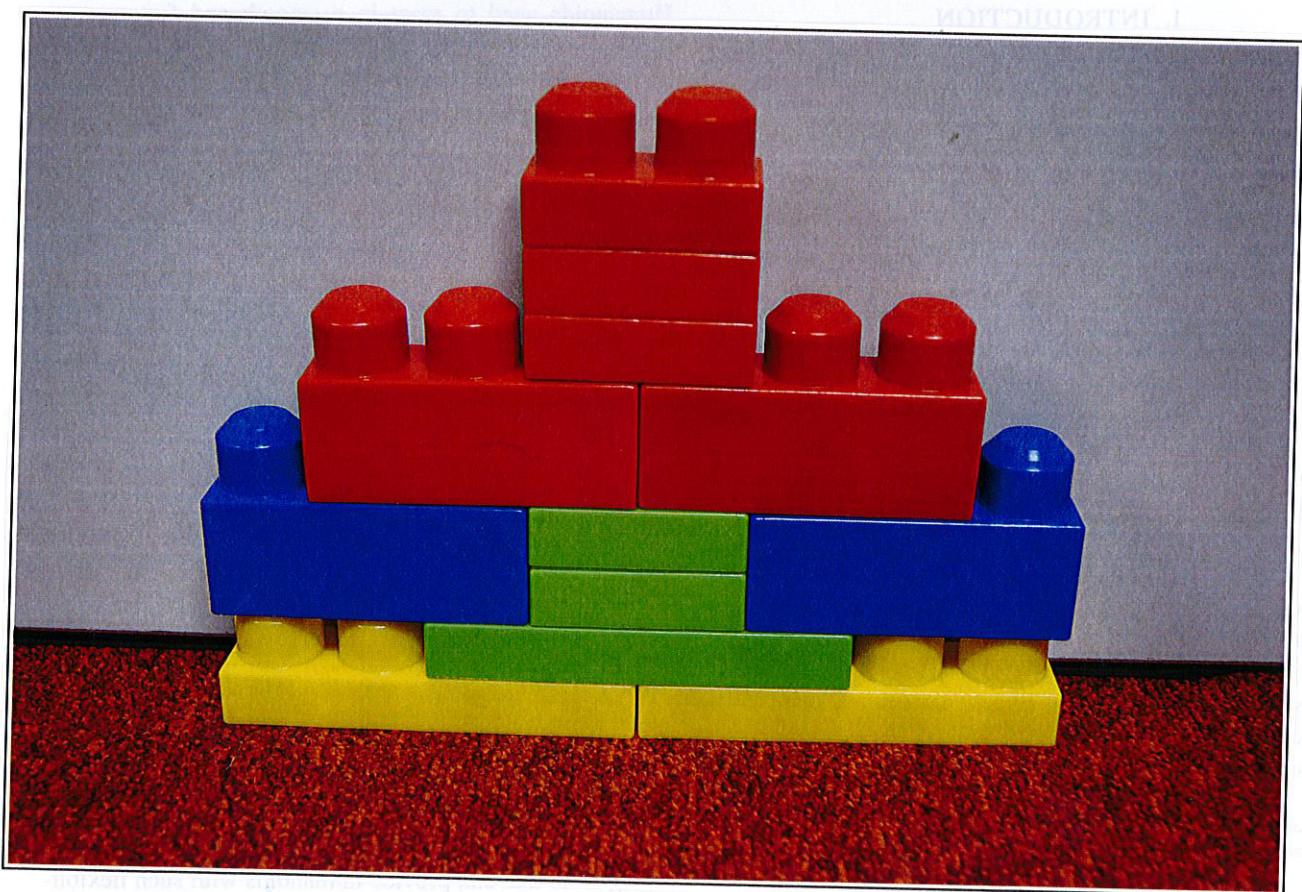


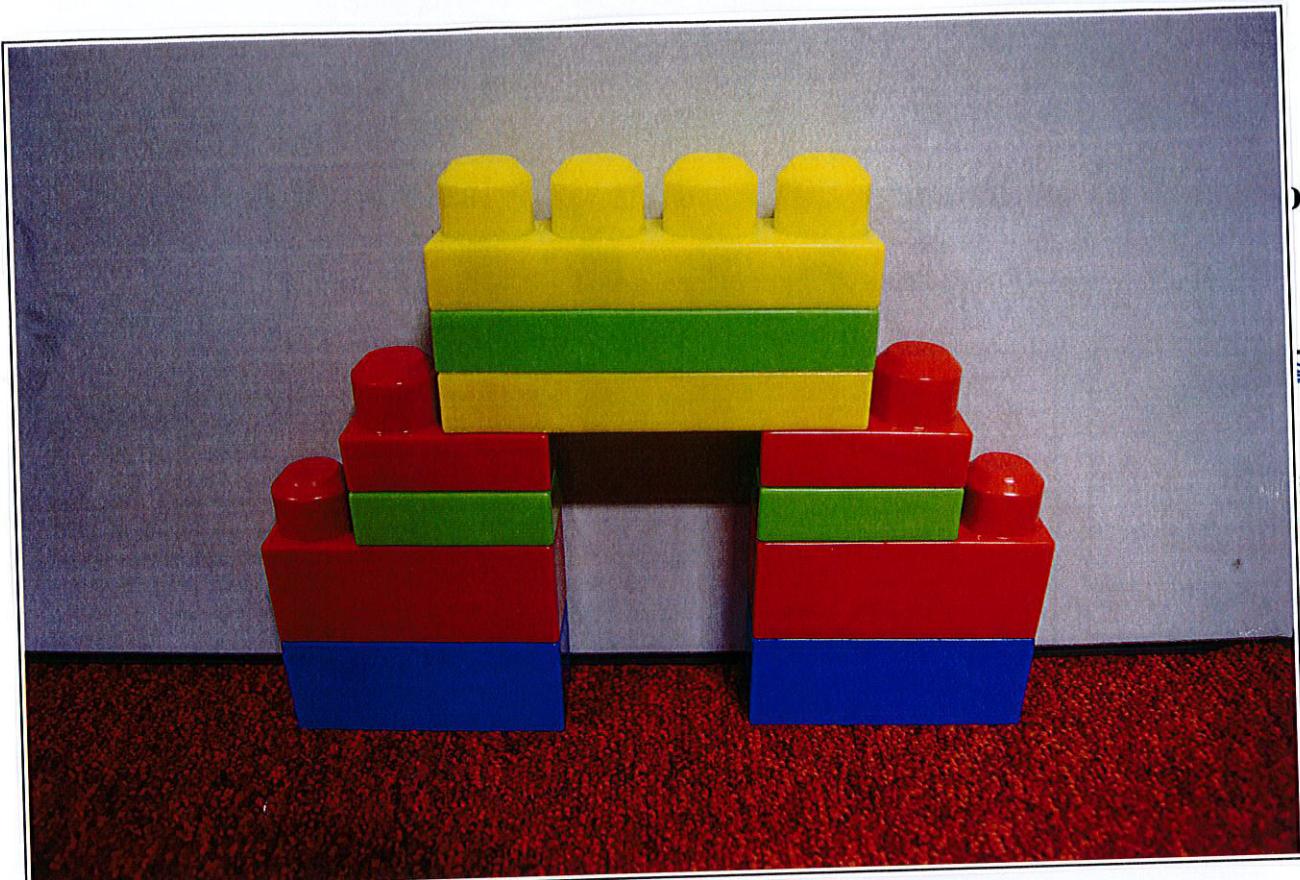
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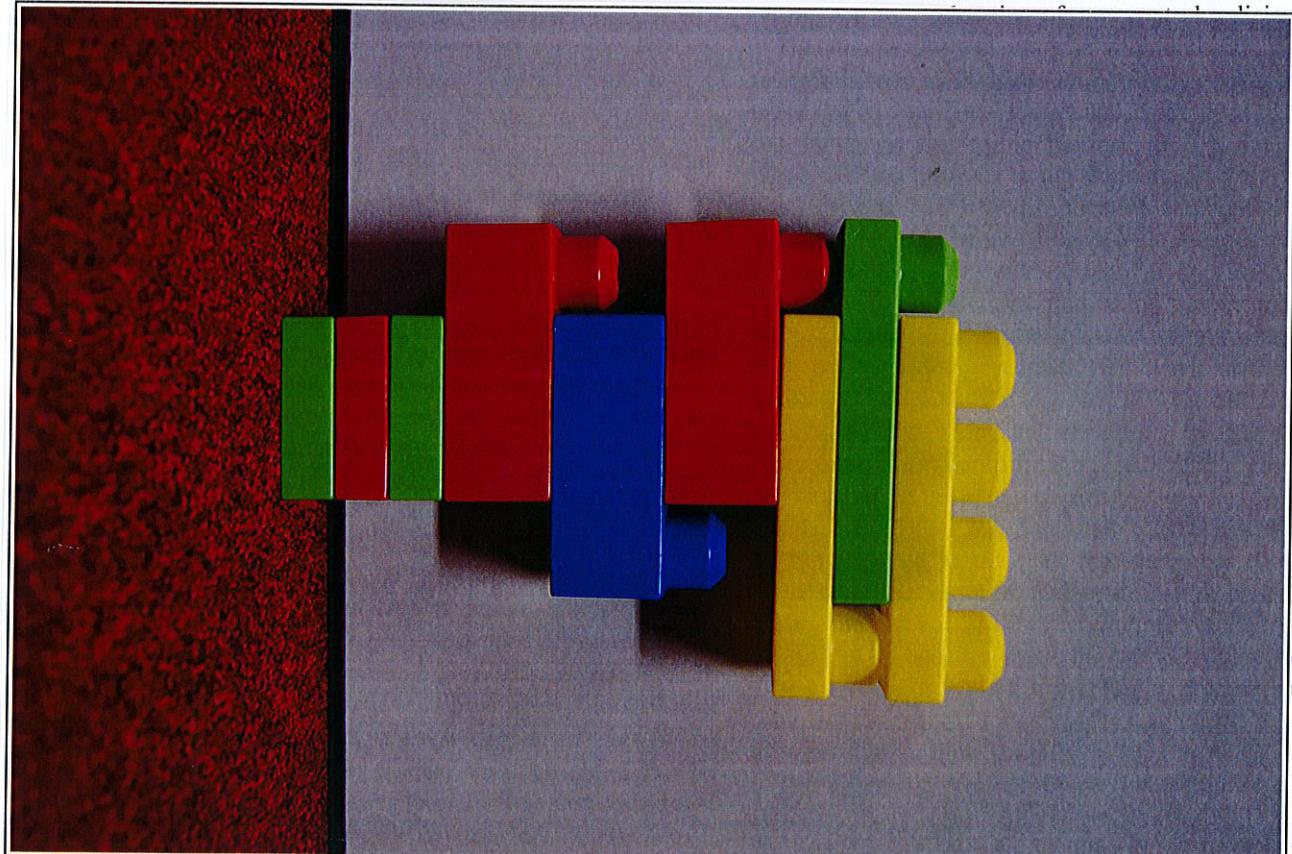
The COMAN compliant humanoid with time-based and time-invariant movements, including bimanual coordination skills.

let the system store, exchange, and re-use this knowledge in an efficient way, as well as to let the robot refine the skill

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Istituto Italiano di Tecnologia (IIT), Via Morego 30, 16163 Genova, Italy.
name.surname@iit.it.

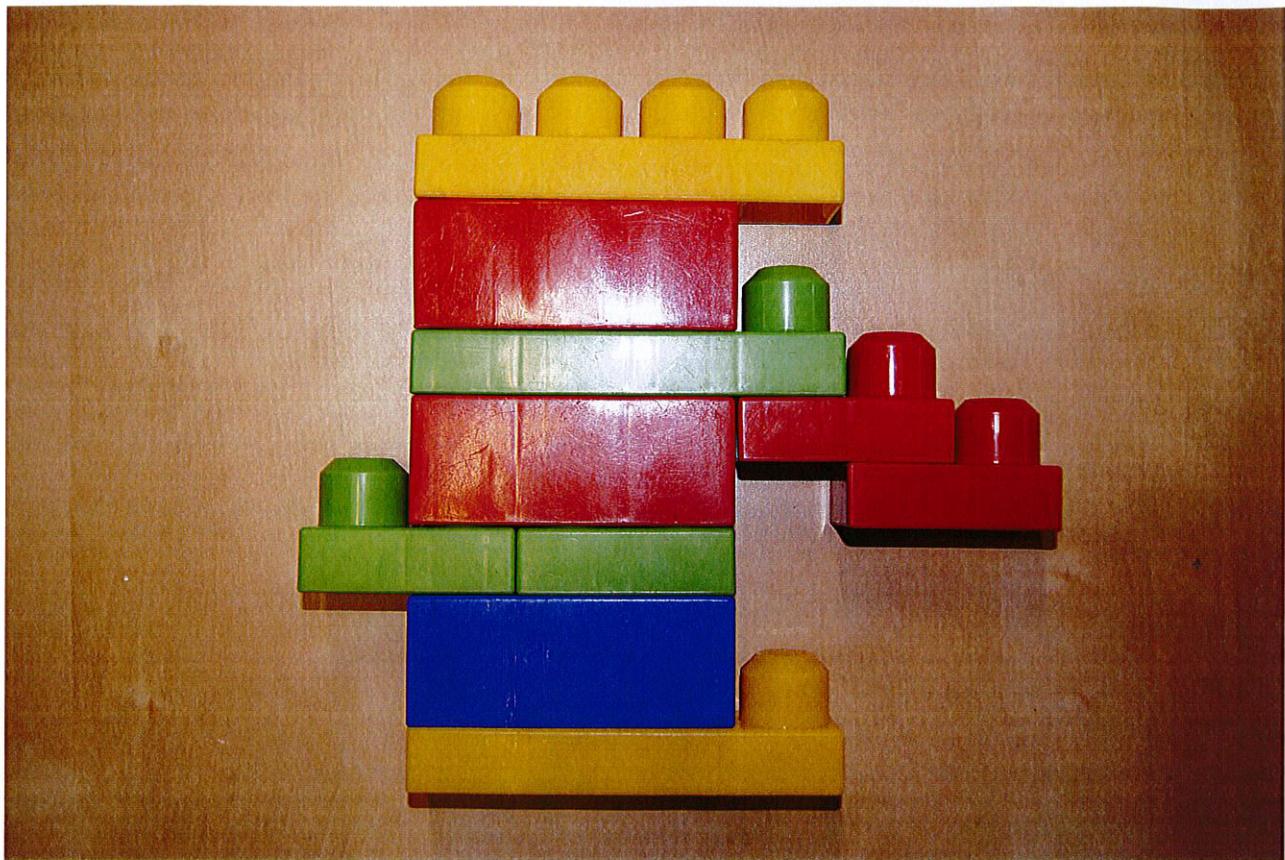
This work was partially supported by the AMARSi European project under contract FP7-ICT-248311, and by the STIFF-FLOP European project under contract FP7-ICT-287728.

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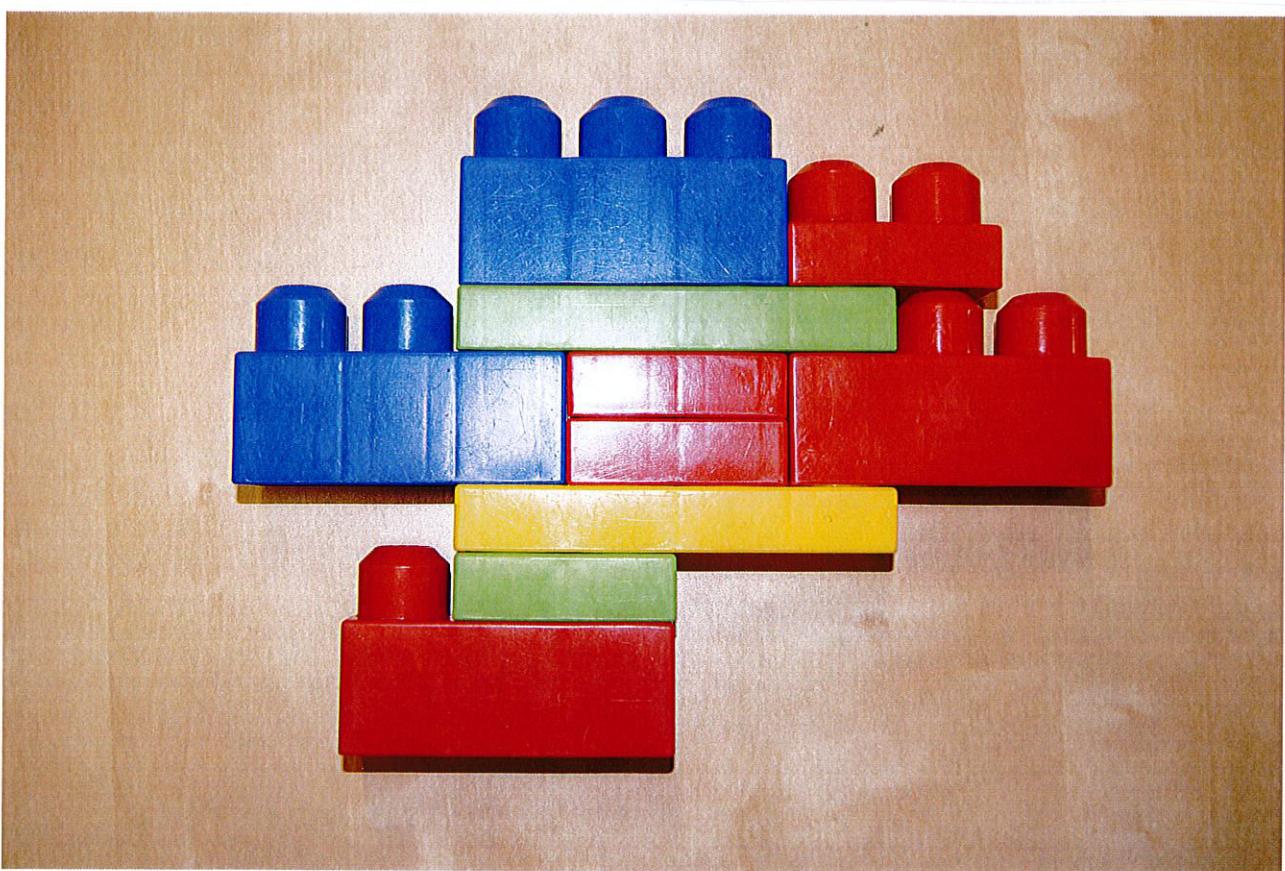
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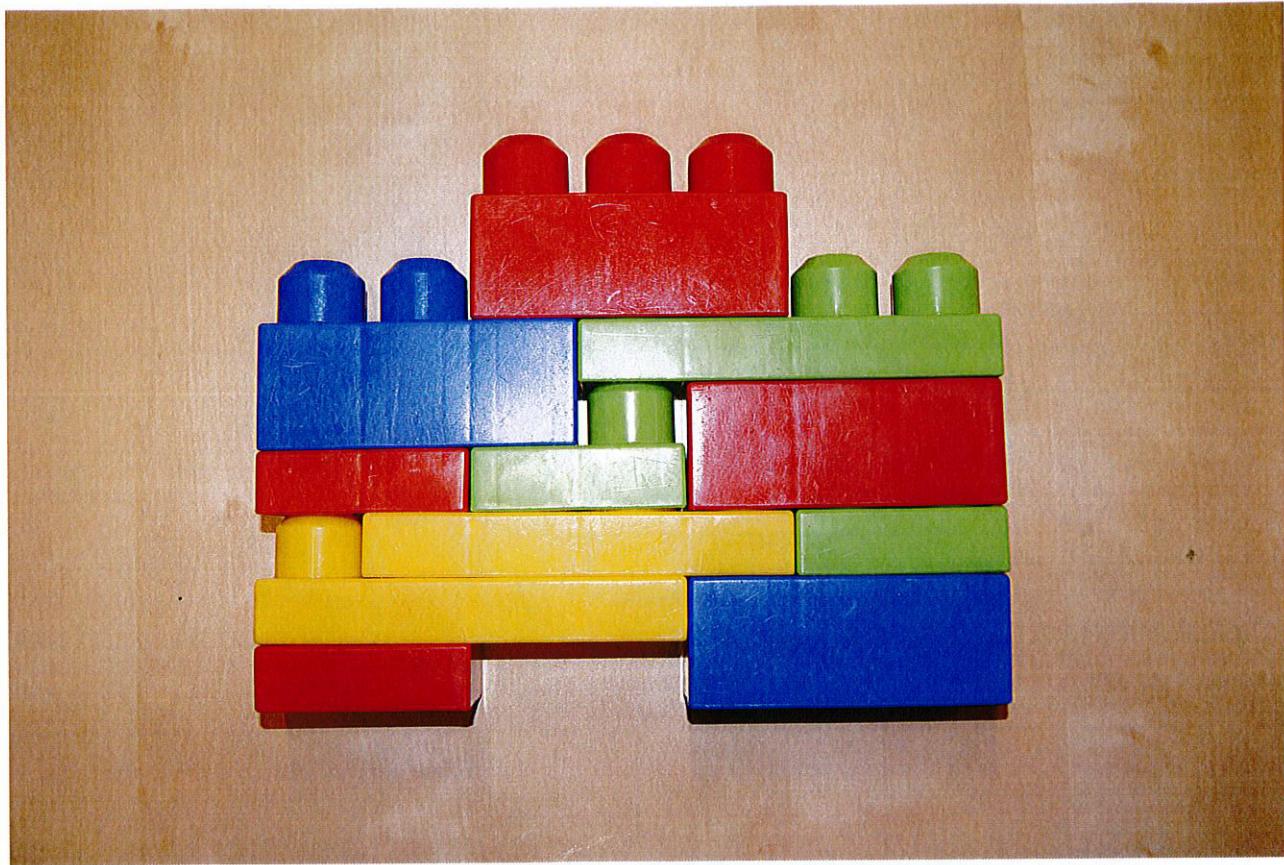
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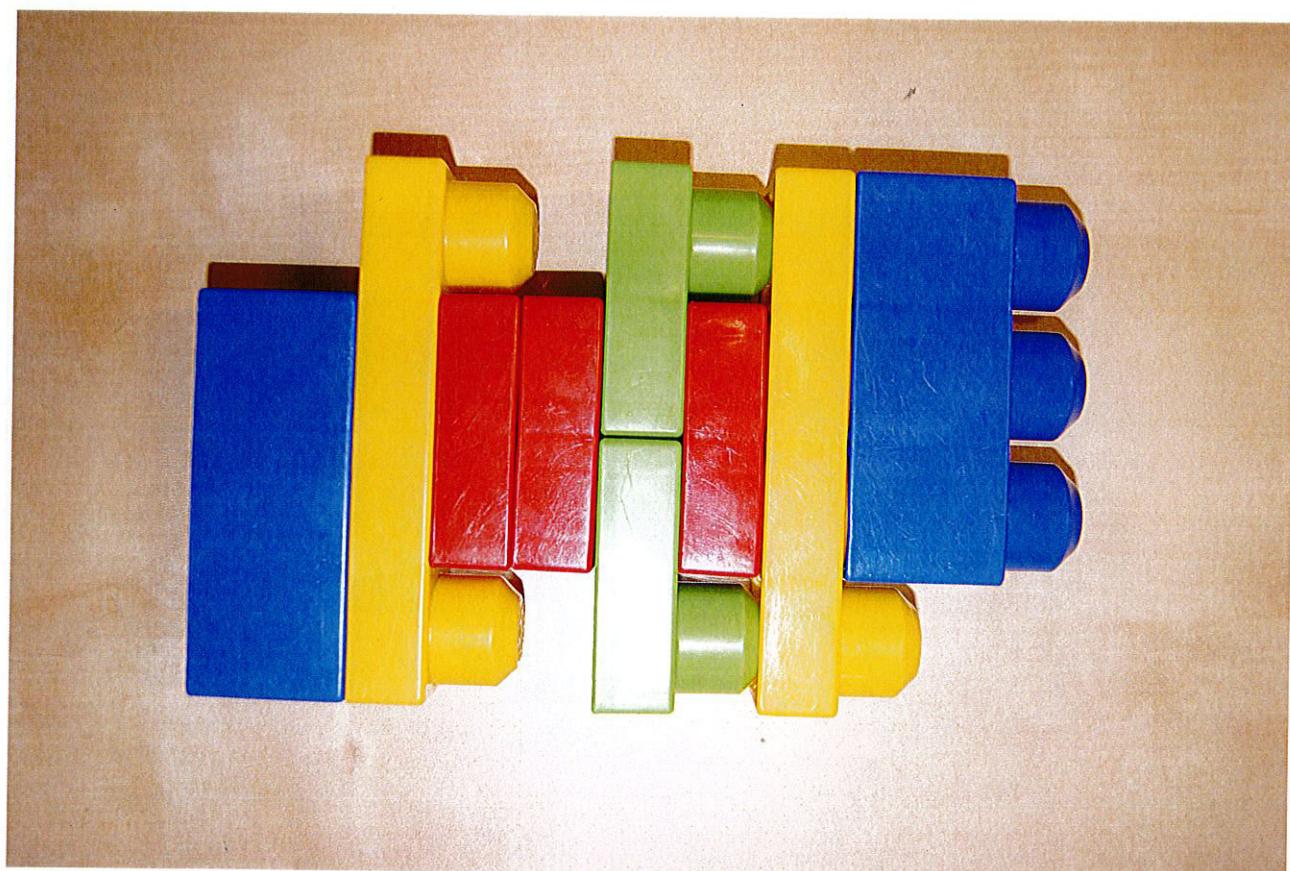
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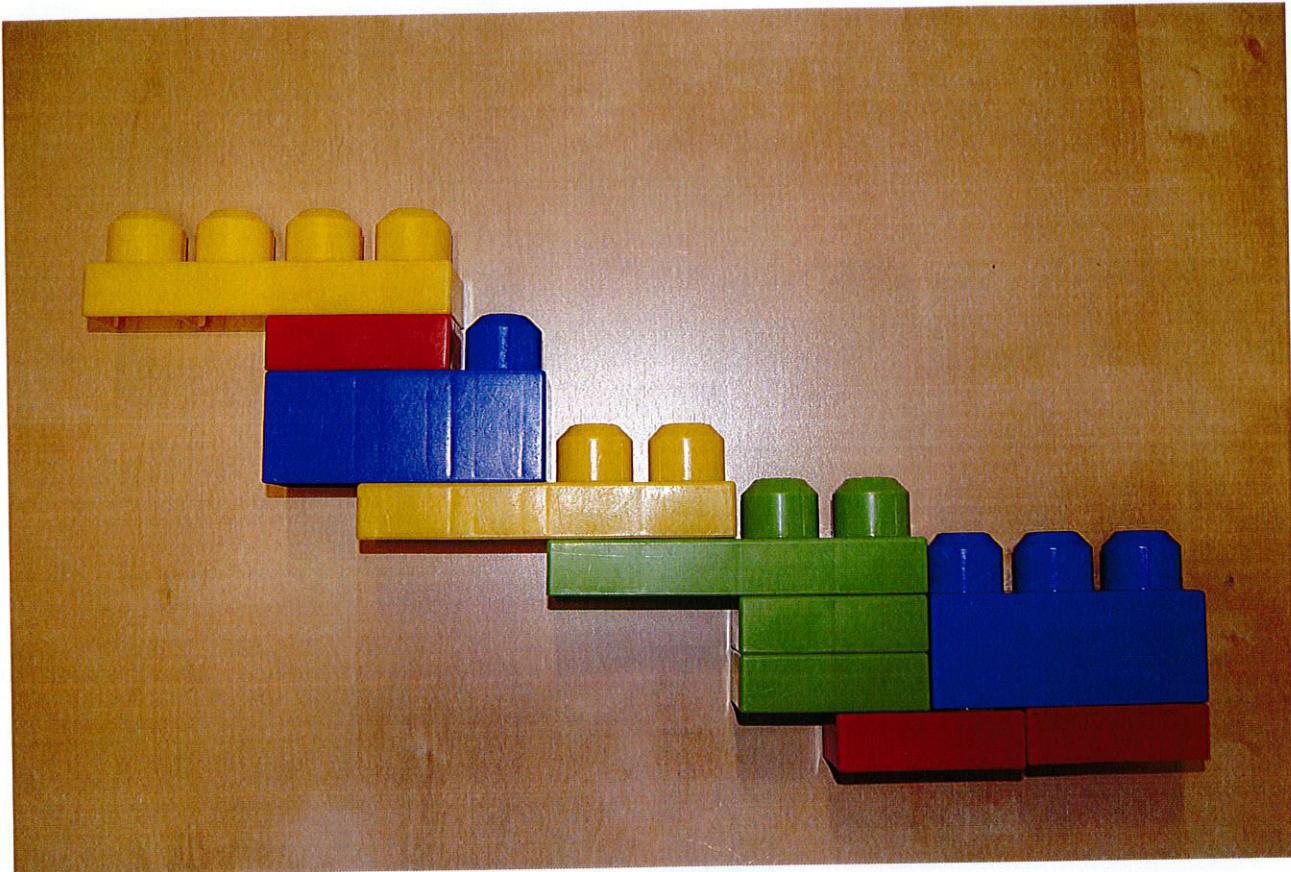


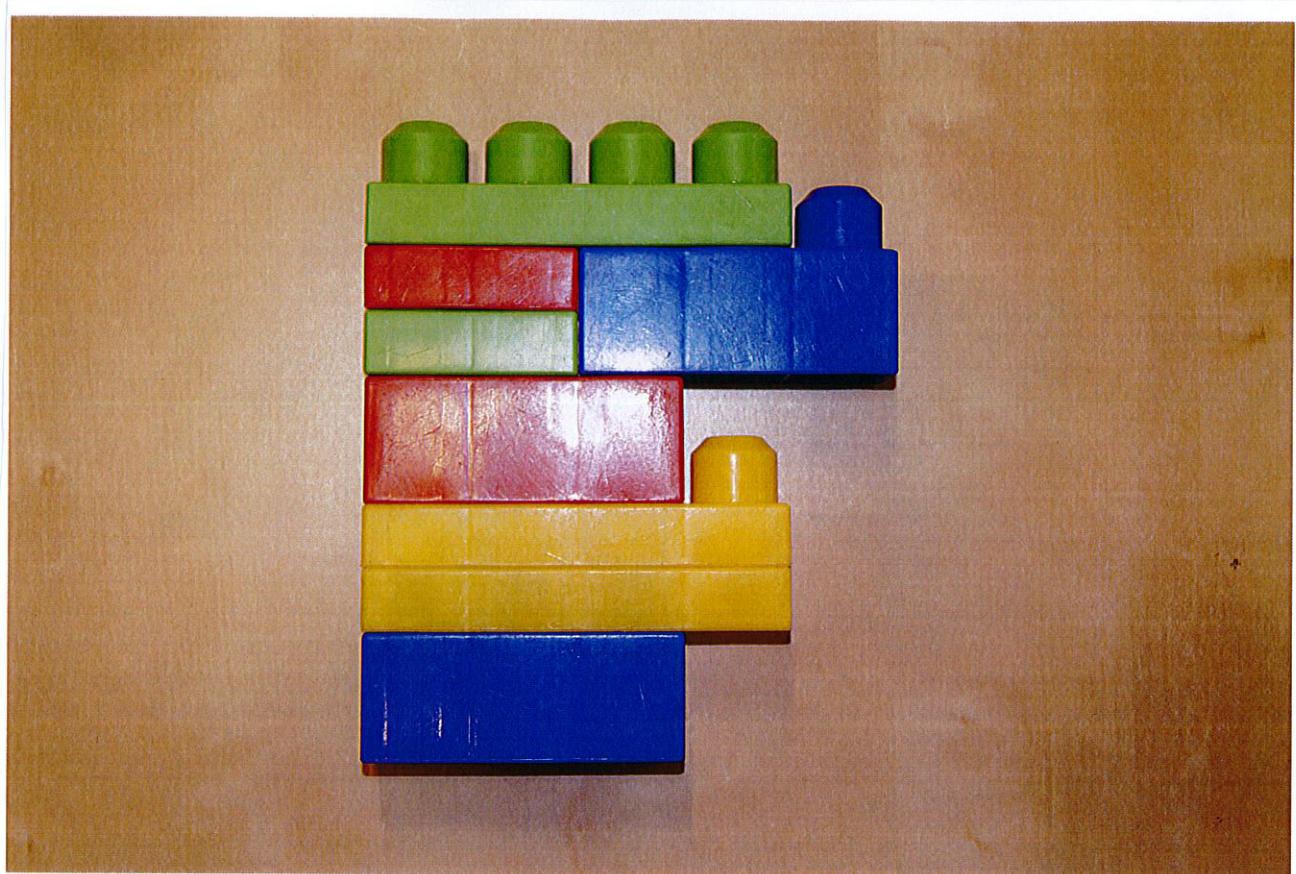
...small town with small houses. Intelligent children...
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INTERSECTION



...small town with small houses. Intelligent children...

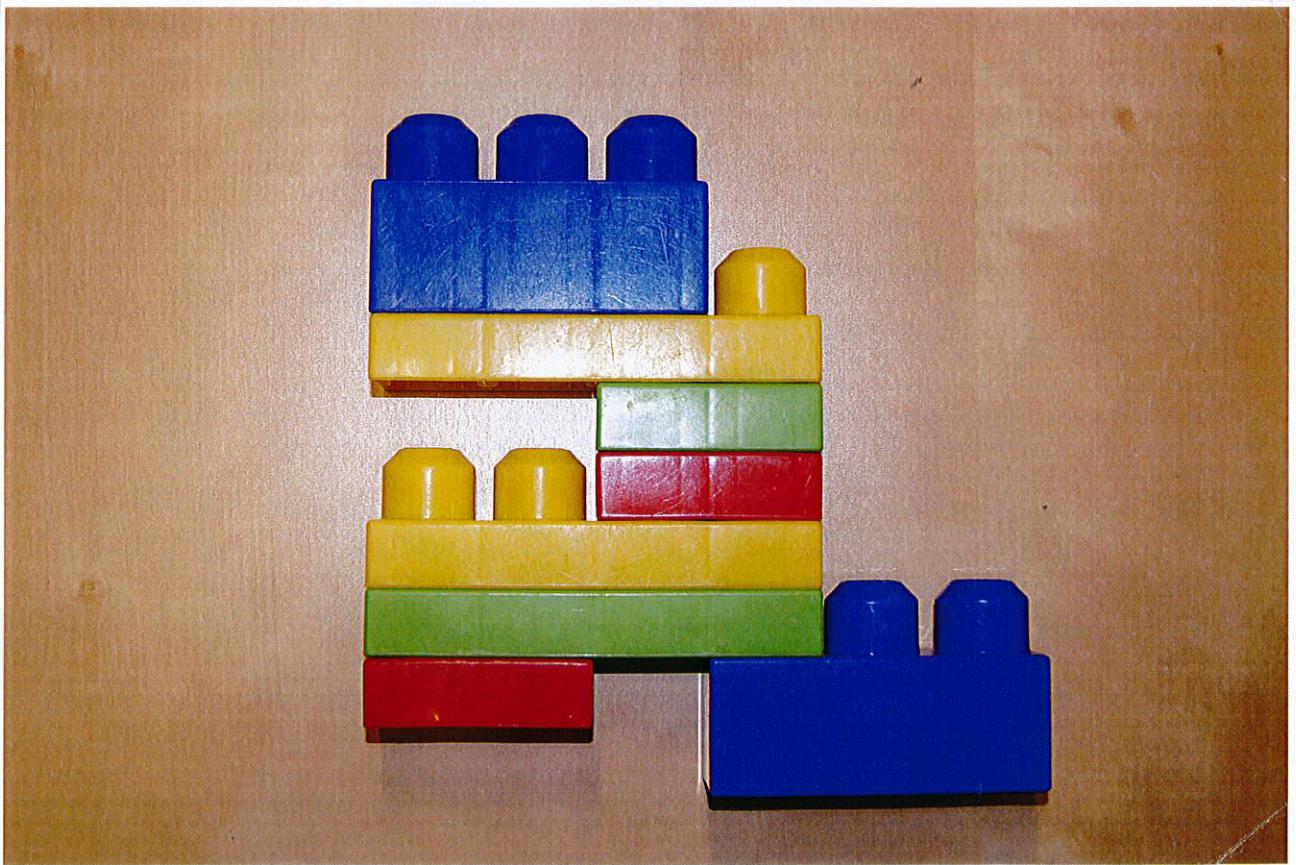




of the world's largest companies have adopted open source as a way to build better products faster and more inexpensively. Now it's time for you to do the same. This book will show you how.

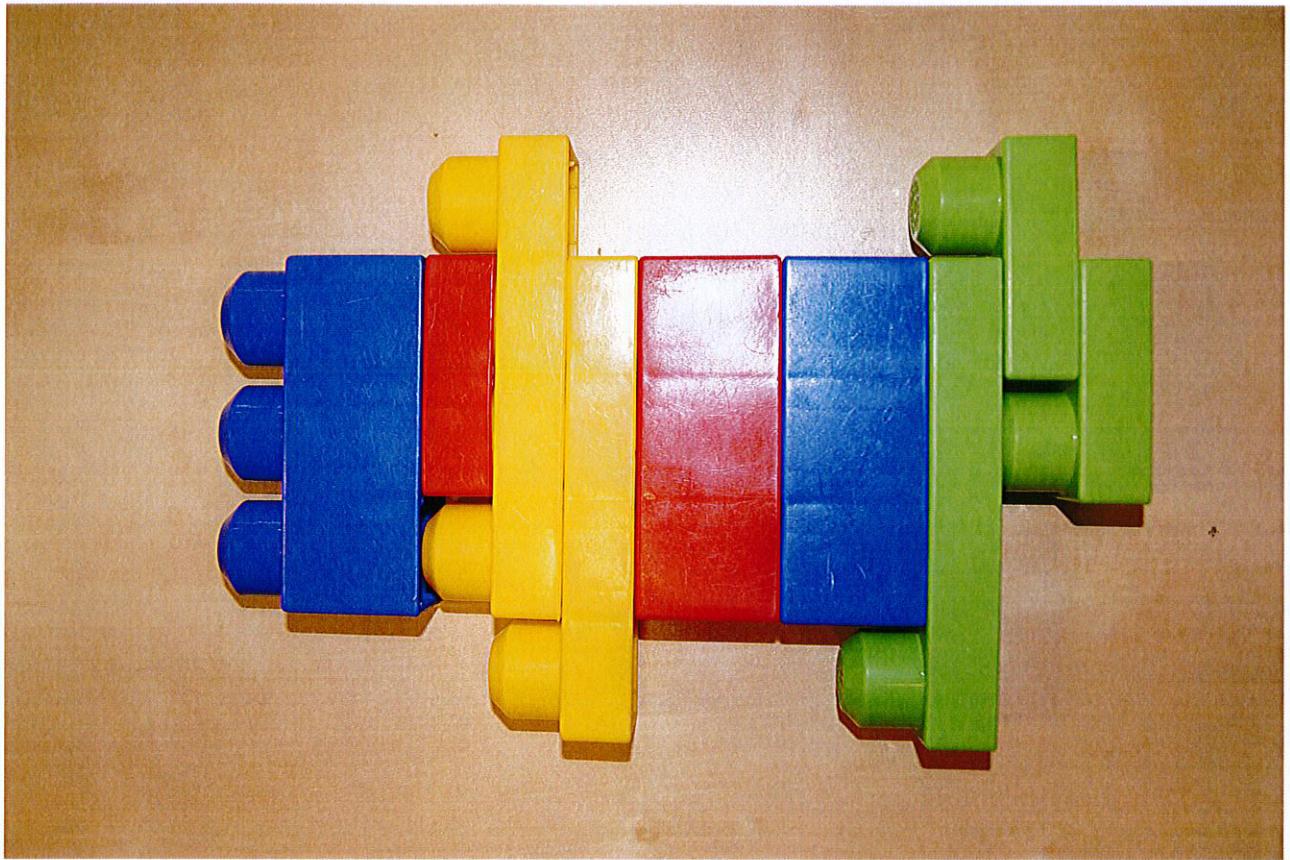
It's a step-by-step guide to the basics of open source development, from setting up your first repository to writing your first line of code.

I. INTRODUCTION



THE OPEN SOURCE REVOLUTION IS COMING. ARE YOU READY?

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I. INTRODUCTION

