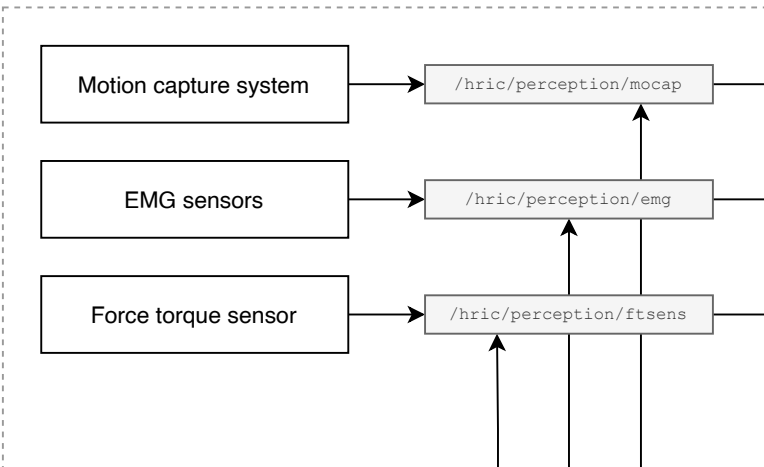
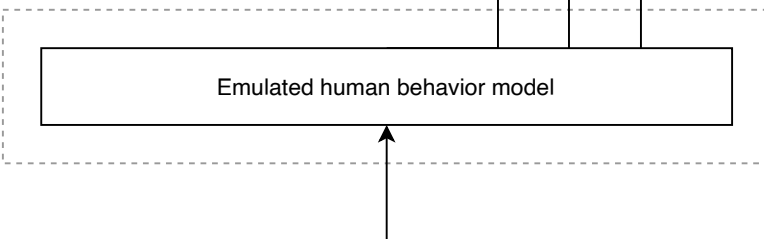


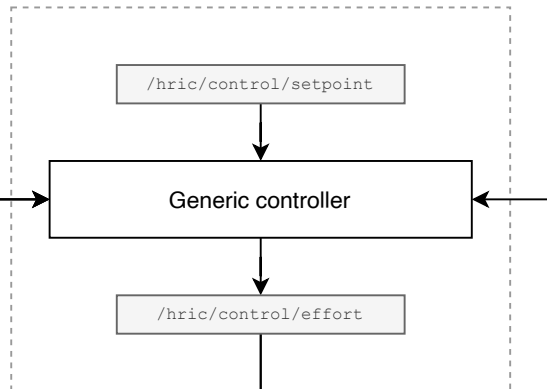
## Perception



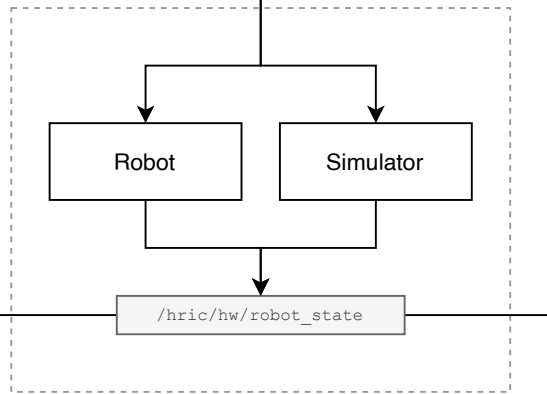
## Emulated Perception



## Control



## Hardware Interfaces



Group

ROS node

ROS topic