

Documentation of CPU project

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Chapter 1

ISA

In this chapter we will introduce the ISA of our CPU. Many different and important aspects of the ISA will be covered. Covered topics are:

- [ISA Table](#)
- [ISA Instruction Formats](#)
- [ISA Encoding](#)

1.1 ISA Table

The given ISA to our group consists of 12 commands, spread into arithmetic, logical, branching and memory categories.

Table 1.1: ISA table

Type	Assembly Instruction
Arithmetic	add, sub, mul
Logical	and, or, nor, nand, andi, ori
Branching	bnq
Memory	lw, sw

Do note that in our CPU all ISA instructions mentioned in table 1.1, deal with registers to get and store data; no operation can be dealt with direct access to memory.

1.2 ISA Instruction Formats

In this CPU we have two types of instruction formats: 1. R-type¹ 2. V-type²; and in this section we will go through details of these formats.

These are the divided assembly instructions of the CPU:

Table 1.2: r-type and v-type instructions

Type	Assembly Instruction	Count
R-type	add, sub, mul, and, or, nor, nand	7
V-type	bnq, lw, sw, andi, ori	5

The instruction format for **recognizing the instruction**³, looks like this:

Table 1.3: Instruction format of r-type and v-type instructions

Type	Opcode	Rs	Rt	Rd	Don't Care	Funct
R	000	nnnn	nnnn	nnnn	14-bit	nnn
Type	Opcode	Rs	Rt	immediate value		
V	nnn	nnnn	nnnn	21-bit		

¹Register format instruction

²Value format instruction

³encoding the assembly instruction in binary

1.3 ISA Encoding

All CPUs only understand zeros and ones, in order to tell the CPU to do this and to do that, we have to encode the instructions.

The instruction code table is below:

Table 1.4: ISA encoding

Instruction (r-type)	Opcode	Funct
add	000	001
sub	000	010
mul	000	011
and	000	100
or	000	101
nor	000	110
nand	000	111

Instruction (v-type)	Opcode
bnq	111
lw	001
sw	010
andi	100
ori	101

Chapter 2

Registers

In this chapter we will look at the register file of the CPU and the design decisions of this important part. Covered topics are:

- Number Of Registers
- Naming Conventions of Registers
- Capacity Of Registers

All the operations which take place in the CPU get their operands and store their results in the register file. For example the instruction:

`add $r1, $r2, $r3`

Which means $\$r3 = \$r1 + \$r2$, the data are fetched from the registers $\$r1$, $\$r2$ and $\$r3$.

There are some decisions for the design of the register file of the CPU which will be discussed below.

2.1 Number Of Registers

After discussions between the team members we decided to put 16 registers in the register file of the CPU.

With this number of registers, we can access them by a four-bit number, because $16 = 2^4$

2.2 Naming Conventions of Registers

The registers are names as follows:

1. \$zero
2. \$at
3. \$a1
4. \$a2
5. \$a3
6. \$l1
7. \$l2
8. \$l3
9. \$t1
10. \$t2
11. \$t3
12. \$t4
13. \$t5
14. \$t6
15. \$t7
16. \$t8

2.2.1 Register Specifications

These register specifications are done just for convenience and safety of the compiled programs. For example, a logical operation operands are better to be placed in \$l# registers. This convention will guarantee the data safety during the program execution.

2.2.1.1 \$zero register

Because the value 0 is used a lot, we put it here. This register will not be overwritten.

2.2.1.2 \$at register

This is the register provided for the assembler to use on its own.

2.2.1.3 a# registers

a# registers are named after the word `arithmetic`. These registers are specific for arithmetic operations.

2.2.1.4 l# registers

l# registers are named after the word `logical`. These registers are specific for arithmetic operations.

2.2.1.5 t# registers

t# registers are named after the word `temporary`. These registers can be used freely by the compiler or assembly programmer.

2.3 Capacity Of Registers

This CPU's registers are 32-bit registers with the capability of parallel load and read.

Chapter 3

Control Unit

Control Unit and Data Path are the two hearts of all CPUs. In this chapter we will show the design of our CPU's control unit.

Control unit, produces some signals to power on or power off some parts of the data path to control the data flow between the gates, registers, the alu and multiplexers of the data path. The table below shows all the control unit signals we need for our ISA (discussed in [ISA](#) chapter) Here is the table of all

3.1 Control Unit Signals Table

The meaning of zeros and ones in the table, are explained in the footnote of the table.

Table 3.1: Control Unit Signals

Control Signal	add	sub	mul	and	or	nor	nand	bng	lw	sw	andi	ori
RegDst	1 ^a	1	1	1	1	1	x	0 ^b	x	0	0	0
ALUSrc	0 ^c	0	0	0	0	0	0	1 ^d	1	1	1	1
MemToReg	0 ^e	0	0	0	0	0	x	1 ^f	x	0	0	0
RegWrite	1 ^g	1	1	1	1	1	x	1	x	1	1	1
MemWrite	0	0	0	0	0	0	0	0	1 ^h	0	0	0
Branch	0	0	0	0	0	0	0	1 ⁱ	0	0	0	0
ALUctrl	add	sub	mul	and	or	nor	nand	sub	add	add	and	or

^aRd^bRt^ca register^dimmediate value^efrom ALU result to a register^ffrom memory to a register^gwrite to register from ALU^hwrite to memory from ALUⁱput one in the branch's and gate.

3.2 Control Unit Design¹

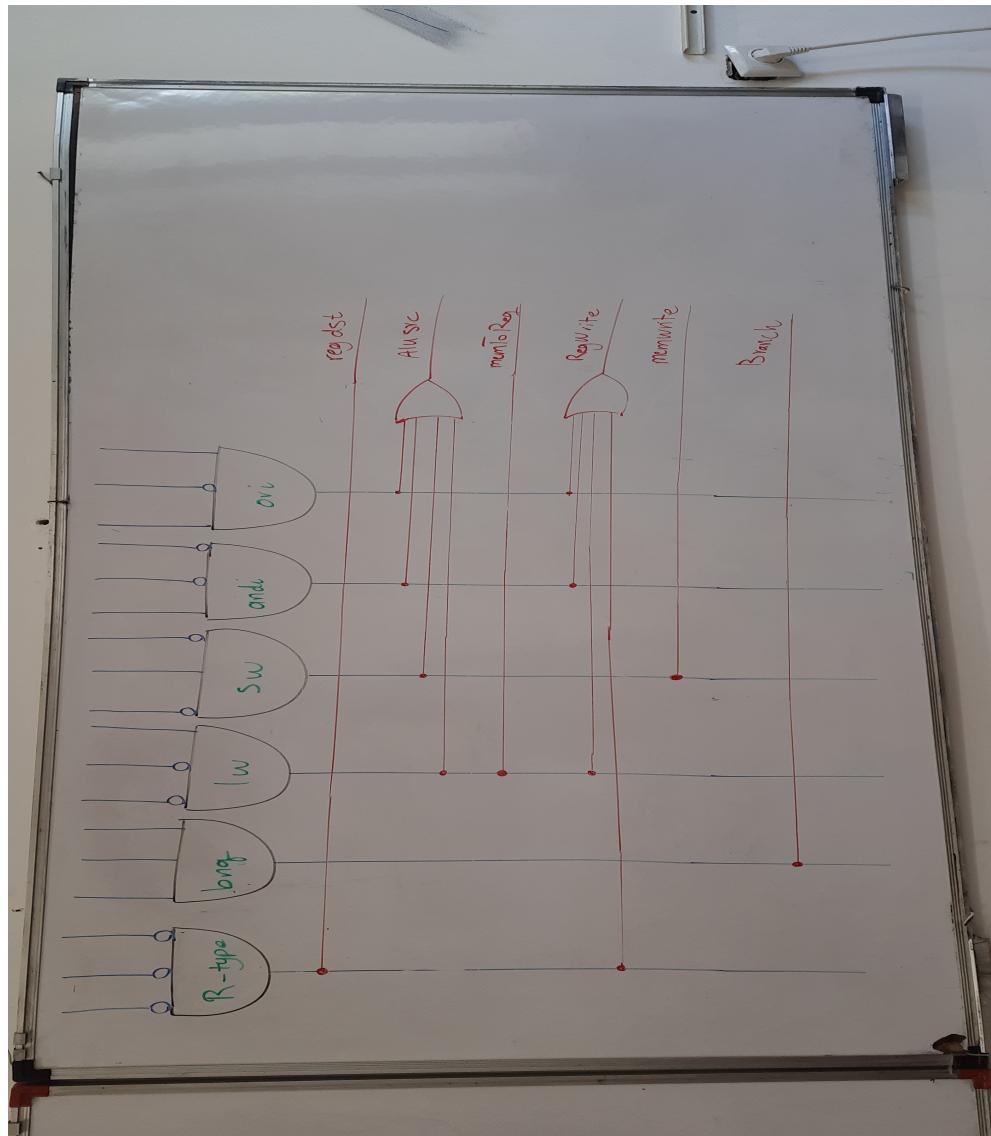


Figure 3.1: Main Control Unit Design

¹These pictures will be designed in Lagisim and replaced

ALU ops:

R-type	R-i	R-l	func	ALU code
0 0 0	-	-	add	0 0 1
0 0 -	-	-	sub	0 1 0
0 1 0	-	-	mul	0 1 1
0 1 -	-	-	and	1 0 0
1 0 0	-	-	or	1 0 1
1 0 -	-	-	nor	1 1 0
1 1 -	-	-	nand	1 1 1

ALU ops:

R-type	R-i	R-l	OP	ALU code
0 0 0	-	-	long	1 1 1
0 0 -	-	-	lw	0 0 1
0 1 0	-	-	sw	0 1 0
0 1 -	-	-	add	0 0 1
1 0 0	-	-	addi	1 0 0
1 0 -	-	-	ori	1 0 1
1 1 0	-	-	or	1 0 1
1 1 -	-	-	nor	1 1 0
-	-	-	nand	1 1 1

Figure 3.2: ALU Control truth table

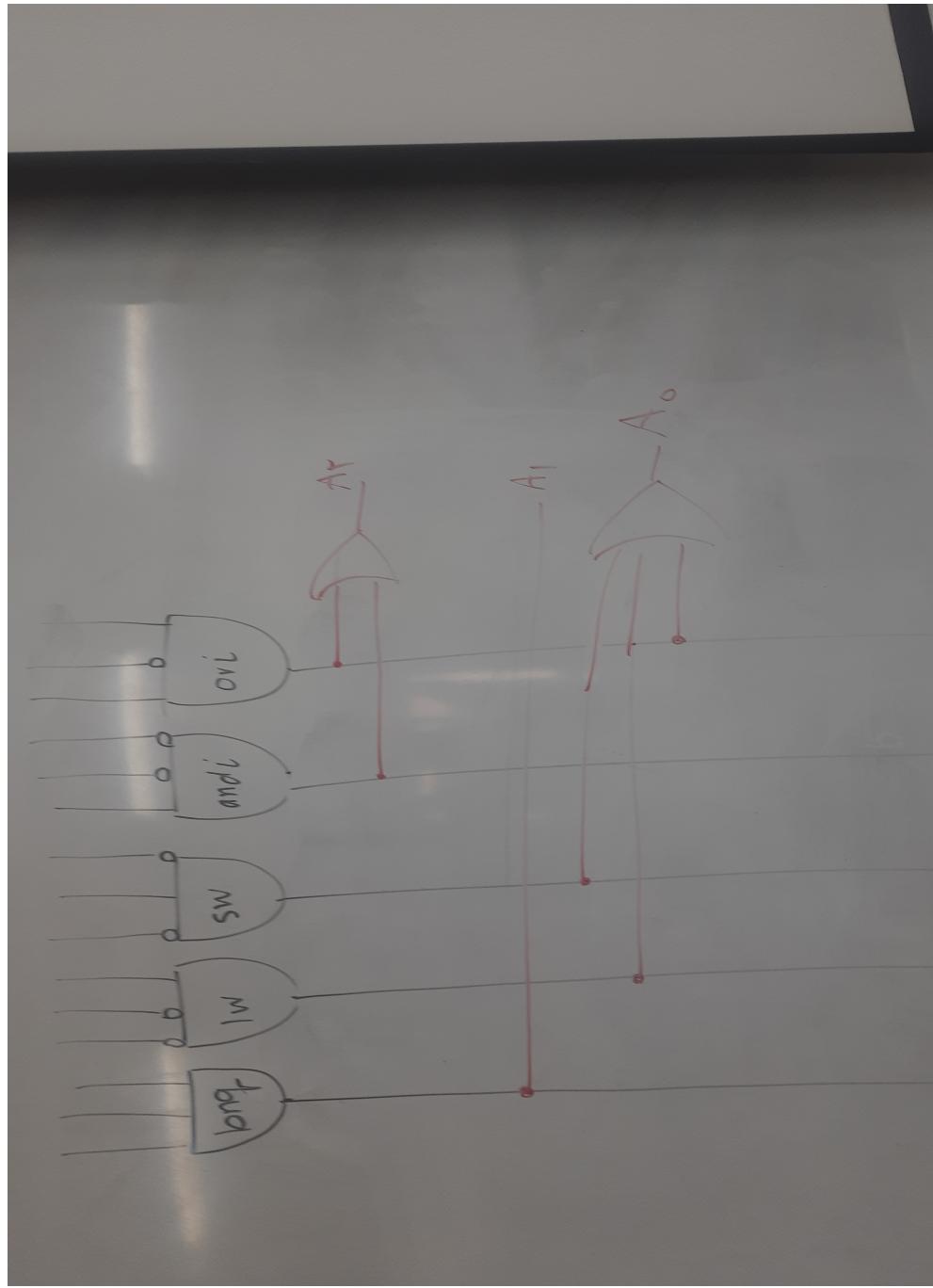


Figure 3.3: ALU Control Design